# Orientation Ramsey thresholds for cycles and cliques ${ }^{1}$ 

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#### Abstract

If $G$ is a graph and $\vec{H}$ is an oriented graph, we write $G \rightarrow \vec{H}$ to say that every orientation of the edges of $G$ contains $\vec{H}$ as a subdigraph. We consider the case in which $G=G(n, p)$, the binomial random graph. We determine the threshold $p_{\vec{H}}=p_{\vec{H}}(n)$ for the property $G(n, p) \rightarrow \vec{H}$ for the cases in which $\vec{H}$ is an acyclic orientation of a complete graph or of a cycle.


A Ramsey-type property. For each (undirected) graph $G$ and oriented graph $\vec{H}$, we write $G \rightarrow \vec{H}$ to mean that every orientation of $G$ contains a copy of $\vec{H}$; the orientation Ramsey number $\vec{R}(\vec{H})$ is $\inf \left\{n: K_{n} \rightarrow \vec{H}\right\}$. This parameter has been investigated in a number of articles $[8,12-16,19-25,29-32$, among others], most of which concern a conjecture of Sumner [32]. Sumner's universal tournament conjecture states that $\vec{R}(\vec{T}) \leqslant 2 e(\vec{T})$ for every oriented tree $\vec{T}$; this has been confirmed for all sufficiently large trees by Kühn, Mycroft and Osthus [19, 20]; see also [1, 26].

Thresholds. Thresholds for Ramsey-type properties are widely studied as well (see, e.g., [17, 27] and the many references therein). We call $p_{\vec{H}}=p_{\vec{H}}(n)$ a threshold for $G(n, p) \rightarrow \vec{H}$ if

$$
\mathbb{P}[G(n, p) \rightarrow \vec{H}]= \begin{cases}0 & \text { if } p \ll p_{\vec{H}} \\ 1 & \text { if } p \gg p_{\vec{H}}\end{cases}
$$

where $a \ll b$ (or, equivalently, $b \gg a$ ) means $\lim _{n \rightarrow \infty} a_{n} / b_{n} \rightarrow 0$. As is customary, we speak of 'the threshold $p_{\vec{H}}$ ', since $p_{\vec{H}}$ is unique within constant factors. If $\vec{H}$ is acyclic, then the property $G(n, p) \rightarrow \vec{H}$ is non-trivial and monotone, and hence [3] it has a threshold $p_{\vec{H}}=p_{\vec{H}}(n)$. The regularity method can be used to give an upper bound for $p_{\vec{H}}=p_{\vec{H}}(n)$ (it suffices to combine ideas from [17, Section 8.5] and, say, [10]). For an alternative approach giving the same upper bound, based on the methods of [28], see [7]. For any graph or digraph $G$, the maximum density and (when $v(G) \geqslant 3$ ) the maximum 2-density of $G$ are, respectively,

$$
m(G):=\max _{\substack{J \subseteq G \\ v(J) \geqslant 1}} \frac{e(J)}{v(J)} \quad \text { and } \quad m_{2}(G):=\max _{\substack{J \subseteq G \\ v(\bar{J}) \geqslant 3}} \frac{e(J)-1}{v(J)-2}
$$

Theorem 1. Let $\vec{H}$ be an acyclically oriented graph. There exists a constant $C=C(\vec{H})$ such that, if $p \geqslant C n^{-1 / m_{2}(\vec{H})}$, then $\mathbb{P}[G(n, p) \rightarrow \vec{H}] \rightarrow 1$ as $n \rightarrow \infty$.

Contribution. We determine the orientation Ramsey threshold for all acyclic orientations of the complete graph $K_{t}$ and cycle $C_{t}$, for each $t \geqslant 3$. We also determine the threshold for certain oriented bipartite graphs. We call a digraph $\vec{H}$ anti-directed if each vertex in $\vec{H}$ has either no inneighbours or no outneighbours (so $\vec{G}$ is bipartite and all arcs point to the same part).

[^0]orientation Ramsey number

Theorem 2. If $\vec{H}$ is an acyclic orientation of $K_{t}$ or $C_{t}$, then

$$
p_{\vec{H}}(n)= \begin{cases}n^{-1 / m_{( }\left(K_{4}\right)} & \text { if } t=3 \\ n^{-1 / m_{2}(\vec{H})} & \text { if } t \geqslant 4\end{cases}
$$

is the threshold for $G(n, p) \rightarrow \vec{H}$. Moreover, if $\vec{H}$ is an anti-directed orientation of a strictly 2-balanced graph $H$ such that $\delta(H) \geqslant 2$ and $m_{2}(H)-\left\lfloor m_{2}(H)\right\rfloor \leqslant 1 / 2$, then

$$
p_{\vec{H}}(n)=n^{-1 / m_{2}(\vec{H})}
$$

is the threshold for $G(n, p) \rightarrow \vec{H}$.
In view of Theorem 1, to prove Theorem 2 (except for the case in which $\vec{H}$ is an orientation of $K_{3}$ ), it suffices to prove the so called 0 -statement, that is, it is enough to show that if $p \ll n^{-1 / m_{2}(\vec{H})}$, then $G(n, p) \rightarrow \vec{H}$ holds with vanishing probability. Our proof of this 0 -statement uses recent advances in the study of Ramsey-type thresholds: a framework developed by Nenadov, Person, Škorić and Steger [27] (outlined below) and structural results of Barros, Cavalar, Mota and Parczyk [2].

We need only a simplified version of the results in [27] (see Definitions 10 and 11 in [27]). Let $G$ and $H$ be graphs, where $\delta(H)>1$. An edge $e \in E(G)$ is $H$-closed if $e$ belongs to at least two copies of $H$ in $G$. A copy of $H$ in $G$ is $H$-closed if at least three of its edges are $H$-closed, and $G$ is $H$-closed if all vertices and edges of $G$ lie in copies of $H$ and every copy of $H$ in $G$ is $H$-closed. Finally, $G$ is an $H$-block if $G$ is $H$-closed and for each proper non-empty subset $E^{\prime} \subsetneq E(G)$ there exists a copy $H^{\prime}$ of $H$ in $G$ such that $E\left(H^{\prime}\right) \cap E^{\prime} \neq \varnothing$ and $E\left(H^{\prime}\right) \backslash E^{\prime} \neq \varnothing$.

Theorem $3-[27$, Corollary 13]. Let $H$ be a strictly 2 -balanced graph with at least 3 edges such that $H$ is not a matching. If $p \ll n^{-1 / m_{2}(H)}$, then with high probability every $H$-block $F$ of $G(n, p)$ satisfies $m(F)<m_{2}(H)$.

Since complete graphs and cycles are strictly 2-balanced, Theorem 3 reduces the proof of the 0 -statement of the case $t \geqslant 4$ in Theorem 2 to showing that $G \nrightarrow \vec{H}$ for every graph $G$ whose $H$-blocks have maximum density strictly below $m_{2}(H)$. This is achieved for cycles using results from [2], whereas for tournaments and anti-directed graphs, as well as for the case $t=3$ of Theorem 2 we use ad hoc methods (see Theorems 8, 12 and 13). Theorem 2 is proved in Section 4.

Remark. Other Ramsey-type properties for directed graphs include requiring copies to be induced $[4,9,18]$ and allowing colourings plus orientations [5, 6].

## 1 Auxiliary definitions and results

We follow standard notation (see, e.g., [11,17]). A $k$-path is a path with $k$ vertices; $k$-cycles are defined similarly. A directed $k$-path is an oriented path $v_{1} \rightarrow \cdots \rightarrow v_{k}$. A directed $k$-cycle is oriented as $v_{1} \rightarrow \cdots \rightarrow v_{k} \rightarrow v_{1}$. Let $\vec{G}$ be an oriented graph. A maximal directed path in $\vec{G}$ is called a block. A path or block is long if it has at least 3 edges. The following exercise
directed path or cycle
block, long is left to the reader.
| Lemma 4. If $G$ is a graph, then $\delta(J) \leqslant 2 m(G)$ for each $J \subseteq G$ (i.e., $G$ is $2 m(G)$-degenerate). |

Let $G$ and $H$ be graphs, and let $\vec{H}$ be an orientation of $H$. We denote by $\mathcal{C}_{H}(G)$ the edge intersection graph of $H$ in $G$, whose vertices correspond to copies of $H$ in $G$ and whose edges join distinct copies which share a common edge in $G$. An $H$-component is a subgraph of $G$ formed by the union of all copies of $H$ in some connected component of $\mathfrak{C}_{H}(G)$. Note that $G \nrightarrow \vec{H}$ if and only if each $H$-component of $G$ admits an $\vec{H}$-free orientation. Let $G$ and $H$ be graphs and let $C$ be an $H$-component of $G$. If $H_{1}$ is an arbitrary copy of $H$ in $C$, then there exists a sequence $H_{1} \subseteq H_{2} \subseteq \cdots \subseteq H_{t}=C$ with the following property. For each $i \in[t-1]$, there exists a copy $H^{\prime}$ of $H$ such that $H^{\prime} \nsubseteq H_{i}, E\left(H^{\prime}\right) \cap E\left(H_{i}\right) \neq \varnothing$ and $H_{i+1}=H_{i} \cup H^{\prime}$. We say that $\left(H_{1}, \ldots, H_{t}\right)$ constructs $C$, and call $\left(H_{1}, \ldots, H_{t}\right)$ a construction sequence of $C$. For each $i \in[t-1]$, we say that a vertex or edge of $H_{i+1}$ is new in $H_{i+1}$ if it is not contained in $H_{i}$, and say that $F \subseteq H_{i+1}$ is new (in $H_{i+1}$ ) if $F$ contains a new edge in $H_{i+1}$. Moreover, if $H_{1}^{\prime}$ is a copy of $H$ in $H_{i}$, then there exists a construction sequence ( $H_{1}^{\prime}, \ldots, H_{j}^{\prime}$ ) of $H_{i}$ starting with $H_{1}^{\prime}$, and hence a construction sequence $\left(H_{1}^{\prime}, \ldots, H_{j}^{\prime}, H_{i+1}, \ldots, H_{t}\right)$ of $C$.

Let $G$ be a graph and suppose $E \subseteq E(G)$. We write $G[E]$ for the subgraph of $G$ consisting of the edges in $E$ and the vertices in $G$ which are incident with those edges. We call $H$ strictly 2-balanced if $m_{2}(F)<m_{2}(H)$ for each proper subgraph $F \subseteq H$.

Lemma 5 - [27, Lemma 14]. Let $G$ and $H$ be graphs. If $G$ is $H$-closed, then $E(G)$ admits a partition $\left\{E_{1}, \ldots, E_{k}\right\}$ such that $G\left[E_{1}\right], \ldots, G\left[E_{k}\right]$ are $H$-blocks and each copy of $H$ in $G$ lies entirely in one of these $H$-blocks.

Let $\vec{H}$ be an orientation of a graph $H$. We say $\vec{H}$ is 2-Ramsey-avoidable if for all $e, f \in E(H)$, every orientation of $e, f$ can be extended to an $\vec{H}$-free orientation of $H$.
Remark 6. Let $k \geqslant 4$. If $\vec{H}$ is either an orientation of $C_{k}$, a transitive tournament $\mathrm{TT}_{k}$, or an anti-directed orientation of a graph $H$ with $\delta(H)>1$, then $\vec{H}$ is 2-Ramsey-avoidable.

Proof. Let $H$ be the underlying graph of $\vec{H}$. In each of the following cases, let $e, f \in E(H)$ be chosen and oriented arbitrarily; it suffices to complete an $\vec{H}$-free orientation of $H$.

Suppose $\vec{H}$ is an orientation of $C_{k}$. Note that we can complete the orientation of $e, f$ to orientations $\vec{C}_{1}, \vec{C}_{2}$ of $C_{k}$ such that $\vec{C}_{1}$ has a block of length at least $k-1 \geqslant 3$ and $\vec{C}_{2}$ has no long block. If $\vec{H}$ has a block of length at least $k-1$, then we pick $\vec{C}_{2}$, else we pick $\vec{C}_{1}$.

If $\vec{H} \simeq \mathrm{TT}_{k}$, we complete the orientation of $K_{k}$ so that it contains a directed triangle (some triangle in $H$ has at most one edge already oriented).

In the remaining case (anti-directed graph), we complete the orientation of $H$ forming a directed 3 -path (since $k \geqslant 4$, some $v \in V(H)$ is incident with precisely one of $e, f$, while $\delta(H)>1$ implies some other edge incident with $v$ has not been oriented).

Remark 6 will be used with the next lemma and Theorem 3 to establish our main results.
Lemma 7. Let $G$ be a graph and let $\vec{H}$ be 2-Ramsey-avoidable. If $B \nrightarrow \vec{H}$ for each $H$-block $B$ of $G$, then $G \nrightarrow \vec{H}$.

Proof. Let $H$ be the underlying graph of $\vec{H}$. To show that $G$ admits an $\vec{H}$-free orientation, we may assume each edge of $G$ lies in a copy of $H$ (the orientation of other edges is irrelevant).

Let $G_{0}=G$ and, for each $i=1,2, \ldots$ proceed as follows. If $G_{i-1}$ is $H$-closed, then stop, set $m:=i-1$ and $F:=G_{m}$. Otherwise, some copy $F_{i}$ of $H$ in $G_{i-1}$ has at most two $H$-closed edges in $G_{i-1}$. Form $G_{i}$ by deleting from $G_{i-1}$ each non- $H$-closed edge of $F_{i}$, and then each isolated vertex. Note that $G_{i-1}=G_{i} \cup F_{i}$ and that each $e \in E\left(G_{i}\right)$ lies in some copy of $H$.
$\qquad$

Note that $F$ is $H$-closed. By Lemma $5, F$ can be partitioned into a collection $\mathcal{B}$ of edgedisjoint $H$-blocks such that each copy of $H$ in $F$ lies entirely in some $B \in \mathcal{B}$. By assumption, $B \nrightarrow \vec{H}$ for each $B \in \mathcal{B}$, so $F$ admits a $\vec{H}$-free orientation $\vec{F}$ (the disjoint union of $\vec{H}$-free orientations of each $B \in \mathcal{B}$ ).

Finally, we extend $\vec{G}_{m}:=\vec{F}$ to an $\vec{H}$-free orientation $\vec{G}_{0}$ of $G$. For each $i=m, m-1, \ldots, 1$, let $\vec{G}_{i-1}$ extend $\vec{G}_{i}$ by orienting the edges $E\left(F_{i}\right) \backslash E\left(G_{i}\right)$ so that $F_{i}$ is $\vec{H}$-free (this is possible because $\vec{H}$ is 2-Ramsey-avoidable). Clearly, no copy of $H$ in $G$ induces $\vec{H}$ in $\vec{G}$, so $G \nrightarrow \vec{H}$.

## 2 Transitive triangles

Let $\mathrm{TT}_{3}$ be the transitive triangle. In this section we show that the upper bound for $p_{\mathrm{TT}_{3}}(n)$ given in Theorem 1 is not tight.
| Theorem 8. The function $p_{\mathrm{TT}_{3}}(n)=n^{-1 / m\left(K_{4}\right)}$ is the threshold for $G(n, p) \rightarrow \mathrm{TT}_{3}$.

Let $W_{5}$ be the graph we obtain by adding to $C_{4}$ a new universal vertex.
Proposition 9. If $G$ is a $K_{3}$-component such that $u w, v w \in E(G)$ and $u v \notin E(G)$, then there exists $J \subseteq G$ such that either $v(J)=6$ and $e(J)=9$ or $J+u v$ is isomorphic to $K_{4}$ or $W_{5}$.

Proof. Let $F_{1} \cdots F_{s}$ be a shortest path in $\mathcal{C}_{K_{3}}(G)$ such that $u w \in E\left(F_{1}\right)$ and $v w \in E\left(F_{s}\right)$. It suffices to show the following.

- If $s=2$, then $J:=F_{1} \cup \cdots \cup F_{s}$ satisfies $J+u v \simeq K_{4}$.
- If $s=3$, then $J:=F_{1} \cup \cdots \cup F_{s}$ satisfies $J+u v \simeq W_{5}$.
- If $s \geqslant 4$, then $J:=F_{1} \cup F_{2} \cup F_{3} \cup F_{4}$ satisfies $v(J)=6$ and $e(J)=9$.

It is simple to check that the following hold by the choice of $F_{1} \cdots F_{s}$.
(i) $\left|E\left(F_{i}\right) \cap E\left(F_{i-1}\right)\right|=1$ for all $i \in[s] \backslash\{1\}$;
(ii) $\left|E\left(F_{i}\right) \cap \bigcup_{j<i} E\left(F_{j}\right)\right|=1$ for each $i \in[s] \backslash\{1\}$; and
(iii) Each $e \in E(G)$ belongs to at most two triangles in $F_{1} \cup \cdots \cup F_{s}$.

The statement for $s=2$ follows by (i) since $F_{1} \simeq K_{3}$. If $s=3$, then $v(J)=5$ (by (i) and (ii)), so $J+u v \simeq W_{5}$. By (i), for each $i \in[s] \backslash\{1\}$ we have $\left|V\left(F_{i}\right) \backslash \bigcup_{j \in[i-1]} V\left(F_{j}\right)\right| \leqslant 1$, so $v\left(F_{1} \cup \cdots \cup F_{s}\right) \leqslant s+2$. Moreover, (ii) implies $e\left(F_{i}\right)=2 i+1$ for each $i \in[s]$. If $s=4$, then $e(J)=9$. Clearly $5 \leqslant v(J) \leqslant 6$; note that $v(J) \neq 5$ as otherwise there exists $e \in E(J)$ which belongs to three distinct triangles in $J$, contradicting (iii).

Let $\left(H_{1}, \ldots, H_{t}\right)$ be a $K_{3}$-component. For each $i \in[t-1]$, either $(A)$ there are two new edges in $H_{i+1}$ and one new vertex in $H_{i+1} ;(B)$ there are two new edges in $H_{i+1}$ and $V\left(H_{i+1}\right)=V\left(H_{i}\right)$; or $(C)$ there is exactly one new edge in $H_{i+1}$ and $V\left(H_{i+1}\right)=V\left(H_{i}\right)$. A graph $H$ is $A B$-constructible if no construction sequence of a $K_{3}$-component of $H$ contains a step of type $(C)$.
| Proposition 10. If a graph $H$ is $A B$-constructible, then $H \nrightarrow \mathrm{TT}_{3}$.

Proof. We may assume that $H$ is itself a single $K_{3}$-component $\left(H_{1}, \ldots, H_{t}\right)$, as edges which do not belong to a copy of $K_{3}$ in $H$ can be arbitrarily oriented and distinct $K_{3}$-components may be independently oriented. First note that, at each step, exactly one new copy of $K_{3}$ is
added. This is clearly true for steps of type $(A)$. Moreover, it is easy to see that if $H_{\alpha+1}$ is created by a step of type $(B)$ and the new edges create two distinct copies of $K_{3}$ in $H_{\alpha+1}$, then $H$ admits a construction sequence with a step of type $(C)$, a contradiction. We orient $H_{1}$ forming a directed triangle and, for each $\alpha \in[t-1]$, orient the two new edges in $H_{\alpha+1}$ so as to form a new directed triangle. The resulting orientation is $\mathrm{TT}_{3}$-free.

Our final ingredient is the following classical result (see, e.g., [17]).
Theorem 11 - [17]. Let $H$ be a fixed graph. Then

$$
\lim _{n \rightarrow \infty} \mathbb{P}[H \subseteq G(n, p)]=\left\{\begin{array}{l}
1, \text { if } p \gg n^{-1 / m(H)} \\
0, \text { if } p \ll n^{-1 / m(H)}
\end{array}\right.
$$

Proof of Theorem 8. If $p \gg n^{-2 / 3}$, then $K_{4} \subseteq G(n, p)$ with high probability by Theorem 11; hence $G(n, p) \rightarrow \mathrm{TT}_{3}$ with high probability (as $\left.K_{4} \rightarrow \mathrm{TT}_{3}\right)$.

Now suppose that $p \ll n^{-2 / 3}$. Let $\mathcal{E}$ be the event that $G(n, p)$ is not $A B$-constructible. By Proposition 10 , it suffices to show that $\mathbb{P}[\mathcal{E}]=\mathrm{o}(1)$. Let $\mathcal{J}$ be set of all nonisomorphic graphs of order 6 and size 9. By Proposition 9, every $K_{3}$-component of $G(n, p)$ which is not $A B$-constructible contains either $K_{4}, W_{5}$ or some $J \in \mathcal{J}$. Using Markov's inequality, we have

$$
\begin{aligned}
\mathbb{P}[\mathcal{E}] & \leqslant \mathbb{P}\left[K_{4} \subseteq G(n, p)\right]+\mathbb{P}\left[W_{5} \subseteq G(n, p)\right]+\sum_{J \in \mathcal{J}} \mathbb{P}[J \subseteq G(n, p)] \\
& \leqslant \sum_{J \in\left\{K_{4}, W_{5}\right\} \cup \mathcal{Z}} \mathbb{E}\left[\left|\left\{J^{\prime} \subseteq G(n, p): J^{\prime} \simeq J\right\}\right|\right] \leqslant n^{4} p^{6}+n^{5} p^{8}+|\mathcal{J}| n^{6} p^{9}
\end{aligned}
$$

Since $p \ll n^{-2 / 3}$ and $|\mathcal{J}|=\Theta(1)$, we have $\mathbb{P}[\mathcal{E}]=o(1)$.

## 3 Graphs with low maximum 2-density

The following sections show that $G \nrightarrow \vec{H}$ for some classes of oriented graphs, when $\vec{H}$ has at least four vertices and $m(G)<m_{2}(\vec{H})$.

### 3.1 Transitive Tournaments

We denote a tournament on $k$ vertices by $T_{k}$, writing $\mathrm{TT}_{k}$ if it is transitive.
| Theorem 12. If $k \geqslant 4$ and $G$ is a graph with $m(G)<m_{2}\left(K_{k}\right)$, then $G \nrightarrow \mathrm{TT}_{k}$.

Proof. The proof is by induction on $n:=v(G)$. The case $n=1$ is trivial. Assume $n \geqslant 2$ and that $G^{\prime} \nrightarrow \mathrm{TT}_{k}$ whenever $m\left(G^{\prime}\right)<m_{2}\left(K_{k}\right)$ and $v\left(G^{\prime}\right)<n$. By Lemma 4, $\operatorname{deg}_{G}(u) \leqslant k$ for some $u \in V(G)$. Let $G^{\prime}=G-u$, so $m\left(G^{\prime}\right)<m_{2}\left(K_{k}\right)$ and $G^{\prime}$ admits a $\mathrm{TT}_{3}$-free orientation $\vec{G}$. We shall extend $\vec{G}$ to an orientation of $G$ such that each $T_{k}$ containing $u$ has a directed cycle.

We may assume that $u$ lies in some copy of $K_{k}$, say $K$; so $\operatorname{deg}(u) \geqslant k-1$. If $K$ is the only copy of $K_{k}$ containing $u$, then choose two vertices $v, w \in V(K-u)$ and orient the edges $u v$ and $u w$ so that $\{u, v, w\}$ induces a directed triangle. Otherwise let $K^{\prime}$ be some $K_{k}$ containing $u$ other than $K$. Hence we must have $\operatorname{deg}(u)=k$. Let $v$ be the unique vertex in $V(K) \backslash V\left(K^{\prime}\right)$, and $w$ be the unique vertex in $V\left(K^{\prime}\right) \backslash V(K)$. Since $k-2 \geqslant 2$, there are at least two vertices $x$ and $y$ in $V\left(K \cap K^{\prime}\right) \backslash\{u\}$. Orient the edges $u v, u x, u w$ and $u y$ so that each of $\{u, v, x\}$ and $\{u, w, y\}$ induces a directed triangle. Since every $K_{k}$ containing $u$ has at least three vertices in $\{v, w, x, y\}$, the partial orientation of each $K_{k}$ contains a directed cycle. Any remaining un-oriented edge may be arbitrarily oriented.

### 3.2 Anti-directed digraphs

We now turn to anti-directed orientations of $K_{t, t}, C_{2 t}$ and other bipartite graphs.
Theorem 13. Let $G$ and $H$ be graphs, where $\delta(H) \geqslant 2$. If $\vec{H}$ is an anti-directed orientation of $H$ and $m(G)<\delta(H)-1 / 2$, then $G \nrightarrow \vec{H}$.

Proof. We proceed by induction on $v(G)$. If $v(G) \leqslant 2$, then $G \nrightarrow \vec{H}$. Let $\delta:=\delta(H)$. By Lemma 4, there exists $v \in V(G)$ with $\operatorname{deg}(v)=\delta(G) \leqslant 2 \delta-2$. By induction, $G-v \nrightarrow \vec{H}$. Fix an $\vec{H}$-free orientation of $G-v$, orient $\lfloor\delta(G) / 2\rfloor$ edges incident with $v$ towards $v$ and the remaining $\lceil\delta(G) / 2\rceil$ edges away from $v$. Note that any copy of $H$ in $G$ containing $v$ necessarily has two edges incident with $v$ oriented in opposite directions, since $\delta(H) \geqslant 2$ and $\lceil\delta(G) / 2\rceil \leqslant \delta(H)-1$.

Corollary 14. Let $G$ and $H$ be graphs such that $H$ is strictly 2-balanced, $\delta(H) \geqslant 2$ and $m_{2}(H)-$ $\left\lfloor m_{2}(H)\right\rfloor \leqslant 1 / 2$. If $\vec{H}$ is an anti-directed orientation of $H$ and $m(G)<m_{2}(H)$, then $G \nrightarrow \vec{H}$.

Proof. We have $(e(H-u)-1) /(v(H-u)-2)<(e(H)-1) /(v(H)-2)$ for all $u \in V(H)$, since $H$ is strictly 2 -balanced. It follows that $m_{2}(H)<\delta(H)$, so $\left\lfloor m_{2}(H)\right\rfloor+1 \leqslant \delta(H)$. Since $m(G)<m_{2}(H) \leqslant\left\lfloor m_{2}(H)\right\rfloor+1 / 2 \leqslant \delta(H)-1 / 2$, we can apply Theorem 13.

### 3.3 Cycles

We now consider orientations of $\ell$-cycles, where $\ell \geqslant 4$. The main results are Theorems 17 and 23 , which deal with the cases $\ell \geqslant 5$ and $\ell=4$, respectively. (We also include a simple proof for the case $\ell \geqslant 8$, see Theorem 16.)

Lemma 15. Let $\vec{C}$ be an oriented cycle with a long block. If $G$ is a graph and $m(G)<m_{2}(\vec{C})$, then $G \nrightarrow \vec{C}$.

Proof. Note that $v(\vec{C}) \geqslant 4$, so $m_{2}(\vec{C}) \leqslant m_{2}\left(C_{4}\right)=3 / 2$. By Lemma 4, $G$ is 2-degenerate, hence $\chi(G) \leqslant 3$. Fix a proper colouring $c: V(G) \rightarrow\{1,2,3\}$, and orient each edge towards its endvertex with the largest colour. This orientation contains no long block, so $G \nrightarrow \vec{C}$.

While the next result is superseded by Theorem 17, its proof is much simpler.
Theorem 16. Let $\vec{C}$ be an orientation of $C_{\ell}$, where $\ell \geqslant 8$. If $G$ is a graph and $m(G)<m_{2}(\vec{C})$, then $G \nrightarrow \vec{C}$.

Proof. Let $\ell=e(\vec{C})$. If $\vec{C}$ contains a long block, then the theorem holds by Lemma 15 , so we assume that the longest block of $\vec{C}$ has length at most 2 .

Suppose, looking for a contradiction, that the statement is false. Without loss of generality let $G$ be a minimal counterexample (with respect to the subgraph relation). That is, $m(G)<m_{2}(\vec{C})$ and $G \rightarrow \vec{C}$, and $G^{\prime} \nrightarrow \vec{C}$ for each proper subgraph $G^{\prime} \subseteq G$. Let $W$ be the set of vertices in $G$ with degree 2 .

If there exists an edge $u v$ joining vertices $u, v \in W$, then (since $G$ is minimal) $u v$ lies in an $\ell$-cycle. Moreover, $G \backslash\{u, v\} \nrightarrow \vec{C}$; so there exists an orientation $\vec{G}$ of $G \backslash\{u, v\}$ which avoids $\vec{C}$. Note that each $\ell$-cycle in $G$ is either completely oriented in $\vec{G}$ (while avoiding $\vec{C}$ ), or contains the three (not yet oriented) edges incident with either $u$ or $v$. We extend $\vec{G}$ by orienting these edges so that they form a directed path or cycle. Since, by assumption, the
length of any block of $\vec{C}$ is at most two, it follows that $\vec{G}$ is an orientation of $G$ avoiding $\vec{C}$, a contradiction.

Hence no edge of $G$ lies in $W$. By the minimality of $G$, every vertex $v \in V(G)$ lies an $\ell$-cycle, so $\delta(G) \geqslant 2$. Let $n:=v(G)$. Since each vertex of $W$ has degree 2,

$$
2|W|+3(n-|W|) \leqslant \sum_{v \in V(G)} d(v)=2 e(G) \leqslant 2 m(G) n<2 n \frac{\ell-1}{\ell-2} .
$$

It follows that $|W| \geqslant n(1-2 /(\ell-2))$ and

$$
2\left(1-\frac{2}{\ell-2}\right) n \leqslant 2|W| \leqslant e(G) \leqslant m(G) n=\left(1+\frac{1}{\ell-2}\right) n,
$$

which is a contradiction for $\ell \geqslant 8$.

### 3.3.1 Cycles of length at least 5

We now generalise Theorem 16 for oriented cycles with at least 5 vertices.
Theorem 17. Let $\vec{C}$ be an orientation of $C_{\ell}$, where $\ell \geqslant 5$. If $G$ is a graph and $m(G)<m_{2}\left(C_{\ell}\right)$, then $G \nrightarrow \vec{C}$.

Barros, Cavalar, Mota and Parczyk [2] obtained a detailed characterisation of the construction sequences of $C_{\ell}$-components; we state their result below in a slightly modified form (the original has ' $\ell \geqslant 5$ ' in place of ' $\ell \geqslant 4$ ', but the same proof holds).
Proposition 18-[2, Proposition 7]. Let $\ell \geqslant 4$ be an integer, $G$ be a graph with $m(G)<m_{2}\left(C_{\ell}\right)$ and $\left(H_{1}, \ldots, H_{t}\right)$ be a $C_{\ell}$-component of $G$. The following holds for every $1 \leqslant i \leqslant t-1$. If $C$ is an $\ell$-cycle added to $H_{i}$ to form $H_{i+1}$, then there exists a labelling $C=u_{1} u_{2} \cdots u_{\ell} u_{1}$ such that exactly one of the following occurs, where $2 \leqslant j \leqslant \ell$ and $3 \leqslant k \leqslant \ell-1$.
$\left(A_{j}\right) u_{1} u_{2} \cdots u_{j}$ is a $j$-path in $H_{i}$ and $u_{j+1}, \ldots, u_{\ell} \notin V\left(H_{i}\right)$;
$\left(B_{k}\right) u_{1} u_{2} \in E\left(H_{i}\right), u_{2} u_{3} \notin E\left(H_{i}\right),\left\{u_{3}, \ldots, u_{\ell}\right\} \backslash\left\{u_{k}\right\} \subseteq V\left(H_{i+1}\right) \backslash V\left(H_{i}\right), u_{k} \in V\left(H_{i}\right)$.
If ( $H_{1}, \ldots, H_{t}$ ) constructs a $C_{\ell}$-component, then for each $i \in[t-1]$ the new edges in $H_{i+1}$ form a path (by Proposition 18). We denote this path by $Q_{i}$, write $x_{i}, z_{i}$ for its endvertices and $Q_{i}, x_{i}, z_{i}$ $y_{i}$ for the sole internal vertex of $Q_{i}$ in $H_{i}$, if it exists. (Again by Proposition 18, $V\left(Q_{i}\right) \cap V\left(H_{i}\right) \quad y_{i}$ is either $\left\{x_{i}, z_{i}\right\}$ or $\left\{x_{i}, y_{i}, z_{i}\right\}$.) We write type $(i)$ to denote the operation $\left(\left(A_{j}\right)\right.$ or $\left(B_{k}\right)$, type( $(i)$ where $2 \leqslant j \leqslant \ell$ and $3 \leqslant k \leqslant \ell-1$ ) which constructs $H_{i+1}$ from $H_{i}$.
Proposition 19- [2]. Let $\ell \geqslant 5$. If $G=\left(H_{1}, \ldots, H_{t}\right)$ is a $C_{\ell}$-component and $m(G)<m_{2}\left(C_{\ell}\right)$, then for all distinct $i, j \in[t-1]$ and each $k \in\{3, \ldots, \ell-1\}$ we have the following.

- If type $(i)=\left(A_{\ell}\right)$, then every other step is of type $\left(A_{2}\right)$ or $\left(A_{3}\right)$.
- If type $(i)=\left(A_{\ell-1}\right)$, then every other step is of type $\left(A_{2}\right),\left(A_{3}\right)$ or $\left(A_{\ell-1}\right)$.
- If type $(i)=\operatorname{type}(j)=\left(A_{\ell-1}\right)$, then $\ell=5$ and every other step is of type $\left(A_{2}\right)$.
- If type $(i)=\left(B_{k}\right)$, then every other step is of type $\left(A_{2}\right)$.

We also use the following results.
Remark 20. Let $G$ be a $C_{5}$-component. If $G$ can be constructed solely by steps of type ( $A_{2}$ ), then every cycle in $G$ has length congruent to $2(\bmod 3)$.

Proof. The proof is by induction on $i \in[t]$ where $\left(H_{1}, \ldots, H_{t}\right)$ is the construction sequence of $G$. The base holds because $H_{1}$ is a 5 -cycle. Now suppose every cycle in $H_{i}$ has length congruent to $2(\bmod 3)$, where $i \geqslant 1$. We form $H_{i+1}$ by a step of type $\left(A_{2}\right)$, i.e., by adding an 5 -path $P$ joining the endvertices of an edge $u v$ of $H_{i}$. Any new cycle $C$ is formed by an $u v$-path $P^{\prime}$ in $H_{i}$, together with $P$. If $P^{\prime}=u v$, then $C$ has length 5 , and the claim holds. On the other hand, if $u v \notin E\left(P^{\prime}\right)$, then $C=P^{\prime} \cup P$, but since $C^{\prime}:=P^{\prime}+u v$ is a cycle in $H_{i}$, it follows that $e\left(C^{\prime}\right) \equiv 2(\bmod 3)$, so $e(C)=e\left(P^{\prime}\right)+e(P)=e\left(C^{\prime}\right)-1+e(P) \equiv 2(\bmod 3)$.

Remark 21. Let $G$ be a $C_{5}$-component. If $G$ is constructed solely by steps of the types $\left(A_{2}\right)$ and $\left(A_{3}\right)$, then $G$ contains no $C_{3}$ and no $C_{4}$.

Proof. Let $\left(H_{1}, \ldots, H_{t}\right)$ be a construction sequence of $G$. Note that $C_{3} \nsubseteq G$ : indeed, $H_{1} \simeq C_{5}$, so $C_{3} \nsubseteq H_{1}$; moreover, for each $i \in[t-1]$ we have $H_{i+1}=H_{i} \cup Q_{i}$ and $Q_{i}$ is a path of length at least 3 which is internally disjoint from $H_{i}$, so $C_{3} \nsubseteq H_{i+1}$.

Similarly $C_{4} \nsubseteq H_{1}$, and if $H_{i} \cup Q_{i}$ contains a $C_{4}$, then type $(i)=\left(A_{3}\right)$, so $x_{i}$ and $z_{i}$ are connected by a path $x_{i} w z_{i}$ in $H_{i}$ (which, together with $Q_{i}$, creates a $C_{5}$ ). But then $x_{i} w z_{i} x_{i}$ is a $C_{3}$ in $G$, a contradiction.

We are now in position to prove the main result of this section.
Proof of Theorem 17. Let $G$ be a graph with $m(G)<(\ell-1) /(\ell-2)$, where $\ell \geqslant 5$, and let $\vec{C}$ be an oriented $\ell$-cycle. By Lemma 15 , if $\vec{C}$ contains a long block, then $G \nrightarrow \vec{C}$, so we may assume that every block of $\vec{C}$ has length at most two. We will show that the $C_{\ell}$-components of $G$ admit an orientation in which every $\ell$-cycle has a long block. It suffices to consider one such component $F$, as $C_{\ell}$-components can be independently oriented (they do not share edges) and remaining edges can be arbitrarily oriented (each $\ell$-cycle in $G$ lies in some $C_{\ell}$-component).

Let $F=\left(H_{1}, \ldots, H_{t}\right)$ be a $C_{\ell}$-component of $G$. Hence, for all $i \in[t-1]$, each $\ell$-cycle $C \subseteq H_{i+1}$ which did not exist in $H_{i}$ contains either the path $x_{i} Q_{i} y_{i}$ or $y_{i} Q_{i} z_{i}$ (if $Q_{i}$ intersects $H_{i}$ in three vertices) or the whole path $Q_{i}$.
$\rightarrow$ Case 0. For each $i \in[t-1]$ we have type $(i) \notin\left\{\left(A_{\ell-1}\right),\left(A_{\ell}\right),\left(B_{3}\right), \ldots,\left(B_{\ell-1}\right)\right\}$.
For each $i \in[t-1]$, every new cycle in $H_{i+1}$ contains $Q_{i}$ and $e\left(Q_{i}\right) \geqslant 3$. We construct an orientation of $F$ which avoids $\vec{C}$ as follows. Fix a directed orientation of $H_{1}$, and for each $i \in[t-1]$ fix a directed orientation of $Q_{i}$. Clearly $H_{1}$ does not contain $\vec{C}$, and for each $i \in[t-1]$ every new $\ell$-cycle in $H_{i+1}$ contains a long block (since $Q_{i}$ is directed), so $F \nrightarrow \vec{C}$.
$\rightarrow$ Case 1. There is precisely one index $i \in[t-1]$ such that type $(i)=\left(A_{\ell-1}\right)$.
Let $Q_{i}=x_{i} v z_{i}$ and let $C$ be an $\ell$-cycle in $H_{i}$ containing $z_{i}$. We may assume that $H_{1}=C$. Note that $e\left(Q_{j}\right) \geqslant 3$ for each $j \in[t-1] \backslash\{i\}$ since (by Proposition 19) type $(j) \in\left\{\left(A_{2}\right),\left(A_{3}\right)\right\}$. We orient $F$ as follows.

Firstly, orient $H_{1}$ so that $z_{i}$ is the origin of a long block, and so that $z_{i}$ has no inneighbours in $H_{1}$. Secondly, for each $j \in[i-1]$, orient $Q_{j}$ forming a directed path, while ensuring that $z_{i}$ has no inneighbours in $H_{j+1}$. (This is possible since, if $Q_{j}$ contains $z_{i}$, then $z_{i}$ is an endvertex of $Q_{j}$.) Orient $Q_{i}$ as a directed path from $x_{i}$ to $z_{i}$. Finally, for each $j \in[t-1] \backslash[i]$ orient $Q_{j}$ so as to form a directed path.

Clearly, the orientation of $H_{1}$ avoids $\vec{C}$. Since $e\left(Q_{j}\right) \geqslant 3$ for each $j \in[t-1] \backslash\{i\}$, each new $\ell$-cycle in $H_{j+1}$ has a long block (as it contains $Q_{j}$ ). Finally, every new cycle $C$ in $H_{i+1}$ must contain $Q_{i}$ as well as some edge $z_{i} z \in E\left(H_{i}\right)$. As $z_{i}$ has no inneighbours in $H_{i}$, the edge


Figure 1: Orientations in Case 2. Left: orientation of $H_{1}$; note $H_{1}$ has a long block starting from $z_{i}$ (since $\ell \geqslant 5$ ). Centre and right: orientations of $Q_{\alpha}$ (where $\alpha \neq i$ ); in the figure, $a \notin\left\{z_{i}\right\} \cup N, r \in N$ and $q \in\left\{z_{i}\right\} \cup N$, where $N:=N_{H_{i}}\left(z_{i}\right)$.
$z_{i} z$ extends the directed path $x_{i} \rightarrow v \rightarrow z_{i}$, forming a long block in $C$. This shows that every $\ell$-cycle has a long block, so $F \nrightarrow \vec{C}$.
$\rightarrow$ Case 2. There exists $i \in[t-1]$ such that type $(i)=\left(A_{\ell}\right)$.
Let $\alpha \in[t-1]$. By Proposition 19, if $\alpha \neq i$, then type $(\alpha) \in\left\{\left(A_{2}\right),\left(A_{3}\right)\right\}$, so $e\left(Q_{\alpha}\right) \geqslant 3$. We may assume that $H_{1}$ is an $\ell$-cycle in $H_{i}$ containing $z_{i}$. We orient the edges of $F$ as follows. Let $N$ be the set of neighbours of $z_{i}$ in $H_{i}$.

First orient $H_{1}$ with two blocks, each with length at least 2 and origin $z_{i}$ (see Figure 1). Next, for each $j \in[i-1]$, we do the following. If no endvertex of $Q_{j}$ lies in $\left\{z_{i}\right\} \cup N$, fix an arbitrary directed orientation of $Q_{j}$. If a single endvertex $q$ of $Q_{j}$ lies in $\left\{z_{i}\right\} \cup N$, then orient $Q_{j}$ to form a directed path with origin $q$. If both endvertices $q, r$ of $Q_{j}$ lie in $\left\{z_{i}\right\} \cup N$, where we assume $r \neq z_{i}$, then orient $Q_{j}$ so that it has precisely two blocks, starting from $q$ and $r$, and so that the latter has precisely one arc. Finally, orient $x_{i} \rightarrow z_{i}$, and for each $j \in[t-1] \backslash[i]$ fix a directed orientation of $Q_{j}$ (see Figure 1).

Let us check that every $\ell$-cycle in $F$ has a long block. This is clearly true in $H_{1}$. Now suppose $\alpha \in[t-1] \backslash\{i\}$. Note that each new cycle in $H_{\alpha+1}$ contains $Q_{\alpha}$ and that $e\left(Q_{\alpha}\right) \geqslant 3$ since type $(\alpha) \in\left\{\left(A_{2}\right),\left(A_{3}\right)\right\}$. Moreover, $Q_{\alpha}$ has a block of length at least $e\left(Q_{\alpha}\right)-1$ if $\alpha<i$, and a block of length at least $e\left(Q_{\alpha}\right)$ if $\alpha>i$. Hence, if $e\left(Q_{\alpha}\right) \geqslant 4$ or if $\alpha>i$, then $Q_{\alpha}$ has a long block. So we may suppose that $\ell=5, e\left(Q_{\alpha}\right)=3$ and $\alpha \in[i-1]$. Hence type $(\alpha)=\left(A_{3}\right)$ and there is precisely one new 5 -cycle $C$ in $H_{\alpha+1}$ (as otherwise two 3 -paths joining $x_{\alpha}$ and $z_{\alpha}$, would form a 4 -cycle in $H_{\alpha}$, contradicting Remark 21). If $\left|\left\{x_{\alpha}, z_{\alpha}\right\} \cap\left(\left\{z_{i}\right\} \cup N\right)\right| \leqslant 1$, then $C$ has a long block containing $Q_{\alpha}$. Otherwise, $\left\{x_{\alpha}, z_{\alpha}\right\} \subseteq\left\{z_{i}\right\} \cup N$. Note that $x_{\alpha} z z_{\alpha} \subseteq H_{\alpha}$ for some $z \in V\left(H_{\alpha}\right)$ since $C \subseteq H_{\alpha+1}$; if $z_{i} \in\left\{x_{\alpha}, z_{\alpha}\right\}$, then $x_{\alpha} z_{\alpha} \in E\left(H_{i}\right)$, so $x_{\alpha} z_{\alpha} z x_{\alpha}$ is a triangle in $H_{i}$, contradicting Remark 21. Therefore $z_{i} \notin\left\{x_{\alpha}, z_{\alpha}\right\}$, so $C=Q_{\alpha} \cup x_{\alpha} z_{i} z_{\alpha}$ (since $z \neq z_{i}$ implies $x_{\alpha} z z_{\alpha} z_{i} x_{\alpha}$ is a 4 -cycle in $H_{i}$, which contradicts Remark 21). Since $Q_{\alpha}$ has a directed 3-path from either $x_{\alpha}$ or $z_{\alpha}$ to a vertex $w \in V\left(Q_{\alpha}\right) \backslash V\left(H_{\alpha}\right)$, and both $x_{\alpha}$ and $z_{\alpha}$ are outneighbours of $z_{i}$, it follows that $C$ has a long block.

To conclude Case 2, we consider the new $\ell$-cycles in $H_{i+1}$. Each of these cycles contains the arc $x_{i} \rightarrow z_{i}$, so it suffices to show that every 3 -path $z_{i} z w$ in $H_{i}$ is directed from $z_{i}$ to $w$. Note that for each $j \in[i-1]$ and each pair of distinct new edges $e_{1}, e_{2}$ in $H_{j+1}$, there exist distinct new vertices $v_{1} \in e_{1}, v_{2} \in e_{2}$ in $H_{j+1}$. It follows that either $z_{i} z w \subseteq H_{1}$; or $z w \subseteq Q_{\alpha}$ and $z$ is an endvertex of $Q_{\alpha}$ for some $\alpha \in[i-1]$; or $z_{i} z w \subseteq Q_{\beta}$ and $z_{i}$ is an endvertex of $Q_{\beta}$ for some $\beta \in[i-1]$. In each of these cases $z_{i} z w$ has the required orientation.

Since every $\ell$-cycle of $F$ is a long block and $F \nrightarrow \vec{C}$.
$\rightarrow$ Case 3. There exist $i, j \in[t-1]$ such that type $(i)=\operatorname{type}(j)=\left(A_{\ell-1}\right)$.
By Proposition 19 we have $\ell=5$ and type $(\alpha)=\left(A_{2}\right)$ for each $\alpha \in[t-1] \backslash\{i, j\}$. We may suppose $i<j$. Let $P=x_{i} u_{2} u_{3} z_{i} \subseteq H_{i}$ and $Q=x_{j} v_{2} v_{3} z_{j} \subseteq H_{j}$, and let $Q_{i}=x_{i} u_{5} z_{i}$ and


Figure 2: Unions of distinct 4-paths with common endvertices.
$Q_{j}=x_{j} v_{5} z_{j}$. By Remark 20, every cycle in $H_{i}$ has length congruent to 2 modulo 3 , so $H_{i}$ contains no $C_{3}$, no $C_{4}$ and no $C_{6}$. In particular, since the union of internally disjoint 4-paths with common ends contains $C_{3}, C_{4}$ or $C_{6}$ cycle of length 3,4 or 6 (see Figure 2), we conclude that $P$ is the unique 4-path between $x_{i}$ and $z_{i}$ in $H_{i}$, and hence the unique such path in $H_{i+1}$. The argument splits into three cases according to how the 5 -cycles in $H_{i}$ intersect $P$.
$\rightarrow$ Case (a). There exists a 5 -cycle $C$ in $H_{i}$ containing $P$.
We may assume $H_{1}=C$ and $i=1$. Let $C=x_{i} u_{2} u_{3} z_{i} x x_{i}$ (so $H_{2}=H_{i+1}=C \cup x_{i} u_{5} z_{i}$ ). We first prove that

$$
\begin{equation*}
H_{j} \text { contains no } C_{3}, \text { no } C_{6} \text {, and precisely one } C_{4} \tag{1}
\end{equation*}
$$

Crucially, note that a step of type $\left(A_{2}\right)$ cannot create a $C_{3}$ or a $C_{4}$. Therefore, since $H_{1} \simeq C_{5}$, each $C_{3}$ and each $C_{4}$ in $H_{j}$ were created in the $i$-th step resulting in $H_{i+1}$. Since $H_{i+1}$ is the union of $C$ and $z_{i} u_{5} x_{i}$, we conclude that $C_{3} \nsubseteq H_{i+1}$, so $C_{3} \nsubseteq H_{j}$; moreover, the unique $C_{4} \subseteq H_{j}$ is $x_{i} x z_{i} u_{5} x_{i}$. It remains to show that $H_{j}$ contains no $C_{6}$. Suppose, looking for a contradiction, that $\alpha \in[j-1]$ is the smallest index such that $H_{\alpha+1}$ has a 6 -cycle $C^{\prime}$. Note that $H_{i+1}$ contains no $C_{6}$, so $\alpha>i$. Since type $(\alpha)=\left(A_{2}\right)$, it follows that $C^{\prime}$ contains a path $a b c d e$ whose edges are new in $H_{\alpha+1}$, so $C^{\prime}=a b c d e f a$ for some $f \in V\left(H_{\alpha}\right)$. Moreover, $a b c d e a$ is a (new) 5 -cycle in $H_{\alpha+1}$. We conclude that aefa is a 3 -cycle in $H_{\alpha}$, a contradiction since $C_{3} \nsubseteq H_{j}$. This proves (1).

Claim 22. There exists $e \in E\left(H_{j}\right)$ with $e \cap\left\{x_{j}, z_{j}\right\} \neq \varnothing$ which lies in every 4-path from $x_{j}$ to $z_{j}$ in $H_{j}$.

Proof. By (1), each 4-path between $x_{j}$ and $z_{j}$ in $H_{j}$ other than $Q$ intersects $x_{j} v_{2} v_{3} z_{j}$ (i.e., $Q$ ) in precisely one edge $h$; moreover, $h \neq v_{2} v_{3}$ (as $C_{3} \nsubseteq H_{j}$, see Figure 2). If Claim 22 is false, then there are paths $x_{j} x v_{3} z_{j}$ and $x_{j} v_{2} y z_{j}$ in $H_{j}$ with $x \neq v_{2}$ and $y \neq v_{3}$. But this contradicts (1), because then either $H_{j}$ has a 3 -cycle $x_{j} x v_{2} x_{j}$ (if $x=y$ ) or $H_{j}$ contains two distinct 4-cycles $x_{j} x v_{3} v_{2} x_{j}$ and $v_{2} v_{3} z_{j} y v_{2}$ (if $x \neq y$ ).

We now return to the proof of Case (a), describing the orientation of $F$. Let $e$ be the edge common to all 4-paths between $x_{j}$ and $z_{j}$ in $H_{j}$ (as per Claim 22). Orient $H_{1}$ so that it is a directed cycle. For every $\alpha \in[t-1] \backslash\{j\}$, orient the new edges to form a directed path. Finally, orient $x_{j} v_{5} z_{j}$ so that the path it forms with $e$ is directed.

Let us check that every 5-cycle in $F$ has a long block. Clearly, the two 5 -cycles in $H_{2}$ have each a long block. For each $\alpha \in[t-1] \backslash\{i, j\}$, each new 5 -cycle in $H_{\alpha+1}$ contains $Q_{\alpha}$ and hence has a long block $\left(e\left(Q_{\alpha}\right) \geqslant 3\right.$ since type $\left.(\alpha)=\left(A_{2}\right)\right)$. Finally, every new 5 -cycle in $H_{j+1}$ contains the directed path formed by $e$ and $x_{j} v_{5} z_{j}$. We conclude that $F \nrightarrow \vec{C}$.
$\rightarrow$ Case (b). There exists a 5 -cycle $C$ in $H_{i}$ containing precisely two edges of $P$.
We may assume that no 5-cycle in $H_{i}$ contains all edges of $P$, otherwise we would be done by Case (a). Note that cannot avoid $u_{2} u_{3}$, since $C_{3} \nsubseteq H_{i}$. We may therefore assume that $C$ is a 5 -cycle in $H_{i}$ with $z_{i} u_{3} u_{2} \subseteq C$ and that $H_{1}=C$.

Let $\alpha \in[t-1]$ be such that $u_{2} x_{i}$ is new in $H_{\alpha+1}$, and let $C_{\alpha}$ be a new 5 -cycle in $H_{\alpha+1}$ containing $u_{2} x_{i}$. Note that type $(\alpha)=\left(A_{2}\right)$, so $Q_{\alpha}=u_{2} x_{i} x y v$, where $u_{2}, v \in V\left(H_{\alpha}\right)$ and $x_{i}, x, y \notin V\left(H_{\alpha}\right)$. We modify the construction sequence of $F$, to a construction sequence of $F$ where the $i$-th step is omitted and the $\alpha$-th step is replaced by consecutive steps adding, in this order, $u_{2} x_{i} u_{5} z_{i}$ and $x_{i} x y v$. In the new sequence, type $(\alpha)=\operatorname{type}(\alpha+1)=\left(A_{3}\right)$, $\operatorname{type}(j)=\left(A_{4}\right)=\left(A_{\ell-1}\right)$ and each other step remains of type $\left(A_{2}\right)$. By the argument in Case $2, F \nrightarrow \vec{C}$.
$\rightarrow$ Case (c). Every 5 -cycle in $H_{i}$ contains at most one edge of $P$.
This is similar to the preceding case. Let $C=H_{1}$ be a 5 -cycle containing $z_{i} u_{3}$. We first show that if $u_{2} u_{3}$ is new in $H_{\alpha+1}$ and $u_{2} x_{i}$ is new $H_{\beta+1}$, then $\alpha<\beta<i$. Indeed, $\alpha, \beta<i$ by definition, and $\alpha \neq \beta$ as otherwise the new cycles in $H_{\alpha+1}$ would contain two edges of $P$. Moreover, type $(\alpha)=\operatorname{type}(\beta)=\left(A_{2}\right)$ by Proposition 19 , so each new edge in $H_{\alpha+1}$ and $H_{\beta+1}$ must contain at least one new endvertex. Hence $\alpha<\beta$.

Let $Q_{\beta}=u_{2} x_{i} x y v$, where $u_{2}, v \in V\left(H_{\beta}\right)$ and $x_{i}, x, y \notin V\left(H_{\beta}\right)$. As in Case (b), we define an alternative construction sequence of $F$, where the $i$-th step is omitted and the $\beta$-th step is replaced by consecutive steps adding $u_{2} x_{i} u_{5} z_{i}$ and $x_{i} x y v$ (in this order). By Case $2, F \nrightarrow \vec{C}$.
$\rightarrow$ Case 4. There exists $i \in[t-1]$ such that type $(i)=\left(B_{j}\right)$, where $3 \leqslant j \leqslant \ell-1$.
By Proposition 19, for each $\alpha \in[t-1] \backslash\{i\}$ we have type $(\alpha)=\left(A_{2}\right)$, and thus $e\left(Q_{\alpha}\right) \geqslant 3$. Recall that $y_{i} \in V\left(Q_{i}\right) \cap H_{i}$. Note that no new cycle in $H_{i+1}$ avoids both $x_{i} Q_{i} y_{i}$ and $y_{i} Q_{i} z_{i}$.

If a new $\ell$-cycle in $H_{i+1}$ contains $x_{i} Q_{i} y_{i}$ but not $y_{i} Q_{i} z_{i}$, then some construction sequence of $F$ satisfies the hypothesis of one of the previous cases (by replacing the $i$-th step in $\left(H_{1}, \ldots, H_{t}\right)$ by consecutive steps adding $x_{i} Q_{i} y_{i}$ and $\left.y_{i} Q_{i} z_{i}\right)$, and $F \nrightarrow \vec{C}$. We argue similarly if a new $\ell$-cycle in $H_{i+1}$ avoids $x_{i} Q_{i} y_{i}$.

If every new $\ell$-cycle in $H_{i+1}$ contains all of $Q_{i}$, then for each $\alpha \in[t-1]$ every new cycle in $H_{\alpha+1}$ contains $Q_{\alpha}$. We fix a directed orientation of $H_{1}$ and orient $Q_{\alpha}$ as a directed path for each $\alpha \in[t-1]$. Then $H_{1}$ has a long block and for each $\alpha \in[t-1]$ the new $\ell$-cycles in $H_{\alpha+1}$ have a long block as well (since $e\left(Q_{\alpha}\right) \geqslant 3$ ). Therefore $F \nrightarrow \vec{C}$.

### 3.3.2 Cycles of length 4

To conclude this section we consider orientations of 4-cycles.
Theorem 23. Let $\vec{C}$ be an orientation of $C_{4}$. If $G$ is a graph and $m(G)<m_{2}\left(C_{4}\right)$, then $G \nrightarrow \vec{C}$.

To prove Theorem 23 we use the following proposition.
Proposition 24. Let $G=\left(H_{1}, \ldots, H_{t}\right)$ be a $C_{4}$-component such that $m(G)<m_{2}\left(C_{4}\right)$. If $\operatorname{type}(i)=\left(B_{3}\right)$ for some $i$, then type $(j)=\left(A_{2}\right)$ for each $j \in[t-1] \backslash\{i\}$.

Proof. For each $j \in[t-1]$, let $v_{j}$ and $e_{j}$ be respectively the number of new vertices and new edges in $H_{j+1}$, By Proposition 18 we have $e_{j} \geqslant 3 v_{j} / 2$ and $e_{j}>v_{j}$ for each $j \in[t-1]$. Suppose type $(i)=\left(B_{3}\right)$ and fix $j \in[t-1] \backslash\{i\}$. We have

$$
\frac{3}{2}=m_{2}\left(C_{4}\right)>m(G)=\frac{4+\sum_{\alpha \in[t-1]} e_{\alpha}}{4+\sum_{\alpha \in[t-1]} v_{\alpha}} \geqslant \frac{4+3+e_{j}+\sum_{\alpha \in[t-1] \backslash\{i, j\}} 3 v_{\alpha} / 2}{4+1+v_{j}+\sum_{\alpha \in[t-1] \backslash\{i, j\}} v_{\alpha}}
$$

so $v_{j}>2\left(e_{j}-v_{j}\right)-1$. Hence $v_{j} \geqslant 2$ (because $\left.v_{j}<e_{j}\right)$ and type $(j)=\left(A_{2}\right)$.
Proof of Theorem 23. If $\vec{C}$ is anti-directed or contains a long block, then $G \nrightarrow \vec{C}$ by Corollary 14 and Theorem 15, respectively. We may therefore assume $\vec{C}$ has precisely two
blocks of length 2 ; we may also assume that $G$ is a $C_{4}$-component with construction sequence $\left(H_{1}, \ldots, H_{t}\right)$, because distinct $C_{4}$-components can be independently oriented and edges in no $C_{4}$-component can be arbitrarily oriented.

If there is no step of type $B_{3}$, then $G$ is bipartite. (Indeed, $H_{1} \simeq C_{4}$ and steps of type $\left(A_{2}\right),\left(A_{3}\right)$, or $\left(A_{4}\right)$ preserve bipartiteness.) Fix a proper 2-colouring of $G$ and orient every edge towards the same colour class. This avoids directed paths with length 2 , so $G \nrightarrow \vec{C}$.

On the other hand, if type $(i)=\left(B_{3}\right)$, then every other step is of type $\left(A_{2}\right)$ by Proposition 24 . Let $u_{1} u_{2} u_{3} u_{4} u_{1}$ be the new cycle in $H_{i+1}$, where $u_{1} u_{2} \in H_{i}$ (and $u_{2} u_{3}, u_{3} u_{4}, u_{4} u_{1} \notin E\left(H_{i}\right)$, $\left.u_{1}, u_{2}, u_{3} \in V\left(H_{i}\right), u_{4} \notin V\left(H_{i}\right)\right)$. We may assume that $H_{1}$ is a 4-cycle $u_{1} u_{2} a b u_{1}$.

If every new 4-cycle in $H_{i+1}$ contains $u_{2} u_{3} u_{4} u_{1}$, we orient $H_{1}$ as a directed cycle and the new edges in each step as directed paths. Clearly $H_{1}$ has a long block and, for each $\alpha \in[t-1]$, every new 4 -cycle in $H_{\alpha+1}$ contains a long block (formed by $Q_{\alpha}$ ), so $G \nrightarrow \vec{C}$.

Finally, if a 4-cycle in $H_{i}$ contains $u_{2} u_{3}$ but avoids $u_{3} u_{4} u_{1}$, then we may replace the $i$-th step (of type $\left(B_{3}\right)$ ) by one $\left(A_{4}\right)$-step (adding $u_{2} u_{3}$ ) and one ( $A_{3}$ )-step (adding $u_{3} u_{4} u_{1}$ ). This yields a construction sequence free from $\left(B_{3}\right)$, which implies (as argued above) that $G$ is bipartite and $G \nrightarrow \vec{C}$. Similarly, if $H_{i}$ contains a new 4 -cycle which avoids $u_{2} u_{3}$, then we may replace the $i$-th step by one $\left(A_{3}\right)$-step (adding $u_{3} u_{4} u_{1}$ ) and one $\left(A_{4}\right)$-step (adding $\left.u_{2} u_{3}\right)$, and also conclude that $G \nrightarrow \vec{C}$.

## 4 Proof of the main theorem (Theorem 2)

Theorem 8 establishes the case $t=3$ of Theorem 2. We may therefore suppose $\vec{H}$ is either an acyclic orientation of $H \in\left\{K_{t}, C_{t}\right\}$, with $t \geqslant 4$, or that $\vec{H}$ is an anti-directed orientation of a strictly 2-balanced graph $H$ with $\delta(H) \geqslant 2$. In each one of these cases $\vec{H}$ is 2-Ramsey-avoidable (by Remark 6), so (by Theorems 1 and 3 together with Lemmas 5 and 7) it suffices to show that $G \nrightarrow \vec{H}$ whenever $m(G)<m_{2}(H)$. Indeed, this follows by Theorem 12 (when $H$ is complete), Theorems 17 and 23 (when $H$ is a cycle) and by Corollary 14 otherwise.

## 5 Concluding remarks

We have shown that if $\vec{H}$ is an oriented clique or cycle, then the threshold for $G(n, p) \rightarrow \vec{H}$ is $n^{-1 / m_{2}(\vec{H})}$ if and only if $\vec{H} \neq \mathrm{TT}_{3}$. Interestingly, $\mathrm{TT}_{3}$ is not the only exception. For instance, let $\vec{G}$ be the digraph obtained from an oriented tree $\vec{T}$ of order $n^{1 / 2-\varepsilon}$, for any fixed $\varepsilon>0$, by identifying with each $v \in V(\vec{T})$ the source of a distinct copy $\vec{H}_{v}$ of $\mathrm{TT}_{3}$. It can be shown that $p_{\vec{G}} \ll n^{-1 / m_{2}(\vec{G})}=n^{-1 / m_{2}\left(\mathrm{TT}_{3}\right)}$. In a forthcoming paper, the authors describe a richer class of digraphs with this property.

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