Asymptotic analysis of a Neumann problem in a domain with cusp. Application to the collision problem of rigid bodies in a perfect fluid.

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Abstract

We study a two dimensional collision problem for a rigid solid immersed in a cavity filled with a perfect fluid. We are led to investigate the asymptotic behavior of the Dirichlet energy associated to the solution of a Laplace Neumann problem as the distance $\varepsilon > 0$ between the solid and the cavity's bottom tends to zero. Denoting by $\alpha > 0$ the tangency exponent at the contact point, we prove that the solid always reaches the cavity in finite time, but with a non zero velocity for $\alpha < 2$ (real shock case), and with null velocity for $\alpha \ge 2$ (smooth landing case). Our proof is based on a suitable change of variables sending to infinity the cusp singularity at the contact. More precisely, for every $\varepsilon \ge 0$, we transform the Laplace Neumann problem into a generalized Neumann problem set on a domain containing a horizontal strip $]0, \ell_{\varepsilon}[\times]0, 1[$, where $\ell_{\varepsilon} \to +\infty$.

Keywords. Neumann Laplacian, cusp, asymptotic analysis, singular perturbation, fluid-structure, contact, collision.

1 Introduction: motivation, problem setting and statement of the main results

In this paper, we are interested in the asymptotic analysis of a singular perturbed problem for the Laplace Neumann equation in a domain Ω_{ε} depending on a small parameter ε . The typical configuration we have in mind is the one depicted on Figure 1, namely the situation where Ω_{ε} is the domain located between two smooth surfaces situated at a distance ε and touching each other at one single cuspid point (the origin) in the limit case $\varepsilon = 0$.

More precisely, we denote by C a smooth, open, bounded and connected set in \mathbb{R}^2 and we assume that C is symmetric with respect to the ordinate axis, that the origin belongs to the boundary of C and that, near the origin, the boundary ∂C is locally a straight line, the domain C being locally situated above ∂C . We denote by S_0 a compact, connected set, symmetric with respect to the ordinate axis as well and such that, for some $\varepsilon^* > 0$, the inclusion $S_{\varepsilon} := S_0 + \varepsilon e_2 \subset C$ holds for every $0 < \varepsilon \leq \varepsilon^*$ (throughout the paper, $\{e_1, e_2\}$ stands for an orthonormal basis). With these settings, we have $\Omega_{\varepsilon} := C \setminus S_{\varepsilon}$ for every $0 \leq \varepsilon \leq \varepsilon^*$ and we assume that there exists $\delta^* > 0$ such that Ω_{ε} is locally, near the origin described by:

$$\{\xi := (\xi_1, \xi_2) \in \mathbb{R}^2 : |\xi_1| < \delta^*, \ 0 < \xi_2 < H_{\varepsilon}(\xi_1)\},\$$

where

$$H_{\varepsilon}(\xi_1) := \kappa |\xi_1|^{1+\alpha} + \varepsilon,$$

the constants $\kappa > 0$ and $\alpha > 0$ (called the tangency exponent) being given.

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Figure 1: The symmetric domains Ω_{ε} for $\varepsilon > 0$ and the singular limit domain Ω_0 .

The Neumann problem we shall consider is the following one:

$$-\Delta U_{\varepsilon} = F_{\varepsilon} \quad \text{in } \Omega_{\varepsilon} \tag{1.1a}$$

 $\partial_n U_{\varepsilon} = G_{\varepsilon} \quad \text{on } \Gamma_{\varepsilon}$ $\partial_{\varepsilon} U_{\varepsilon} = 0 \quad \text{on } \partial C$ (1.1b)

$$\partial_n U_{\varepsilon} = 0 \quad \text{on } \partial \mathsf{C}, \tag{1.1c}$$

where $\Gamma_{\varepsilon} := \partial S_{\varepsilon}$ denotes the boundary of the inclusion, n is the unit normal to $\partial \Omega_{\varepsilon}$ directed toward the exterior of Ω_{ε} and F_{ε} and G_{ε} are given functions respectively defined on Ω_{ε} and Γ_{ε} and satisfying the compatibility condition:

$$\int_{\Omega_{\varepsilon}} F_{\varepsilon} \,\mathrm{d}\xi + \int_{\Gamma_{\varepsilon}} G_{\varepsilon} \,\mathrm{d}s = 0.$$
(1.2)

Our main objective in this paper is to study the asymptotic behavior of U_{ε} as $\varepsilon \to 0^+$, and more specifically, the behavior of the associated Dirichlet energy $\int_{\Omega_{\varepsilon}} |\nabla U_{\varepsilon}|^2 d\xi$ as $\varepsilon \to 0^+$. For simplicity, only volume data F_{ε} and boundary data G_{ε} symmetric with respect to the ordinate axis will be considered.

Let us now describe the physical problem motivating such an asymptotic analysis.

1.1 Underlying fluid-structure contact problem

We are interested in investigating the possibility of a collision between a neutrally buoyant rigid solid with the bottom of the bounded cavity where it is immersed. In addition to the solid, the cavity is supposed to be filled with a perfect fluid.

Sticking to the notation of the previous section, we denote by C the cavity (C has the same properties as in the previous section), and for every time t > 0, by S_t the domain occupied by the solid and by Ω_t the fluid domain.

To simplify, we shall assume furthermore that at the initial time:

- 1. $S_{t=0} = S_{\varepsilon^*}$ (S_{ε^*} has the same properties as above, in particular regarding topology and symmetry).
- 2. The flow is irrotational, which entails, according to Helmholtz's third theorem, that it will remain irrotational for every time;
- 3. The velocity of the solid is vertical.

With these settings, for symmetry reason, the motion of the solid will take place along the ordinate axis only and S_t and Ω_t will remain symmetric with respect to this axis at every moment.

In particular, the lowest point of S_t (which we assume, for the time being, to be unique) has coordinates $(0, \varepsilon(t))$ and the velocity of the solid is therefore $(0, \varepsilon'(t))$ (here and subsequently, the prime denotes the time derivative).

Classically in ideal fluid theory, according to Hypothesis 2 above, we introduce at every time $t \ge 0$ the Kirchhoff potential $\varphi(t, \cdot)$ related to the vertical motion of the solid. This function solves a Laplace equation in Ω_t with Neumann boundary conditions, namely:

$$-\Delta\varphi(t,\cdot) = 0 \quad \text{in } \Omega_t \tag{1.3a}$$

$$\partial_n \varphi(t, \cdot) = n_2 \quad \text{on } \Gamma_t$$
 (1.3b)

$$\partial_n \varphi(t, \cdot) = 0 \quad \text{on } \partial \mathsf{C},$$
 (1.3c)

where $\Gamma_t := \partial S_t$ and $n = (n_1, n_2)$ stands for the unit normal to $\partial \Omega_t$ directed towards the outside of the fluid. The Eulerian velocity of the fluid reads:

$$u(t, \cdot) = \varepsilon'(t) \nabla \varphi(t, \cdot) \quad \text{in } \Omega_t \qquad (t \ge 0).$$

Notice at this point that the domains, and thus also the potential function, depend on t only through $\varepsilon(t)$. Consequently, from now on, we shall return to the notation of the previous section and we will denote by Ω_{ε} , S_{ε} , Γ_{ε} and $\varphi(\varepsilon, \cdot)$ respectively Ω_t , S_t , Γ_t and $\varphi(t, \cdot)$.

The dynamics governing the motion of the solid can now be derived easily from the conservation of energy of the frictionless fluid/solid system. We denote by m_s the mass of the solid and by ρ_f the density of the fluid. Recall that the solid is assumed to be neutrally buoyant, so the total energy of the system reduces to the kinetic energy which reads merely $E(\varepsilon, \varepsilon') := \frac{1}{2}(m_s + m_f(\varepsilon))|\varepsilon'|^2,$

where

$$m_f(\varepsilon) := \varrho_f \int_{\Omega_{\varepsilon}} |\nabla \varphi(\varepsilon, \xi)|^2 \,\mathrm{d}\xi, \tag{1.4}$$

is the so-called added mass of the solid. Denoting by $\varepsilon'_0 < 0$ the initial value of $\varepsilon'(t)$ (the initial velocity being $(0, \varepsilon'_0)$), the identity $E(\varepsilon(t), \varepsilon'(t)) = E(\varepsilon^*, \varepsilon'_0)$ for every t > 0 leads to the following first order autonomous Cauchy problem for ε :

$$\varepsilon'(t) = \varepsilon'_0 \sqrt{\frac{m_s + m_f(\varepsilon^*)}{m_s + m_f(\varepsilon(t))}}, \quad t > 0$$
(1.5a)

$$\varepsilon(t)|_{t=0} = \varepsilon^* > 0. \tag{1.5b}$$

It is proved in [4] in a more general context that the function

$$\varepsilon \in]0, \varepsilon^*] \mapsto m_f(\varepsilon) \in \mathbb{R}^+$$

is analytic, so there is no regularity issue as long as $\varepsilon(t) > 0$. Actually, classical results for ODE ensure that the solution exists as long as $\varepsilon(t) > 0$ (i.e. as long as the solid does not touch the boundary of the cavity). Considering the Cauchy problem (1.5), it is clear that the asymptotic behavior of the solid when getting closer to the cavity's bottom relies on the asymptotic behavior of $m_f(\varepsilon)$ as $\varepsilon \to 0^+$. The following cases can occur:

- 1. The added mass $m_f(\varepsilon)$ is uniformly bounded for every $\varepsilon \ge 0$. It entails that ε' is bounded from above by a negative constant and hence the solid will collide with the cavity's boundary in finite time with nonzero velocity (real shock case);
- 2. The added mass $m_f(\varepsilon)$ goes to $+\infty$ as ε goes to 0. Depending on the strength of the blow up, two sub-cases are to be considered:
 - (a) The solid reaches the boundary of the cavity in finite time with zero velocity ("smooth landing" case, no shock);
 - (b) The solution to the Cauchy problem (1.5) exists for every time $t \ge 0$. In this case $\varepsilon(t) \to 0$ as $t \to +\infty$ (infinite time touchdown case);

The study of collisions between rigid solids was first addressed, to our knowledge, in [16] where the authors prove the lack of collision for a 1D model in which the fluid motion is governed by Burgers' equations and the solids are reduced to material points. This result has been generalized, but still for viscous fluid driven by the Navier-Stokes equations, in 2D and 3D in [6] and [7]. These studies assert that "frontal collisions" can not occur in a viscous fluid, contrarily to what happens in a perfect fluid. Indeed, in [8] the authors prove for a 2D model that a ball immersed in a perfect fluid can hit a wall with non zero velocity in finite time.

In the present paper, we aim to extend this result to more general two dimensional configurations.

1.2 Back to the model problem: a singularly perturbed boundary value problem

As already mentioned above, we will restrict our analysis to symmetric configurations (geometry, sources). For the sake of simplicity, we will use the same notation to denote the full domains C , S_{ε} and Ω_{ε} and their intersections with the half-plane $\{\xi_1 < 0\}$. In addition to $\Gamma_{\varepsilon} := \partial S_{\varepsilon}$ and $\partial \mathsf{C}$, the boundary $\partial \Omega_{\varepsilon}$ is hence from now on composed of $\Gamma^b_{\varepsilon} := \{(0, \xi_2) : 0 < \xi_2 < \varepsilon\}$ and $\Gamma^t_{\varepsilon} := \partial \Omega_{\varepsilon} \setminus (\partial \mathsf{C} \cup \Gamma_{\varepsilon} \cup \Gamma^b_{\varepsilon})$ (see Figure 2). The analysis



Figure 2: The new domain Ω_{ε} ($\varepsilon \ge 0$).

of Problem 1.3 (in the symmetric case considered here) leads to solving the following problem set in the half cavity:

$$-\Delta U_{\varepsilon} = 0 \qquad \text{in } \Omega_{\varepsilon} \tag{1.6a}$$

$$\partial_{\tau} U_{\tau} = n \cdot e_{2}$$
 on Γ_{τ} (1.6b)

$$\partial_n U_{\varepsilon} = 0 \qquad \text{on } \partial \Omega_{\varepsilon} \setminus \Gamma_{\varepsilon}, \tag{1.6c}$$

which is nothing but a particular case of System 1.1, specifying $F_{\varepsilon} = 0$ and $G_{\varepsilon} = n \cdot e_2$.

As already mentioned concerning the general system 1.1, the main objective of this paper is to study the convergence of U_{ε} solution to System (1.6) and obtain the first order term of the asymptotics of the Dirichlet energy associated to U_{ε} , namely the quantity

$$E_{\varepsilon} := \int_{\Omega_{\varepsilon}} |\nabla U_{\varepsilon}(\xi)|^2 \,\mathrm{d}\xi. \tag{1.7}$$

Notice that, up to a multiplicative constant, this quantity coincides with the added mass defined in (1.4).

Deriving the asymptotics of the Dirichlet energy (1.7) requires to solve two main difficulties:

- 1. The solution U_{ε} for $\varepsilon > 0$ and the solution U_0 for $\varepsilon = 0$ (if it exists) are not defined on the same domains (respectively Ω_{ε} and Ω_0) and thus, they can not be "compared" in a simple way.
- 2. The domain Ω_0 is strongly singular due to the presence of a cusp at the contact point.

Let us now formally explain our main ideas to overcome these two difficulties. The key ingredient we use is a suitable change of coordinates $x = \Psi_{\varepsilon}(\xi)$ defined for every $\varepsilon \ge 0$ (i.e. including the limit case) such that, denoting $\omega_{\varepsilon} := \Psi_{\varepsilon}(\Omega_{\varepsilon})$, we have:

$$\omega_{\varepsilon} = D \cup R_{\varepsilon}$$
 with $D \cap R_{\varepsilon} = \emptyset$

and where (see Figure 8)

- D is a fixed domain (i.e. independent of $\varepsilon \ge 0$);
- R_{ε} stands for the rectangle $[0, \ell_{\varepsilon}] \times [0, 1]$, where $\ell_{\varepsilon} \nearrow \ell_{0} := +\infty$ as ε goes to 0.

Denoting by n the unit outer normal to $\partial \omega_{\varepsilon}$ and setting τ the tangent vector to $\partial \omega_{\varepsilon}$ such that $\tau^{\perp} = n$ and

$$u_{\varepsilon} := U_{\varepsilon}(\Psi_{\varepsilon}^{-1}), \qquad f_{\varepsilon} := F_{\varepsilon}(\Psi_{\varepsilon}^{-1}) |\det D\Psi_{\varepsilon}^{-1}|, \qquad g_{\varepsilon} := G_{\varepsilon}(\Psi_{\varepsilon}^{-1}) |D\Psi_{\varepsilon}^{-1}\tau|, \qquad \gamma_{\varepsilon} := \Psi_{\varepsilon}(\Gamma_{\varepsilon}),$$

we will show that the general problem (1.1) is transformed into a new boundary value problem set in ω_{ε} :

$$-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla u_{\varepsilon}) = f_{\varepsilon} \quad \text{in } \omega_{\varepsilon} \tag{1.8a}$$

$$\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot n = g_{\varepsilon} \quad \text{on } \gamma_{\varepsilon} \tag{1.8b}$$

$$\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot n = 0 \quad \text{on } \partial \omega_{\varepsilon} \setminus \gamma_{\varepsilon}. \tag{1.8c}$$

Notice that the compatibility condition (1.2) for the functions F_{ε} and G_{ε} yields:

$$\int_{\omega_{\varepsilon}} f_{\varepsilon} \, \mathrm{d}x + \int_{\gamma_{\varepsilon}} g_{\varepsilon} \, \mathrm{d}s = 0$$

Here, \mathbb{A}_{ε} denotes the 2 by 2 matrix with continuous coefficients defined by

$$\mathbb{A}_{\varepsilon} := \left[(D\Psi_{\varepsilon}) \circ \Psi_{\varepsilon}^{-1} \right] \left[(D\Psi_{\varepsilon}) \circ \Psi_{\varepsilon}^{-1} \right]^{\mathbf{T}} |\det(D\Psi_{\varepsilon}^{-1})|.$$
(1.9)

The Dirichlet energy E_{ε} defined by (1.7) takes the form

$$E_{\varepsilon} = \int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot \nabla u_{\varepsilon} \, \mathrm{d}x$$

Regarding the boundary value problem (1.8), we note the following

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- 1. In the new system of coordinates $x = (x_1, x_2)$, comparing the solution u_{ε} and the solution u_0 is now possible since $(\omega_{\varepsilon})_{\varepsilon \ge 0}$ is an increasing sequence of domains, all of them included in the (unbounded) domain ω_0 . In the new system of coordinates, the cusp singularity is sent to infinity.
- 2. The operator involved is not anymore the Laplace operator but the second order operator $-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla \cdot)$ (which depends on $\varepsilon \ge 0$). However, as we will see later, this operator is uniformly elliptic with respect to $\varepsilon \ge 0$ and $x \in \omega_{\varepsilon}$.

Motivated by the physical problem (1.3), we will mainly focus on system (1.8), obtained from System 1.6 after applying the change of variables, i.e. for a volume source term $f_{\varepsilon} = 0$ and boundary data $g_{\varepsilon} = D\Psi_{\varepsilon}^{-1}\tau \cdot e_1$. Recalling that the cusp is locally described by the equation $\xi_2 = H_0(\xi_1) = \kappa |\xi_1|^{1+\alpha}$ (with $\kappa, \alpha > 0$), our main result can be stated as follows:

Theorem 1 For every $\varepsilon > 0$, let u_{ε} be a solution to

$$-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla u_{\varepsilon}) = 0 \qquad \quad in \ \omega_{\varepsilon} \tag{1.10a}$$

$$\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot n = D \Psi_{\varepsilon}^{-1} \tau \cdot e_1 \quad on \ \gamma_{\varepsilon} \tag{1.10b}$$

$$A_{\varepsilon} \nabla u_{\varepsilon} \cdot n = 0 \qquad on \ \partial \omega_{\varepsilon} \setminus \gamma_{\varepsilon}. \tag{1.10c}$$

Then the following alternative holds true:

1. For $\alpha < 2$: System 1.10 with $\varepsilon = 0$ admits a finite energy solution u_0 . Moreover,

$$\|\nabla u_{\varepsilon} - \nabla u_0\|_{L^2(\omega_{\varepsilon})} \to 0 \text{ and } E_{\varepsilon} \to E_0 < \infty \text{ as } \varepsilon \to 0^+.$$

2. For $\alpha \ge 2$: System 1.10 with $\varepsilon = 0$ has no finite energy solution and two kinds of blow up are possible as $\varepsilon \to 0^+$ for the Dirichlet energy E_{ε} :

$$E_{\varepsilon} \underset{\varepsilon=0}{\sim} \begin{cases} \frac{1}{3} \kappa^{-1} |\ln(\varepsilon)| & \text{if } \alpha = 2\\ \frac{1}{3} \varepsilon^{\frac{3}{1+\alpha} - 1} \kappa^{-\frac{3}{1+\alpha}} \frac{3\pi/(1+\alpha)}{\sin(3\pi/(1+\alpha))} & \text{if } \alpha > 2. \end{cases}$$
(1.11)

Let us emphasize that the behavior of the Dirichlet energy only depends on the nature of the cusp (i.e. the constants κ and α) and not on other geometric features of the fluid domain.

This result follows immediately from the gathering of Theorem 4 and Theorem 5 below.

Regarding the collision problem, we claim:

Corollary 1 In case 1 of the Theorem ($\alpha < 2$), the solid will collide with the cavity's boundary in finite time with non zero velocity (real shock case). In case 2 ($\alpha \ge 2$), the solid reaches the cavity's bottom in finite time but with null velocity (smooth landing case).

This corollary is a restatement of Corollary 2 for the case $\alpha < 2$. The case $\alpha \ge 2$ results from the following lemma (whose proof is postponed to Appendix B) and the estimates (1.11).

Lemma 1 Assume that $E_{\varepsilon} \to +\infty$ as $\varepsilon \to 0^+$ and that there exists $\beta < 2$ such that $E_{\varepsilon} = O(\varepsilon^{-\beta})$, then the solid reaches the cavity's bottom in finite time but with null velocity (smooth landing case).

Several references can be found in the literature regarding the asymptotics of the Dirichlet problem near a tangency point of smooth components of the boundary, see for instance the papers of Maz'ya, Nazarov and Plamenevskij [10, 11, 12] and their book [13, Chapter 14]. The Neumann problem has been investigated more recently. In particular the singular behavior of the limit problem is derived in [14, 15] while the full asymptotics with respect to the small parameter ε is studied in [3, 2]. In particular, Cardone, Nazarov and Sokolowski provide in [2] the first order asymptotics for the Neumann problem with thin ligaments in arbitrary dimension. However these papers deal with the case where the tangency exponent α of the cusp is an even integer 2m.

In this paper, we propose a new method to obtain the first order approximation of the solution for the two dimensional Neumann Laplacian problem for arbitrary tangency exponent $\alpha > 0$. Our method relies on the use of a suitable change of variables leading to the study of Neumann problems set on the domains ω_{ε} and on a precise description of the asymptotic behavior at infinity of the solutions u_{ε} of these problems when ε tends to 0. Let us point out the main advantages of our approach :

- 1. Since ω_{ε} defines an increasing sequence, the solutions u_{ε} and the (potential) limit solution u_0 can be easily compared on the domain ω_{ε} in which they are both defined.
- 2. The cases $\varepsilon > 0$ and the limit case $\varepsilon = 0$ can be handled exactly in the same way in the new geometry ω_{ε} . Indeed, using an appropriate weighted Sobolev space (with a decaying weight as $x_1 \to \infty$), we will deal with uniformly elliptic Neumann problems on the domains ω_{ε} for all $\varepsilon \ge 0$.
- 3. In the new variables, the strength of the cusp (i.e. the parameter α) appears only in the operators and the boundary data of the Neumann problems and does not appear in the weight used in the functional spaces. Let us also emphasize that this makes our approach valid for arbitrary $\alpha > 0$, integer or not.
- 4. Finally, let us point out that our method can be, in principle, generalized to higher dimensions. The limit problem initially set on $\Omega_{\varepsilon} \subset \mathbb{R}^d$ is then transformed into a problem set on $\mathbb{R}^{d-1}_+ \times (0, 1)$.

1.3 Outline

The paper is organized as follows. In Section 2 we collect some preliminary but elementary remarks on the asymptotic behavior of the Dirichlet energy as ε tends to 0. The change of variables near the cusp and its main properties are given in Section 3. For the sake of clarity, its full construction (near and far from the cusp) is described in Appendix A. The rest of the paper deals with the analysis of the general boundary problems (1.8) set in ω_{ε} and obtained after applying the change of variables to System 1.1. In Section 4, we describe the functional framework used to study the asymptotic behavior of the solutions u_{ε} of these problems as ε goes to 0. We introduce appropriate weighted Sobolev spaces and we prove some useful lemmas (a trace theorem and a Poincaré-Wirtinger inequality involving constants which are uniform with respect to ε). In Section 5, we provide a well-posedness result for the problem (1.8) with $\varepsilon = 0$, set in the unbounded domain ω_0 and a convergence result of u_{ε} (towards u_0) in the energy space for well prepared data (i.e. data having a suitable decay rate at infinity). These results are applied in Section 6 to investigate the asymptotic behavior of the Dirichlet energy E_{ε} for the particular system 1.10. We show that for $\alpha < 2$ (recall that α is the coefficient describing the strength of the cusp) and $\varepsilon = 0$, the Neumann datum in (1.10b) is well prepared. This leads to the well-posedness of the limit problem and to a finite limit energy E_0 . On the contrary, for $\alpha \ge 2$, the boundary data in (1.10b) does not have the decay rate required to apply the results of Section 5. In this case, we prove the existence of a singular (non decaying) solution for the problem (1.10) when $\varepsilon = 0$ and the blow up of the Dirichlet energy E_{ε} as ε tends to 0⁺. In view of the collision issue, the first term of the asymptotics of E_{ε} is also given. Finally, in Section 7, we show through some examples how the method can be adapted to deal with more general configurations.

2 Some preliminary remarks on the asymptotic behavior

In order to get a first intuition about the behavior of the solution U_{ε} of (1.6) as ε goes to 0, we collect here some general remarks about the problem and some comparison results obtained thanks to elementary considerations.

First of all, we recall a result proved by Nazarov *et al* in [15, Section 5], providing a non existence result of finite energy solutions for Problem 1.6, when $\varepsilon = 0$. The proof being short, it is given for the sake of completeness.

Proposition 1 The variational formulation

$$\int_{\Omega_0} \nabla U \cdot \nabla V \,\mathrm{d}\xi = \int_{\Gamma_0} G_0 \, V \,\mathrm{d}\sigma, \qquad \forall V \in H^1(\Omega_0), \tag{2.1}$$

where $G_0 := n \cdot e_2$ has no solution $U \in H^1(\Omega_0)$ if $\alpha \ge 2$.

Proof: Using a contradiction argument, let us assume that there exists $U \in H^1(\Omega_0)$ satisfying the variational formulation (2.1). Given a neighborhood of the cusp $\mathcal{V}_0 \subset \Omega_0$ and a function $\chi \in C_0^{\infty}(\mathbb{R})$ with support in]1/2, 1[such that $\int_{\mathbb{R}} \chi > 0$, define the sequence of test functions

$$V_k(\xi) = \begin{cases} 0 & \text{if } \xi \in \Omega_0 \setminus \overline{\mathcal{V}_0} \\ 2^{\frac{k\alpha}{2}} \chi(2^k \xi_1) & \text{if } \xi \in \mathcal{V}_0. \end{cases}$$

It can be easily checked that the sequence $(V_k)_k$ is bounded in $H^1(\Omega_0)$ and using the dominated convergence theorem that

$$\lim_{k \to \infty} \int_{\Omega_0} \nabla U \cdot \nabla V_k \, \mathrm{d}\xi = 0$$

On the other hand, for the right-hand side of (2.1), we note that

$$\int_{\Gamma_0} G_0 V_k \, \mathrm{d}\sigma = 2^{\frac{k\alpha}{2}} \int_{\mathbb{R}} \chi(2^k \xi_1) \, \mathrm{d}\xi_1$$
$$= 2^{k\left(\frac{\alpha}{2} - 1\right)} \int_{\mathbb{R}} \chi(s) \, \mathrm{d}s,$$

which tends to $+\infty$ if $\alpha > 2$ and to a non zero finite limit if $\alpha = 2$, leading to a contradiction.

The above result suggests that the limit energy E_0 is infinite for $\alpha \ge 2$. Using the Dirichlet principle, i.e. the identity

$$E_{\varepsilon} = \max_{U \in H^1(\Omega_{\varepsilon})} \left\{ \int_{\Gamma_{\varepsilon}} n_2 U \, \mathrm{d}\sigma - \frac{1}{2} \int_{\Omega_{\varepsilon}} |\nabla U|^2 \, \mathrm{d}\xi \right\},\tag{2.2}$$

available for every $\varepsilon > 0$, we first prove the following energy blow up for $\alpha > 2$:

Proposition 2 For every $\alpha > 2$, there exists a constant $C_{\alpha} > 0$ such that the Dirichlet energy (1.7) satisfies

$$E_{\varepsilon} \geqslant C_{\alpha} \varepsilon^{\frac{3}{\alpha+1}-1} \quad \forall \varepsilon > 0.$$
(2.3a)

In the case where the solid has locally a flat bottom (i.e. contact would occur along a segment), there exists $C_{\infty} > 0$ such that

$$E_{\varepsilon} \ge C_{\infty} \varepsilon^{-1} \quad \forall \varepsilon > 0.$$
 (2.3b)

Remark 1 Surprisingly enough, we notice by comparing with the results of Theorem 1 and Proposition 6 that the estimates (2.3) are sharp. Estimates (2.3) prevent the rigid body from colliding with the cavity's wall with non-zero velocity but do not permit to decide between the two remaining choices: "smooth landing" in finite time or "infinite time touchdown".

Proof: The main idea consists in building a suitable test function in the Dirichlet principle (2.2). We seek this function as a piecewise polynomial. For the sake of simplicity and unless necessary, we will drop in the notation the dependence on ε of the quantities introduced in the proof.



Figure 3: The partition of Ω_{ε} into $\mathcal{O}_1 \cup \mathcal{O}_2 \cup \mathcal{O}_3$.

Let us begin by introducing the following partition of Ω_{ε} . The set \mathcal{O}_1 and \mathcal{O}_2 are as pictured on Figure 3 and $\mathcal{O}_3 := \Omega_{\varepsilon} \setminus (\overline{\mathcal{O}_1 \cup \mathcal{O}_2})$. The constants $\zeta_1 < 0$ and $\zeta'_1 < 0$ will be specified later on.

Denoting by ζ the point $(\zeta_1, H_{\varepsilon}(\zeta_1))$, we define the following polynomial functions:

$$W_1(\xi) := -\frac{1}{2\varepsilon} (\xi_1^2 - \xi_2^2) \quad \text{and} \quad W_2(\xi) := \frac{1}{2\varepsilon} (\xi_2 + H_{\varepsilon}(\zeta_1))(\xi_2 - h(\xi_1)) + W_1(\zeta),$$

where

$$h(\xi_1) := \frac{H_{\varepsilon}(\zeta_1)}{\zeta_1 - \zeta_1'} (\xi_1 - \zeta_1')$$

Finally, the test function to be used in (2.2) reads:

$$W(\xi) := \begin{cases} W_1(\xi) & \text{in } \mathcal{O}_1 \\ W_2(\xi) & \text{in } \mathcal{O}_2 \\ W_1(\zeta) & \text{in } \mathcal{O}_3. \end{cases}$$
(2.4)

One can easily check that $W \in H^1(\Omega_{\varepsilon})$ and that on the boundary Γ_{ε} of the solid we have:

$$W(\xi) = \begin{cases} W_1(\xi) & \text{on } \overline{\mathcal{O}_1} \cap \Gamma_{\varepsilon} \\ W_1(\zeta) & \text{otherwise on } \Gamma_{\varepsilon}. \end{cases}$$

Based on formula (2.2), we can obtain a lower bound for E_{ε} as follows:

$$E_{\varepsilon} \ge \int_{\Gamma_{\varepsilon}} n_2 W \,\mathrm{d}\sigma - \frac{1}{2} \int_{\Omega_{\varepsilon}} |\nabla W|^2 \,\mathrm{d}\xi.$$

Since $\int_{\Gamma_{\varepsilon}} n_2 \, \mathrm{d}\sigma = 0$ and W is a constant function on $\Gamma_{\varepsilon} \setminus \bar{\mathcal{O}}_1$, we can rewrite the inequality above as:

$$E_{\varepsilon} \ge \int_{\Gamma_{\varepsilon} \cap \mathcal{O}_1} n_2 W_1 \,\mathrm{d}\sigma - W_1(\zeta) \int_{\Gamma_{\varepsilon} \cap \mathcal{O}_1} n_2 \,\mathrm{d}\sigma - \frac{1}{2} \int_{\mathcal{O}_1} |\nabla W_1|^2 \,\mathrm{d}\xi - \frac{1}{2} \int_{\mathcal{O}_2} |\nabla W_2|^2 \,\mathrm{d}\xi. \tag{2.5}$$

We can now compute explicitly every term arising in the right hand side of this estimate. We have:

$$\int_{\Gamma_{\varepsilon}\cap\mathcal{O}_1} n_2 W_1 \,\mathrm{d}\sigma = -\frac{1}{2\varepsilon} \int_0^{|\zeta_1|} \left[\xi_1^2 - (H_{\varepsilon}(\xi_1))^2\right] \,\mathrm{d}\xi_1,$$

and then, after some elementary algebra, we get:

$$\int_{\Gamma_{\varepsilon}\cap\mathcal{O}_1} n_2 W_1 \,\mathrm{d}\sigma = \frac{1}{\varepsilon} \left[\frac{\kappa^2 |\zeta_1|^{3+2\alpha}}{6+4\alpha} - \frac{|\zeta_1|^3}{6} \right] + \frac{\kappa |\zeta_1|^{2+\alpha}}{2+\alpha} + \varepsilon \frac{|\zeta_1|}{2}. \tag{2.6}$$

Addressing the second term in the right hand side of (2.5) and observing that $\int_{\Gamma_{\varepsilon}\cap\mathcal{O}_1} n_2 \,\mathrm{d}\sigma = |\zeta_1|$, we get:

$$-W_{1}(\zeta) \int_{\Gamma_{\varepsilon} \cap \mathcal{O}_{1}} n_{2} d\sigma = \frac{|\zeta_{1}|}{2\varepsilon} \left[\zeta_{1}^{2} - (H_{\varepsilon}(\zeta_{1}))^{2} \right]$$
$$= \frac{1}{2\varepsilon} \left[|\zeta_{1}|^{3} - \kappa^{2} |\zeta_{1}|^{3+2\alpha} \right] - \kappa |\zeta_{1}|^{2+\alpha} - \varepsilon \frac{|\zeta_{1}|}{2}.$$
(2.7)

The third term is computed as follows:

$$\int_{\mathcal{O}_1} |\nabla W_1|^2 \,\mathrm{d}\xi = \frac{1}{\varepsilon^2} \int_0^{|\zeta_1|} \int_0^{H_{\varepsilon}(\xi_1)} (\xi_1^2 + \xi_2^2) \,\mathrm{d}\xi,$$

and this expression leads to:

$$\int_{\mathcal{O}_1} |\nabla W_1|^2 \,\mathrm{d}\xi = \frac{1}{\varepsilon^2} \left[\frac{\kappa |\zeta_1|^{4+\alpha}}{4+\alpha} + \frac{\kappa^3 |\zeta_1|^{4+3\alpha}}{12+9\alpha} \right] + \frac{1}{\varepsilon} \left[\frac{\kappa^2 |\zeta_1|^{3+2\alpha}}{3+2\alpha} + \frac{|\zeta_1|^3}{3} \right] + \frac{\kappa |\zeta_1|^{2+\alpha}}{2+\alpha} + \varepsilon \left[\frac{|\zeta_1|}{3} \right]. \tag{2.8}$$

For the last term of (2.5), we have:

$$\int_{\mathcal{O}_2} |\nabla W_2|^2 \,\mathrm{d}\xi = \int_{\zeta_1'}^{\zeta_1} \int_0^{H_0(\xi_1)} |\partial_{\xi_1} W_2(\xi)|^2 + |\partial_{\xi_2} W_2(\xi)|^2 \,\mathrm{d}\xi$$

where

$$\partial_{\xi_1} W_2(\xi) = -\frac{1}{2\varepsilon} (H_\varepsilon(\zeta_1) + \xi_2) H_0'(\xi_1) \quad \text{and} \quad \partial_{\xi_2} W_2(\xi) = \frac{1}{2\varepsilon} (H_\varepsilon(\zeta_1) - H_0(\xi_1)) + \frac{1}{\varepsilon} \xi_2.$$

After a tedious but straightforward computation, we obtain that:

$$\int_{\mathcal{O}_2} |\partial_{\xi_1} W_2(\xi)| \, \mathrm{d}\xi = \frac{11}{48} \frac{1}{\varepsilon^2} \frac{(H_\varepsilon(\zeta_1))^5}{|\zeta_1' - \zeta_1|} \quad \text{and} \quad \int_{\mathcal{O}_2} |\partial_{\xi_2} W_2(\xi)| \, \mathrm{d}\xi = \frac{7}{48} \frac{1}{\varepsilon^2} (H_\varepsilon(\zeta_1))^3 |\zeta_1' - \zeta_1|. \tag{2.9}$$

Now, we choose $\zeta_1 = -(\varepsilon/\kappa)^{\frac{1}{\alpha+1}}$ (so that $H_{\varepsilon}(\zeta_1) = 2\varepsilon$) and $\zeta'_1 = \zeta_1 - \varepsilon$. Substituting (2.6), (2.7), (2.8), and (2.9) into (2.5), we obtain the following asymptotic expansion:

$$\begin{split} \int_{\Gamma_{\varepsilon}\cap\mathcal{O}_{1}} n_{2}W_{1}\,\mathrm{d}\sigma - W_{1}(\zeta) \int_{\Gamma_{\varepsilon}\cap\mathcal{O}_{1}} n_{2}\,\mathrm{d}\sigma - \frac{1}{2}\int_{\mathcal{O}_{1}} |\nabla W_{1}|^{2}\,\mathrm{d}\xi - \frac{1}{2}\int_{\mathcal{O}_{2}} |\nabla W_{2}|^{2}\,\mathrm{d}\xi \\ &= \left(\frac{\alpha+1}{6\alpha+24}\right)\kappa^{-\frac{3}{\alpha+1}}\varepsilon^{\frac{3}{\alpha+1}-1} + o\left(\varepsilon^{\frac{3}{\alpha+1}-1}\right) \end{split}$$

For ε small enough, we get (2.3a). For a solid with a flat bottom, it suffices to replace H_0 by 0 in all the estimates and ζ_1 by a small constant (such that $H_0 = 0$ on $]\zeta_1, 0[$), to get the claimed result (2.3b). The proof is now complete.

The two following propositions allow comparing the Dirichlet energy after simple changes in the geometry.

Proposition 3 Let us denote by $E_{\varepsilon}^{[\mathsf{C},S_0]}$ the Dirichlet energy corresponding to a solid of shape S_0 in a cavity C . If $\mathsf{C}^1 \subset \mathsf{C}^2$ then

$$E_{\varepsilon}^{[\mathsf{C}^1,S_0]} \ge E_{\varepsilon}^{[\mathsf{C}^2,S_0]} \quad \forall \varepsilon > 0.$$
(2.10)

In other words, this Proposition asserts that the bigger the cavity is, the lower is the Dirichlet energy.

Proof: For every $\varepsilon > 0$, we set $\Omega_{\varepsilon}^k := \mathsf{C}^k \setminus S_{\varepsilon}$ (k = 1, 2). For every function $U \in H^1(\Omega_{\varepsilon}^2)$, its restriction to Ω_{ε}^1 belongs to $H^1(\Omega_{\varepsilon}^1)$ and we have the obvious inequality:

$$\int_{\Gamma_{\varepsilon}} n_2 U \,\mathrm{d}\sigma - \frac{1}{2} \int_{\Omega_{\varepsilon}^2} |\nabla U|^2 \,\mathrm{d}\xi \leqslant \int_{\Gamma_{\varepsilon}} n_2 U \,\mathrm{d}\sigma - \frac{1}{2} \int_{\Omega_{\varepsilon}^1} |\nabla U|^2 \,\mathrm{d}\xi.$$

The conclusion follows then from the Dirichlet principle (2.2).

The next Proposition tells us that the Dirichlet energy can be compared for configurations that are images one from the other by a global C^1 diffeormorphism.

Proposition 4 Let B be a large ball containing a cavity C. For every $0 \leq \varepsilon \leq \varepsilon^*$, consider the usual configuration involving a solid S_0 , its domain S_{ε} , its boundary $\Gamma_{\varepsilon} := \partial S_{\varepsilon}$ and the fluid domain $\Omega_{\varepsilon} := \mathsf{C} \setminus S_{\varepsilon}$.

Let $\tilde{H}_0 : \mathbb{R} \to \mathbb{R}$ be a given C^1 function. Let \mathcal{U} be an open set containing Γ_{ε} for every $\varepsilon \ge 0$ small enough (see Figure 4).

For every C^1 diffeomorphism $\Phi: B \to B$ such that

$$\Phi(\xi_1, \xi_2) = (\xi_1, \xi_2 + \dot{H}_0(\xi_1)), \quad \forall \xi = (\xi_1, \xi_2) \in \mathcal{U},$$
(2.11)

the following estimate holds true (for every $\varepsilon > 0$ small enough):

$$c_1 E_{\varepsilon}^{[\mathsf{C},S_0]} \leqslant E_{\varepsilon}^{[\tilde{\mathsf{C}},\tilde{S}_0]} \leqslant c_2 E_{\varepsilon}^{[\mathsf{C},S_0]},$$

where $\tilde{\mathsf{C}} := \Phi(\mathsf{C})$, $\tilde{S}_0 := \Phi(S_0)$ and $c_1 > 0$ and $c_2 > 0$ are two constants depending only on C , S_0 and Φ . Notice that the ecompution (2.11) satisfies that

Notice that the assumption
$$(2.11)$$
 entails that

$$\Phi(S_{\varepsilon}) = S_{\varepsilon}$$
 and $\Phi(\Omega_{\varepsilon}) = \Omega_{\varepsilon}$

for every $\varepsilon \ge 0$ small enough, where $\Omega_{\varepsilon} := \mathsf{C} \setminus S_{\varepsilon}$ and $\tilde{\Omega}_{\varepsilon} := \tilde{\mathsf{C}} \setminus \tilde{S}_{\varepsilon}$ and that the local parameterization of the fluid domain $\tilde{\Omega}_{\varepsilon}$ near the origin is now given by

$$\{\xi \in \mathbb{R}^2 : |\xi_1| < \delta^*, H_0(\xi_1) < \xi_2 < H_{\varepsilon}(\xi_1) + H_0(\xi_1)\}.$$



Figure 4: The open set \mathcal{U} containing the solid's boundary for every $\varepsilon \ge 0$.

Proof: Let $\phi : [0,1] \to \Gamma_0$ be a parameterization of the boundary of the solid when $\varepsilon = 0$. Then $\phi_{\varepsilon} = \phi + \varepsilon e_2$ is a parameterization of Γ_{ε} and $\Phi \circ \phi_{\varepsilon}$ a parameterization of $\tilde{\Gamma}_{\varepsilon} := \Phi(\Gamma_{\varepsilon}) = \partial \tilde{S}_{\varepsilon}$ for every $\varepsilon \ge 0$.

For every $\varepsilon > 0$ and every $v \in H^1(\tilde{\Omega}_{\varepsilon})$, we have:

$$\int_{\tilde{\Gamma}_{\varepsilon}} n_2 v \, \mathrm{d}\sigma = \int_0^1 [(D\Phi(\phi(s))\phi'(s))^{\perp} \cdot e_2] v(\Phi(\phi(s)) \, \mathrm{d}s$$
$$= -\int_0^1 [\phi'(s) \cdot D\Phi(\phi(s))^{\mathbf{T}} e_1] v(\Phi(\phi(s)) \, \mathrm{d}s.$$

From assumption (2.11), we infer that $D\Phi(\phi(s))^{\mathbf{T}}e_1 = e_1$ and therefore:

$$\int_{\tilde{\Gamma}_{\varepsilon}} n_2 v \, \mathrm{d}\sigma = \int_{\Gamma_{\varepsilon}} n_2 \, \tilde{v} \, \mathrm{d}\sigma, \qquad (2.12)$$

where $\tilde{v} := v \circ \Phi$.

On the other hand, we have upon the change of variables $x = \Phi(\xi)$ the identity:

$$\int_{\bar{\Omega}_{\varepsilon}} |\nabla v|^2 \,\mathrm{d}\xi = \int_{\Omega_{\varepsilon}} \mathbb{A}\nabla \tilde{v} \cdot \nabla \tilde{v} \,\mathrm{d}x,\tag{2.13}$$

where $\mathbb{A} := (D\Phi)^{-1}(D\Phi)^{-\mathbf{T}} |\det D\Phi|$. The matrix \mathbb{A} is positive-definite and hence there exist two positive constants λ_1 and λ_2 such that

$$\lambda_1 |X|^2 \leqslant \mathbb{A}(\xi) X \cdot X \leqslant \lambda_2 |X|^2,$$

for every $X \in \mathbb{R}^2$ and every $\xi \in \overline{\mathsf{C}}$. Without loss of generality, we can assume that $\lambda_1 \leq 1 \leq \lambda_2$. Gathering (2.12) and (2.13), we get:

$$\int_{\tilde{\Gamma}_{\varepsilon}} n_2 v \, \mathrm{d}\sigma - \frac{1}{2} \int_{\tilde{\Omega}_{\varepsilon}} |\nabla v|^2 \, \mathrm{d}\xi = \int_{\Gamma_{\varepsilon}} n_2 \, \tilde{v} \, \mathrm{d}\sigma - \frac{1}{2} \int_{\Omega_{\varepsilon}} \mathbb{A} \nabla \tilde{v} \cdot \nabla \tilde{v} \, \mathrm{d}x$$

and then, since $\lambda_1 \leq 1$, according to (2.2) we get

$$E_{\varepsilon}^{[\mathsf{C},S_0]} \leqslant \lambda_1 E_{\varepsilon}^{[\tilde{\mathsf{C}},\tilde{S}_0]}.$$
(2.14)

Remarking that Φ^{-1} enjoys the properties required for Φ to get (2.14), we deduce that we also have:

$$E_{\varepsilon}^{[\tilde{\mathsf{C}},\tilde{S}_0]} \leqslant \lambda_2^{-1} E_{\varepsilon}^{[\mathsf{C},S_0]}.$$

The claim of the Proposition follows.



Typical illustrations of the above result are given in Figures 5 and 6.

Figure 5: According to Proposition 4, the Dirichlet energy behaves similarly as $\varepsilon \to 0^+$ for all of these cases.



Figure 6: Another example of two configurations where, according to Proposition 4, the Dirichlet energy can be compared as $\varepsilon \to 0^+$ (notice on this example how we take advantage of working with a half configuration and then recover a full configuration by symmetry).

Application. Combining Propositions 2, 3 and 4, we can deduce an estimate for the case where the bottom of the solid is concave (see Figure 7, on the right) and where there are two contact points for $\varepsilon = 0$. Indeed, with the notation of Figure 7, according to Proposition 3, for every $\varepsilon > 0$ we have

$$E_{\varepsilon}^{[\mathsf{C}^1, S_0^1]} \geqslant E_{\varepsilon}^{[\mathsf{C}^2, S_0^2]}$$

and according to Proposition 4, there exists a constant c > 0 such that

$$c E_{\varepsilon}^{[\mathsf{C}^2, S_0^2]} \geqslant E_{\varepsilon}^{[\mathsf{C}^3, S_0^3]}.$$

Using now Proposition 2, we infer the existence of a constant C > 0 such that:

$$C\varepsilon^{-1} \ge E_{\varepsilon}^{[\mathsf{C}^3, S_0^3]}$$

Consequently, the energy blow up is no greater in case 3 than in case 1.



Figure 7: The energy blow-up in these 3 cases can be compared thanks to Proposition 3 and 4.

3 From the physical domain to the semi-infinite strip

In this section, we describe the change of coordinates $x = \Psi_{\varepsilon}(\xi)$, $0 \leq \varepsilon \leq \varepsilon^*$, used in the sequel to transform the Laplace Neumann problem (1.8) set on Ω_{ε} into an elliptic Neumann problem set on $\omega_{\varepsilon} := \Psi_{\varepsilon}(\Omega_{\varepsilon}) = D \cup R_{\varepsilon}$ (see Figure 8), where D is a fixed domain and $R_{\varepsilon} =]0, \ell_{\varepsilon}[\times]0, 1[$. Our change of variables is a generalization to the case $\varepsilon > 0$ of the one introduced by Ibuki [9] and used later by Grisvard in [5] and Acosta *et al.* in [1] to study the well-posedness and the regularity of Laplace problems in domains with cusps (in other words this corresponds in our problem to the limit case $\varepsilon = 0$). The full description of the diffeomorphism $\Psi_{\varepsilon} \in C^1(\overline{\Omega_{\varepsilon}, \overline{\omega_{\varepsilon}})}$ is given in Appendix A. For the sake of clarity, we only give here its definition on some neighborhood of the contact region. More precisely, for every $\varepsilon \ge 0$ and given $\delta < 0$ small enough, let

$$\mathcal{V}_{\varepsilon} := \{\xi \in \mathbb{R}^2 : \delta < \xi_1 < 0, \, 0 < \xi_2 < H_{\varepsilon}(\xi_1)\} \subset \Omega_{\varepsilon}.$$
(3.1)

Then, we set in $\mathcal{V}_{\varepsilon}$:

$$\Psi_{\varepsilon}(\xi) = \begin{pmatrix} \rho_{\varepsilon}(\xi_1) \\ \frac{\xi_2}{H_{\varepsilon}(\xi_1)} \end{pmatrix}, \quad \forall \xi \in \mathcal{V}_{\varepsilon},$$
(3.2)

where the function $\rho_{\varepsilon} : [\delta, 0[\to \mathbb{R}^+ \text{ is given by}]$

$$\rho_{\varepsilon}(\xi_1) := \int_{\delta}^{\xi_1} \frac{\mathrm{d}s}{H_{\varepsilon}(s)}.$$
(3.3)

Introducing

$$\ell_{\varepsilon} := \lim_{\xi_1 \to 0^+} \rho_{\varepsilon}(\xi_1),$$

We note that $\ell_{\varepsilon} < +\infty$ for $\varepsilon > 0$ and $\ell_0 := +\infty$. More precisely, based on the identity:

$$\int_0^{+\infty} \frac{\mathrm{d}s}{s^{1+\alpha}+1} = \frac{\pi/(\alpha+1)}{\sin(\pi/(\alpha+1))}$$

we can easily verify that:

$$\ell_{\varepsilon} \underset{\varepsilon=0}{\sim} \varepsilon^{-\frac{\alpha}{\alpha+1}} \kappa^{-\frac{1}{\alpha+1}} \left(\frac{\pi/(\alpha+1)}{\sin(\pi/(\alpha+1))} \right).$$
(3.4)

Setting $R_{\varepsilon} := \Psi_{\varepsilon}(\mathcal{V}_{\varepsilon})$, we get:

$$R_{\varepsilon} =]0, \ell_{\varepsilon}[\times]0, 1[. \tag{3.5})$$

We define the reciprocal function to ρ_{ε} as being:

$$\mu_{\varepsilon} := \rho_{\varepsilon}^{-1} : [0, \ell_{\varepsilon}[\to [\delta, 0[. \tag{3.6})]$$

When $\varepsilon = 0$, the function μ_{ε} can be made explicit and we have:

$$\mu_0(x_1) = -(\alpha \kappa)^{-\frac{1}{\alpha}} (x_1 + \hat{x}_1)^{-\frac{1}{\alpha}}, \qquad (3.7)$$

where $\hat{x}_1 = (\alpha \kappa)^{-1} |\delta|^{-\alpha}$. For all $\varepsilon \ge 0$, the function Ψ_{ε}^{-1} admits the following expression in R_{ε} :

$$\Psi_{\varepsilon}^{-1}(x) = \begin{pmatrix} \mu_{\varepsilon}(x_1) \\ x_2 H_{\varepsilon}(\mu_{\varepsilon}(x_1)) \end{pmatrix}, \quad \forall x \in R_{\varepsilon}.$$
(3.8)

We collect, in the following Lemma, some properties of the function μ_{ε} ($\varepsilon \ge 0$) that will be useful in the sequel:

Lemma 2 1. The following uniform convergence result holds true:

$$\|\mu_{\varepsilon} - \mu_0\|_{C^0([0,\ell_{\varepsilon}])} \to 0 \text{ as } \varepsilon \to 0^+.$$
(3.9)

2. There exist three positive constants C_1 , C_2 and C_3 , depending on α , κ and δ only, such that, for every $\varepsilon \ge 0$ and every $x_1 \in [0, \ell_{\varepsilon}]$:

$$|\mu_{\varepsilon}(x_1)| \leqslant C_1 (1+x_1)^{-\frac{1}{\alpha}} \tag{3.10a}$$

$$|H_{\varepsilon}(\mu_{\varepsilon})| \leqslant C_2 (1+x_1)^{-1-\frac{1}{\alpha}}$$
(3.10b)

$$|H_0'(\mu_{\varepsilon})| \leq C_2 (1+x_1)^{-1}.$$
 (3.10c)

The proof in postponed to Appendix B.

In Appendix A, we explain how to define Ψ_{ε} in $\Omega_{\varepsilon} \setminus \mathcal{V}_{\varepsilon}$ in such a way that $\Psi_{\varepsilon}(\Omega_{\varepsilon} \setminus \mathcal{V}_{\varepsilon})$ defines a domain D which is independent of ε (see Figure 8).



Figure 8: The domain Ω_{ε} and its image ω_{ε} by Ψ_{ε} . In particular, $D := \Psi_{\varepsilon}(\Omega_{\varepsilon} \setminus \mathcal{V}_{\varepsilon})$ does not depend on $\varepsilon \ge 0$.

Notice that $\ell_{\varepsilon} \nearrow +\infty$ (= ℓ_0) as $\varepsilon \searrow 0^+$ and therefore that we have the nice inclusion properties:

$$\varepsilon' > \varepsilon \Rightarrow \omega_{\varepsilon'} \subset \omega_{\varepsilon} \qquad \forall \varepsilon, \varepsilon' \ge 0.$$

Proposition 5 The following convergence property holds:

$$\|\Psi_{\varepsilon}^{-1} - \Psi_{0}^{-1}\|_{C^{1}(\overline{\omega}_{\varepsilon})} \to 0 \text{ as } \varepsilon \to 0^{+}.$$
(3.11a)

Moreover, if $\alpha > 1$, we also have:

$$\|\Psi_{\varepsilon}^{-1} - \Psi_{0}^{-1}\|_{C^{2}(\overline{R}_{\varepsilon})} \to 0 \text{ as } \varepsilon \to 0^{+}.$$
(3.11b)

Proof: We focus on the convergence on the rectangle R_{ε} , the rest the proof being given in Appendix A.

For all $\varepsilon \ge 0$, recall that the expression of the function Ψ_{ε}^{-1} in R_{ε} is given in (3.8).

We have $\mu_{\varepsilon}' = H_{\varepsilon}(\mu_{\varepsilon}), \ \mu_{\varepsilon}'' = H_0'(\mu_{\varepsilon})H_{\varepsilon}(\mu_{\varepsilon}) \text{ and } \mu_{\varepsilon}''' = H_0''(\mu_{\varepsilon})H_{\varepsilon}(\mu_{\varepsilon})^2 + H_0'(\mu_{\varepsilon})^2H_{\varepsilon}(\mu_{\varepsilon}) \text{ for all } \varepsilon \ge 0.$ Since the functions H_0 and H_0' are bounded and uniformly continuous on the compact $[\delta, 0]$ (because $\alpha > 0$), and the same holds true for H_0'' if $\alpha > 1$, the conclusion follows from (3.9).

We can now make explicit the matrix \mathbb{A}_{ε} , arising in the statement of the Neumann problem (1.8) (at least in the rectangle R_{ε}), based on formulas (1.9) and (3.8):

$$\mathbb{A}_{\varepsilon}(x) = \mathrm{Id} + x_2 H_0'(\mu_{\varepsilon}(x_1)) \begin{pmatrix} 0 & -1 \\ -1 & x_2 H_0'(\mu_{\varepsilon}(x_1)) \end{pmatrix} \qquad (\varepsilon \ge 0, \ x \in R_{\varepsilon}).$$
(3.12)

We claim:

Lemma 3 1. The following convergence result holds true:

$$\|\mathbb{A}_{\varepsilon} - \mathbb{A}_0\|_{C^0(\overline{\omega}_{\varepsilon})} \to 0 \text{ as } \varepsilon \to 0^+.$$
(3.13a)

If $\alpha > 1$, we also have:

$$\|\mathbb{A}_{\varepsilon} - \mathbb{A}_0\|_{C^1(\overline{R}_{\varepsilon})} \to 0 \ as \ \varepsilon \to 0^+.$$
(3.13b)

2. There exist two constants $0 < \lambda_1 < \lambda_2$, independent of $\varepsilon \ge 0$, such that:

$$\lambda_1 |X|^2 \leqslant \mathbb{A}_{\varepsilon}(x) X \cdot X \leqslant \lambda_2 |X|^2, \qquad \forall X \in \mathbb{R}^2, \ \forall x \in \omega_{\varepsilon}.$$
(3.14)

Proof: The convergences (3.13) are a straightforward consequence of Proposition 5.

The definition (1.9) of \mathbb{A}_{ε} ($\varepsilon \ge 0$) entails that $\mathbb{A}_{\varepsilon}(x)$ is positive-definite for every $\varepsilon \ge 0$ and every $x \in \omega_{\varepsilon}$. Since the eigenvalues depend continuously on the matrix, it suffices to prove (3.14) for $\varepsilon = 0$ to get the conclusion of the Lemma. We would be done if $\overline{\omega}_0$ were a compact. The way out consists in computing the expression of the eigenvalues of \mathbb{A}_0 in \mathbb{R}_0 . Indeed, we get:

$$\lambda_j(x) = F_j(|x_2 H'_0(\mu_{\varepsilon}(x_1))|), \quad j = 1, 2$$

where

$$F_1(X) := 1 + \frac{1}{2}X\left[X - \sqrt{X^2 + 4}\right], \quad F_2(X) := 1 + \frac{1}{2}X\left[X + \sqrt{X^2 + 4}\right]$$

and $F_1(X) \ge \lambda_1 := F_1((\alpha + 1)\kappa|\delta|^{\alpha}) > 0$ and $F_2(X) \le \lambda_2 := F_2((\alpha + 1)\kappa|\delta|^{\alpha})$ for every $X \in [0, (\alpha + 1)\kappa|\delta|^{\alpha}]$. The proof is now complete.

4 Functional framework

The domain ω_{ε} being bounded for $\varepsilon > 0$ and $-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla \cdot)$ being an elliptic operator, problem (1.8) is a wellposed Neumann problem for every $\varepsilon > 0$, the solution being uniquely defined in $H^1(\omega_{\varepsilon})$, up to an additive constant (and provided the compatibility condition is satisfied). In order to study the well-posedness of this system when $\varepsilon = 0$, we need to introduce a suitable functional framework since the domain ω_0 is infinite in the x_1 direction. More precisely, for every $\varepsilon \ge 0$ and every $\beta \in \mathbb{R}$, we introduce on ω_{ε} and $\partial \omega_{\varepsilon}$ respectively the measures

$$\mathrm{d}\nu_{\beta}(x) := \begin{cases} (1+x_1)^{\beta} \,\mathrm{d}x & \text{if } x \in R_{\varepsilon} \\ \mathrm{d}x & \text{if } x \in D. \end{cases} \quad \text{and} \quad \mathrm{d}\nu_{\beta}^{S}(x) := \begin{cases} (1+x_1)^{\beta} \,\mathrm{d}x_1 & \text{if } x \in \gamma_{\varepsilon}^{R} \\ \mathrm{d}s & \text{if } x \in \gamma_{\varepsilon}^{D}, \end{cases}$$

where $\gamma_{\varepsilon}^{R} := \{(x_{1}, 1) : 0 < x_{1} < \ell_{\varepsilon}\}$ and $\gamma_{\varepsilon}^{D} := \gamma_{\varepsilon} \setminus \gamma_{\varepsilon}^{R}$.

Since the cases $\beta = -2$ and $\beta = 2$ will play a particular role, we set

$$\mathrm{d}m = \mathrm{d}\nu_{-2}, \quad \mathrm{d}m^{-1} = \mathrm{d}\nu_2, \quad \mathrm{d}\sigma = \mathrm{d}\nu_{-2}^S \quad \text{and} \quad \mathrm{d}\sigma^{-1} = \mathrm{d}\nu_2^S.$$

Throughout, $L^1(\omega_{\varepsilon}, d\nu_{\beta})$, $L^2(\omega_{\varepsilon}, d\nu_{\beta})$, $L^1(\gamma_{\varepsilon}, d\nu_{\beta}^S)$ and $L^2(\gamma_{\varepsilon}, d\nu_{\beta}^S)$ stand for the Lebesgue spaces of integrable and square-integrable functions respectively for the measures $d\nu_{\beta}$ and $d\nu_{\beta}^S$.

For every $\varepsilon \ge 0$ and every $\beta \in \mathbb{R}$, we define the weighted Sobolev spaces:

$$H^{1}(\omega_{\varepsilon}, \mathrm{d}\nu_{\beta}) := \left\{ u \in L^{2}(\omega_{\varepsilon}, \mathrm{d}\nu_{\beta}) : \partial_{x_{i}} u \in L^{2}(\omega_{\varepsilon}), i = 1, 2 \right\}.$$

In the particular case $\beta = 2$, we also set:

$$H_N^1(\omega_{\varepsilon}, \mathrm{d}m) = \left\{ u \in H^1(\omega_{\varepsilon}, \mathrm{d}m) : \int_{\omega_{\varepsilon}} u \,\mathrm{d}m = 0 \right\}.$$
(4.1)

This space is well defined (regarding the L^1 condition for $\varepsilon = 0$), as it will be verified in Lemma 6 below.

Since ω_{ε} is bounded for $\varepsilon > 0$, the space $H^1(\omega_{\varepsilon}, d\nu_{\beta})$ is, for every $\beta \in \mathbb{R}$, isomorphic to the classical Sobolev space $H^1(\omega_{\varepsilon})$. However, the use of the weight is more convenient as it will allow us to obtain estimates (in the trace theorems, for the continuity and the coercivity) involving constants which are uniform with respect to $\varepsilon \ge 0$.

The introduction of the space $H^1_N(\omega_{\varepsilon}, \mathrm{d}m)$ is motivated by the following definition of solutions:

Definition 1 (Finite energy solution) For $\varepsilon \ge 0$, let be $f_{\varepsilon} \in L^2(\omega_{\varepsilon}, \mathrm{d}m^{-1})$ an $g_{\varepsilon} \in L^2(\omega_{\varepsilon}, \mathrm{d}\sigma^{-1})$ satisfying the compatibility condition:

$$\int_{\omega_{\varepsilon}} f_{\varepsilon} \, \mathrm{d}x + \int_{\gamma_{\varepsilon}} g_{\varepsilon} \, \mathrm{d}x = 0.$$
(4.2)

Then, a function $u_{\varepsilon} \in H^1_N(\omega_{\varepsilon}, \mathrm{d}m)$ is called a finite energy solution to System (1.8) if:

$$\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot \nabla v \, \mathrm{d}x = \int_{\Omega_{\varepsilon}} f_{\varepsilon} v \, \mathrm{d}x + \int_{\Gamma_{\varepsilon}} g_{\varepsilon} v \, \mathrm{d}s, \qquad \forall v \in H^1_N(\omega_{\varepsilon}, \mathrm{d}m).$$
(4.3)

The corresponding Dirichlet energy is defined by:

$$E_{\varepsilon} := \int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot \nabla u_{\varepsilon} \, \mathrm{d}x. \tag{4.4}$$

Remark 2 When $\varepsilon = 0$, we have $f_0/m \in L^2(\omega_0, \mathrm{d}m)$ and $g_0/m \in L^2(\gamma_0, \mathrm{d}\sigma)$. We can rewrite (4.2) as:

$$\int_{\omega_0} \frac{f_0}{m} \,\mathrm{d}m + \int_{\gamma_0} \frac{g_0}{m} \,\mathrm{d}\sigma = 0$$

which indeed makes sense according to Lemma 6 stated below.

Remark 3 Since f_{ε} and g_{ε} satisfy the compatibility condition (4.2), we can equivalently replace $H^1_N(\omega_{\varepsilon}, \mathrm{d}m)$ by $H^1(\omega_{\varepsilon}, \mathrm{d}m)$ in the statement of Problem 4.3, for every $\varepsilon \ge 0$.

Remark 4 It can be easily checked that for data satisfying in the physical domain the (classical) conditions $F_0 \in L^2(\Omega_0)$ and $G_0 \in L^2(\Gamma_0)$, we have necessarily $f_0 \in L^2(\omega_0, d\nu_{2+2/\alpha})$ and $g_0 \in L^2(\gamma_0, d\nu_{1+1/\alpha})$. It is also worth noticing that $L^2(\omega_0, d\nu_{2+2/\alpha}) \subset L^2(\omega_0, dm^{-1})$ for all $\alpha > 0$, while $L^2(\gamma_0, d\nu_{1+1/\alpha}) \subset L^2(\omega_0, d\sigma^{-1})$ for $\alpha \leq 1$. In particular, (non zero) constant functions are in $L^2(\omega_0, d\sigma^{-1})$ only for $\alpha < 2$.

In the rest of this section, we collect some useful results about the functional space $H_N^1(\omega_{\varepsilon}, \mathrm{d}m)$ (trace theorems, Poincaré inequality, extension operator from ω_{ε} to ω_0), paying a very careful attention to ensure that the constants appearing in these continuity estimates are independent of $\varepsilon \ge 0$. These results will be used in Section 5 to study the well-posedness of the variational problem (4.3) for $\varepsilon = 0$.

Note that $H^1(\omega_0, dm)$ contains functions like $x \mapsto \ln(1+|x|)$, which tends to $+\infty$ as $|x| \to +\infty$. However, we have the following density result:

Lemma 4 The space

$$\mathcal{E}(\omega_0) = \{ u |_{\omega_0} : u \in C_0^\infty(\mathbb{R}^2) \}$$
(4.5)

is dense in $H^1(\omega_0, \mathrm{d}m)$.

Proof: For every integer $n \ge 1$, define the cut-off function χ_n on ω_0 by setting $\chi_n(x) = 1$ in D and, for every $x = (x_1, x_2) \in R_0$:

$$\chi_n(x) = \begin{cases} 1 & \text{if } x_1 \leq n \\ 1 - \ln\left(\frac{1+x_1}{1+n}\right) & \text{if } n < x_1 \leq N := (n+1)e - 1 \\ 0 & \text{if } x_1 > N. \end{cases}$$

Let u be in $H^1(\omega_0, \mathrm{d}m)$ and set $u_n = u\chi_n$. We have:

$$\int_{\omega_0} |\nabla(u - u_n)|^2 \, \mathrm{d}x = \int_{\omega_0} |\nabla u - \chi_n \nabla u - u \nabla \chi_n)|^2 \, \mathrm{d}x$$
$$\leqslant 2 \left(\int_{\omega_0} (1 - \chi_n) |\nabla u|^2 \, \mathrm{d}x + \int_{\omega_0} u^2 |\nabla \chi_n|^2 \, \mathrm{d}x \right)$$

Let $\mathcal{O}_n^+ = \{x_1 > n\} \cap R_0$ and $\mathcal{O}_n^- = \omega_0 \setminus \overline{\mathcal{O}_n^+}$. We deduce from the last estimate that:

$$\int_{\omega_0} |\nabla(u - u_n)|^2 \, \mathrm{d}x \leq 2 \left(\int_{\mathcal{O}_n^+} |\nabla u|^2 \, \mathrm{d}x + \int_{\mathcal{O}_n^+} u^2 \, \mathrm{d}m \right)$$

and hence $\|\nabla(u-u_n)\|_{L^2(\omega_0)}$ goes to 0 as n goes to $+\infty$. Since $\|u-u_n\|_{L^2(\omega_0,dm)}$ obviously goes to 0 as well, we get that $\|u-u_n\|_{H^1(\omega_0,dm)}$ tends to 0.

Now, given $\eta > 0$, fix n large enough such that

$$\|u - u_n\|_{H^1(\omega_0, \mathrm{d}m)} \leqslant \eta, \tag{4.6}$$

and let M be an integer larger that N. Classical density results for the standard Sobolev space $H^1(\mathcal{O}_M^-, \mathrm{d}m)$ on the bounded domain \mathcal{O}_M^- ensure the existence of $v \in C_0^\infty(\mathbb{R}^2)$ such that

$$\|u_n - v\|_{H^1(\mathcal{O}_M^-, \mathrm{d}m)} \leqslant \eta. \tag{4.7}$$

In particular, this implies that on the rectangle $\Re := N, M[\times]0, 1$ we have

$$\|v\|_{H^1(\mathfrak{R},\mathrm{d}m)} \leqslant \eta. \tag{4.8}$$

Set then $u^* = \theta v \in C_0^{\infty}(\mathbb{R}^2)$, where $\theta \in C_0^{\infty}(\mathbb{R})$ is a (one dimensional) cutt-off function satisfying $0 \leq \theta(x_1) \leq 1$ for all $x_1 \in \mathbb{R}$, $\theta(x_1) = 1$ for $x_1 < N$, $\theta(x_1) = 0$ for $x_1 > M$. Then, we have

$$\begin{aligned} \|u_n - u^*\|_{H^1(\omega_0, \mathrm{d}m)}^2 &= \|u_n - u^*\|_{H^1(\mathcal{O}_N^-, \mathrm{d}m)}^2 + \|u^*\|_{H^1(\mathcal{O}_N^+, \mathrm{d}m)}^2 \\ &= \|u_n - v\|_{H^1(\mathcal{O}_N^-, \mathrm{d}m)}^2 + \|\theta v\|_{H^1(\mathfrak{R}, \mathrm{d}m)}^2 \\ &\leqslant \|u_n - v\|_{H^1(\mathcal{O}_M^-, \mathrm{d}m)}^2 + \|\theta v\|_{H^1(\mathfrak{R}, \mathrm{d}m)}^2. \end{aligned}$$

Using (4.7) and (4.8), the last inequality shows that

$$||u_n - u^*||_{H^1(\omega_0, \mathrm{d}m)} \leq Cr$$

for some constant C > 0 (depending only on θ). Combining this estimate with (4.6) yields

$$||u - u^*||_{H^1(\omega_0, \mathrm{d}m)} \leq (C+1)\eta$$

which concludes the proof, since η is arbitrary.

The following Lemma explains why the case $\beta = 2$ plays a particular role in the analysis:

Lemma 5 For any real number β , we have the following continuous embedding:

$$H^1(\omega_0, \mathrm{d}\nu_\beta) \hookrightarrow H^1(\omega_0, \mathrm{d}m).$$

Proof: The result would be obvious if ω_0 were bounded. For the sake of simplicity and without loss of generality, we only show that

$$H^1(R_0, \mathrm{d}\nu_\beta) \hookrightarrow H^1(R_0, \mathrm{d}m),$$

which is equivalent to prove that the continuous embedding

$$H^1(R_0, \mathrm{d}\nu_\beta) \hookrightarrow L^2(R_0, \mathrm{d}m),$$

holds true. Let n be an integer greater than 3 and let u be in $C^1(\overline{\mathfrak{R}_n})$ where, for every k > 0, \mathfrak{R}_k denotes the rectangle $\{0 < x_1 < k\} \cap R_0$. Define the cutt-off function χ in R_0 by:

$$\chi(x) = \begin{cases} 1 & \text{if } 0 \leqslant x_1 < 1, \\ 2 - x_1 & \text{if } 1 \leqslant x_1 < 2, \\ 0 & \text{if } 2 \leqslant x_1, \end{cases}$$

and set $v = u\chi$ and $w = u(1 - \chi)$. We have:

$$\int_{\mathfrak{R}_n} u^2 \,\mathrm{d}m \leqslant 2 \left(\int_{\mathfrak{R}_2} v^2 \,\mathrm{d}m + \int_{\mathfrak{R}_n} w^2 \,\mathrm{d}m \right). \tag{4.9}$$

On the one hand:

$$\int_{\mathfrak{R}_2} v^2 \, \mathrm{d}m \leqslant C \int_{\mathfrak{R}_2} v^2 \, \mathrm{d}\nu_\beta \leqslant C \int_{\mathfrak{R}_2} u^2 \, \mathrm{d}\nu_\beta,$$

where the constant C depends only on β . On the other hand, for every $x \in \mathfrak{R}_n$:

$$|w(x)|^2 = 2 \int_0^{x_1} w(s, x_2) \partial_{x_1} w(s, x_2) \,\mathrm{d}s,$$

and hence:

$$\int_{\mathfrak{R}_n} |w|^2 \,\mathrm{d}m = 2 \int_0^1 \int_0^n \int_0^{x_1} w(s, x_2) \partial_{x_1} w(s, x_2) (1+x_1)^{-2} \,\mathrm{d}s \,\mathrm{d}x_1 \,\mathrm{d}x_2.$$

Invoking Fubini's theorem, we get:

$$\int_{\mathfrak{R}_n} |w|^2 \,\mathrm{d}m = 2 \int_0^1 \int_0^n w(s, x_2) \partial_{x_1} w(s, x_2) \left(\int_s^n (1+x_1)^{-2} \,\mathrm{d}x_1 \right) \,\mathrm{d}s \,\mathrm{d}x_2,$$

and Cauchy-Schwarz inequality leads to:

$$\int_{\Re_n} |w|^2 \, \mathrm{d}m \leqslant 2 \left(\int_{\Re_n} |\nabla w|^2 \, \mathrm{d}x \right)^{1/2} \left(\int_{\Re_n} u^2 \left(\int_s^n (1+x_1)^{-2} \, \mathrm{d}x_1 \right)^2 \, \mathrm{d}s \, \mathrm{d}x_2 \right)^{1/2}$$

Noticing that for every $n \ge 3$:

$$\left(\int_{s}^{n} (1+x_{1})^{-2} \,\mathrm{d}x_{1}\right)^{2} \leq (1+s)^{-2},$$

and hence:

$$\begin{split} \left(\int_{\mathfrak{R}_n} |w|^2 \,\mathrm{d}m\right)^{1/2} &\leqslant 2 \left(\int_{\mathfrak{R}_n} |\nabla w|^2 \,\mathrm{d}x\right)^{1/2} \\ &= 2 \left(\int_{\mathfrak{R}_n} |(1-\chi)\nabla u - u\nabla\chi|^2 \,\mathrm{d}x\right)^{1/2} \\ &\leqslant 2^{3/2} \left(\int_{\mathfrak{R}_n} |\nabla u|^2 \,\mathrm{d}x\right)^{1/2} + 2^{3/2} \left(\int_{\mathfrak{R}_2} u^2 \,\mathrm{d}x\right)^{1/2} \\ &\leqslant 2^{3/2} \left(\int_{\mathfrak{R}_n} |\nabla u|^2 \,\mathrm{d}x\right)^{1/2} + C \left(\int_{\mathfrak{R}_2} u^2 \,\mathrm{d}\nu_\beta\right)^{1/2}, \end{split}$$

where the constant C depends on β only. In (4.9), we get:

$$\int_{\mathfrak{R}_n} u^2 \,\mathrm{d}m \leqslant C \left(\int_{\mathfrak{R}_n} |\nabla u|^2 \,\mathrm{d}x + \int_{\mathfrak{R}_2} u^2 \,\mathrm{d}\nu_\beta \right)^{1/2},$$

where $C = C(\beta)$. Since $C^1(\overline{\mathfrak{R}_n})$ is dense in $H^1(\mathfrak{R}_n)$, we deduce that this estimate still holds true for every $u \in H^1(\mathfrak{R}_n)$.

Let now u be any function in $H^1(\omega_0, d\nu_\beta)$ and denote by $u_n = u|_{\mathfrak{R}_n} \in H^1(\mathfrak{R}_n)$. Applying the last estimate to u_n and letting n go to $+\infty$, we obtain the claimed result.

Remark 5 Let β_1 and β_2 be two real numbers such that $\beta_1 \ge \beta_2$. It is obvious to check that:

 $H^1(\omega_0, \mathrm{d}\nu_{\beta_1}) \hookrightarrow H^1(\omega_0, \mathrm{d}\nu_{\beta_2}).$

Then, it follows from Lemma 5 that for every $\beta \leq -2$, we have $H^1(\omega_0, d\nu_\beta) = H^1(\omega_0, dm)$.

The next result shows in particular that the average of functions of $H^1(\omega_0, dm)$ can be considered, and therefore the space $H^1_N(\omega_{\varepsilon}, dm)$ introduced in (4.1) is well defined for $\varepsilon = 0$.

Lemma 6 For every $\beta < -3/2$, we have the following continuous embedding:

$$L^{2}(\omega_{0}, \mathrm{d}m) \hookrightarrow L^{1}(\omega_{0}, \mathrm{d}\nu_{\beta}) \quad and \quad L^{2}(\gamma_{0}, \mathrm{d}\sigma) \hookrightarrow L^{1}(\gamma_{0}, \mathrm{d}\nu_{\beta}^{S}).$$
 (4.10)

Proof : One can simply observe that for every u in $L^2(\omega_0, dm)$, we have

$$\int_{R_0} |u(x)| (1+x_1)^{\beta} \, \mathrm{d}x = \int_{R_0} |u(x)| (1+x_1)^{-1} (1+x_1)^{\beta+1} \, \mathrm{d}x$$
$$\leqslant \|u\|_{L^2(R_0,\mathrm{d}m)} \left(\int_{R_0} (1+x_1)^{2\beta+2} \, \mathrm{d}x \right)^{1/2}$$

The conclusion follows for the first embedding in (4.10). The second embedding is proved exactly the same way. \Box

In order to establish a convergence result as ε tends to 0, we need to be able to extend functions defined on ω_{ε} to ω_0 in such a way that the extension operator be uniformly bounded with respect to ε . The following result provides the existence of such an operator. **Lemma 7 (Extension operator)** For every $\varepsilon > 0$ small enough, there exists an extension operator:

$$T_{\varepsilon}: H^1(\omega_{\varepsilon}, \mathrm{d}m) \to H^1(\omega_0, \mathrm{d}m),$$

such that

$$||T_{\varepsilon} u||_{H^{1}(\omega_{0}, \mathrm{d}m)} \leqslant \sqrt{3} ||u||_{H^{1}(\omega_{\varepsilon}, \mathrm{d}m)}.$$

Proof: Since $D \subset \omega_{\varepsilon}$ for every $\varepsilon \ge 0$, it is sufficient to define R_{ε} from $H^1(R_{\varepsilon}, \mathrm{d}m)$ to $H^1(R_0, \mathrm{d}m)$. For every $\varepsilon > 0$, set

$$\ell_{\varepsilon}^* := \ell_{\varepsilon}(2 - e^{-1}) + (1 - e^{-1}),$$

and let χ_{ε} be the cutt-off function defined in R_0 as follows:

$$\chi_{\varepsilon}(x) = \begin{cases} 1 & \text{if } x_1 < \ell_{\varepsilon} \\ 1 + \ln\left(1 + \frac{\ell_{\varepsilon} - x_1}{\ell_{\varepsilon} + 1}\right) & \text{if } \ell_{\varepsilon} \leqslant x_1 < \ell_{\varepsilon}^* \\ 0 & \text{if } \ell_{\varepsilon}^* \leqslant x_1. \end{cases}$$

Note that $0 \leq \chi_{\varepsilon}(x) \leq 1$ for every $x \in R_0$. Moreover, for $\varepsilon > 0$ small enough, the quantity $\ell_{\varepsilon}^- := 2\ell_{\varepsilon} - \ell_{\varepsilon}^*$ is positive and for every $x \in R_0$ such that $x_1 > \ell_{\varepsilon}^-$ we have:

$$|\chi_{\varepsilon}'(2\ell_{\varepsilon} - x_1)|^2 = m(x_1) = (1 + x_1)^{-2}.$$
(4.11)

For every $u \in H^1(R_{\varepsilon}, \mathrm{d}m)$, we define $T_{\varepsilon}u$ in R_0 as follows:

$$(T_{\varepsilon}u)(x) = \begin{cases} u(x_1, x_2) & \text{if } x_1 \leqslant \ell_{\varepsilon} \\ \chi_{\varepsilon}(x_1)u(2\ell_{\varepsilon} - x_1, x_2) & \text{if } \ell_{\varepsilon} \leqslant x_1 < \ell_{\varepsilon}^* \\ 0 & \text{if } \ell_{\varepsilon}^* \leqslant x_1. \end{cases}$$

It can be easily verified that $T_{\varepsilon} u \in H^1_{loc}(R_0)$. Moreover, we have:

$$\begin{split} \int_{R_0} |\nabla(T_{\varepsilon}u)|^2 \, \mathrm{d}x &= \int_{R_{\varepsilon}} |\nabla u_{\varepsilon}|^2 \, \mathrm{d}x \\ &+ \int_{R_0 \cap \{\ell_{\varepsilon} < x_1 < \ell_{\varepsilon}^*\}} |\partial_{x_1}\chi_{\varepsilon}(x)u(2\ell_{\varepsilon} - x_1, x_2) - \chi_{\varepsilon}(x)\partial_{x_1}u(2\ell_{\varepsilon} - x_1, x_2)|^2 \, \mathrm{d}x \\ &+ \int_{R_0 \cap \{\ell_{\varepsilon} < x_1 < \ell_{\varepsilon}^*\}} |\partial_{x_2}u(2\ell_{\varepsilon} - x_1, x_2)|^2 \, \mathrm{d}x. \end{split}$$

Applying the change of variables $x'_1 = 2\ell_{\varepsilon} - x_1$ in the last two integrals of the right hand side and using Cauchy-Schwarz inequality, we get by using (4.11) that:

$$\int_{R_0} |\nabla(T_{\varepsilon}u)|^2 \,\mathrm{d}x \leqslant \int_{R_{\varepsilon}} |\nabla u_{\varepsilon}|^2 \,\mathrm{d}x + 2 \int_{R_0 \cap \{\ell_{\varepsilon}^- < x_1 < \ell_{\varepsilon}\}} u^2 \,\mathrm{d}m + 2 \int_{R_0 \cap \{\ell_{\varepsilon}^- < x_1 < \ell_{\varepsilon}\}} |\nabla u|^2 \,\mathrm{d}x.$$
ntly

Consequently

 $\int_{R_0} |\nabla(T_{\varepsilon}u)|^2 \,\mathrm{d}x \leqslant 3 \|u\|_{H^1(R_{\varepsilon},\mathrm{d}m)}^2.$ (4.12)

On the other hand, we also have:

$$\int_{R_0} |T_{\varepsilon}u|^2 \,\mathrm{d}m \leqslant \int_{R_{\varepsilon}} |u_{\varepsilon}|^2 \,\mathrm{d}m + \int_{R_0 \cap \{\ell_{\varepsilon}^- < x_1 < \ell_{\varepsilon}\}} |\chi_{\varepsilon}(2\ell_{\varepsilon} - x_1, x_2)|^2 |u(x)|^2 \,\mathrm{d}m$$
$$\leqslant 2||u||^2_{L^2(R_{\varepsilon}, \mathrm{d}m)}.$$

The announced estimate follows then immediately by combining (4.12) and the last inequality.

Lemma 8 (Uniform trace mapping) Let $\mathcal{E}(\omega_0)$ be the functional space defined by (4.5). Then, the mapping

$$u \in \mathcal{E}(\omega_0) \mapsto u|_{\gamma_0} \in L^2(\gamma_0, \, \mathrm{d}\sigma)$$

can be uniquely extended as a linear continuous operator:

$$\Lambda_0: u \in H^1(\omega_0, \mathrm{d}m) \to L^2(\gamma_0, \mathrm{d}\sigma).$$

Moreover, denoting by Λ_{ε} the usual trace mapping from $H^1(\omega_{\varepsilon})$ into $L^2(\gamma_{\varepsilon})$ for $\varepsilon > 0$, there exists a constant C > 0 (independent of $\varepsilon \ge 0$) such that, for every $\varepsilon \ge 0$:

$$\|\Lambda_{\varepsilon}(u)\|_{L^{2}(\gamma_{\varepsilon}, \mathrm{d}\sigma)} \leqslant C \|u\|_{H^{1}(\omega_{\varepsilon}, \mathrm{d}m)}.$$
(4.13)

Proof: Classically, it is sufficient to prove the existence of Λ_0 defined as an application from $H^1(R_0, dm)$ into $L^2(\gamma_0^R, d\sigma)$. For every $u \in \mathcal{E}(R_0)$, we have:

$$|u(x_1,1)|^2 = \int_0^1 \frac{\mathrm{d}}{\mathrm{d}s} (|u(x_1,s)|^2 s) \mathrm{d}s$$

= $2 \int_0^1 \partial_{x_2} u(x_1,s) u(x_1,s) \mathrm{sd}s + \int_0^1 |u(x_1,s)|^2 \mathrm{d}s.$

Multiplying both sides of this equality by $(1 + x_1)^{-2}$, integrating from 0 to $+\infty$ with respect to x_1 and using Cauchy-Schwarz inequality, we get:

$$\int_{\gamma_0^R} u^2(x_1, 1) \,\mathrm{d}\sigma \leqslant 2 \left(\int_{R_0} |\partial_{x_2} u|^2 \,\mathrm{d}x \right)^{1/2} \left(\int_{R_0} u^2 \,\mathrm{d}\nu_\beta \right)^{1/2} + \int_{R_0} u^2 \,\mathrm{d}m,$$

where $\beta = -4$. According to Remark 5, we deduce that there exists a constant C > 0 such that:

$$\int_{\gamma_0^R} u^2(x_1, 1) \, \mathrm{d}\sigma \leqslant C \|u\|_{H^1(R_0, \mathrm{d}m)}^2.$$

We conclude to the existence of Λ_0 by recalling the density of $\mathcal{E}(\omega_0)$ into $H^1(\omega_0, dm)$ proved in Lemma 4. To get the uniform estimate (4.13), we write that, for every $u \in H^1(\omega_{\varepsilon})$ and using Lemma 7:

$$\|\Lambda_{\varepsilon}(u)\|_{L^{2}(\gamma_{\varepsilon},\mathrm{d}\sigma)} \leqslant \|\Lambda_{0}(T_{\varepsilon}u)\|_{L^{2}(\gamma_{0},\mathrm{d}\sigma)} \leqslant \tilde{C}\|T_{\varepsilon}u\|_{H^{1}(\omega_{0},\mathrm{d}m)} \leqslant C\|u_{\varepsilon}\|_{H^{1}(\omega_{\varepsilon},\mathrm{d}m)},$$

where \tilde{C} and C are positive constants independent of $\varepsilon \ge 0$. The proof is now complete.

Lemma 9 (Poincaré-Wirtinger inequality) There exists a constant C > 0 (independent of ε) such that for every $\varepsilon \ge 0$:

$$\|u\|_{L^{2}(\omega_{\varepsilon}, \mathrm{d}m)} \leqslant C \|\nabla u\|_{L^{2}(\omega_{\varepsilon})}, \quad \forall u \in H^{1}_{N}(\omega_{\varepsilon}, \mathrm{d}m).$$

$$(4.14)$$

Proof: The result is proved in two steps. Using a direct calculation, we first show that this inequality holds on the (finite or semi-infinite) strip $R_{\varepsilon} :=]0, \ell_{\varepsilon}[\times]0, 1[$ with $C = \sqrt{2}$:

$$\|u\|_{L^2(R_{\varepsilon}, \mathrm{d}m)} \leqslant \sqrt{2} \|\nabla u\|_{L^2(R_{\varepsilon})}, \quad \forall u \in H^1_N(R_{\varepsilon}, \mathrm{d}m).$$

$$(4.15)$$

Next, we prove by contradiction that inequality (4.15) implies (4.14).

Let u be a function in $C^1(\overline{R_{\varepsilon}})$ or $\mathcal{E}(R_0)$ if $\varepsilon = 0$. For every $x = (x_1, x_2)$ and $x' = (x'_1, x'_2)$ in R_{ε} , we have:

$$u(x_1, x_2) - u(x'_1, x'_2) = u(x_1, x_2) - u(x'_1, x_2) + u(x'_1, x_2) - u(x'_1, x'_2)$$
$$= \int_{x'_1}^{x_1} \partial_{x_1} u(s, x_2) \, \mathrm{d}s + \int_{x'_2}^{x_2} \partial_{x_2} u(x'_1, s) \, \mathrm{d}s.$$

Multiplying by $\left[(1+x_1)^2 m(R_{\varepsilon})\right]^{-1}$ and integrating the last equation with respect to x_1 from 0 to ℓ_{ε} , we get:

$$\frac{1}{m(R_{\varepsilon})} \int_{0}^{\ell_{\varepsilon}} (1+x_{1})^{-2} u(x_{1},x_{2}) \, \mathrm{d}x_{1} - u(x_{1}',x_{2}') = \frac{1}{m(R_{\varepsilon})} \int_{0}^{\ell_{\varepsilon}} \left(\int_{x_{1}'}^{x_{1}} \partial_{x_{1}} u(s,x_{2}) \, \mathrm{d}s \right) (1+x_{1})^{-2} \, \mathrm{d}x_{1} + \int_{x_{2}'}^{x_{2}} \partial_{x_{2}} u(x_{1}',s) \, \mathrm{d}s.$$
(4.16)

Applying Fubini's theorem to the first term of the right hand side, we get:

$$\int_0^{\ell_{\varepsilon}} \left(\int_{x_1'}^{x_1} \partial_{x_1} u(s, x_2) \, \mathrm{d}s \right) (1+x_1)^{-2} \, \mathrm{d}x_1 = \int_{x_1'}^{\ell_{\varepsilon}} \partial_{x_1} u(s, x_2) \left(\int_s^{\ell_{\varepsilon}} (1+x_1)^{-2} \, \mathrm{d}x_1 \right) \, \mathrm{d}s.$$

Integrating now (4.16) with respect to x_2 from 0 to 1, we deduce that:

$$\left| u(x') - \frac{1}{m(R_{\varepsilon})} \int_{R_{\varepsilon}} u(x) \,\mathrm{d}m \right| \leq \frac{1}{m(R_{\varepsilon})} \int_{R_{\varepsilon}} |\partial_{x_1} u(s, x_2)| (1+s)^{-1} \,\mathrm{d}s \,\mathrm{d}x_2 + \int_0^1 |\partial_{x_2} u(x'_1, s)| \,\mathrm{d}s.$$

According to Cauchy-Schwarz inequality, we get:

$$\left| u(x') - \frac{1}{m(\omega_{\varepsilon})} \int_{\omega_{\varepsilon}} u(x) \,\mathrm{d}m \right|^2 \leq 2 \left[\frac{1}{m(\omega_{\varepsilon})} \|\partial_{x_1} u\|_{L^2(\omega_{\varepsilon})}^2 + \int_0^1 |\partial_{x_2} u(x'_1, s)|^2 \,\mathrm{d}s \right],$$

and then, multiplying by $(x'_1 + 1)^{-2}$ and integrating with respect to x' on ω_{ε} , we obtain:

$$\int_{\omega_{\varepsilon}} \left| u(x') - \frac{1}{m(\omega_{\varepsilon})} \int_{\omega_{\varepsilon}} u(x) \, \mathrm{d}m \right|^2 \mathrm{d}m(x') \leq 2 \left[\|\partial_{x_1} u\|_{L^2(\omega_{\varepsilon})}^2 + \|\partial_{x_2} u\|_{L^2(\omega_{\varepsilon})}^2 \right],$$

which shows that (4.15) holds true.

Now, we show by contradiction that (4.14) also holds. If not, there would exist two sequences $(\varepsilon_n)_{n \ge 1} \searrow 0$ and $(u_n)_{n \ge 1}$, with $u_n \in H^1_N(\omega_n, dm)$ (for the sake of clarity, we set $\omega_n := \omega_{\varepsilon_n}$ throughout the proof), such that

$$\|u_n\|_{L^2(\omega_n, \mathrm{d}m)} = 1 \tag{4.17a}$$

$$\|\nabla u_n\|_{L^2(\omega_n)} \to 0 \quad \text{as } n \to +\infty.$$
(4.17b)

On the one hand, setting $\overline{u_n} := \frac{1}{m(R_n)} \int_{R_n} u_n \, \mathrm{d}m$, the function defined on $R_n := R_{\varepsilon_n}$ by $u_n - \overline{u_n}$ obviously satisfies $v_n \in H^1_N(R_n, \mathrm{d}m)$ and, thanks to (4.15) and (4.17b),

$$\|u_n - \overline{u_n}\|_{L^2(R_n, \mathrm{d}m)} \leqslant \sqrt{2} \|\nabla u_n\|_{L^2(R_n)} \to 0 \quad \text{as } n \to +\infty,$$

and thus

$$\|u_n - \overline{u_n}\|_{H^1(R_n, \mathrm{d}m)} \to 0 \quad \text{as } n \to +\infty.$$
(4.18)

Moreover, using Cauchy-Schwarz inequality and (4.17a), we have

$$\left|\overline{u_{n}}\right| = \frac{1}{m(R_{n})} \int_{R_{n}} \left|u_{n}\right| \mathrm{d}m \leqslant \frac{1}{\sqrt{m(R_{n})}} \leqslant \frac{1}{\sqrt{m(R_{1})}} < \infty.$$

Consequently, there exists a constant $U_R \in \mathbb{R}$ such that the sequence of real numbers $(\overline{u_n})_{n \ge 1}$ converge (up to a subsequence) to U_R . According to (4.18), this shows that

$$||u_n - U_R||_{H^1(R_n, \mathrm{d}m)} \to 0 \quad \text{as } n \to +\infty.$$
 (4.19)

On the other hand, on the domain $D = \omega_n \setminus R_n$, we immediately get from (4.17a) and (4.17b), using the compactness of the injection from $H^1(D)$ into $L^2(D)$, that (up to a subsequence) there exists a constant $U_D \in \mathbb{R}$ such that

$$\|u_n - U_D\|_{H^1(D)} \to 0 \quad \text{as } n \to +\infty.$$

$$(4.20)$$

The continuity of the trace of $u_n \in H^1_N(\omega_n, dm)$ through the interface $\partial D \cap \partial R_n$ implies that $U_R = U_D := U$. Since $u_n \in H^1_N(\omega_n, dm)$, this common value U is necessarily zero, as

$$0 = \int_{\omega_n} u_n \,\mathrm{d}m = \int_D u_n \,\mathrm{d}m + \int_{R_n} u_n \,\mathrm{d}m \to (m(D) + m(R_0))U \quad \text{as } n \to +\infty.$$

But this fact is on contradiction with (4.17a), (4.19) and (4.20).

5 Some abstract well-posedness and convergence results

We are now in position to prove the well-posedness of the Neumann problem in the unbounded domain ω_0 and a convergence result as ε tends to 0. Applying Riesz representation Theorem, we immediately get by Poincaré-Wirtinger inequality (see Lemma 9) the following well-posedness and uniqueness result:

Theorem 2 For every $f_0 \in L^2(\omega_0, \mathrm{d}m^{-1})$ and every $g_0 \in L^2(\gamma_0, \mathrm{d}\sigma^{-1})$ satisfying the compatibility condition

$$\int_{\omega_0} f_0 \,\mathrm{d}x + \int_{\gamma_0} g_0 \,\mathrm{d}s = 0,$$

there exists a unique finite energy solution $u_0 \in H^1_N(\omega_0, \mathrm{d}m)$ (in the sense of Definition 1) to Problem 4.3 when $\varepsilon = 0$.

Remark 6 (Regularity of the solutions) Investigating the maximal regularity for the solution u_0 in term of weighted Sobolev spaces is out of the range of our study. However, we can mention the following very basic result: In case $g_0 \in H^{1/2}_{loc}$, then it is classical to verify that $u_0|_{\mathfrak{R}_n} \in H^2(\mathfrak{R}_n)$ for every $n \ge 0$ (recall that $\mathfrak{R}_n :=]0, n[\times]0, 1[)$. Moreover, still for every $n \ge 0$, the function $u_0^n := u_0|_{\mathfrak{R}_n}$ satisfies

$$-\operatorname{div}(\mathbb{A}_0 \nabla u_0^n) = f_0 \text{ in } L^2(\mathfrak{R}_n) \quad and \quad \mathbb{A}_0 \nabla u_0^n \cdot n = g_0 \text{ in } H^{1/2}(\gamma_0^n),$$

where γ_0^n is the upper boundary of \mathfrak{R}_n .

As already mentioned in the beginning of the previous Section, the existence and uniqueness of a solution $u_{\varepsilon} \in H^1_N(\omega_{\varepsilon}, \mathrm{d}m)$ for Problem 4.3 when $\varepsilon > 0$ is classical. So, let us now investigate the convergence of u_{ε} as $\varepsilon \to 0^+$.

Notice that every functions $f_{\varepsilon} \in L^2(\omega_{\varepsilon}, \mathrm{d}m^{-1})$ and $g_{\varepsilon} \in L^2(\gamma_{\varepsilon}, \mathrm{d}\sigma^{-1})$ can be seen as functions of $L^2(\omega_0, \mathrm{d}m^{-1})$ and $L^2(\gamma_0, \mathrm{d}\sigma^{-1})$ respectively by setting $f_{\varepsilon} := 0$ in $\omega_0 \setminus \omega_{\varepsilon}$ and $g_{\varepsilon} := 0$ on $\gamma_0 \setminus \gamma_{\varepsilon}$.

Theorem 3 For every $\varepsilon \ge 0$, let $f_{\varepsilon} \in L^2(\omega_{\varepsilon}, \mathrm{d}m^{-1})$ and $g_{\varepsilon} \in L^2(\gamma_{\varepsilon}, \mathrm{d}\sigma^{-1})$ be given such that the compatibility condition (4.2) is satisfied and denote by $u_{\varepsilon} \in H^1_N(\omega_{\varepsilon}, \mathrm{d}m)$ the unique solution to Problem 4.3.

Assume that

$$f_{\varepsilon} \to f_0 \text{ in } L^2(\omega_0, \mathrm{d}m^{-1}) \quad and \quad g_{\varepsilon} \to g_0 \text{ in } L^2(\gamma_0, \mathrm{d}\sigma^{-1}).$$
 (5.1)

Then, under the convergence result (3.13a), we have:

$$\|\nabla(u_0 - u_{\varepsilon})\|_{L^2(\omega_{\varepsilon})} \to 0 \quad as \ \varepsilon \to 0^+, \tag{5.2a}$$

$$\left| \int_{\omega_0} \mathbb{A}_0 \nabla u_0 \cdot \nabla u_0 \, \mathrm{d}x - \int_{\omega_\varepsilon} \mathbb{A}_\varepsilon \nabla u_\varepsilon \cdot \nabla u_\varepsilon \, \mathrm{d}x \right| \to 0 \quad as \ \varepsilon \to 0^+.$$
(5.2b)

Proof : Throughout this proof, C will denote a constant that may change from line to line, but that is independent of ε .

Taking $v = u_{\varepsilon} \in H^1(\omega_{\varepsilon}, \mathrm{d}m)$ in (4.3) (see Remark 3), we get that:

$$\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot \nabla u_{\varepsilon} \, \mathrm{d}x \leqslant \|f_{\varepsilon}\|_{L^{2}(\omega_{0},\mathrm{d}m^{-1})} \|u_{\varepsilon}\|_{L^{2}(\omega_{\varepsilon},\mathrm{d}m)} + \|g_{\varepsilon}\|_{L^{2}(\gamma_{0},\,\mathrm{d}\sigma^{-1})} \|u_{\varepsilon}\|_{L^{2}(\gamma_{\varepsilon},\,\mathrm{d}\sigma)}.$$

Since \mathbb{A}_{ε} is positive definite uniformly (with respect to ε) according to Lemma 3, and since the continuity of the trace operator and the Poincaré-Wirtinger constants are uniform with respect to $\varepsilon \ge 0$ as well (as asserted in Lemma 8 and Lemma 9), we obtain that:

$$\|\nabla u_{\varepsilon}\|_{L^{2}(\omega_{\varepsilon})}^{2} \leqslant C(\|f_{\varepsilon}\|_{L^{2}(\omega_{0},\mathrm{d}m^{-1})} + \|g_{\varepsilon}\|_{L^{2}(\gamma_{0},\mathrm{d}\sigma^{-1})})\|\nabla u_{\varepsilon}\|_{L^{2}(\omega_{\varepsilon})},$$

and therefore, using again Lemma 9:

$$\|u_{\varepsilon}\|_{H^{1}(\omega_{\varepsilon}, \mathrm{d}m)} \leqslant C, \quad \forall \varepsilon \ge 0.$$
(5.3)

Specifying now $v = u_0|_{\omega_{\varepsilon}} - u_{\varepsilon} \in H^1(\omega_{\varepsilon}, \mathrm{d}m)$ in (4.3), we get:

$$\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot (\nabla u_0 - \nabla u_{\varepsilon}) \, \mathrm{d}x = \int_{\omega_{\varepsilon}} f_{\varepsilon}(u_0 - u_{\varepsilon}) \, \mathrm{d}x + \int_{\gamma_{\varepsilon}} g_{\varepsilon}(u_0 - u_{\varepsilon}) \, \mathrm{d}s.$$
(5.4)

On the other hand, taking $v = u_0 - T_{\varepsilon} u_{\varepsilon} \in H^1(\omega_0, dm)$ in (4.3) when $\varepsilon = 0$, where T_{ε} is the extension operator introduced in Lemma 7, we get:

$$\int_{\omega_0} \mathbb{A}_0 \nabla u_0 \cdot (\nabla u_0 - \nabla T_\varepsilon u_\varepsilon) \,\mathrm{d}x = \int_{\omega_0} f_0(u_0 - T_\varepsilon u_\varepsilon) \,\mathrm{d}x + \int_{\gamma_0} g_0(u_0 - T_\varepsilon u_\varepsilon) \,\mathrm{d}s.$$
(5.5)

Setting $\omega_{\varepsilon}^{c} := \omega_{0} \setminus \omega_{\varepsilon} = [\ell_{\varepsilon}, +\infty[\times]0, 1[$ and $\gamma_{\varepsilon}^{c} = \gamma_{0} \setminus \gamma_{\varepsilon}$ and subtracting (5.4) from (5.5), we obtain:

$$\int_{\omega_{\varepsilon}} \mathbb{A}_{0} (\nabla u_{0} - \nabla u_{\varepsilon}) \cdot (\nabla u_{0} - \nabla u_{\varepsilon}) \, \mathrm{d}x = -\int_{\omega_{\varepsilon}} (\mathbb{A}_{0} - \mathbb{A}_{\varepsilon}) \nabla u_{\varepsilon} \cdot (\nabla u_{0} - \nabla u_{\varepsilon}) \, \mathrm{d}x \\ -\int_{\omega_{\varepsilon}^{c}} \mathbb{A}_{0} \nabla u_{0} \cdot (\nabla u_{0} - \nabla T_{\varepsilon} u_{\varepsilon}) \, \mathrm{d}x + \int_{\omega_{\varepsilon}} (f_{0} - f_{\varepsilon})(u_{0} - u_{\varepsilon}) \, \mathrm{d}x + \int_{\gamma_{\varepsilon}} (g_{0} - g_{\varepsilon})(u_{0} - u_{\varepsilon}) \, \mathrm{d}s \\ + \int_{\omega_{\varepsilon}^{c}} f_{0}(u_{0} - T_{\varepsilon} u_{\varepsilon}) \, \mathrm{d}x + \int_{\gamma_{\varepsilon}^{c}} g_{0}(u_{0} - T_{\varepsilon} u_{\varepsilon}) \, \mathrm{d}s.$$
(5.6)

Lemma 7 together with the estimate (5.3) ensure that $||T_{\varepsilon}u_{\varepsilon}||_{H^{1}(\omega_{\varepsilon}, \mathrm{d}m)} \leq C$ for every $\varepsilon \geq 0$. On the other hand, taking into account the convergence result (3.13a) and the hypothesis (5.1) in (5.6), we get

$$\int_{\omega_{\varepsilon}} \mathbb{A}_0(\nabla u_0 - \nabla u_{\varepsilon}) \cdot (\nabla u_0 - \nabla u_{\varepsilon}) \, \mathrm{d}x \longrightarrow 0 \quad \text{as } \varepsilon \to 0^+,$$

and (5.2a) follows with (3.14).

To prove now (5.2b), we write that:

$$\int_{\omega_0} \mathbb{A}_0 \nabla u_0 \cdot \nabla u_0 \, \mathrm{d}x - \int_{\omega_\varepsilon} \mathbb{A}_\varepsilon \nabla u_\varepsilon \cdot \nabla u_\varepsilon \, \mathrm{d}x = \int_{\omega_\varepsilon} \mathbb{A}_0 (\nabla u_0 - \nabla u_\varepsilon) \cdot (\nabla u_0 + \nabla u_\varepsilon) \, \mathrm{d}x + \int_{\omega_\varepsilon} (\mathbb{A}_0 - \mathbb{A}_\varepsilon) \nabla u_\varepsilon \cdot \nabla u_\varepsilon \, \mathrm{d}x,$$

and the conclusion follows, invoking again the same aforementioned boundedness and convergence arguments. \Box

6 Application to the collision problem

The weak formulation of System 1.10 reads, for every $\varepsilon \ge 0$:

$$\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot \nabla v \, \mathrm{d}x = \int_{\Gamma_{\varepsilon}} g_{\varepsilon} v \, \mathrm{d}s, \qquad \forall v \in H^{1}_{N}(\omega_{\varepsilon}, \mathrm{d}m),$$
(6.1)

where $g_{\varepsilon} = D\Psi_{\varepsilon}^{-1}\tau \cdot e_1$. This quantity can be made explicit on $\gamma_{\varepsilon}^R = \{(x_1, 1) : 0 < x_1 < \ell_{\varepsilon}\}$ using the expression (3.8) of Ψ_{ε}^{-1} . Thus we get

 $g_{\varepsilon} = H_{\varepsilon}(\mu_{\varepsilon}) \quad \text{on } \gamma_{\varepsilon}^{R}.$

Notice that although the expression of the matrix \mathbb{A}_{ε} depends on α (i.e. on the nature of the cusp) and on $\varepsilon \ge 0$, this dependence is somehow irrelevant regarding the well-posedness of Problem 6.1 because, as asserted by Lemma 3, the matrix is always uniformly elliptic and therefore the left hand side of (6.1) always defines a symmetric, elliptic bilinear form on $H^1_N(\omega_{\varepsilon}, dm)$, according to Lemma 9.

All of the relevant information regarding the well-posedness of Problem 6.1 is carried by the boundary data g_{ε} . Considering Theorem 2, a sufficient condition for Problem 6.1 to be well-posed when $\varepsilon = 0$ is $g_0 \in L^2(\gamma_0, d\sigma^{-1})$ while, according to Theorem 3, the convergence of the solution u_{ε} toward u_0 and of the Dirichlet energy E_{ε} toward E_0 is ensured if $g_{\varepsilon} \to g_0$ in $L^2(\gamma_0, d\sigma^{-1})$. These conditions are easy to check and lead to distinguish two cases, a sub-critical case $\alpha < 2$ and a super-critical case $\alpha \ge 2$. Let us emphasize that the critical value 2 is nothing but the dimension, and this is in agreement with the results of [2, 15].

6.1 The sub-critical case $\alpha < 2$

Theorem 4 When $\alpha < 2$, the following assertions hold true:

- 1. Well posedness of the limit problem: The Neumann boundary value problem (6.1) is well posed for $\varepsilon = 0$. In particular, the corresponding Dirichlet energy E_0 is finite.
- 2. Convergence of solutions: $\|\nabla u_{\varepsilon} \nabla u_0\|_{L^2(\omega_{\varepsilon})} \to 0$ as $\varepsilon \to 0^+$, where u_{ε} and u_0 are the solutions to Problem (6.1) for $\varepsilon > 0$ and $\varepsilon = 0$ respectively.
- 3. Convergence of the Dirichlet energy: The Dirichlet energy E_{ε} corresponding to Problem (6.1) with $\varepsilon > 0$ tends to E_0 , the finite Dirichlet energy of the problem when $\varepsilon = 0$.

Considering the implication of this result for the physical problem of collision, we deduce that the added mass (1.4) is bounded uniformly in $\varepsilon \ge 0$. Using this estimate in (1.5), we get that the velocity of the solid is bounded from below and therefore:

Corollary 2 When $\alpha < 2$, the solid meets the cavity's wall in finite time with non-zero velocity (real shock case).

Proof of Theorem 4: As already mentioned, the first point of the Theorem is a straightforward consequence of Theorem 2. Indeed, applying Theorem 2 with $f_0 = 0$ and $g_0 = H_0(\mu_0)$, we get existence and uniqueness of a solution if $g_0 \in L^2(\gamma_0, d\sigma^{-1})$. Considering (3.7), we deduce that:

$$g_0 \sim_{x_1 = +\infty} \kappa^{-\frac{1}{\alpha}} \alpha^{-1 - \frac{1}{\alpha}} x_1^{-1 - \frac{1}{\alpha}},$$

and requiring g_0 to be in $L^2(\gamma_0, d\sigma^{-1})$ leads to $\alpha < 2$.

The two remaining points result from Theorem 3. It suffices to prove that $g_{\varepsilon} := H_{\varepsilon}(\mu_{\varepsilon})$ (extended by 0 on $]\ell_{\varepsilon}, +\infty[)$ converges to $g_0 := H_0(\mu_0)$ in $L^2(\gamma_0, d\sigma^{-1})$. According to Lemma 2, we get that g_{ε} tends to g_0 a.e. on \mathbb{R}_+ and that:

$$|g_{\varepsilon} - g_0|^2 \leqslant C(1+x_1)^{-2-\frac{2}{\alpha}},$$

for some constant C > 0 independent of $\varepsilon \ge 0$. The conclusion follows from the dominated convergence theorem.

6.2 The super-critical case $\alpha \ge 2$

When $\alpha \ge 2$, the boundary term $g_0 := H_0(\mu_0)$ in Problem 6.1 is not anymore in $L^2(\gamma_0, d\sigma^{-1})$, preventing from reasoning as in the previous section.

Actually, we already know, from Proposition 1, that Problem 6.1 (when $\varepsilon = 0$) does not admit finite energy solution in this case and from Proposition 2 that $E_{\varepsilon} \to +\infty$ as $\varepsilon \to 0^+$.

In order to derive the first term in the asymptotic expansion of E_{ε} when ε goes to 0 in this case, we proceed as follows. For every $\varepsilon \ge 0$ we seek an ansatz u_{ε}^s to u_{ε} , that contains all the information about the asymptotic behavior at infinity of u_{ε} when $\varepsilon \to 0$, responsible of the blow up of the Dirichlet energy as $\varepsilon \to 0$. Equivalently, in the physical domain, this ansatz contains all the information about the appearance of the cusp singularity at the contact point. In particular, u_{ε}^s will be shown to satisfy:

$$\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^{s} \cdot \nabla u_{\varepsilon}^{s} \mathrm{d}x \to +\infty \quad \text{as} \quad \varepsilon \to 0^{+}.$$
(6.2)

This is why we call this ansatz as the singular part of the solution (which is a slight abuse of language since u_{ε} is smooth and has finite Dirichlet energy for every $\varepsilon > 0$), and we will refer to $u_{\varepsilon}^r := u_{\varepsilon} - u_{\varepsilon}^s$ as the regular part of u_{ε} .

The ansatz u_{ε}^{s} will be derived by adapting to our semi-infinite strip the multiscale expansion method used in [2, 15] to obtain the singular behavior near the contact point (in the physical domain). More precisely, for every $\varepsilon \ge 0$, the ansatz u_{ε}^{s} will be constructed such that the following properties hold true:

- The function u_{ε}^{s} is smooth, supported in R_{ε} and extended by 0 in D, and the quantity $\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^{s} \cdot n$ vanishes on the boundary $\partial \omega_{\varepsilon} \setminus \gamma_{\varepsilon}$. This implies in particular that for every $\varepsilon > 0$, the function u_{ε}^{s} satisfies the weak formulation (4.3) with source terms $(f_{\varepsilon}^{s}, g_{\varepsilon}^{s}) \in L^{2}(\omega_{\varepsilon}, \mathrm{d}m^{-1}) \times L^{2}(\gamma_{\varepsilon}, \mathrm{d}\sigma^{-1})$, where $f_{\varepsilon}^{s} := -\operatorname{div}(\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^{s})$ in ω_{ε} and $g_{\varepsilon}^{s} := \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^{s} \cdot n$ on γ_{ε} .
- If we set

$$f_{\varepsilon}^{r} := -\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla u_{\varepsilon}^{r}) = -f_{\varepsilon}^{s} \text{ in } \omega_{\varepsilon} \quad \text{and} \quad g_{\varepsilon}^{r} := \mathbb{A}_{\varepsilon}\nabla u_{\varepsilon}^{r} \cdot n = g_{\varepsilon} - g_{\varepsilon}^{s} \text{ on } \gamma_{\varepsilon}, \tag{6.3}$$

then for $\varepsilon = 0$, $f_0^r \in L^2(\omega_0, \mathrm{d}m^{-1})$, $g_0^r \in L^2(\gamma_0, \mathrm{d}\sigma^{-1})$ and the following convergences hold true:

$$\|f_{\varepsilon}^r - f_0^r\|_{L^2(\omega_{\varepsilon}, \mathrm{d}m^{-1})} \to 0 \quad \text{and} \quad \|g_{\varepsilon}^r - g_0^r\|_{L^2(\gamma_{\varepsilon}, \mathrm{d}\sigma^{-1})} \to 0 \text{ as } \varepsilon \to 0^+.$$

Then, according to Lemma 6 and since f_{ε}^r and g_{ε}^r satisfy the compatibility condition for every $\varepsilon > 0$ (this follows from the fact that u_{ε}^s is smooth and $\int_{\omega_{\varepsilon}} g_{\varepsilon} \, \mathrm{d}s = 0$), we can pass to the limit in (4.2) to get:

$$\int_{\omega_0} f_0^r \,\mathrm{d}x + \int_{\gamma_0} g_0^r \,\mathrm{d}s = 0.$$

Consequently, for every $\varepsilon \ge 0$, u_{ε}^r is a solution (in the sense of Definition 1) of Problem (4.3) with the source terms $(f_{\varepsilon}^r, g_{\varepsilon}^r)$ given by (6.3). On the other hand, the properties of f_{ε}^r and g_{τ}^{ε} ensure, thanks to Theorem 3, that $u_0^r \in H_N^1(\omega_0, dm)$ and that

$$\|\nabla u_{\varepsilon}^r - \nabla u_0^r\|_{L^2(\omega_{\varepsilon})} = \|\nabla u_{\varepsilon} - \nabla (u_{\varepsilon}^s + u_0^r)\|_{L^2(\omega_{\varepsilon})} \to 0 \quad \text{as} \quad \varepsilon \to 0^+.$$

Considering the limit problem ($\varepsilon = 0$), this construction will provide a natural solution

$$u_0 = u_0^s + u_0^r,$$

which does not belong to $H^1(\omega_0, dm)$, leading to supplement Definition 1 with:

Definition 2 (Infinite energy solution) Let $u_0^r \in H_N^1(\omega_0, \mathrm{d}m)$ be a solution to System (1.8) (for $\varepsilon = 0$) with volume source term $f_0^r \in L^2(\omega_0, \mathrm{d}m^{-1})$ an boundary data $g_0^r \in L^2(\omega_0, \mathrm{d}\sigma^{-1})$ satisfying the compatibility condition

$$\int_{\omega_0} f_0^r dx + \int_{\gamma_0} g_0^r ds = 0.$$
 (6.4)

Let u_0^s be a smooth function, supported in R_0 (and extended by 0 in D) with infinite Dirichlet energy and such that $\mathbb{A}_0 \nabla u_0^s \cdot n = 0$ on $\partial \omega_0 \setminus \gamma_0$ and denote

$$f_0^s := -\operatorname{div}(\mathbb{A}_0 \nabla u_0^s) \text{ in } \omega_0 \quad and \quad g_0^s := \mathbb{A}_0 \nabla u_0^s \cdot n \text{ on } \gamma_0.$$

Then the function:

$$u_0 := u_0^s + u_0^r,$$

set in ω_0 is called an infinite energy solution to System (1.8) (for $\varepsilon = 0$) with volume source term $f_0 := f_0^r + f_0^s$ and boundary data $g_0 := g_0^r + g_0^s$.

Remark 7 The (smooth) function u_0^s is required to be supported in R_0 in order to ensure that the expression of the volume source term f_0^s makes sense. Indeed, the entries of the matrix \mathbb{A}_0 are only supposed to be continuous in D whereas they are C^1 in R_0 .

We can now give the expression of the ansatz u_{ε}^s : Let χ be a smooth cut-off function defined in ω_0 such that $\chi = 1$ in $]1, +\infty[\times]0, 1[$, χ is independent of x_2 in $]0, 1[\times]0, 1[$ and $\chi = 0$ in D. For every $\varepsilon \ge 0$, we define the function u_{ε}^s in ω_{ε} by setting:

$$u_{\varepsilon}^{s}(x) = \chi(x) \left[-\int_{0}^{x_{1}} \mu_{\varepsilon}(s) \,\mathrm{d}s + \frac{1}{2} x_{2}^{2} \left[H_{\varepsilon}(\mu_{\varepsilon}(x_{1})) - \mu_{\varepsilon}(x_{1}) H_{0}'(\mu_{\varepsilon}(x_{1})) \right] \right],\tag{6.5}$$

for every $x \in \omega_{\varepsilon}$. The following Lemma, the proof of which is given in Appendix B, asserts that the Dirichlet energy indeed blows up as ε goes to 0^+ :

Lemma 10 The Dirichlet energy of u_{ε}^{s} behaves as follows when $\varepsilon \to 0^{+}$:

$$\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^{s} \cdot \nabla u_{\varepsilon}^{s} \mathrm{d}x \underset{\varepsilon=0}{\sim} \begin{cases} \frac{1}{3} \kappa^{-1} |\ln(\varepsilon)| & \text{if } \alpha = 2\\ \frac{1}{3} \varepsilon^{\frac{3}{1+\alpha}-1} \kappa^{-\frac{3}{1+\alpha}} \frac{3\pi/(1+\alpha)}{\sin(3\pi/(1+\alpha))} & \text{if } \alpha > 2. \end{cases}$$
(6.6)

Theorem 5 When $\alpha \ge 2$, the following assertions hold true:

1. There exists a function $u_0^r \in H^1(\omega_0, \mathrm{d}m)$ such that

$$\|\nabla u_{\varepsilon} - \nabla (u_{\varepsilon}^{s} + u_{0}^{r})\|_{L^{2}(\omega_{\varepsilon})} \to 0 \qquad as \ \varepsilon \to 0^{+}.$$

- 2. The function $u_0 := u_0^s + u_0^r$ is an infinite energy solution to System (1.10) (with $\varepsilon = 0$), in the sense of Definition 2.
- 3. The Dirichlet energy of u_{ε} behaves as the Dirichlet energy of u_{ε}^{s} as $\varepsilon \to 0^{+}$.

Proof: For the sake of clarity, we provide a constructive proof to explain how to obtain the ansatz (6.5). Our method can be seen as an adaptation for every $\varepsilon \ge 0$ of the multiscale expansion method used in [15] in the case $\varepsilon = 0$.

First, recall that the system (1.8) under consideration reads:

$$-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla u_{\varepsilon}) = 0 \quad \text{in } \omega_{\varepsilon} \tag{6.7a}$$

$$\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot n = g_{\varepsilon} \quad \text{on } \gamma_{\varepsilon} \tag{6.7b}$$

$$\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot n = 0 \quad \text{on } \partial \omega_{\varepsilon} \setminus \gamma_{\varepsilon}, \tag{6.7c}$$

where we have set

$$g_{\varepsilon}(x) = D\Psi_{\varepsilon}^{-1}\tau \cdot e_1 = H_{\varepsilon}(X_{\varepsilon}^1), \qquad \qquad X_{\varepsilon}^1 := \mu_{\varepsilon}(x_1).$$

On the rectangle R_{ε} , we have:

$$-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla u_{\varepsilon})(x) = -\partial_{x_{1}^{2}}^{2}u_{\varepsilon}(x) + 2x_{2}H_{0}'(X_{1}^{\varepsilon})\partial_{x_{1}x_{2}}^{2}u_{\varepsilon}(x) - \left[1 + \left(x_{2}H_{0}'(X_{1}^{\varepsilon})\right)^{2}\right]\partial_{x_{2}^{2}}^{2}u_{\varepsilon}(x) + H_{0}'(\mu_{\varepsilon})\partial_{x_{1}}u_{\varepsilon} - x_{2}\left[2H_{0}'(X_{1}^{\varepsilon})^{2} + H_{0}''(X_{1}^{\varepsilon})H_{\varepsilon}(X_{1}^{\varepsilon})\right]\partial_{x_{2}}u_{\varepsilon}(x).$$
(6.8)

We seek an approximate solution to System (6.7) in R_{ε} in the form:

$$\hat{u}_{\varepsilon}^{s}(x) = v_{\varepsilon}(X_{1}^{\varepsilon}) + H_{\varepsilon}(X_{1}^{\varepsilon})V_{\varepsilon}(X_{1}^{\varepsilon}, x_{2}), \quad \forall x = (x_{1}, x_{2}) \in R_{\varepsilon},$$
(6.9)

the functions v_{ε} and V_{ε} being to be determined. With (6.8) we get:

$$-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla\hat{u}_{\varepsilon}^{s})(x) = -H_{\varepsilon}(X_{1}^{\varepsilon})\left[\partial_{x_{2}^{2}}^{2}V_{\varepsilon}(X_{1}^{\varepsilon}, x_{2}) + H_{\varepsilon}(X_{1}^{\varepsilon})v_{\varepsilon}''(X_{1}^{\varepsilon})\right] + \hat{f}_{\varepsilon}^{s}(x)$$
(6.10a)

where

$$\begin{aligned} \hat{f}_{\varepsilon}^{s}(x) &:= -H_{\varepsilon}(X_{1}^{\varepsilon}) \Big\{ H_{0}^{\prime\prime}(X_{1}^{\varepsilon}) H_{\varepsilon}(X_{1}^{\varepsilon}) V_{\varepsilon}(X_{1}^{\varepsilon}, x_{2}) + x_{2}^{2} H_{0}^{\prime}(X_{1}^{\varepsilon})^{2} \partial_{x_{2}^{2}}^{2} V_{\varepsilon}(X_{1}^{\varepsilon}, x_{2}) \\ &+ 2H_{0}^{\prime}(X_{1}^{\varepsilon}) H_{\varepsilon}(X_{1}^{\varepsilon}) [\partial_{x_{1}} V_{\varepsilon}(X_{1}^{\varepsilon}, x_{2}) - x_{2} \partial_{x_{1}x_{2}}^{2} V_{\varepsilon}(X_{1}^{\varepsilon}, x_{2})] \\ &- x_{2} H_{0}^{\prime\prime}(X_{1}^{\varepsilon}) H_{\varepsilon}(X_{1}^{\varepsilon}) \partial_{x_{2}} V_{\varepsilon}(X_{1}^{\varepsilon}, x_{2}) + H_{0}(X_{1}^{\varepsilon})^{2} \partial_{x_{1}^{2}}^{2} V_{\varepsilon}(X_{1}^{\varepsilon}, x_{2}) \Big\}. \quad (6.10b) \end{aligned}$$

On γ_{ε}^{R} , i.e. for $x = (x_{1}, 1), 0 < x_{1} < \ell_{\varepsilon}$ or equivalently $\delta < X_{1}^{\varepsilon} < 0$, we have:

$$\mathbb{A}_{\varepsilon}\nabla\hat{u}_{\varepsilon}^{s}\cdot n(x_{1},1) = H_{\varepsilon}(X_{1}^{\varepsilon})\left[-v_{\varepsilon}'(X_{1}^{\varepsilon})H_{0}'(X_{1}^{\varepsilon}) + \partial_{x_{2}}V_{\varepsilon}(X_{1}^{\varepsilon},1)\right] + \hat{r}_{\varepsilon}^{s}(x),$$
(6.10c)

where:

$$\hat{r}^{s}_{\varepsilon}(x) := H_{\varepsilon}(X_{1}^{\varepsilon}) \Big\{ H_{0}'(X_{1}^{\varepsilon})^{2} [\partial_{x_{2}} V_{\varepsilon}(X_{1}^{\varepsilon}, 1) - V_{\varepsilon}(X_{1}^{\varepsilon}, 1)] - H_{\varepsilon}(X_{1}^{\varepsilon}) H_{0}'(X_{1}^{\varepsilon}) \partial_{x_{1}} V_{\varepsilon}(X_{1}^{\varepsilon}, 1) \Big\}.$$

$$(6.10d)$$

On the lower boundary $\{(x_1, 0) : 0 < x_1 < \ell_{\varepsilon}\}$, we have:

$$\mathbb{A}_{\varepsilon} \nabla \hat{u}_{\varepsilon}^{s} \cdot n(x_{1}, 0) = H_{\varepsilon}(X_{1}^{\varepsilon}) \partial_{x_{2}} V_{\varepsilon}(X_{1}^{\varepsilon}, 0).$$
(6.10e)

Finally, on the vertical right boundary $\{(\ell_{\varepsilon}, x_2) : 0 < x_2 < 1\}$ we get:

$$\mathbb{A}_{\varepsilon} \nabla \hat{u}_{\varepsilon}^{s} \cdot n(\ell_{\varepsilon}, x_{2}) = \varepsilon [v_{\varepsilon}^{\prime}(0) + \varepsilon \partial_{x_{1}} V_{\varepsilon}(0, x_{2})].$$
(6.10f)

The function \hat{u}_{ε}^s is supposed to be an ansatz for u_{ε} , so in view of the expressions (6.10), we seek the functions v_{ε} and V_{ε} in order to cancel the "leading" (i.e. less decreasing) terms in (6.10a). We also want the Neumann boundary conditions for \hat{u}_{ε} to approximate "at best" the boundary conditions of u_{ε} . This leads to the following one dimensional Neumann system that must be satisfied for every fixed $\delta < X_1^{\varepsilon} < 0$:

$$-\partial_{x_2^2}^2 V_{\varepsilon}(X_1^{\varepsilon}, \cdot) = H_{\varepsilon}(X_1^{\varepsilon}) v_{\varepsilon}''(X_1^{\varepsilon}) \qquad \text{on }]0, 1[$$
(6.11a)

$$\partial_{x_2} V_{\varepsilon}(X_1^{\varepsilon}, 1) = 1 + v_{\varepsilon}'(X_1^{\varepsilon}) H_0'(X_1^{\varepsilon})$$
(6.11b)

$$\partial_{x_2} V_{\varepsilon}(X_1^{\varepsilon}, 0) = 0. \tag{6.11c}$$

The compatibility condition, necessary for this System to admit solutions, reads:

$$H_{\varepsilon}(X_1^{\varepsilon})v_{\varepsilon}''(X_1^{\varepsilon}) + 1 + v_{\varepsilon}'(X_1^{\varepsilon})H_0'(X_1^{\varepsilon}) = 0, \quad \delta < X_1^{\varepsilon} < 0.$$

It can been rewritten as:

$$\frac{d^2}{dx_1^2}(v_{\varepsilon}(\mu_{\varepsilon}(x_1))) = -\mu_{\varepsilon}'(x_1).$$

We choose as a solution to this EDO, the one which vanishes at $x_1 = 0$:

$$v_{\varepsilon}(\mu_{\varepsilon}(x_1)) = -\int_0^{x_1} \mu_{\varepsilon}(s) \,\mathrm{d}s.$$
(6.12)

We deduce that:

$$-H_{\varepsilon}(X_1^{\varepsilon})v_{\varepsilon}''(X_1^{\varepsilon}) = 1 + v_{\varepsilon}'(X_1^{\varepsilon})H_0'(X_1^{\varepsilon}) = \frac{H_{\varepsilon}(X_1^{\varepsilon}) - X_1^{\varepsilon}H_0'(X_1^{\varepsilon})}{H_{\varepsilon}(X_1^{\varepsilon})}$$

whence we infer the expression of V_{ε} :

$$V_{\varepsilon}(x_1, x_2) = \frac{1}{2} x_2^2 \left[\frac{H_{\varepsilon}(X_1^{\varepsilon}) - X_1^{\varepsilon} H_0'(X_1^{\varepsilon})}{H_{\varepsilon}(X_1^{\varepsilon})} \right],$$
(6.13)

and then the expression of $\hat{u}_{\varepsilon}^{s}$ in R_{ε} thanks to (6.9):

$$\hat{u}_{\varepsilon}^{s}(x_{1}, x_{2}) = -\int_{0}^{x_{1}} \mu_{\varepsilon}(s) \,\mathrm{d}s + \frac{1}{2}x_{2}^{2} \left[H_{\varepsilon}(X_{1}^{\varepsilon}) - X_{1}^{\varepsilon}H_{0}'(X_{1}^{\varepsilon})\right].$$
(6.14)

Reconsidering now the expressions (6.10a) and (6.10c), we have by construction $-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla\hat{u}_{\varepsilon}^{s}) = \hat{f}_{\varepsilon}^{s}$ in ω_{ε} , $\mathbb{A}_{\varepsilon}\nabla\hat{u}_{\varepsilon}^{s} \cdot n = \hat{r}_{\varepsilon}^{s} + g_{\varepsilon} := \hat{g}_{\varepsilon}^{s}$ on γ_{ε}^{R} and $\mathbb{A}_{\varepsilon}\nabla\hat{u}_{\varepsilon}^{s} \cdot n = 0$ on the lower and right boundaries of R_{ε} (according respectively to (6.10e) and (6.10f)). Recalling that χ is the cut-off function introduced above Lemma 10, we can define u_{ε}^{s} in the whole domain ω_{ε} by setting:

$$u_{\varepsilon}^{s}(x) := \chi(x)\hat{u}_{\varepsilon}^{s}(x), \qquad (x \in \omega_{\varepsilon}),$$

and we recover the announced expression (6.5).

It remains to verify now that u_{ε}^{s} indeed carries the "singular" part of u_{ε} . Straightforward computation leads to:

$$\begin{aligned} -\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla u_{\varepsilon}^{s}) &= f_{\varepsilon}^{s} \quad \text{in } \omega_{\varepsilon} \\ \mathbb{A}_{\varepsilon}\nabla u_{\varepsilon}^{s} \cdot n &= g_{\varepsilon}^{s} \quad \text{on } \gamma_{\varepsilon} \\ \mathbb{A}_{\varepsilon}\nabla u_{\varepsilon}^{s} \cdot n &= 0 \quad \text{on } \partial\omega_{\varepsilon} \setminus \gamma_{\varepsilon} \end{aligned}$$

where:

$$\begin{aligned} f_{\varepsilon}^{s} &= \left[-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla\chi)\hat{u}_{\varepsilon}^{s} - 2\mathbb{A}_{\varepsilon} : (\nabla\chi\otimes\nabla\hat{u}_{\varepsilon}^{s}) \right] + \chi\hat{f}_{\varepsilon}^{s} \quad \text{in } \omega_{\varepsilon} \\ g_{\varepsilon}^{s} &= \left[\hat{u}_{\varepsilon}^{s}(\mathbb{A}_{\varepsilon}\nabla\chi) \cdot n\right] + \chi\hat{g}_{\varepsilon}^{s} \qquad \text{on } \gamma_{\varepsilon}. \end{aligned}$$
(6.15a)

The function $u_{\varepsilon}^r := u_{\varepsilon} - u_{\varepsilon}^s$ satisfies:

$$-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla u_{\varepsilon}^{r}) = f_{\varepsilon}^{r} \quad \text{in } \omega_{\varepsilon}$$

$$(6.16a)$$

$$\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^{r} \cdot n = g_{\varepsilon}^{r} \quad \text{on } \gamma_{\varepsilon} \tag{6.16b}$$

$$\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^{r} \cdot n = 0 \quad \text{on } \partial \omega_{\varepsilon} \setminus \gamma_{\varepsilon}, \tag{6.16c}$$

where:

$$f_{\varepsilon}^{r} = -f_{\varepsilon}^{s} \text{ in } \omega_{\varepsilon} \quad \text{and} \quad g_{\varepsilon}^{r} = g_{\varepsilon} - g_{\varepsilon}^{s} \text{ on } \gamma_{\varepsilon}.$$
 (6.17)

For every $\varepsilon > 0$ the functions f_{ε}^s and g_{ε}^s satisfy the compatibility condition (they are defined as being respectively the divergence and the flux across the boundary of the smooth vector field $\mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^s$). Moreover, $\int_{\gamma_{\varepsilon}} g_{\varepsilon} \, \mathrm{d}s = 0$ for every $\varepsilon \ge 0$. We deduce that f_{ε}^r and g_{ε}^r satisfy the compatibility condition as well (for every $\varepsilon > 0$).

The following Lemma ensures that the ansatz function u_{ε}^{s} does the job it has be designed for:

Lemma 11 The function f_0^r belongs to $L^2(\omega_0, \mathrm{d}m^{-1})$, the function g_0^r belongs to $L^2(\gamma_0, \mathrm{d}\sigma^{-1})$ and they satisfy the compatibility condition (6.4). Moreover, we have the following convergence results:

$$\|f_{\varepsilon}^{r} - f_{0}^{r}\|_{L^{2}(\omega_{\varepsilon}, \mathrm{d}m^{-1})} \to 0 \quad and \quad \|g_{\varepsilon}^{r} - g_{0}^{r}\|_{L^{2}(\gamma_{\varepsilon}, \mathrm{d}\sigma^{-1})} \to 0 \ as \ \varepsilon \to 0^{+}.$$
(6.18)

The proof is postponed to Appendix B.

To complete the proof of the two firsts points of the theorem, it suffices now to apply Theorem 3. Finally, the last remaining point results from the second triangular inequality:

$$\left| \left(\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon} \cdot \nabla u_{\varepsilon} \, \mathrm{d}x \right)^{\frac{1}{2}} - \left(\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^{s} \cdot \nabla u_{\varepsilon}^{s} \, \mathrm{d}x \right)^{\frac{1}{2}} \right| \leqslant \left(\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^{r} \cdot \nabla u_{\varepsilon}^{r} \, \mathrm{d}x \right)^{\frac{1}{2}},$$

together with Lemma 10 and again Theorem 3. The proof of the theorem is now complete.

7 Back to miscellaneous cases of Section 2

In Section 2 we state some results allowing comparing the Dirichlet energy for different configurations, some of them being not covered by our general study. We show in this Section that the method used to determine the asymptotic of the Dirichlet energy in the previous Section can be adapted to the case where the bottom of the solid is locally flat (referred to as "the flat case" in the sequel).

7.1 The flat case

We shall now focus on the cases depicted on the left of Fig. 6, i.e. where the bottom of the solid is locally flat. Being more specific, we consider the case where the function H_{ε} has the following expression (hereafter, in addition to the already defined constants, δ' is a negative number such that $\delta < \delta' < 0$):

$$H_{\varepsilon}(\xi_1) = \begin{cases} \hat{H}_{\varepsilon}(\xi_1 - \delta') & \text{if } \delta \leqslant \xi_1 < \delta' \\ \varepsilon & \text{if } \delta' \leqslant \xi_1 < 0, \end{cases}$$

where $\hat{H}_{\varepsilon}(\xi_1) := \kappa |\xi_1|^{1+\alpha} + \varepsilon$ with $\alpha > 2$. Denoting $\hat{\delta} := \delta - \delta' < 0$, we can define, associated with \hat{H}_{ε} and $\hat{\delta}$, the functions $\hat{\rho}_{\varepsilon}$, $\hat{\mu}_{\varepsilon}$, $\hat{\Psi}_{\varepsilon}$ and $\hat{\Psi}_{\varepsilon}^{-1}$ based on formula (3.3), (3.6), (3.2) and (3.8). We will also need the constant $\hat{\ell}_{\varepsilon} := \lim_{\xi_1 \to 0^+} \hat{\rho}_{\varepsilon}(\xi_1)$. Observe now that, corresponding to H_{ε} and using the very same formula as above, we get:

$$\rho_{\varepsilon}(\xi_1) = \begin{cases} \hat{\rho}_{\varepsilon}(\xi_1 - \delta') & \text{if } \delta \leqslant \xi_1 < \delta' \\ \frac{1}{\varepsilon}(\xi_1 - \delta') + \hat{\ell}_{\varepsilon} & \text{if } \delta' \leqslant \xi_1 < 0, \end{cases}$$

with $\ell_{\varepsilon} := \rho_{\varepsilon}(0) = \hat{\ell}_{\varepsilon} - \frac{\delta'}{\varepsilon} \ (\ell_0 = +\infty)$. Notice that the function $\rho_{\varepsilon=0}$ is only defined for $\delta \leq \xi_1 < \delta'$. For $\varepsilon \geq 0$, the inverse of ρ_{ε} defined on $[0, \ell_{\varepsilon}]$ reads:

$$\mu_{\varepsilon}(x_1) = \begin{cases} \hat{\mu}_{\varepsilon}(x_1) + \delta' & \text{if } 0 \leqslant x_1 < \hat{\ell}_{\varepsilon} \\ \varepsilon(x_1 - \hat{\ell}_{\varepsilon}) + \delta' & \text{if } \hat{\ell}_{\varepsilon} \leqslant x_1 < \ell_{\varepsilon}. \end{cases}$$

We deduce that, for every $\varepsilon \ge 0$:

$$H_{\varepsilon}(\mu_{\varepsilon}(x_{1})) = \begin{cases} \hat{H}_{\varepsilon}(\hat{\mu}_{\varepsilon}(x_{1})) & \text{if } 0 \leqslant x_{1} < \hat{\ell}_{\varepsilon} \\ \varepsilon & \text{if } \hat{\ell}_{\varepsilon} \leqslant x_{1} < \ell_{\varepsilon}, \end{cases} \quad \text{and} \quad H_{\varepsilon}^{(k)}(\mu_{\varepsilon}(x_{1})) = \begin{cases} \hat{H}_{\varepsilon}^{(k)}(\hat{\mu}_{\varepsilon}(x_{1})) & \text{if } 0 \leqslant x_{1} < \hat{\ell}_{\varepsilon} \\ 0 & \text{if } \hat{\ell}_{\varepsilon} \leqslant x_{1} < \ell_{\varepsilon}, \end{cases}$$
(7.1)

where $k \ge 1$ stands for the derivative of order k (if well defined). On the rectangle R_{ε} , we get:

$$\Psi_{\varepsilon}^{-1} = \hat{\Psi}_{\varepsilon}^{-1} + \begin{pmatrix} \delta' \\ 0 \end{pmatrix} \text{ in } \hat{R}_{\varepsilon} =]0, \hat{\ell}_{\varepsilon}[\times]0, 1[\text{ and } \Psi_{\varepsilon}^{-1}(x) = \varepsilon \begin{pmatrix} x_1 - \hat{\ell}_{\varepsilon} \\ x_2 \end{pmatrix} + \begin{pmatrix} \delta' \\ 0 \end{pmatrix} \text{ in } [\hat{\ell}_{\varepsilon}, \ell_{\varepsilon}[\times]0, 1[.$$

According to formula (1.9), we deduce that:

$$\mathbb{A}_{\varepsilon} = \begin{cases} \hat{\mathbb{A}}_{\varepsilon} & \text{in } \hat{R}_{\varepsilon} :=]0, \hat{\ell}_{\varepsilon}[\times]0, 1[\\ \varepsilon \text{Id} & \text{in } [\hat{\ell}_{\varepsilon}, \ell_{\varepsilon}[\times]0, 1[. \end{cases}$$
(7.2)

Notice once more that $\hat{R}_{\varepsilon=0} = R_{\varepsilon=0} =]0, +\infty[\times]0, 1[$. Considering (7.2), we deduce that the conclusions of Lemma 3 still holds true. This convergence results is required in Theorem 3, while all the results of Section 4 are completely independent of the change of variables. We can now jump directly to the computation of the ansatz function. The general expression (6.5) leads to, in our case:

$$u_{\varepsilon}^{s}(x) = \begin{cases} \hat{u}_{\varepsilon}^{s}(x) - \delta'\chi(x) \left[x_{1} + \frac{1}{2}x_{2}^{2}\hat{H}_{0}'(\hat{\mu}_{\varepsilon}(x_{1})) \right] & \text{if } x \in \hat{\omega}_{\varepsilon} \\ -\int_{0}^{\hat{\ell}_{\varepsilon}} \hat{\mu}_{\varepsilon}(s) \,\mathrm{d}s + \frac{\varepsilon}{2}(x_{2}^{2} - x_{1}^{2} + 2x_{1}\ell_{\varepsilon} - \hat{\ell}_{\varepsilon}^{2}) & \text{if } x \in [\hat{\ell}_{\varepsilon}, \ell_{\varepsilon}[\times]0, 1[, \infty]) \end{cases}$$

where $\hat{u}_{\varepsilon}^{s}$ is the ansatz for the problem corresponding to \hat{H}_{ε} and χ the cut-off function defined above identity (6.5). The mirror image of Lemma 10 is

Lemma 12 The Dirichlet energy of u_{ε}^{s} behaves as follows when $\varepsilon \to 0^{+}$:

$$\int_{\omega_{\varepsilon}} \mathbb{A}_{\varepsilon} \nabla u_{\varepsilon}^s \cdot \nabla u_{\varepsilon}^s \, \mathrm{d} x \underset{\varepsilon=0}{\sim} \frac{|\delta'|^3}{3} \varepsilon^{-1}.$$

Unlike the other cases, neither κ nor α appear in the expression of the leading term in the asymptotic expansion of the energy. They would probably play a role in lower order terms only. This observation lead us to think that the technical condition $\alpha > 2$ have to be understood as a regularity assumption for the solid's boundary and is not related with the "strength" of the cusp of the fluid domain when $\varepsilon = 0$.

We can now claim:

Proposition 6 Theorem 5 is true for the flat case. In particular, the Dirichlet energy behaves as follows when ε goes to 0:

$$E_{\varepsilon} \underset{\varepsilon=0}{\sim} \frac{|\delta'|^3}{3} \varepsilon^{-1}.$$
(7.3)

Proof: It suffices to verify that Lemma 11 and more precisely that the expressions (B.5) are in the appropriate function spaces. There is a subtlety here because the decay properties (3.10) are not true in our case. However, with (7.1) and (B.5) and since there is at least one derivative of H_0 in every product arising in the right hand side of the expressions (B.5), it can be verify that we still get enough decay rate to get the conclusion.

Considering the problem of collision, we can apply Lemma 1 to get:

Proposition 7 In the flat case, the solid reaches the cavity's bottom in finite time with null velocity (smooth landing case).

7.2 Other cases

Combining (7.3) with the results of Section 2, we can easily deduce the following:

- In the situation depicted in the right of Fig. 6, the solid will collide with the outer boundary in finite time with null velocity (smooth landing case).
- In both configurations in the right of Fig.7, the solid will behave the same way when approaching the outer boundary and reach it in finite time. It is not possible (without further computations) to determine wether the velocity is null or not at the touching time.

A Construction of the change of variables

In this Section, we aim to construct the diffeomorphisms Ψ_{ε} ($0 \leq \varepsilon \leq \varepsilon^*$) earlier introduced in Section 3.

Recall the definitions (3.1) of $\mathcal{V}_{\varepsilon}$ ($0 \leq \varepsilon \leq \varepsilon^*$). Since we need to emphasize the dependance in δ , we denote it rather $\mathcal{V}_{\varepsilon}(\delta)$ in this Section and we recall that Ψ_{ε} has already been defined in $\mathcal{V}_{\varepsilon}(\delta)$ in Section 3.

To simplify the construction, there is no loss of generality in assuming that (up to a rescaling) $H_0(\delta) = 1$. Let us define $\hat{\Psi}_{\varepsilon} := \Psi_{\varepsilon} + \delta e_1$ and notice that, on the left vertical boundary of $\mathcal{V}_{\varepsilon}(\delta)$, we have:

$$\hat{\Psi}((\delta,\xi_2)) = \left(\delta,\frac{\xi_2}{1+\varepsilon}\right), \qquad (0 < \xi_2 < 1+\varepsilon).$$

Starting from this observation, our leading idea is to extend $\hat{\Psi}_{\varepsilon}$ (rather than Ψ_{ε}) as a perturbation of the identity in $\Omega_{\varepsilon} \setminus \overline{\mathcal{V}}_{\varepsilon}(\delta)$. We proceed in several steps.

First step. We introduce an open cover $(U_k)_{1 \le k \le 3}$ of Ω_{ε} (see Figure 9), such that:

- 1. $\Omega_{\varepsilon} \subset U_1 \cup U_2 \cup U_3$ for every $\varepsilon \ge 0$ small enough;
- 2. There exists $\delta'' < \delta' < \delta$ such that:

$$\mathcal{V}_{\varepsilon}(\delta') \subset U_1 \subset \mathcal{V}_{\varepsilon}(\delta'')$$
 and $U_k \cap \mathcal{V}_{\varepsilon}(\delta') = \varnothing$ $(k = 2, 3),$

for every $\varepsilon \ge 0$ small enough;

3. $\Gamma_{\varepsilon} \cap U_3 = \emptyset$ for every $\varepsilon \ge 0$ small enough.

Consider $(\chi_k)_{1 \leq k \leq 3}$ a partition of unity subordinated to the open cover U_k (k = 1, 2, 3) and let us define $\hat{\Psi}^k_{\varepsilon}$ (k = 1, 2, 3) three functions respectively defined in U_1 , U_2 and U_3 and out of which we are going to build $\hat{\Psi}_{\varepsilon}$.



Figure 9: The open cover $(U_k)_{1 \leq k \leq 3}$ of Ω_{ε} (for $\varepsilon > 0$ and $\varepsilon = 0$).

Step 2. (Construction of $\hat{\Psi}_{\varepsilon}^1$). For every $\varepsilon \ge 0$, we define the function

$$\hat{\rho}_{\varepsilon}(\xi_1) = \delta + \int_{\delta}^{\xi_1} F_{\varepsilon}(t) \,\mathrm{d}t \qquad (\delta'' < \xi_1 < 0), \tag{A.1a}$$

where the function $F_{\varepsilon} \in C^0([\delta'', 0[)$ is given by:

$$F_{\varepsilon}(t) = \begin{cases} 1 & \text{if } \xi_1 < \delta' \\ \frac{\varepsilon}{1+\varepsilon} \left(a \, t^2 + b \, t + c \right) + 1 & \text{if } \delta' < \xi_1 \leqslant \delta \\ H_{\varepsilon}(t)^{-1} & \text{if } \xi_1 > \delta, \end{cases}$$
(A.1b)

with

$$a = -\frac{3}{\left(\delta - \delta'\right)^2}, \quad b = \frac{2\left(\delta + 2\,\delta'\right)}{\left(\delta - \delta'\right)^2}, \quad c = -\frac{\delta'(2\delta + \delta')}{\left(\delta - \delta'\right)^2}.$$
(A.1c)

We set $\hat{\ell}_{\varepsilon} := \hat{\rho}_{\varepsilon}(0)$ ($\varepsilon > 0$) and $\hat{\ell}_0 := +\infty$.

For $\varepsilon \ge 0$ small enough, F_{ε} is positive and we denote $\hat{\mu}_{\varepsilon} :]\delta'', \hat{\ell}_{\varepsilon}[\rightarrow]\delta'', 0[$ the inverse of $\hat{\rho}_{\varepsilon}$. Define now a C^1 function \hat{H} on $]\delta'', 0]$, as on Figure 10, satisfying in particular:

$$\hat{H}_0(\xi_1) = \begin{cases} H_0(\xi_1) & \text{if } \xi_1 > \delta \\ 1 & \text{if } \xi_1 < \delta'. \end{cases}$$



Figure 10: Graph of the functions $\hat{\rho}_{\varepsilon}$ (left) and \hat{H}_0 (right).

The function $\hat{\Psi}^1_{\varepsilon}$ is defined on $\mathcal{V}_{\varepsilon}(\delta'')$ as follows:

$$\Psi_{\varepsilon}^{1}(\xi) = \begin{pmatrix} \hat{\rho}_{\varepsilon}(\xi_{1}) \\ \kappa_{\varepsilon}(\xi)\xi_{2} - \varepsilon\chi_{2}(\xi) \end{pmatrix}$$
(A.2a)

where

$$\kappa_{\varepsilon}(\xi) = \frac{H_0(\hat{\rho}_{\varepsilon}(\xi_1)) + \varepsilon \chi_2(\xi)}{H_{\varepsilon}(\xi_1)}.$$
(A.2b)

Step 3. We introduce $\hat{\Psi}_{\varepsilon}^2 = \mathrm{Id} - \varepsilon e_2$ and $\hat{\Psi}_{\varepsilon}^3 = \mathrm{Id} \ (\varepsilon \ge 0)$ and we claim that the function $\hat{\Psi}_{\varepsilon}$ defined by:

$$\hat{\Psi}_{\varepsilon} := \sum_{k=1}^{3} \chi_k \hat{\Psi}_{\varepsilon}^k,$$

fulfilled the requirements. More precisely, setting $\Psi_{\varepsilon} = \hat{\Psi}_{\varepsilon} - \delta e_1$ ($\varepsilon \ge 0$), we have:

Proposition 8 The function Ψ_{ε} enjoys the following properties:

- 1. For every $\varepsilon \ge 0$, the set $D := \Psi_{\varepsilon}(\Omega_{\varepsilon} \setminus \overline{\mathcal{V}}_{\varepsilon}(\delta))$ is independent of ε .
- 2. For every $\varepsilon \ge 0$, Ψ_{ε} is C^1 , invertible and Ψ_{ε}^{-1} is C^1 .
- 3. $\|\Psi_{\varepsilon}^{-1} \Psi_0^{-1}\|_{C^1(\overline{D})} \to 0 \text{ as } \varepsilon \to 0^+.$

Proof: Since $\hat{\Psi}_{\varepsilon}$ and Ψ_{ε} only differ in a translation, the proof is carried out with $\hat{\Psi}_{\varepsilon}$ instead of Ψ_{ε} .

The first point is easily verified by computing the image of the boundary of $\Omega_{\varepsilon} \setminus \overline{\mathcal{V}}_{\varepsilon}(\delta)$. Indeed, denoting

$$\hat{\mathcal{V}}_{\varepsilon} := \{ (x_1, x_2) \in \Omega_{\varepsilon} : \delta'' < x_1 < \delta, \, 0 < \xi_2 < H_{\varepsilon}(\xi_1) \},\$$

we have:

$$\begin{split} \hat{\Psi}_{\varepsilon}(\Gamma_{\varepsilon} \cap \hat{\mathcal{V}}_{\varepsilon}) &= \{ x = (x_1, x_2) \in \mathbb{R}^2 \, : \, \delta'' < \, x_1 < \delta, \, x_2 = \hat{H}_0(x_1) \} \\ \hat{\Psi}_{\varepsilon}(\Gamma_{\varepsilon} \cap U_2) &= \Gamma \cap U_2 \\ \hat{\Psi}_{\varepsilon}(\Gamma'_{\varepsilon} \cap (U_3 \cup \hat{\mathcal{V}}_{\varepsilon})) &= \Gamma' \cap (U_3 \cup \hat{\mathcal{V}}_{\varepsilon}). \end{split}$$

For the second and third points of the Proposition, we proceed as follows:

a We prove that $\hat{\Psi}_{\varepsilon} : \mathcal{V}_{\varepsilon}(\delta') \mapsto R'_{\varepsilon}$, where:

$$R'_{\varepsilon} := \{ (x_1, x_2) \in \mathbb{R}^2 : \delta' < x_1 < \ell_{\varepsilon}, \ 0 < x_2 < \hat{H}_0(x_1) \},\$$

is a C^1 diffeomorphism by studying its inverse, which can be made explicit. With the expression of this inverse, we also prove rather easily that $\|\hat{\Psi}_{\varepsilon}^{-1} - \hat{\Psi}_{0}^{-1}\|_{C^1(\overline{R}'_{\varepsilon})} \to 0$ as $\varepsilon \to 0^+$.

- b By noticing that $\hat{\Psi}_{\varepsilon}$ is a C^1 , ε -perturbation of the identity in $\Omega_{\varepsilon} \setminus \mathcal{V}_{\varepsilon}(\delta')$, we prove that $\hat{\Psi}_{\varepsilon}$ is also a C^1 diffeomorphism from $\Omega_{\varepsilon} \setminus \mathcal{V}_{\varepsilon}(\delta')$ onto its image and that $\|\hat{\Psi}_{\varepsilon}^{-1} \hat{\Psi}_{0}^{-1}\|_{C^{1}(\overline{\Psi_{\varepsilon}(\Omega_{\varepsilon}\setminus\mathcal{V}_{\varepsilon}(\delta'))})} \to 0$ as $\varepsilon \to 0^{+}$.
- c We get the conclusion of the Proposition by remarking that

$$\det D\hat{\Psi}_{\varepsilon} \neq 0 \quad \text{in } \Omega_{\varepsilon}, \tag{A.3}$$

and

$$\hat{\Psi}_{\varepsilon}(\mathcal{V}_{\varepsilon}(\delta')) \cap \hat{\Psi}_{\varepsilon}(\Omega_{\varepsilon} \setminus \mathcal{V}_{\varepsilon}(\delta')) = \emptyset.$$
(A.4)

The inverse of $\hat{\Psi}_{\varepsilon}$ in $\mathcal{V}_{\varepsilon}(\delta')$ is:

$$\hat{\Psi}_{\varepsilon}^{-1}(x) = \begin{pmatrix} \hat{\mu}_{\varepsilon}(x_1) \\ \frac{H_{\varepsilon}(\hat{\mu}_{\varepsilon}(x_1))}{\hat{H}_0(x_1)} x_2 \end{pmatrix}.$$
(A.5)

Following the lines of the proof of Proposition 5, we verify that $\hat{\Psi}_{\varepsilon} : \mathcal{V}_{\varepsilon}(\delta') \mapsto R'_{\varepsilon}$ is indeed a C^1 diffeomorphism and that $\|\hat{\Psi}_{\varepsilon}^{-1} - \hat{\Psi}_{0}^{-1}\|_{C^1(\overline{R}'_{\varepsilon})} \to 0$ as $\varepsilon \to 0^+$.

Let us denote now $\mathcal{U}_{\varepsilon} := \Omega_{\varepsilon} \setminus \mathcal{V}_{\varepsilon}(\delta')$. With our construction, we get, for every $\xi \in \mathcal{U}_{\varepsilon}$:

$$\hat{\Psi}_{\varepsilon}(\xi) = \xi + \varepsilon F_{\varepsilon}(\xi), \tag{A.6}$$

where:

$$F_{\varepsilon}(\xi) := \left[\chi_1(\xi) \frac{\chi_2(\xi) - 1}{H_{\varepsilon}(\xi_1)} \xi_2 - \chi_2(\xi) - \chi_1(\xi) \chi_2(\xi) \right]$$

Since F_{ε} is lipschitz continuous uniformly in ε for every ε small enough, we deduce that $\hat{\Psi}_{\varepsilon}$ is one-to-one in $\mathcal{U}_{\varepsilon}$ for every ε small enough. Finally $\hat{\Psi}_{\varepsilon}$ is a bijection from $\mathcal{U}_{\varepsilon}$ onto its image. From expression (A.6), according to the local inversion theorem, we get that $\hat{\Psi}_{\varepsilon}^{-1}$ is also C^1 . Using once again (A.6), it is clear that $\|\hat{\Psi}_{\varepsilon} - \hat{\Psi}_0\|_{C^1(\overline{\mathcal{U}}_{\varepsilon})} \to 0$ as $\varepsilon \to 0^+$ with $\hat{\Psi}_0 = \text{Id}$.

It remains to address the convergence of $\hat{\Psi}_{\varepsilon}^{-1}$ into $\hat{\Psi}_{0}^{-1} = \text{Id in } \hat{\Psi}(\overline{\mathcal{U}}_{\varepsilon})$. On the one hand, we have:

$$\|\hat{\Psi}_{\varepsilon}^{-1} - \mathrm{Id}\|_{L^{\infty}(\hat{\Psi}_{\varepsilon}(\overline{\mathcal{U}}_{\varepsilon}))} = \|\hat{\Psi}_{\varepsilon} - \mathrm{Id}\|_{L^{\infty}(\overline{\mathcal{U}}_{\varepsilon})} = \varepsilon \|F_{\varepsilon}\|_{L^{\infty}(\overline{\mathcal{U}}_{\varepsilon})}.$$
(A.7)

On the other hand, we have:

$$D\hat{\Psi}_{\varepsilon}(\xi) = \mathrm{Id} + \varepsilon DF_{\varepsilon}(\xi) \tag{A.8}$$

and thus, since DF_{ε} is clearly uniformly bounded with respect to ε in $L^{\infty}(\overline{\mathcal{U}}_{\varepsilon})$ by some constant C, its inverse is given via the Neumann series

$$(D\hat{\Psi}_{\varepsilon}(\xi))^{-1} = \mathrm{Id} + \varepsilon G_{\varepsilon}(\xi),$$

with

$$G_{\varepsilon}(\xi) = -\sum_{k=0}^{+\infty} (-\varepsilon)^k DF_{\varepsilon}(\xi)^{k+1}$$

provided ε is small enough, or more precisely for $\|\varepsilon DF_{\varepsilon}\|_{L^{\infty}(\overline{\mathcal{U}}_{\varepsilon})} < 1$. For such ε , we can write that:

$$\begin{split} \|D\hat{\Psi}_{\varepsilon}^{-1} - \mathrm{Id}\|_{L^{\infty}(\hat{\Psi}_{\varepsilon}(\overline{\mathcal{U}}_{\varepsilon}))} &= \|(D\hat{\Psi}_{\varepsilon} \circ \hat{\Psi}_{\varepsilon}^{-1})^{-1} - \mathrm{Id}\|_{L^{\infty}(\hat{\Psi}_{\varepsilon}(\overline{\mathcal{U}}_{\varepsilon}))} \\ &= \|(D\hat{\Psi}_{\varepsilon})^{-1} - \mathrm{Id}\|_{L^{\infty}(\overline{\mathcal{U}}_{\varepsilon})} \\ &= \varepsilon \|G_{\varepsilon}\|_{L^{\infty}(\overline{\mathcal{U}}_{\varepsilon})} \\ &\leq \varepsilon \|DF_{\varepsilon}\|_{L^{\infty}(\overline{\mathcal{U}}_{\varepsilon})} \\ &\leqslant C\varepsilon. \end{split}$$
(A.9)

Gathering the estimates (A.7) and (A.9), we finally get:

$$\|\hat{\Psi}_{\varepsilon}^{-1} - \hat{\Psi}_{0}^{-1}\|_{C^{1}(\hat{\Psi}_{\varepsilon}(\overline{\mathcal{U}}_{\varepsilon}))} \to 0 \text{ as } \varepsilon \to 0^{+}.$$

We prove (A.3) by direct computation, using (A.5) for $\xi \in \mathcal{V}_{\varepsilon}(\delta')$ and (A.8) for $\xi \in \Omega_{\varepsilon} \setminus \mathcal{V}_{\varepsilon}(\delta')$. Notice in particular that (A.8) remains true "up to the boundary" between $\mathcal{V}_{\varepsilon}(\delta')$ and $\Omega_{\varepsilon} \setminus \mathcal{V}_{\varepsilon}(\delta')$. The non-overlapping property (A.4) is easily verified and the proof is now complete.

B Proofs of technical results

Proof of Lemma 2: One easily checks that the function $F_{\varepsilon} := \mu_{\varepsilon} - \mu_0$ is positive on $[0, \ell_{\varepsilon}]$, which leads to:

$$|\mu_{\varepsilon}| \leqslant |\mu_0|,$$

and (3.10a) follows from (3.7). Moreover, we have $F'_{\varepsilon} = H_0(\mu_0)[G_{\varepsilon} - 1]$ where

$$G_{\varepsilon} := \frac{H_{\varepsilon}(\mu_{\varepsilon})}{H_0(\mu_0)}$$

Straightforward computations lead to:

$$G'_{\varepsilon} = G_{\varepsilon}[H'_0(\mu_{\varepsilon}) - H'_0(\mu_0)],$$

which is a positive function on $[0, \ell_{\varepsilon}]$. Since $G_{\varepsilon}(0) = 1 + \varepsilon/H_0(\delta) > 1$, we deduce that $F'_{\varepsilon} > 0$ and then that:

$$\|\mu_{\varepsilon} - \mu_0\|_{C^0([0,\ell_{\varepsilon}])} = -\mu_0(\ell_{\varepsilon}),$$

and (3.9) follows with (3.7) and (3.4).

Still from (3.7) and (3.4), we infer that:

$$G_{\varepsilon}(\ell_{\varepsilon}) \underset{\varepsilon=0}{\sim} \left[\alpha \frac{\pi/(\alpha+1)}{\sin(\pi/(\alpha+1))} \right]^{1+\frac{1}{\alpha}},$$

whence we deduce that, on $[0, \ell_{\varepsilon}]$, we have:

$$|H_{\varepsilon}(\mu_{\varepsilon})| \leqslant CH_0(\mu_0)$$

for some constant C > 0 dependent on α only. Combining this estimate again with (3.7) and (3.4), we get (3.10b).

Finally, since $|\mu_{\varepsilon}| \leq |\mu_0|$, we have

$$|H_0'(\mu_{\varepsilon})| \leqslant |H_0'(\mu_0)|,$$

and (3.10c) follows, using (3.7) and (3.4). The proof is now complete.

Proof of Lemma 1: Let us recall that the Cauchy problem (1.5) we are dealing with can be rewritten as:

$$\varepsilon'(t) = \varepsilon'_0 F(\varepsilon(t), \varepsilon^*), \quad t > 0$$
 (B.1a)

$$\varepsilon(t)|_{t=0} = \varepsilon^*,$$
 (B.1b)

with

$$F(\varepsilon, \varepsilon^*) := \sqrt{\frac{m_s + m_f(\varepsilon^*)}{m_s + m_f(\varepsilon)}}$$

and $\varepsilon^* > 0$ and $\varepsilon'_0 < 0$ are given. As already mentioned, it is proved in [4] that the function

 $\varepsilon \in]0, \varepsilon^*[\mapsto m_f(\varepsilon) \in \mathbb{R}^+$

is analytic and hence the function $F(\cdot, \varepsilon^*)$: $]0, \varepsilon^*[\to \mathbb{R}^+$ has the same regularity.

The hypothesis $E_{\varepsilon} \to +\infty$ as $\varepsilon \to 0^+$ entails that $F(\cdot, \varepsilon^*) \to 0$ as $\varepsilon \to 0^+$ and therefore that the velocity of the solid tends to 0 when approaching the outer boundary: real shock can not occur in this case.

The hypothesis $E_{\varepsilon} = O(\varepsilon^{-\beta})$ means that there exists $0 < \varepsilon^{\dagger} < \varepsilon^*$ and C > 0 such that

$$E_{\varepsilon} < C\varepsilon^{-\beta} \quad (0 < \varepsilon < \varepsilon^{\dagger})$$

This estimate entails that, for a different positive constant still denoted by C:

$$F(\varepsilon,\varepsilon^*) > C\varepsilon^{\frac{\beta}{2}} \quad (0 < \varepsilon < \varepsilon^{\dagger}). \tag{B.2}$$

On the other hand, the function $F(\cdot, \varepsilon^*)$ is bounded from below on the compact $[\varepsilon^{\dagger}, \varepsilon^*]$ by some constant c > 0. We deduce that $\varepsilon'(t) < c\varepsilon'_0$ as long as $\varepsilon(t) > \varepsilon^{\dagger}$. To simplify, let us relabel t = 0 the time for which $\varepsilon(t) = \varepsilon^{\dagger}$ (this time being no greater than $\varepsilon_{\eta}/(c\varepsilon'_0)$).

Using now the estimate (B.2) in the Cauchy problem, now restated as:

$$\begin{split} \varepsilon'(t) &= \varepsilon'_0 F(\varepsilon(t), \varepsilon^*), \quad t > 0 \\ \varepsilon(t)|_{t=0} &= \varepsilon^{\dagger}, \end{split}$$

we deduce that (changing again the value of the positive constant C):

$$\varepsilon(t) \leqslant \left[C\varepsilon'_0 t + (\varepsilon^{\dagger})^{-\frac{\beta}{2}+1}\right]^{\frac{2}{2-\beta}}$$

and therefore, the solid meets the cavity's wall in finite time.

Proof of Lemma 10: The Dirichlet energy of u_{ε}^{s} is decomposed as follows:

$$\int_{\omega_{\varepsilon}} |\nabla u_{\varepsilon}^{s}(x)|^{2} \,\mathrm{d}x = \int_{\omega_{\varepsilon} \setminus]1, \ell_{\varepsilon}[\times]0,1[} |\nabla u_{\varepsilon}^{s}(x)|^{2} \,\mathrm{d}x + \int_{1}^{\ell_{\varepsilon}} \int_{0}^{1} |\nabla u_{\varepsilon}^{s}(x_{1},x_{2})|^{2} \,\mathrm{d}x_{2} \,\mathrm{d}x_{1}.$$

The first integral in the right hand side is uniformly bounded for $\varepsilon \ge 0$, so let us focus on the latter.

In $]1, \ell_{\varepsilon}[\times]0, 1[$, we have:

$$\partial_{x_1} u_{\varepsilon}^s(x) = -\mu_{\varepsilon}(x_1) \left[1 + \frac{1}{2} x_2^2 H_0''(\mu_{\varepsilon}(x_1)) H_{\varepsilon}(\mu_{\varepsilon}(x_1)) \right]$$

$$\partial_{x_2} u_{\varepsilon}^s(x) = x_2 \left[H_{\varepsilon}(\mu_{\varepsilon}(x_1)) - \mu_{\varepsilon}(x_1) H_0'(\mu_{\varepsilon}(x_1)) \right].$$

Expending $|\partial_{x_1} u_{\varepsilon}^s(x)|^2 + |\partial_{x_2} u_{\varepsilon}^s(x)|^2$, and using the estimates (3.10), we obtain that the only remaining term which is not uniformly bounded (with respect to $\varepsilon \ge 0$) by a function in $L^1(\omega_0)$ is:

$$\int_{1}^{\ell_{\varepsilon}} \int_{0}^{1} |\mu_{\varepsilon}(x_{1})|^{2} dx_{2} dx_{1} = \int_{1}^{\ell_{\varepsilon}} |\mu_{\varepsilon}(x_{1})|^{2} dx_{1}$$

The change of variables $\xi_1 = \mu_{\varepsilon}(x_1)$ leads to:

$$\int_{1}^{\ell_{\varepsilon}} |\mu_{\varepsilon}(x_{1})|^{2} \, \mathrm{d}x_{1} = \int_{\mu_{\varepsilon}(1)}^{0} \frac{\xi_{1}^{2} \, \mathrm{d}\xi_{1}}{\kappa |\xi_{1}|^{1+\alpha} + \varepsilon}.$$

Setting now $\zeta = \kappa^{\frac{1}{\alpha+1}} \xi_1 / \varepsilon^{\frac{1}{\alpha+1}}$, we can transform the expression above into:

$$\int_{\mu_{\varepsilon}(1)}^{0} \frac{\xi_1^2 \,\mathrm{d}\xi_1}{\kappa |\xi_1|^{1+\alpha} + \varepsilon} = \kappa^{-\frac{3}{\alpha+1}} \varepsilon^{\frac{3}{1+\alpha}-1} \int_{\beta(\varepsilon)}^{0} \frac{\zeta^2 \,\mathrm{d}\zeta}{|\zeta|^{1+\alpha} + 1}$$

where $\beta(\varepsilon) := \kappa^{-\frac{1}{1+\alpha}} \mu_{\varepsilon}(1) \varepsilon^{-\frac{1}{1+\alpha}}$. We have now to distinguish, according to the value of α :

$$\int_{\beta(\varepsilon)}^{0} \frac{\zeta^2 \,\mathrm{d}\zeta}{|\zeta|^{1+\alpha}+1} = \begin{cases} \int_{\beta(\varepsilon)}^{0} \frac{\mathrm{d}\zeta}{|\zeta|+1} + \int_{\beta(\varepsilon)}^{0} \frac{|\zeta|-1}{|\zeta|^3+1} \,\mathrm{d}\zeta & \text{if } \alpha = 2\\ \int_{-\infty}^{0} \frac{\zeta^2 \,\mathrm{d}\zeta}{|\zeta|^{1+\alpha}+1} - \int_{-\infty}^{\beta(\varepsilon)} \frac{\zeta^2 \,\mathrm{d}\zeta}{|\zeta|^{1+\alpha}+1} & \text{if } \alpha > 2. \end{cases}$$
(B.3)

,

We deduce that, when $\alpha = 2$:

$$\int_{\beta(\varepsilon)}^{0} \frac{\zeta^2 \, \mathrm{d}\zeta}{|\zeta|^{1+\alpha} + 1} \underset{\varepsilon=0}{\sim} |\ln|\beta(\varepsilon)|| \underset{\varepsilon=0}{\sim} \frac{1}{3} |\ln(\varepsilon)|.$$

When $\alpha > 2$, since the second term in (B.3) tends to 0 with ε , we are led to compute the value of:

$$\int_0^{+\infty} \frac{x^2 \,\mathrm{d}x}{x^{1+\alpha}+1}.$$

Yet another change of variable, namely $y = x^3$, allows us to do that. We finally get:

$$\int_0^{+\infty} \frac{x^2 \, \mathrm{d}x}{x^{1+\alpha}+1} = \frac{1}{3} \int_0^{+\infty} \frac{\mathrm{d}y}{y^{\frac{1+\alpha}{3}}+1} = \frac{1}{3} \frac{3\pi/(1+\alpha)}{\sin(3\pi/(1+\alpha))}.$$

The proof is then complete.

Proof of Lemma 11:

We observe first that $f_{\varepsilon}^r = 0$ in D and $g_{\varepsilon}^r = 0$ in γ_{ε}^D for every $\varepsilon \ge 0$ because of the cut-off function χ and hence ω_{ε} can be replaced by R_{ε} and γ_{ε} by γ_{ε}^R in (6.18). Recall that (identities (6.17) and (6.15)):

$$f_{\varepsilon}^{r} = [\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla\chi)\hat{u}_{\varepsilon}^{s} + 2\mathbb{A}_{\varepsilon} : (\nabla\chi\otimes\nabla\hat{u}_{\varepsilon}^{s})] - \chi\hat{f}_{\varepsilon}^{s} \quad \text{in } \omega_{\varepsilon}$$
(B.4a)

$$g_{\varepsilon}^{r} = \left[-\hat{u}_{\varepsilon}^{s}(\mathbb{A}_{\varepsilon}\nabla\chi) \cdot n + (1-\chi)g_{\varepsilon}\right] - \chi \hat{r}_{\varepsilon}^{s} \qquad \text{on } \gamma_{\varepsilon}.$$
(B.4b)

Using the expressions (6.12) and (6.13) of v_{ε} and V_{ε} in (6.10b) and (6.10d), we get, for every $x \in R_{\varepsilon}$:

$$\begin{split} \hat{f}^{s}_{\varepsilon}(x_{1},x_{2}) &= x_{2}^{2} \left[\frac{3}{2} H_{\varepsilon}(X_{1}^{\varepsilon})^{2} H_{0}^{\prime\prime}(X_{1}^{\varepsilon}) + \frac{1}{2} X_{1}^{\varepsilon} H_{\varepsilon}(X_{1}^{\varepsilon})^{2} H_{0}^{\prime\prime\prime}(X_{1}^{\varepsilon}) \\ &- 3X_{1}^{\varepsilon} H_{\varepsilon}(X_{1}^{\varepsilon}) H_{0}^{\prime}(X_{1}^{\varepsilon}) H_{0}^{\prime\prime}(X_{1}^{\varepsilon}) - 3H_{\varepsilon}(X_{1}^{\varepsilon}) H_{0}^{\prime}(X_{1}^{\varepsilon})^{2} + 3X_{1}^{\varepsilon} H_{0}^{\prime}(X_{1}^{\varepsilon})^{2} \right], \quad (B.5a) \end{split}$$

and for every $x \in \gamma_{\varepsilon}^{R}$:

$$\hat{r}^{s}_{\varepsilon}(x) = \left[\frac{1}{2}X_{1}^{\varepsilon}H_{\varepsilon}(X_{1}^{\varepsilon})H_{0}'(X_{1}^{\varepsilon})H_{0}''(X_{1}^{\varepsilon}) + H_{\varepsilon}(X_{1}^{\varepsilon})H_{0}'(X_{1}^{\varepsilon})^{2} - X_{1}^{\varepsilon}H_{0}'(X_{1}^{\varepsilon})^{3}\right].$$
(B.5b)

Observing that $|H_0''(\mu_{\varepsilon})|$ and $|H_0'''(\mu_{\varepsilon})|$ are uniformly bounded (because $\alpha > 2$), we deduce, according to the estimates (3.10), that the functions:

$$x \mapsto |\hat{f}_{\varepsilon}^s(x)|^2 (1+x_1)^2$$
 and $x \mapsto |\hat{r}_{\varepsilon}^s(x)|^2 (1+x_1)^2$

are uniformly (in $\varepsilon \ge 0$) bounded by a function belonging to $L^1(R_0)$ and $L^1(\gamma_0^R)$ respectively. Invoking again Lemma 2 and applying the dominated convergence theorem, we get that:

$$\|\hat{f}_{\varepsilon}^s - \hat{f}_0^s\|_{L^2(R_{\varepsilon}, \mathrm{d}m^{-1})} \to 0 \quad \text{and} \quad \|\hat{r}_{\varepsilon}^s - \hat{r}_0^s\|_{L^2(\gamma_{\varepsilon}^R, \mathrm{d}\sigma^{-1})} \to 0 \text{ as } \varepsilon \to 0^+.$$

Using Proposition 5, we deduce that $-\operatorname{div}(\mathbb{A}_{\varepsilon}\nabla\chi)$ converges uniformly in $]0,1[\times]0,1[$ to $-\operatorname{div}(\mathbb{A}_{0}\nabla\chi)$ and since, in addition, $\hat{u}_{\varepsilon}^{s}$ converges in $C^{1}([0,1]^{2})$ to \hat{u}_{0}^{s} , we get, according to the identities (B.4) that

$$||f_{\varepsilon}^r - f_0^r||_{L^2(R_{\varepsilon}, \mathrm{d}m)} \to 0 \text{ as } \varepsilon \to 0^+$$

We proceed similarly to show the second convergence result.

We know (see above Lemma11) that f_{ε}^r and g_{ε}^r satisfy the compatibility condition (4.2) for every $\varepsilon > 0$. Lemma 6 and the convergence results above allow us to pass to limit in (4.2). The proof is now complete. \Box

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