Relatively Hyperbolic Groups with Semistable Peripheral Subgroups

M. Haulmark and M. Mihalik

May 3, 2021

Abstract

Suppose G is a finitely presented group that is hyperbolic relative to \mathbf{P} a finite collection of finitely generated proper subgroups of G. Our main theorem states that if each $P \in \mathbf{P}$ has semistable fundamental group at ∞ , then G has semistable fundamental group at ∞ . The problem reduces to the case when G and the members of \mathbf{P} are all one ended and finitely presented. In that case, if the boundary $\partial(G, \mathbf{P})$ has no cut point, then G was already known to have semistable fundamental group at ∞ . We consider the more general situation when $\partial(G, \mathbf{P})$ contains cut points.

1 Introduction

We are interested in the asymptotic behavior of relatively hyperbolic groups. We consider a property of finitely presented groups that has been well studied for over 40 years called semistable fundamental group at ∞ . A locally finite complex Y has semistable fundamental group at ∞ if any two proper rays $r, s : [0, \infty) \to Y$ that converge to the same end of Y are properly homotopic in Y. A finitely presented group G has semistable fundamental group at ∞ if for some (equivalently any) finite complex X with $\pi_1(X) = G$, the universal cover of X has semistable fundamental group at ∞ . (See section 3 for several equivalent notions of semistability.) It is unknown at this time, whether or not all finitely presented groups have semistable fundamental group at ∞ , but in [Mih87] the problem is reduced to considering 1-ended groups. The finitely presented group G satisfies a weaker geometric condition called semistable first homology at ∞ if and only if $H^2(G : \mathbb{Z}G)$ is free abelian (see [GM85]). The question of whether or not $H^2(G : \mathbb{Z}G)$ is free abelian for all finitely presented groups G goes back to H. Hopf. Our main interest is in showing certain relatively hyperbolic groups have semistable fundamental group at ∞ . The work of B. Bowditch [Bow99] and G. Swarup [Swa96] shows that if G is a 1-ended word hyperbolic group then ∂G , the Gromov boundary of G, has no (global) cut point. M. Bestvina and G. Mess [BM91] (Propositions 3.2 and 3.3) show the absence of cut points in ∂G implies ∂G is locally connected. It was pointed out by R. Geoghegan that G has semistable fundamental group at ∞ if and only if ∂G has the shape of a locally connected continuum (see [DS78] for a proof of this fact). In particular, all 1-ended word hyperbolic groups have semistable fundamental group at ∞ .

Relatively hyperbolic groups are a much studied generalization of hyperbolic groups. Semistability only makes sense for finitely generated groups. We only consider finitely presented groups G in our main result. Later in this section and again in §5, we say what it means for a finitely generated group to be hyperbolic relative to a finite collection of finitely generated subgroups. If a finitely generated group G is hyperbolic relative to a collection of finitely generated subgroups **P** the pair (G, \mathbf{P}) has a well-defined compact metric boundary (see §5), denoted $\partial(G, \mathbf{P})$. While all 1-ended hyperbolic groups have locally connected boundary without cut points, the space $\partial(G, \mathbf{P})$ may contain cut points. When $\partial(G, \mathbf{P})$ is connected, it is locally connected (see Theorem 2.3) and the Hahn-Mazurkiewicz Theorem (see Theorem 31.5 of [Wil70] implies it is the continuous image of the interval [0, 1]. This implies $\partial(G, \mathbf{P})$ is path connected and locally path connected, these facts are important in our approach to showing the relatively hyperbolic groups we consider have semistable fundamental group at ∞ . The main theorem of [MSb] solves a semistability problem when $\partial(G, \mathbf{P})$ has no cut point. Note that there is no semistability hypothesis on the peripheral subgroups.

Theorem 1.1 (Theorem 1.1, [MSb]) Suppose G is a 1-ended finitely generated group that is hyperbolic relative to a collection of 1-ended finitely generated proper subgroups $\mathbf{P} = \{P_1, \ldots, P_n\}$. If $\partial(G, \mathbf{P})$ has no cut point, then G has semistable fundamental group at ∞ .

The primary semistability question for relatively hyperbolic groups following Theorem 1.1 is: **Conjecture 1.2** (Conjecture 2.1, [MSb]) Suppose G is a finitely generated group that is hyperbolic relative to a finite collection $\{P_1, \ldots, P_n\}$ of proper finitely generated subgroups. If each P_i has semistable fundamental group at ∞ , then G has semistable fundamental group at ∞ .

Some support for this conjecture appeared in the form of a result of C. Hruska and K. Ruane:

Theorem 1.3 ([*HR*], Theorem 1.1) Let (G, \mathbf{P}) be relatively hyperbolic with no non-central element of order two. Assume each peripheral subgroup $P \in \mathbf{P}$ is slender and coherent and all subgroups of P have semistable fundamental group at ∞ . Then G has semistable fundamental group at ∞ .

When G is finitely presented, the homology version of the conjecture is resolved by the main theorem of [MSa].

Theorem 1.4 (Theorem 1.1, [MSa]) Suppose G is a finitely presented group that is hyperbolic relative to a collection of finitely presented subgroups $\mathbf{P} = \{P_1, \ldots, P_n\}$. If each group $H^2(P_i, \mathbb{Z}P_i)$ is free abelian then $H^2(G, \mathbb{Z}G)$ is free abelian.

While several results in [MSa] are useful to us, the techniques of that paper are insufficient to resolve the conjecture. A new idea of nearly geodesic homotopies in a cusped space is developed here and it is fundamental in proving our results. The main theorem of our paper resolves the conjecture when G is finitely presented.

Theorem 1.5 (Main) Suppose G is a finitely presented group that is hyperbolic relative to a collection of finitely generated subgroups $\mathbf{P} = \{P_1, \ldots, P_n\}$. If each P_i has semistable fundamental group at ∞ then G has semistable fundamental group at ∞ .

All of our work is done in a "cusped" space X for (G, \mathbf{P}) (see §5). When X is Gromov hyperbolic then the pair (G, \mathbf{P}) is said to be *relatively hyperbolic* or that G is hyperbolic relative to \mathbf{P} . This cusped space is a locally finite 2-complex on which G acts by isometries, but not co-compactly (see §5). It follows from ([Bow12], §6 and §9) that the Bowditch boundary for a relatively hyperbolic pair (G, \mathbf{P}) agrees with the Gromov boundary of X. Throughout the paper this boundary is denoted $\partial(G, \mathbf{P})$ and is called the *boundary of the relatively hyperbolic pair* (G, \mathbf{P}) . The base space Y in X is a universal cover of a finite complex with fundamental group G. There are closed neighborhoods X_m of Y in X which are also universal covers of finite complexes with fundamental group G so G has semistable fundamental group at ∞ if and only if some (equivalently any) X_m has semistable fundamental group at ∞ . The proof of Theorem 9.3 shows that for some m, the space X_m (and hence G) has semistable fundamental group at ∞ .

Any proper ray in X_m is properly homotopic to a proper ray in Y. We show two nearly geodesic rays in Y are properly homotopic in X by nearly geodesic homotopies. Using Theorem 8.3, we cut out disks in the domains of our homotopies on which these homotopies stray out of X_m (for some large fixed integer m). The geodesic nature of our homotopies allows us to show that the disks can only occur in a locally finite way (see Claims 1 and 2 of the proof of Theorem 9.1) and hence we can properly fill in our homotopies on these disks by homotopies with image in X_m . This is where we use the hypothesis that the peripheral subgroups are 1-ended and semistable. The resulting homotopies are then combined in a standard way to finish the proof of the theorem. Our nearly geodesic homotopies and the local finiteness arguments of the Claims are the key insights that drive our proofs.

The remainder of the paper is organized as follows. The first order of business is to reduce our problem to the case where G is 1-ended and the peripheral subgroups are 1-ended and have semistable fundamental group at ∞ . This is accomplished in Section 2. Once the reduction is accomplished we need to know boundaries of the resulting relatively hyperbolic groups are path connected and locally path connected. This is accomplished in Section 2. Finally, groups covered by our Main Theorem and not covered by earlier results are described is Section 2. We develop basic semistability background in Section 3. Section 4 is a short section on hyperbolicity and thin triangles. In Section 5 we review the construction of cusped spaces for a relatively hyperbolic group and discuss some of its properties. We develop the idea of a *filter* and a *filter map* in Section 6. Filters are graphs in $[0,1] \times [0,\infty)$ that are geodesically mapped into our cusped space and allow us to produce nearly geodesic homotopies (filter maps). Theorem 6.3 is the main result of this section and all of our initial homotopies are built using this result. Triangulations of our cusped space and $[0,1] \times [0,\infty)$ are developed in Section 7. Filters maps are turned into our first simplicial homotopies in this section. Section 8 contains several tracking results. For each vertex vof Y we construction a geodesic ray r_v in X that stays close to Y. If s_v is a geodesic ray at the base point * in Y converging to the same boundary point as does r_v , then we show that each point of r_v is within δ (the hyperbolicity constant for X) of s_v . The rays r_v are important in the construction of filters and filter maps. Theorem 6.1 of [MSa] is introduced in order to cut out the parts of our simplicial homotopies that leave X_m . Finally, our Main Theorem is proved in Section 9.

2 A Reduction to the One-Ended Case

We begin with a finitely presented group G and a finite collection \mathbf{P} of finitely generated subgroups of G such that G is hyperbolic relative to \mathbf{P} . The members of \mathbf{P} are finitely presented by the following result (proved in [DG13]). For a more general result see [DG017], Theorem 2.11.

Theorem 2.1 ([DG13]) If the group G is finitely presented and hyperbolic relative to a finite collection of proper finitely generated subgroups P_i , then the P_i are finitely presented as well.

The reduction we want comes directly from:

Theorem 2.2 (Theorem 2.9, [MSb]) If Conjecture 1.2 holds true for the case when G and each P_i is finitely presented and 1-ended (and each P_i has semistable fundamental group at ∞), then the conjecture holds true in the more general setting where G and each P_i is finitely presented (with possibly more than 1-end), as long as the P_i have semistable fundamental group at ∞ .

In his thesis [Das20] A. Dasgupta proves that the only cut points in a connected boundary of a finitely generated relatively hyperbolic group are parabolic. Dasgupta combines this result with a result of Bowditch to prove:

Theorem 2.3 ([Das20]) When the Bowditch boundary of a finitely generated relatively hyperbolic group is connected, then it is locally connected.

As noted in the introduction, the Hahn-Mazurkiewicz Theorem combines with Theorem 2.3 to show:

Theorem 2.4 If G is finitely generated, 1-ended and hyperbolic relative to a finite collection \mathbf{P} of finitely generated subgroups then $\partial(G, \mathbf{P})$ is path connected and locally path connected. Results of B. Bowditch (see Theorem 2.13 of [MSb]) determine that cut points appear in $\partial(G, \mathbf{P})$ precisely when (G, \mathbf{P}) admits a non-trivial graph of groups decomposition that is a 'proper peripheral splitting'. Notice that in the following combination result of M. Mihalik and S. Tschantz, there is no restriction on the number of ends of any of the groups involved.

Theorem 2.5 [MT92] Suppose \mathcal{G} is a finite graph of groups decomposition of the finitely presented group G where each edge group is finitely generated and each vertex group is finitely presented with semistable fundamental group at ∞ . Then G has semistable fundamental group at ∞ .

Combining Theorems 1.1 and 2.5 with the splitting result of Bowditch shows many relatively hyperbolic groups (with boundary cut points) have semistable fundamental group at ∞ , but a broad collection of examples are described near the end of Section 2 of [MSb] that are covered by the Main Theorem of this paper and not by previous results. In particular, for any finitely generated (but not finitely presented) recursively presented group Qand finitely presented group P containing a subgroup isomorphic to Q, a finitely presented group $G = A *_Q P$ is described that is hyperbolic relative to P. Here A is finitely generated but not finitely presented. If P has semistable fundamental group at ∞ then our Main Theorem 1.5 implies Ghas semistable fundamental group at ∞ . The techniques of [MSb] break down for such groups.

3 Semistability Background

The best reference for the notion of semistable fundamental group at ∞ is [Geo08] and we use this book as a general reference throughout this section. While semistability makes sense for multiple ended spaces, we are only interested in 1-ended spaces in this article. Suppose K is a locally finite connected CW complex. A ray in K is a continuous map $r : [0, \infty) \to K$. A continuous map $f : X \to Y$ is proper if for each compact set C in Y, $f^{-1}(C)$ is compact in X. Proper rays $r, s : [0, \infty) \to K$ converge to the same end if for any compact set C in K, there is an integer k(C) such that $r([k, \infty))$ and $s([k, \infty))$ belong to the same component of K - C. The space K has semistable fundamental group at ∞ if any two proper rays $r, s : [0, \infty) \to K$ that converge to the same end are properly homotopic (there is a proper map $H : [0, 1] \times [0, \infty) \to X$ such that H(0, t) = r(t) and H(1, t) = s(t)).

Note that when K is 1-ended, this means that K has semistable fundamental group at ∞ if any two proper rays in K are properly homotopic. Suppose C_0, C_1, \ldots is a collection of compact subsets of a locally finite 1-ended complex K such that C_i is a subset of the interior of C_{i+1} and $\bigcup_{i=0}^{\infty} C_i = K$, and $r : [0, \infty) \to K$ is proper, then $\pi_1^{\infty}(K, r)$ is the inverse limit of the inverse system of groups:

$$\pi_1(K-C_0,r) \leftarrow \pi_1(K-C_1,r) \leftarrow \cdots$$

This inverse system is pro-isomorphic to an inverse system of groups with epimorphic bonding maps if and only if K has semistable fundamental group at ∞ (see Theorem 2.1 of [Mih83] or Theorem 16.1.2 of [Geo08]). It is an elementary exercise to see that semistable fundamental group at ∞ is an invariant of proper homotopy type and S. Brick [Bri93] proved that semistability is a quasi-isometry invariant. When K is 1-ended with semistable fundamental group at ∞ , $\pi_1^{\infty}(K, r)$ is independent of proper base ray r (in direct analogy with the fundamental group of a path connected space being independent of base point). Theorem 2.1 of [Mih83] and Lemma 9 of [Mih86], provide several equivalent notions of semistability. Conditions 2 and 3 are the semistability criterion used in the proof of our main theorem.

Theorem 3.1 Suppose K is a connected 1-ended locally finite and simply connected CW-complex. Then the following are equivalent:

- 1. Any two proper rays in K are properly homotopic.
- 2. If r and s are proper rays based at v, then r and s are properly homotopic $rel\{v\}$.
- 3. Given a compact set C in K there is a compact set D in K such that if r and s are proper rays based at v and with image in K - D, then r and s are properly homotopic rel $\{v\}$ in K - C.

If G is a finitely presented group and X is a finite connected complex with $\pi_1(X) = G$ then G has semistable fundamental group at ∞ if the universal cover of X has semistable fundamental group at ∞ . This definition only depends on G (see the proof of Theorem 3 of [LR75] or the opening paragraph of section 16.5 of [Geo08]) and it is unknown if all finitely presented groups have semistable fundamental group at ∞ .

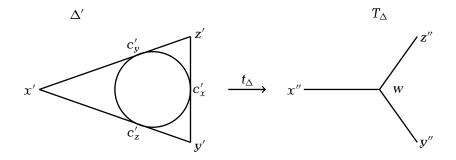


Figure 1: Internal points

4 Hyperbolicity

There are a number of equivalent forms of hyperbolicity for geodesic metric spaces. In this paper we use the following *thin triangles* definition.

Definition 1. Suppose (X, d) is a geodesic metric space. If $\triangle(x, y, z)$ is a geodesic triangle in X, let $\triangle'(x', y', z')$ be a Euclidean comparison triangle (i.e. d'(x', y') = d(x, y) etc., where d' is the Euclidean metric.) There is a surjection $f : \triangle' \to \triangle$ which is an isometry on each side of \triangle' . The maximum inscribed circle in \triangle' meets the side [x', y'] (respectively [x', z'], [y', z']) in a point c'_z (resp. c'_y, c'_x) such that

$$d(x',c_z') = d(x',c_y'), \ d(y',c_x') = d(y',c_z'), \ d(z',c_y') = d(z',c_x').$$

Let $c_x = f(c'_x)$, $c_y = f(c'_y)$ and $c_z = f(c'_z)$. We call the points c_x, c_y, c_z the *internal points* of \triangle . There is a unique continuous function $t_{\triangle} : \triangle' \to T_{\triangle}$ of \triangle' onto a tripod T_{\triangle} , where t_{\triangle} is an isometry on the edges of \triangle' , and T_{\triangle} is a tree with one vertex w of degree 3, and vertices x'', y'', z'' each of degree one, such that $d(w, z'') = d(z', c'_y) = d(z', c'_x)$ etc. (See Figure 1.)

Let f_{\triangle} be the composite map $f_{\triangle} \equiv t_{\triangle} \circ f^{-1} : \triangle \to T_{\triangle}$. We say that $\triangle(x, y, z)$ is $\delta - thin$ if fibers of f_{\triangle} have diameter at most δ in X. In other

words, for all p, q in \triangle ,

$$f_{\triangle}(p) = f_{\triangle}(q)$$
 implies $d_X(p,q) \le \delta$.

The space X is (δ) hyperbolic if there is a constant δ such that all geodesic triangles in X are δ thin.

In a hyperbolic geodesic metric space X the boundary ∂X can be defined in a number of ways. In Section III.H.3 of [BH99] ∂X is defined as the set of equivalence classes [r] of geodesic rays r, where r and s are equivalent if there is a number $K \ge 0$ such that $d(r(k), s(k)) \le K$ for all $k \ge 0$. We say rconverges to [r]. Note that if such a K exists for r, s based at p, then our thin triangle condition forces $d(r(k), s(k)) \le \delta$ for all $k \ge 0$. (Simply consider the geodesic triangle formed by r([0, k + K]), s([0, k + K]) and a geodesic (of length $\le K$) connecting r(k + K) to s(k + K). The internal points on r and s are beyond r(k) and s(k) respectively.)

If X is a δ hyperbolic geodesic metric space then there is a metric d on ∂X (induced from an inner product on X) such that $(\partial X, d)$ is compact (see Proposition 3.7 [BH99]). Intuitively, if r(0) = s(0) then [r] is 'close' to [s] if r and s fellow travel for a 'long' time.

5 Cusped Spaces and Relatively Hyperbolic Groups

Given a finitely generated group G and a collection of finitely generated subgroups \mathbf{P} of G there are a number of equivalent definitions of what it means for the pair (G, \mathbf{P}) to be relatively hyperbolic or G to be relatively hyperbolic with respect to \mathbf{P} . Theorem 5.2 enables us to say the pair (G, \mathbf{P}) is relatively hyperbolic if a certain cusped space is Gromov hyperbolic, so we take this as our definition. The Gromov boundary of this cusped space is the boundary of the pair (G, \mathbf{P}) and is denoted $\partial(G, \mathbf{P})$. This boundary agrees with the Bowditch boundary of the pair (G, \mathbf{P}) .

D. Groves and J. Manning [GM08] investigate a locally finite space X derived from a finitely generated group G and a collection **P** of finitely generated subgroups. The following definitions are directly from [GM08]

Definition 2. Let Γ be any 1-complex. The combinatorial *horoball* based on Γ , denoted $\mathcal{H}(\Gamma)$, is the 2-complex formed as follows:

A) $\mathcal{H}^{(0)} = \Gamma(0) \times (\{0\} \cup \mathbb{N})$

B) $\mathcal{H}^{(1)}$ contains the following three types of edges. The first two types are called horizontal, and the last type is called vertical.

(B1) If e is an edge of Γ joining v to w then there is a corresponding edge \bar{e} connecting (v, 0) to (w, 0).

(B2) If k > 0 and $0 < d_{\Gamma}(v, w) \le 2^k$, then there is a single edge connecting (v, k) to (w, k).

(B3) If $k \ge 0$ and $v \in \Gamma^{(0)}$, there is an edge joining (v, k) to (v, k+1).

C) $\mathcal{H}^{(2)}$ contains three kinds of 2-cells:

(C1) If $\gamma \subset \mathcal{H}^{(1)}$ is a circuit composed of three horizontal edges, then there is a 2-cell (a horizontal triangle) attached along γ .

(C2) If $\gamma \subset \mathcal{H}^{(1)}$ is a circuit composed of two horizontal edges and two vertical edges, then there is a 2-cell (a vertical square) attached along γ .

(C3) If $\gamma \subset \mathcal{H}^{(1)}$ is a circuit composed of three horizontal edges and two vertical ones, then there is a 2-cell (a vertical pentagon) attached along γ , unless γ is the boundary of the union of a vertical square and a horizontal triangle.

Definition 3. Let Γ be a graph and $\mathcal{H}(\Gamma)$ the associated combinatorial horoball. Define a *depth function*

$$\mathcal{D}:\mathcal{H}(\Gamma)\to[0,\infty)$$

which satisfies:

(1) $\mathcal{D}(x) = 0$ if $x \in \Gamma$,

(2) $\mathcal{D}(x) = k$ if x is a vertex (v, k), and

(3) \mathcal{D} restricts to an affine function on each 1-cell and on each 2-cell.

Definition 4. Let Γ be a graph and $\mathcal{H} = \mathcal{H}(\Gamma)$ the associated combinatorial horoball. For $n \geq 0$, let $\mathcal{H}_n \subset \mathcal{H}$ be the full sub-graph with vertex set $\Gamma^{(0)} \times \{0, \ldots, N\}$, so that $\mathcal{H}_n = \mathcal{D}^{-1}[0, n]$. Let $\mathcal{H}^n = \mathcal{D}^{-1}[n, \infty)$ and $\mathcal{H}(n) = \mathcal{D}^{-1}(n)$. The set $\mathcal{H}(n)$ is often called a *horosphere* or n^{th} level horosphere.

Lemma 5.1 (Lemma 3.10, [GM08]) Let $\mathcal{H}(\Gamma)$ be a combinatorial horoball. Suppose that $x, y \in \mathcal{H}(\Gamma)$ are distinct vertices. Then there is a geodesic $\gamma(x, y) = \gamma(y, x)$ between x and y which consists of at most two vertical segments and a single horizontal segment of length at most 3.

Moreover, any other geodesic between x and y is Hausdorff distance at most 4 from this geodesic.

Definition 5. Let G be a finitely generated group, let $\mathbf{P} = \{P_1, \ldots, P_n\}$ be a (finite) family of finitely generated subgroups of G, and let S be a generating set for G containing generators for each of the P_i . For each $i \in \{1, \ldots, n\}$, let T_i be a left transversal for P_i (i.e. a collection of representatives for left cosets of P_i in G which contains exactly one element of each left coset).

For each i, and each $t \in T_i$, let $\Gamma_{i,t}$ be the full subgraph of the Cayley graph $\Gamma(G, S)$ which contains tP_i . Each $\Gamma_{i,t}$ is isomorphic to the Cayley graph of P_i with respect to the generators $P_i \cap S$. Then define

$$X(G, \mathbf{P}, S) = \Gamma(G, S) \cup (\cup \{\mathcal{H}(\Gamma_{i,t})^{(1)} | 1 \le i \le n, t \in T_i\}),$$

where the graphs $\Gamma_{i,t} \subset \Gamma(G,S)$ and $\Gamma_{i,t} \subset \mathcal{H}(\Gamma_{i,t})$ are identified in the obvious way.

The space $X(G, \mathbf{P}, S)$ is called the *cusped* space for G, \mathbf{P} and S. If G and the P_i have finite presentations, let $\mathcal{A} = \langle S; R \rangle$ be such a presentation that includes sub-presentations of the P_i . We add 2-cells to $\Gamma(G, S)$ to form the Cayley 2-complex of this presentation. The resulting expansion of $X(G, \mathbf{P}, S)$ is called the cusped space for G, \mathbf{P} and \mathcal{A} and is denoted $X(G, \mathbf{P}, \mathcal{A})$. The next result shows cusped spaces are fundamentally important spaces. We prove our results in cusped spaces.

Theorem 5.2 (Theorem 3.25, [GM08]) Suppose that G is a finitely generated group and $\mathbf{P} = \{P_1, \ldots, P_n\}$ is a finite collection of finitely generated subgroups of G. Let S be a finite generating set for G containing generating sets for the P_i . A cusped space $X(G, \mathbf{P}, S)$ is hyperbolic if and only if G is hyperbolic with respect to \mathbf{P} .

Assume G is finitely presented and hyperbolic with respect to the subgroups $\mathbf{P} = \{P_1, \ldots, P_n\}$ and S is a finite generating set for G containing generating sets for the P_i . The P_i and their conjugates are called *peripheral* subgroups of G. For a finite presentation \mathcal{A} of G with respect to S, let $Y(\mathcal{A})$ be the Cayley 2-complex for \mathcal{A} . So Y is simply connected with 1-skeleton $\Gamma(G, S)$, and the quotient space G/Y has fundamental group G. The cusped space $X(G, \mathbf{P}, S)$ is quasi-isometric to the cusped space $X(G, \mathbf{P}, \mathcal{A})$ and so one is hyperbolic if and only if the other is hyperbolic, and these two spaces have the same boundary. For $g \in G$ and $i \in \{1, \ldots, n\}$ we call gP_i a *peripheral coset* in a cusped space. The depth functions on the horoballs over the peripheral cosets extend to $X(G, \mathbf{P}, \mathcal{A})$. So that

$$\mathcal{D}: X(G, \mathbf{P}, \mathcal{A}) \to [0, \infty)$$

where $\mathcal{D}^{-1}(0) = Y$ and for each horoball H (over a peripheral coset) we have $H \cap \mathcal{D}^{-1}(m) = H(m), \ H \cap \mathcal{D}^{-1}[0,m] = H_m \text{ and } H \cap \mathcal{D}^{-1}[m,\infty) = H^m$. We call each H^m an *m*-horoball.

Lemma 5.3 (Lemma 3.26, [GM08]) If a cusped space X is δ -hyperbolic, then the m-horoballs of X are convex for all $m \geq \delta$.

Given two points x and y in a horoball H, there is a shortest path in H from x to y of the form (α, τ, β) where α and β are vertical and τ is horizontal of length ≤ 3 . Note that if α is non-trivial and ascending and β is non-trivial and descending, then τ has length either 2 or 3.

If $Y(\mathcal{A})$ is the Cayley 2-complex for the finite presentation \mathcal{A} of the group G, then the isometric action of G on Y extends to an isometric action of G on $X(G, \mathbf{P}, \mathcal{A})$. This action is height preserving. In the following lemmas, $X = X(G, \mathbf{P}, \mathcal{A})$.

Lemma 5.4 (Lemma 5.1, [MSb]) Suppose t_1 and t_2 are vertices of depth $\overline{d} \geq \delta$ in a horoball H of X. Then for each $i \in \{1, 2\}$, there is a geodesic γ_i from * to t_i such that γ_i has the form $(\eta_i, \alpha_i, \tau_i, \beta_i)$, where the end point x_i of η_i is the first point of γ_i in the horosphere $H(\overline{d})$, α_i and β_i are vertical and of the same length in $H^{\overline{d}}$ and τ_i is horizontal of length ≤ 3 . Furthermore $d(x_1, x_2) \leq 2\delta + 1$.

Lemma 5.5 (Lemma 2.28, [HM]) Let P be an element of **P**, g be an element of G and q be a closest point of gP to * (the identity vertix of Y). If ψ is a geodesic from * to gP that meets gP only in its terminal point, then the terminal point of ψ is within $6\delta + 4$ of q.

Lemma 5.6 (Lemma 4.4, [MSa]) Given an integer K, there is an integer $A_{5.6}(K)$ such that if γ is an edge path loop in X of length $\leq K$, then γ is homotopically trivial in $B_{A_{5.6}(K)}(v)$ for any vertex v of γ .

Lemma 5.7 (Lemma 3.3, [HM]) Suppose $\tilde{\lambda} = (\lambda, \psi, \bar{\lambda})$ is a cusp geodesic from $x \in qP$ to $y \in qP$ and $d(x, y) \geq 2\delta$. Let ν be a geodesic in X from xto y. Then $|\tilde{\lambda}| \leq |\nu| + \delta$ and the *i*th vertex of ν is within 2δ of the *i*th vertex of $\tilde{\lambda}$. If $|\nu| \leq n \leq |\tilde{\lambda}|$ then the n^{th} vertex of $\tilde{\lambda}$ is within 2δ of y. Finally, the mid point of ν is an interior point of the geodesic triangle with sides ν , the first half of $\tilde{\lambda}$ and the second half of $\tilde{\lambda}$.

6 Filters, Filter Maps and Metrics

Our reductions imply the group G is 1-ended as is each $P_i \in \mathbf{P}$. Let \mathcal{A} be a finite presentation for G that contains finite sub-presentations for the P_i . Let X be the cusped space $X(G, \mathbf{P}, \mathcal{A})$. The compact metric space $\partial(G, \mathbf{P})$ is path connected and locally path connected (Theorem 2.4). The space $Y \subset X$ is the Cayley 2-complex of \mathcal{A} . For a peripheral cos qP_i , let $\Gamma(qP_i)$ be the copy of the Cayley 2-complex of P_i in Y containing g. We use d for our metric on $\partial X = \partial(G, \mathbf{P})$. Any proper ray in X is properly homotopic to a proper edge path ray in the 1-skeleton of X. Hence when we show a space has semistable fundamental group at ∞ it suffices to show all proper edge path rays are properly homotopic. Since X is quasi-isomorphic to the 1-skeleton of X, one is hyperbolic if and only if the other is hyperbolic. Let d be the edge path metric on $X^{(1)}$, the 1-skeleton of X. If A is a subcomplex of $X^{(1)}$ let $B_n(A)$ be the neighborhood of radius n about A. For any subcomplex A of X, define St(A) to be A, union all vertices connected by an edge to a vertex of A, union all 2-cells of X all of whose vertices belong to St(A). Define $St_n(A)$ inductively as $St(St_{n-1}(A))$. Note that if $A^{(1)}$ is the 1-skeleton of A, then $B_n(A^{(1)})$ is the 1-skeleton of $St_n(A)$. In particular, if for $n \ge 1$, the 1-skeleton of $St_n(v)$ is $B_n(v)$ for all vertices v of X.

Definition 6. A filter F is the realization of a connected graph in $[0, 1] \times [0, \infty)$ with the following properties:

(1) Each vertex is of the form (t, n) for some integer $n \ge 0$ and some $t \in [0, 1]$. The points (0, 0) and (0, 1) are vertices of F.

(2) Each edge of F is either vertical or horizontal. A vertical edge is the convex hull of vertices (t, n) and (t, n+1). If (t, n) is a vertex of F, then (t, n) and (t, n+1) are the vertices of a vertical edge (so every vertex is connected by an edge to exactly one vertex directly above it).

(3) A horizontal edge is the convex hull of the vertices (t, n) and (s, n) for some integer $n \ge 0$ and numbers $0 \le t < s \le 1$. The horizontal edges at height n form an edge path from (0, n) to (1, n) with consecutive vertices $(0, n), (t_1, n), (t_2, n), \ldots, (1, n)$ where $t_i < t_{i+1}$ for all i. (Note that the first coordinates of vertices at height n are a subset of the first coordinates of vertices at height n + 1.)

Note that each component of $[0,1] \times [0,\infty) - F$ is a rectangle that is bounded by an edge path loop with exactly two vertical edges, one horizontal edge at height n and all other edges horizontal at height n + 1.

The idea is to build filters and proper homotopies that map any vertical edge path in the filter to a geodesic edge path in the 1-skeleton of X. Infinitely many of these homotopies will then be combined in a proper way to show that every proper ray in Y is properly homotopic to a certain (nearly geodesic) ray in Y by a proper homotopy in X_M for some fixed integer M.

Let $\delta \geq 1$ be the hyperbolicity constant for X. Given $\epsilon > 0$ there is $N(\epsilon) > 0$ such that if $x, y \in \partial X$ and r_x, r_y are geodesic edge path rays at * converging to x and y respectively with $d(r_x(N(\epsilon)), r_y(N(\epsilon))) \leq 2\delta + 1$ then $\hat{d}(x, y) \leq \epsilon$. Given N > 0 there is $\epsilon_1(N)$ such that if $x, y \in \partial X$ and $\hat{d}(x, y) < \epsilon_1(N)$ then for any geodesics r_x and r_y at * converging to x and y respectively, $d(r(N), s(N)) \leq 2\delta + 1$.

Since ∂X is compact, connected and locally path connected we have: Given $\epsilon > 0$ there is $\rho(\epsilon) > 0$ such that if $x, y \in \partial X$ and $\hat{d}(x, y) \leq \rho(\epsilon)$ then there is a path connecting x and y in ∂X of diameter $\leq \epsilon$. Combining these results we have:

Lemma 6.1 Given an integer N there is an integer $M_{6.1}(N) > N$ such that if r and s are geodesic edge path rays at $* \in X$ (converging to $x, y \in \partial X$ respectively) and $d(r(M_{6.1}(N)), s(M_{6.1}(N))) \leq 2\delta + 1$, then there is a path γ in ∂X from x to y such that for any two points w_1 and w_2 in the image of γ and any geodesic edge paths q_1 and q_2 at * converging to w_1 and w_2 respectively, $d(q_1(n), q_2(n)) \leq \delta$ for all $n \leq N$.

Remark 6.2 The next result provides the primary technical tool to proving our main theorem. It gives an analogue to a geodesic homotopy between two geodesic rays in a CAT(0) space. Suppose X is CAT(0). If s_0 and s_1 are geodesic rays at $* \in X$ and γ is a path in ∂X from $s_0 = \gamma(0)$ to $s_1 = \gamma(1)$, then there is a "geodesic" homotopy $H : [0,1] \times [0,\infty) \to X$ from s_0 to s_1 defined by $H(a,t) = \gamma(a)(t)$.

For technical reasons, we need the following result to apply to edge path rays s'_1 and s'_2 that are only "nearly" geodesic. In applications s'_i will be the concatenation of a finite edge path and a geodesic edge path ray. The edge path ray s'_i will synchronously track a geodesic edge path ray.

Theorem 6.3 Suppose $K \ge \delta$ is an integer, s_1 and s_2 are geodesic edge path rays at * in X such that $[s_1] \ne [s_2]$, and for $i \in \{1, 2\}$, s'_i is an edge path ray such that $d(s_i(t), s'_i(t)) \le K$ for all $t \in [0, \infty)$. Let γ be a path in ∂X from $[s_1] = [s'_1]$ to $[s_2] = [s'_2]$. There is a filter $F(s'_1, s'_2, \gamma, K)$ for $[0, 1] \times [0, \infty)$ and a proper homotopy $f : [0, 1] \times [0, \infty) \to X$ (called a filter map for F) of s'_1 to s'_2 rel $\{*\}$, such that:

(1) If (t, n) is a vertex of F with $t \notin \{0, 1\}$ then f restricted to $\{t\} \times [n, \infty)$ is the tail of a geodesic edge path at $* \in X$ representing an element of the path γ (in ∂X).

(2) Each horizontal edge of F is mapped to an edge path of length $\leq K + 2\delta$.

(3) If R (an open rectangle) is a component of $[0,1] \times [0,\infty) - F$ and α is the edge path loop bounding the rectangle R, then $f(\alpha)$ has image in $B_{2K+\delta+1}(f(v)) \subset X$ where v is the upper left vertex of R. Furthermore f(R) has image in $St_{A_{5,6}(2K+\delta+1)}(f(v))$.

(4) If v = (a, b) is a vertex of F and τ is the vertical segment of $[0, 1] \times [0, \infty)$ from (a, 0) to (a, b), then $f(\tau)$ and any geodesic from * to f(v) will $(2\delta + A_{5.6}(2K + \delta + 1))$ -track one another.

Proof: By Lemma 5.6 (and adapting to our notation) there is an integer $A(2K + \delta + 1)$ such that if α is an edge path loop in X with image in $B_{2K+\delta+1}(v)$ for some vertex v of α , then α is homotopically trivial in $St_A(v)$.

We construct the filter $F(s'_1, s'_2, \gamma, K)$. Choose an integer $N_0 \ge 0$ as large as possible such that for any two points w_1 and w_2 in the image of γ and any geodesic edge paths q_1 and q_2 at * converging to w_1 and w_2 respectively, $d(q_1(N), q_2(N)) \le \delta$ for all integers $0 \le N \le N_0$. (Note that $N_0 \ge \frac{\delta}{2}$.) For jan integer between 0 and $N_0 - 1$, the only vertices of $[0, 1] \times [0, \infty)$ are (0, j)and (1, j). The vertical edges are between (0, j - 1) and (0, j), and (1, j - 1)and (1, j). There is a horizontal edge between (0, j) and (1, j).

Next we define f on $[0,1] \times [0, N_0]$ (and on every vertical line above a vertex of $[0,1] \times \{N_0\}$). This process is iterated to define f and the filter F. (i) f(t,0) = * for all $t \in [0,1]$.

(ii) $f(0,t) = s'_1(t)$ and $f(1,t) = s'_2(t)$ for all $t \in [0,\infty)$.

(iii) For n an integer in $\{1, 2, ..., N_0 - 1\}$ let f restricted to the edge $[0, 1] \times \{n\}$ be an edge path of length $\leq 2K + \delta$ from $s'_1(n)$ to $s'_2(n)$. (Such a path exists since there is an edge path of length $\leq \delta$ from $s_1(n)$ to $s_2(n)$ and for $i \in \{1, 2\}$, edge paths of length $\leq K$ from $s'_i(n)$ to $s_i(n)$).

(iv) For $n \in \{1, 2, ..., N_0 - 1\}$, let f restricted to the rectangle $[0, 1] \times [n - 1, n]$ be a homotopy in $St_A(s'_1(n))$ (given by Lemma 5.6) that kills the loop determined by f restricted to the boundary of the rectangle.

(v) For $k \ge 0$, let $N_k = N_0 + k\delta$. Choose points $0 = t_0^0 < t_1^0 < \cdots < t_{k(0)}^0 =$

1 such that for any *i* and two points u_1 and u_2 in $[t_i^0, t_{i+1}^0]$ and any * based geodesic edge paths $q_1 \in \gamma(u_1)$ and $q_2 \in \gamma(u_2)$, we have $d(q_1(n), q_2(n)) \leq \delta$ for all $n \in [0, N_1]$. There are k(0) + 1 vertices $(t_0^0, N_0), (t_1^0, N_0), \dots, (t_{k(0)}^0, N_0)$ at level N_0 in *F* and a horizontal edge between (t_j^0, N_0) and (t_{j+1}^0, N_0) for each *j*. For each $n \in \{1, \dots, k_0 - 1\}$ add a vertical edge path ray $\{t_n^0\} \times [n_0, \infty)$ to *F* (with vertices (t_n^0, n) for each integer $n \geq n_0$.) Let r_n^0 be a geodesic edge path at * converging to $\gamma(t_n^0)$. Let $r_0^0 = s'_1$ and $r_{k(0)}^0 = s'_2$. For $n \in \{0, \dots, k(0)\}$ and $a \in [N_0, \infty)$ define $f(t_n^0, a) = r_n^0(a)$. (This agrees with our earlier definition of f on $\{0, 1\} \times [N_0, \infty)$.

Note that for $n \in \{1, \ldots, k(0) - 2\}$, $d(f(t_n^0, N_0), f(t_{n+1}^0, N_0)) \leq \delta$ and for $n \in \{0, k(0) - 1\}$, $d(f(t_n^0, N_0), f(t_{n+1}^0, N_0)) \leq K + \delta$. For $n \in \{1, \ldots, k(0) - 2\}$ define f restricted to the edge between (t_n^0, N_0) and (t_{n+1}^0, N_0) to be an edge path of length $\leq \delta$. For $n \in \{0, k(0) - 1\}$ define f restricted to the edge between (t_n^0, N_0) and (t_{n+1}^0, N_0) to be an edge path of length $\leq K + \delta$. (see Figure 2).

Recall that $d(s_1(N_0), s'_1(N_0)) \leq K$, $f(0, N_0) = s'_1(N_0)$, and for all $n \in \{0, 1, \ldots, k(0) - 1\}$, $d(s_1(N_0), f(t^0_n, N_0)) \leq \delta$. Hence $d(f(0, N_0), f(t^0_n, N_0)) \leq K + \delta$ for all n. The edge path loop bounding the rectangle $[0, 1] \times [N_0 - 1, N_0]$ is mapped by f to an edge path loop in $St_{2K+\delta+1}(f(0, N_0))$ (recall $K \geq \delta$). This loop is homotopically trivial in $St_A(f(0, N_0))$. Extend f to the rectangle by this homotopy.

Iterate this process on each of the regions $[t_n^0, t_{n+1}^0] \times [N_0, N_1]$ for $n \in \{0, 1, \ldots, k_0 - 1\}$. This extends f to $[0, 1] \times [0, N_1]$ and each vertical ray above a vertex of $[0, 1] \times \{N_1\}$. Repeated iterations defines a filter F and a proper homotopy/filter map on $[0, 1] \times [0, \infty)$.

(proof of part (4)): Again, let $A = A_{5.6}(2K + \delta + 1)$. Say $b = N_i - j$ where $i \ge 1$ and $1 \le j \le \delta$ (if $j = \delta$ then $b = N_{i-1}$). A terminal segment of τ (see (4)) is the vertical segment of F from (a, N_{i-1}) to (a, b). There are integers i and k such that $a = t_k^{i-1}$ (and (t_k^{i-1}, N_{i-1}) is a vertex of the subdivision of the horizontal segment $[0, 1] \times \{N_{i-1}\}$). The geodesic edge path ray r_k^{i-1} at * in X is such that $r_k^{i-1}(t) = f((t_k^{i-1}, t))$ (where again $a = t_k^{i-1}$) for $t \ge N_{i-1}$. (See Figure 3)

We will show that $f(\tau)$ and $r_k^{i-1}|_{[0,b]}$ will $(2\delta + A)$ -track one another. We already have that $f(\tau(t)) = f(t_k^{i-1}, t) = r_k^{i-1}(t)$ for $t \in [N_{i-1}, b]$ (a terminal segment of $f(\tau)$). Choose n such that $t_k^{i-1} \in [t_n^{i-2}, t_{n+1}^{i-2}]$. By construction, the rays r_n^{i-2} and r_k^{i-1} will δ fellow travel on $[0, N_{i-1}]$. By (3), for any rectangle $R = [t_n^{i-2}, t_{n+1}^{i-2}] \times [j, j+1]$ (for j an integer in $[N_{i-2}, N_{i-1} - 1]$), we have

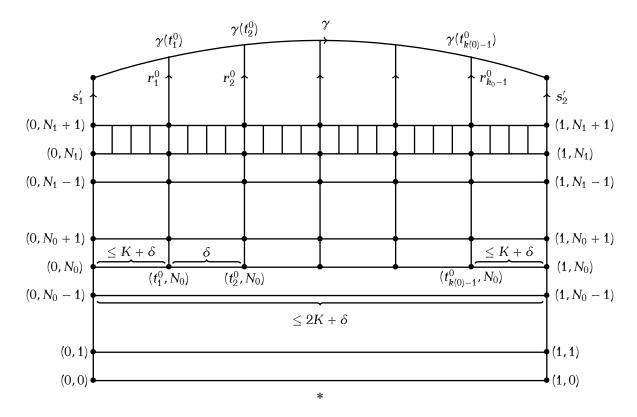


Figure 2: A Filter Homotopy

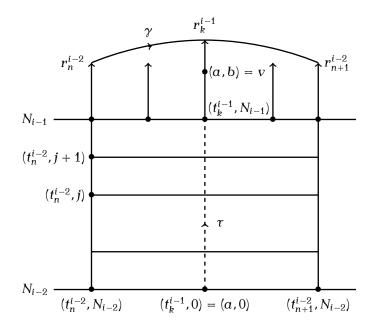


Figure 3: Tracking Geodesics

 $f(R) \subset St_A(r_n^{i-2}(j+1))$. In particular, $f(\tau)$ and r_n^{i-2} will A-track one another on $[N_{i-2}, N_{i-1}]$. Since r_n^{i-2} and r_k^{i-1} will δ -track one another on $[0, N_{i-1}]$, $f(\tau)$ and r_k^{i-1} will $(\delta + A)$ -track one another on $[N_{i-2}, N_{i-1}]$. Next find p such that t_k^{i-1} is between t_p^{i-3} and t_{p+1}^{i-3} and repeat the argument on $[N_{i-3}, N_{i-2}]$ and subsequent intervals to obtain $f(\tau)$ and r_k^{i-1} will $(\delta + A)$ -track one another on [0, b]. Now $r_k^{i-1}|_{[0,b]}$ and any other geodesic from * to f(v) will δ -track one another, completing the proof of (4). \Box

7 Triangulations and Simplicial Homotopies

In this section we define a triangulation of X that respects the action of G. Given a filter F and filter map $f_1 : [0,1] \times [0,\infty) \to X$, we produce a triangulation for $[0,1] \times [0,\infty)$ and a proper simplicial map $f : [0,1] \times [0,\infty) \to X$ that agrees with f_1 on F.

Our primary tool is E. C. Zeeman's relative simplicial approximation theorem. We follow Zeeman's notation.

If K is a simplicial complex, let |K| denote the polyhedron underlying K (also called the *realization* of K). If L is a subcomplex of K, let $(K \mod L)'$ denote the *barycentric derived complex of* K modulo L which is obtained from K by subdividing barycentrically all simplexes of K - L in some order of decreasing dimension. Note that L is a subcomplex of $(K \mod L)'$. Inductively define

$$K_0 = K,$$

$$K_r = (K_{r-1} \ mod \ L)'.$$

In 1964, E. C. Zeeman proved The Relative Simplicial Approximation Theorem.

Theorem 7.1 (Main Theorem, [Zee64]) Let K, M be finite simplicial complexes and L a subcomplex of K. Let $f : |K| \to |M|$ be a continuous map such that the restriction $f|_L$ is a simplicial map from L to M. Then there exists an integer r, and a simplicial map $g : K_r \to M$ such that $g|_L = f|_L$ and g is homotopic to f keeping L fixed.

First a we construct a triangulation of X. Recall that \mathcal{A} is a finite presentation for G and \mathcal{A} contains a finite presentation for each $P \in \mathbf{P}$, as a subpresentation. Each 2-cell of Y is bounded by an edge path (corresponding to a relation of our presentation \mathcal{A} of G). In each 2-cell E add a vertex v (*G*-equivariantly) and an edge from v to each vertex of the boundary of e. Triangles are formed (in the usual way) from the two vertices of an edge in the boundary of E and v. This triangulates E unless its boundary has length 2 (there may be a generator of order 2). In this case, add a vertex to each edge of E, a vertex v to E and add an edge from v to each vertex in the boundary of E. This is done respecting the action of G on Y and gives a triangulation of Y. If E is a 2-cell of a horoball **H** and E has three horizontal edges in its boundary, then E is a triangle of our triangulation. If E has two vertical edges and two horizontal edges, then add a single diagonal edge to E. For each translate gE add a diagonal edge that respects the action of G. If E has two vertical edges and 3 horizontal edges, let v be the common vertex of the two lower horizontal edges. Add edges from v to the two vertices of Ethat are one level above v. In this way no additional vertices are added to any horoball of X and we have a triangulation of X that respects the action of G.

Next suppose $F(s'_1, s'_2, \gamma, K)$ is a filter and $f_1 : [0, 1] \times [0, \infty) \to X$ is a filter map for F. The vertices of F are called *filter vertices*. If e is a horizontal edge of F and $f_1(e)$ is an edge path (of length $\leq 2K + \delta$), then add vertices to e (and replace e by the corresponding edges) so that f_1 is simplicial on e. These new vertices are not called filter vertices. At this point, f_1 is simplicial on our triangulation of F, but we have not dealt with 2-cells yet. Suppose Ris a rectangle of $[0,1] \times [0,\infty) - F$. Add a vertex w to R and an edge from wto each vertex of the boundary of R in order to triangulate \overline{R} (the closure of R). Recall that f_1 restricted to \overline{R} is a homotopy that kills the boundary loop of R in $St_{A_{5.6}(2K+\delta+1)}(f_1(v))$ where v is the upper left (filter) vertex of R. Let $f|_{\overline{R}}$ be a simplicial approximation to f_1 with image in (our triangulated) $St_{A_{5.6}(2K+\delta+1)}(f_1(v))$ such that f agrees with f_1 on the boundary of R. We have shown:

Lemma 7.2 Suppose $F(s'_1, s'_2, \gamma, K)$ is a filter and $f_1 : [0, 1] \times [0, \infty) \to X$ is a filter map for F. There are triangulations of X and $[0, 1] \times [0, \infty)$ and a simplicial map $f : [0, 1] \times [0, \infty) \to X$ that agrees with f_1 on F. Furthermore, for any rectangle R of $[0, 1] \times [0, \infty) - F$, $f(\bar{R}) \subset St_{A_{5.6}(2K+\delta+1)}(f(v))$ where v is the upper left (filter) vertex of \bar{R} . In particular, if w is a vertex of \bar{R} , (in our triangulation of $[0, 1] \times [0, \infty)$ and ϕ is an edge path in \bar{R} from w to the upper left (filter) vertex v of \bar{R} , then

$$d(f(v), f(w)) \le A_{5.6}(2K + \delta + 1)$$

and $f(\phi)$ is an edge path from f(w) to f(v) such that

$$im(f(\phi)) \subset B_{A_{5.6}(2K+\delta+1)}(f(v)) \subset B_{2A_{5.6}(2K+\delta+1)}(f(w)).$$

Hence if $E \ge 0$ and $\mathcal{D}(f(w)) > 2A_{5.6}(2K + \delta + 1) + E$ then the image of ϕ is in the horoball containing f(w) and $\mathcal{D}(f(v)) > A_{5.6}(2K + \delta + 1) + E$.

While more general projections are considered in [MSb] we are only interested in projecting proper edge path rays of X_K into Y. In fact, we need only consider special projections obtained by projecting the individual horizontal edges of a ray into Y.

Suppose $K \ge 0$ and e = (v, w) is an edge in X(K). Say τ is the vertical edge path from Y to v and $\bar{\tau}$ is the vertical edge path from Y to w. Then γ is a projection of e (or $(\tau, e, \bar{\tau}^{-1})$) to Y if γ is a shortest edge path in Y from the initial point τ to the initial point of $\bar{\tau}$. If r is an edge path in X_K with initial and end point in Y or an edge path ray in X_K with initial point in Y, then \hat{r} is a projection of r to Y if \hat{r} is obtained from r by replacing each horizontal edge e of r by a projection of e to Y. Suppose K > 0 is an integer and r is a proper edge path ray in X_K with initial point in Y. We construct a proper simplicial homotopy H from r to a projection of r into Y such that the image of H is in $St_{K+1}(im(r))$. The following is a special case of Lemma 5.6 of [MSb]

Lemma 7.3 Suppose e is an edge of $\overline{H}(K)$ for some integer K > 0. If γ is a projection of e into Y then each vertical line at a vertex of γ passes within 1 horizontal unit of a vertex of e.

Lemma 7.4 Suppose that r is a proper edge path ray at $v \in Y$. Also assume that r has image in X_K for some integer $K \ge 0$. Then a projection of r to Y is properly homotopic rel $\{v\}$ to r by a proper simplicial homotopy with image in $St_{K+1}(im(r))$.

Proof: If e is a horizontal edge e of r then consider $(\tau, e, \bar{\tau}^{-1})$ where τ (respectively $\bar{\tau}$) is vertical from Y to the initial (respectively terminal) point of e. It suffices to show that $(\tau, e, \bar{\tau}^{-1})$ is homotopic to a projection Qe of e by a simplicial homotopy in $St_{K+1}(e)$. Suppose e = (a, b) where a and b are vertices of height $\leq K$. Let γ_0 be a shortest path in Y from the initial point of τ to the initial point of $\bar{\tau}$. If γ_0 is the edge path (e_1, e_2, \ldots, e_n) then there is a vertical pentagon with base (e_1, e_2) , two vertical sides and

a horizontal edge e_1^1 at level 1. Let H_1^1 be the obvious simplicial homotopy of (e_1, e_2) to (b_1, e_1^1, b_3^{-1}) where the b_i are vertical edges. Construct H_1^2 a simplicial homotopy of (e_3, e_4) to (b_3, e_2^1, b_5^{-1}) . Continuing, the last homotopy may have base (e_{n-1}, e_n) (if n is even) or just e_n (if n is odd). Combining these homotopies gives a simplicial homotopy H_1 of $\gamma_0 = (e_1, \ldots, e_n)$ to $(b_1, \gamma_1, b_{n+1}^{-1})$ where $\gamma_1 = (e_1^1, e_2^1, \ldots)$ is horizontal of length $\leq \frac{n}{2} + 1$. Similarly define H_2 a simplicial homotopy of γ_1 to a vertical edge followed by the horizontal edge path γ_2 followed by another vertical edge. Continuing this process, we find that the last homotopy is one with base of length one or two. Hence the top edge is e. Combining these simplicial homotopies gives a simplicial homotopy of γ_0 to $(\tau, e, \overline{\tau}^{-1})$. Lemma 7.3 implies that the image of this homotopy is in $St_{K+1}(e)$. \Box

8 Preliminary Results

In order to build certain ideal triangles, we need a geodesic line in $X_{19\delta}$.

Theorem 8.1 There is an infinite order element $g \in G$ so that if ρ is a geodesic in X from * to g*, then the line $l = (\ldots, g^{-1}\rho, \rho, g\rho, g^2\rho, \ldots)$ is a bi-infinite geodesic that has image in $\mathcal{D}^{-1}([0, 19\delta])$.

Proof: By Theorem 3.33 [GM08] there is a geodesic line ℓ in $\mathcal{D}^{-1}([0, 19\delta])$ and an infinite order element $g_1 \in G$ such that $g_1\ell = \ell$. Certainly the image of ℓ is not a subset of a horoball and so ℓ must contain a vertex $v = h^*$ (for $h \in G$) of Y. The element $g = h^{-1}g_1h$ stabilizes the geodesic line $h^{-1}\ell$ (containing *). If ρ is the subgeodesic of $h^{-1}\ell$ from * to g^* , then $h^{-1}\ell = (\dots, g^{-1}\rho, \rho, g\rho, g^2\rho, \dots)$. Since G is height preserving, $h^{-1}\ell$ has image in $\mathcal{D}^{-1}([0, 19\delta])$. \Box

Let ℓ^+ be the geodesic ray $(\rho, g\rho, g^2\rho, ...)$ at * and let ℓ^- be the geodesic ray $(g^{-1}\rho^{-1}, g^{-2}\rho^{-1}, g^{-3}\rho^{-1}, ...)$ at * (so that ℓ^+ and ℓ^- determine the two ends of ℓ). Let v be a vertex of Y (so that $v \in G$) and consider an ideal geodesic triangle determined by the geodesic line $v\ell$ and two geodesic rays s_v^+ and s_v^- at *, where s_v^+ (respectively s_v^-) converges to the same point of $\partial(G, \mathbf{P})$ as does $v\ell^+$ (respectively $v\ell^-$). This implies that v is within δ of either s_v^+ or s_v^- . In the former case let r_v be $v\ell^+$, otherwise let r_v be $v\ell^-$. We have: **Lemma 8.2** The geodesic r_v at v is either $v\ell^+$ or $v\ell^-$. If α_v is a geodesic from * to v and s_v is the geodesic ray at * such that $[r_v] = [s_v] \in \partial X$, then for each integer $n \ge 0$ the vertex $s_v(n)$ is within δ of the n^{th} vertex of (α_v, r_v) .

The following definition and theorem were critical components in the proof of the homology version of our main theorem. They play an important role in this paper.

Definition 7. We call the pair (E, α) a *disk pair* in the simplicial complex $[0, \infty) \times [0, 1]$ if *E* is an open subset of $[0, \infty) \times [0, 1]$ homeomorphic to \mathbb{R}^2 , *E* is a union of (open) cells, α is an embedded edge path bounding *E* and *E* union α is a closed subspace of $[0, \infty) \times [0, 1]$ homeomorphic to a closed ball or a closed half space in $[0, \infty) \times [0, 1]$. When α is finite, we say the disk pair is finite, otherwise we say it is unbounded.

We will apply the next result with X equal to the cusped space for (G, \mathcal{P}) , Y equal to the Cayley 2-complex of (G, \mathcal{A}) in X and the Z_i being the Gtranslates of the $\Gamma(P_i)$ in X. The set X - Y will be the union of the open horoballs above the Z_i . This result will allow us to start with a proper simplicial homotopy $M : ([0,1] \times [0,\infty), [0,1] \times \{0\}) \to (X,*)$ of proper edge path rays r and s (with images in Y) and "excise" certain parts of $[0,1] \times [0,\infty)$ not mapped into Y. When the homotopy is built primarily from a filter, we will be able to replace it by a proper homotopy between r and s with image completely in X_N for some integer N.

Theorem 8.3 (Theorem 6.1, [MSa]) Suppose

$$M: ([0,1] \times [0,\infty), [0,1] \times \{0\}) \to (X,*)$$

is a proper simplicial homotopy rel{*} of proper edge path rays r and s into a connected locally finite simplicial 2-complex X, where r and s have image in a subcomplex Y of X. Say $\mathcal{Z} = \{Z_i\}_{i=1}^{\infty}$ is a collection of connected subcomplexes of Y such that only finitely many Z_i intersect any compact subset of X. Assume that each vertex of X - Y is separated from Y by exactly one Z_i .

Then there is an index set J such that for each $j \in J$, there is a disk pair (E_j, α_j) in $[0, 1] \times [0, \infty)$ where the E_j are disjoint, M maps α_j to $Z_{i(j)}$ (for some $i(j) \in \{1, 2, \ldots\}$) and $M([0, 1] \times [0, \infty) - \bigcup_{j \in J} E_j) \subset Y$.

9 The Proof of the Main Theorem

In this section we prove there is an integer M_0 such that X_{M_0} has semistable fundamental group at ∞ . Since X_{M_0} is simply connected and G/X_{M_0} is a finite complex. By definition (see §3) G has semistable fundamental group at ∞ if and only if X_{M_0} has semistable fundamental group at ∞ .

Recall that for each vertex v in Y we have defined the geodesic edge path ray r_v at v. If $v \in gP_i$ let Qr_v be some projection of r_v into Y. The next lemma is the key technical fact of the paper. All homotopies that appear following this lemma are derived from homotopies guaranteed by this lemma.

Lemma 9.1 Let $M_0 = 2A_{5.6}(7\delta + 1) + 2\delta + 1$. If e = (v, w) is an edge of a peripheral coset gP_i and d = (w, q) is an edge of Y then:

(1) The edge path ray Qr_v is properly homotopic rel $\{v\}$ to both the edge path ray (e, Qr_w) and to the edge path ray (e, d, Qr_q) , by homotopies in X_{M_0} .

(2) For N > 0 there is $M_{9,1}(N) > N$ such that if $\{v, w\} \cap B_{M_{9,1}(N)}(*) = \emptyset$ then there is an edge path ψ in gP_i from v to w such that Qr_v is properly homotopic rel $\{v\}$ to (ψ, Qr_w) in $X_{M_0} - B_N(*)$.

If $q \notin B_{M_{9,1}(N)}(*)$ then there is an edge path ψ' in gP_i from v to w such that Qr_v is properly homotopic $rel\{v\}$ to (ψ', d, Qr_q) in $X_{M_0} - B_N(*)$. Furthermore, if $gP_i \cap B_N(*) = \emptyset$ then we may take $\psi = \psi' = e$.

Proof: We prove Qr_v is properly homotopic to (e, Qr_w) and (ψ, Qr_w) in parts (1) and (2) of the Lemma. The proof that Qr_v is properly homotopic to (e, d, Qr_q) and (ψ', d, Qr_q) is completely analogous to that argument, with Qr_w simply replaced by (d, Qr_q) .

We begin by proving part (2) of the lemma. Part (1) has an analogous, but more elementary proof that we include at the end. Let $\mathcal{A} = \{A_1, A_2, \ldots, A_m\}$ be the set of peripheral cosets that intersect $B_N(*)$. Choose $K_1 > N+19\delta_1+1$ such that for $j \in \{1, \ldots, m\}$ and v_j a closest vertex of A_j to *, we have $B_{6\delta+4}(v_j) \subset B_{K_1}(*)$. For $j \in \{1, \ldots, m\}$ let H^j be the horoball over A_j . Let c_j be a closest point of $H^j(\delta)$ to *. Let $L = A_{5.6}(7\delta + 1)$. Assume that for $j \in \{1, \ldots, m\}$

$$B_{2L+5\delta+3}(c_j) \subset B_{K_1}(*).$$

We fix the following constants:

$$L = A_{5.6}(7\delta + 1);$$
 $K_2 = 3K_1 + 2L + 16\delta + 3;$ $M = M_{6.1}(K_2).$

Note that M depends only on N. There are two Cases. We will show that if $gP_i = A_j$ for some $j \in \{1, \ldots, m\}$, then $M = M_{9,1}(N)$ satisfies the second conclusion of our lemma. If $gP_i \neq A_j$ for any $j \in \{1, \ldots, m\}$, then a different value for $M_{9,1}(N)$ satisfies the conclusion of the lemma. We finish our proof by choosing $M_{9,1}(N)$ to be the large of the two.

Recall that by Lemma 5.6, if α is an edge path loop in X with image in $B_{7\delta+1}(v)$ for some vertex v of α , then α is homotopically trivial in $St_{A_{5,6}(7\delta+1)}(v) = St_L(v).$

Case 1. Assume that $gP_i = A_1$ and (v, w) is in $X - B_M(*)$.

Say our edge path ray r_v (at v) converges to $x \in \partial X$ and r_w converges to $y \in \partial X$. By Lemma 8.2, the vertex of s_v that is d(v, *) from * is within δ of v. Similarly for s_w . Since these points of s_v and s_w are within $2\delta + 1$ of one another, we have $d(s_v(M), s_w(M)) \leq 2\delta + 1$. By Lemma 6.1, there is a path γ in ∂X from x to y such that for any two points w_1 and w_2 in the image of γ and any geodesic edge paths q_1 and q_2 at * converging to w_1 and w_2 respectively, we have $d(q_1(k), q_2(k)) \leq \delta$ for all $k \leq K_2 = 3K_1 + 2L + 16\delta + 3$. (See Figure 4.)

Suppose β_v is a geodesic from * to v and \bar{v} is the first point of β_v in gP_i . Since $gP_i = A_1$ and v_1 is a closest point of A_1 to *, Lemma 5.5 implies $d(\bar{v}, v_1) \leq 6\delta + 4$ and so

$$\bar{v} \in B_{K_1}(*).$$

Let β'_v be the edge path from * to v obtained from β_v by replacing the segment of β_v from \bar{v} to v by a cusp geodesic and note that this cusp geodesic has length $\geq 2K_1 + 2L + 16\delta + 3$. Let s'_v be β'_v followed by r_v . Similarly define s'_w . Lemma 8.2 implies the n^{th} vertex of s_v is within δ of the n^{th} vertex of (β_v, r_v) for all n. Lemma 5.7 implies that for all $n \geq 0$

$$d(s_v(n), s'_v(n)) \le 3\delta.$$

Similarly for s_w and s'_w . Let $F = F(s'_v, s'_w, \gamma, 3\delta)$ and $f : [0, 1] \times [0, \infty) \to X$ be the filter and filter map of Theorem 6.3 (so that the constant K of Theorem 6.3 is 3δ).

At this point the argument becomes technical. We give a brief outline of the Case 1 argument and refer the reader to Figure 4. We construct a proper homotopy H_v between r_v and the projection Qr_v . Similarly with H_w . Then take simplicial approximations of H_v , H_w and f. Then we combine these three proper simplicial homotopies with simplicial homotopies of β'_v to $Q\beta'_v$

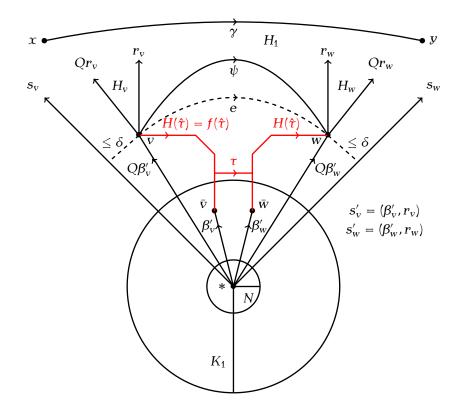


Figure 4: Building Proper Homotopies

and β'_w to $Q\beta'_2$. This gives a proper simplicial homotopy H between Qs'_v and Qs'_{w} . Apply Theorem 8.3 to H. We will show there is a disk pair (D, α) such that both v and w are vertices of $H(\alpha)$. In order to do this, we show there is a path $\hat{\tau}$ in the domain of H that is mapped by H to a path connecting v and w into the horoball above A_1 (so $\hat{\tau}$ belongs to the disk D of a disk pair (D, α)). The path $H(\hat{\tau})$ is represented in Figure 4 by a red path from v to w with τ as a subpath. If ψ is the part of α above $\hat{\tau}$ then $f(\psi)$ is the path ψ of our lemma and we will only use the part of H that lies above ψ to obtain our final homotopy. Other disks of disk pairs of Theorem 8.3 are also removed, but we will show only finitely many can have boundary path in a given peripheral coset and none of these peripheral cosets will in \mathcal{A} . If α' is such a boundary path and α' is finite then we extend our homotopy to the disk it bounds by an arbitrary homotopy that kills α' in the corresponding Cayley 2-complex of its peripheral coset. If α' is unbounded then we extend our homotopy to the disk (halfspace) it bounds by a proper homotopy of two opposite rays forming α' in the corresponding Cayley 2-complex. This gives the proper homotopy described by part (2) of the lemma (and completes the outline).

Recall that in the proof of Lemma 6.3, the number $N_0 \ge 0$ was chosen large as possible such that for any two points w_1 and w_2 in the image of γ and any geodesic edge paths q_1 and q_2 at \ast converging to w_1 and w_2 respectively, $d(q_1(n), q_2(n)) \le \delta$ for all integers $n \in [0, N_0]$. Since $M = M_{6,1}(K_2)$

$$N_0 \ge K_2 = 3K_1 + 2L + 16\delta + 3.$$

As noted earlier, the cusp geodesic from \bar{v} to v has length at least $2K_1 + 2L + 16\delta + 3$ and so its initial vertical segment has length at least $K_1 + L + 8\delta$.

Let $D_1 = d(\bar{v}, *)$ so that $0 \leq D_1 \leq K_1$. Then $s'_v(D_1 + L + K_1 + 8\delta)$ has depth $L + K_1 + 8\delta$ in the horoball over gP_i . In the construction of the filter in Lemma 6.3, for each integer $n < N_0$ there was an edge from (0, n) to (1, n). Since $D_1 \leq K_1$, we have $D_1 + L + K_1 + 8\delta < N_0$. This implies there is an edge in our filter from $(0, D_1 + L + K_1 + 8\delta)$ to $(1, D_1 + L + K_1 + 8\delta)$. The image under f of this edge is an edge path τ of length $\leq 2(3\delta) + \delta = 7\delta$ from $s'_v(D_1 + L + K_1 + 8\delta)$ to $s'_w(D_1 + L + K_1 + 8\delta)$. Since $s'_v(D_1 + L + K_1 + 8\delta)$ has depth $L + K_1 + 8\delta$, the path τ (of length $\leq 7\delta$) has image in the horoball over gP_i . This implies $s'_w(D_1 + L + K_1 + 8\delta)$ is a point of the cusp geodesic from \bar{w} to w (since \bar{w} is the first point of s'_w in that horoball).

(A) Let D_v be the length of the subpath of s'_v from * to v. Similarly define D_w . Let $\hat{\tau}$ be the edge path in the filter from $(0, D_v)$ to $(0, D_1 + L + K_1 + 8\delta)$

followed by the edge from $(0, D_1 + L + K_1 + 8\delta)$ to $(1, D_1 + L + K_1 + 8\delta)$ followed by the edge path from $(1, D_1 + L + K_1 + 8\delta)$ to $(1, D_w)$. The path $f(\hat{\tau})$ follows our cusp geodesic from v to the initial point of τ , then follows τ and then follows our cusp geodesic from the end point of τ to w (see Figure 4). Hence $f(\hat{\tau})$ has image in the horoball over gP_i .

Note that it may be case that $v_1 = \bar{v} = *$ and $D_1 = 0$. Recall that $d(s'_v(n), s_v(n) \leq 3\delta$ for all n (and similarly for s'_w and s_w). If $t \in (0, 1)$ and (t, n) is a vertex of F then d(f(t, n), *) = n. Hence each vertex of $[0, 1] \times [D_1 + L + K_1 + 8\delta, \infty)$ is mapped by f to $X - B_{D_1+L+K_1+5\delta}(*)$. By Lemma 6.3(2), f maps the 1-skeleton of $[0, 1] \times [D_1 + L + K_1 + 8\delta, \infty)$ to $X - B_{D_1+K_1+L+2\delta}(*)$. By Lemma 6.3(3) the boundary of each open rectangle in $[0, 1] \times [D_1 + L + K_1 + 8\delta, \infty) - F$ is mapped by f to $B_{7\delta+1}(f(z))$ for z the upper left vertex of the rectangle. The extension of f to this rectangle has image in $St_L(f(z))$ (by our choice of L and the definition of f in Lemma 6.3). Since $f(z) \in X - B_{D_1+L+K_1+5\delta}(*)$, the image of this rectangle under f has image in $X - St_{D_1+K_1+5\delta}(*)$. Hence:

$$f([0,1] \times [D_1 + L + K_1 + 8\delta, \infty)) \subset X - St_{D_1 + K_1 + 5\delta}(*).$$

Let \bar{f} be a simplicial approximation to f that agrees with f on F. Note that \bar{f} can only differ from f on the open rectangles R of $[0,1] \times [0,\infty) - F$ and $\bar{f}|_{\bar{R}}$ is a simplicial approximation of $f|_{\bar{R}} : \bar{R} \to St_L(z)$ (for z the upper left (filter) vertex of R) that agrees with f on the boundary of R. In particular, $\bar{f}(\bar{R}) \subset St_L(z)$ and

$$f([0,1] \times [D_1 + L + K_1 + 8\delta, \infty)) \subset X - St_{D_1 + K_1 + 5\delta}(*) \subset X - St_{K_1}(*).$$

By Lemma 7.4 there is a proper simplicial homotopy H_v of Qr_v to r_v rel $\{v\}$ with image in the $19\delta + 1$ neighborhood of r_v (and similarly there is H_w for r_w and Qr_w). Since v and w avoid $B_{K_2}(*)$, $K_1 > N + 19\delta + 1$, and $K_2 >$ $3K_1$, the homotopies H_v and H_w avoid $St_{K_1}(*)$. Now combining the proper simplicial homotopies H_v , \bar{f} (from s'_v to s'_w) and H_w gives a proper simplicial homotopy of (β'_v, Qr_v) to (β'_w, Qr_w) . We combine this homotopy with an arbitrary simplicial homotopy of $Q\beta'_v$ to β'_v and of $Q\beta'_w$ to β'_w to obtain a proper simplicial homotopy H of $(Q\beta'_v, Qr_v)(=Qs'_v)$ to $(Q\beta'_w, Qr_w)(=Qs'_w)$.

Apply Theorem 8.3 to H. Each disk pair (E_j, α_j) is mapped by H into a horoball with $H(\alpha_j)$ mapped into a G translate of one of the P_i and $H(E_j)$ mapped into the (open) horoball over that translate of P_i . By (A), one of these E_j , call it D, contains the path $\hat{\tau}$ and H(D) has v and w in its boundary. The boundary of D is composed of two simple edge paths (separated by $\hat{\tau}$) and H composed with either connects v and w. The definition of (the domain of) $\hat{\tau}$ implies one of these paths (call it $\hat{\psi}$) is above $\hat{\tau}$ and has image in $[0,1] \times [D_1 + L + K + 1 + 8\delta, \infty)$ union the domains of the homotopies H_v from Qr_v to r_v and H_w from Qr_w to r_w . Each of these last two homotopies avoid $B_{K_1}(*)$. We have shown that $\bar{f}([0,1] \times [D_1 + L + K_1 + 8\delta, \infty) \subset X - B_{D_1+K_1+5\delta-2}(*) \subset X - B_{K_1}(*)$. Hence H composed with $\hat{\psi}$ and everything above $\hat{\psi}$ avoids $B_{K_1}(*)$. We are only interested in H_1 , the restriction of the homotopy H to the part of its domain above $\hat{\psi}$. We reparametrize the domain of H_1 and alter H_1 on certain disk pairs to obtain a homotopy \hat{H} , so that $H(\hat{\psi}) = \psi = \hat{H}|_{[0,1]\times\{0\}}$ (as mentioned in the statement of our Lemma 9.1).

Claim 1. Suppose hP_j is a peripheral coset, \overline{H} is the horoball over hP_j and c is a closest vertex of $\overline{H}(\delta) (= \mathcal{D}^{-1}(\delta) \cap \overline{H})$ to *. Then there are only finitely many disk pairs (D, α) for $[0, 1] \times [0, \infty)$ and the homotopy H, such that $H(\alpha) \subset hP_j$ and D contains a vertex $z_1 = (a, b)$ of F such that $\mathcal{D}(f(z_1)) \geq L + 2\delta + 1$. Furthermore, each such disk D contains a vertex w'_1 of our filter such that $d(f(w'_1), c) \leq 2L + 5\delta + 3$.

Proof: Suppose (D, α) is such a disk pair. Let α_{z_1} be a geodesic in X from * to $f(z_1)$ (as in Lemma 5.4). Say $\alpha_{z_1}(t) = x$ is the first point of α_{z_1} in $\overline{H}(\delta)$. By Lemma 5.4, $d(x,c) \leq 2\delta + 1$. The segment $\alpha_{z_1}([t, t + L + 2\delta + 1])$ of α_{z_1} (immediately following x) is vertical. Let $z = \alpha_{z_1}(t + L + 2\delta + 1)$. Let β_{z_1} be the vertical segment of $[0,1] \times [0,\infty)$ from (a,0) to $z_1 = (a,b)$ (of length b). By Lemma 6.3(4), $f(\beta_{z_1})$ and α_{z_1} must $(L + 2\delta)$ -track one another. Hence if $w_1 = \beta_{z_1}(t + 2L + \delta + 1)$, then $d(f(w_1), z) \leq L + 2\delta$, and $f(\beta_{z_1}([t + L + 2\delta + 1, b])) \subset \overline{H}^1$. (See Figure 5.) Note that w_1 belongs to an edge of our triangulation of our filter and so within 1 unit of a vertex w'_1 of our filter such that $f(w'_1) \in \overline{H}^1$.

In particular, $d(f(w_1), c) \leq d(f(w_1), z) + d(z, x) + d(x, c) \leq 2L + 5\delta + 2$ and $\beta_{z_1}([t + L + 2\delta + 1, b]) \subset D$ so that $w_1, w'_1 \in D$. In particular, Dcontains a vertex w'_1 , such that $f(w'_1)$ is within $2L + 5\delta + 3$ of c. Since f is proper, $[0, 1] \times [0, \infty)$ contains only finitely many vertices that f maps within $2L + 5\delta + 3$ of c. Since the disks of the disk pairs are all disjoint, the claim follows. \Box

If (D, α) is a disk pair for H, arising from Theorem 8.3 and containing a

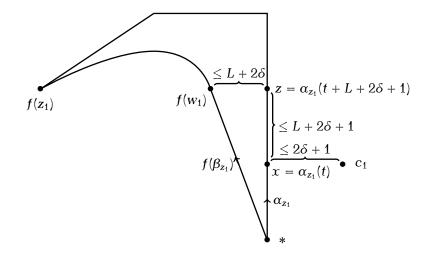


Figure 5: Tracking Paths in a Horoball

vertex v of the filter F such that $\mathcal{D}(f(v)) \geq L + 2\delta + 1$, then remove D from $[0,1] \times [0,\infty)$. Recall that the image of the homotopy H_1 avoids $B_{K_1}(*)$, and if we can properly extend H_1 to the removed disks by a map that avoids $B_N(*)$ and so that the extension has image in $X_{L+2\delta+2}$, we will have the desired homotopy \hat{H} (with $\hat{H}|_{[0,1]\times\{0\}} = H_1(\hat{\psi}) = \psi$ after a reparametrization of the domain of H_1).

Claim 2. If (α, D) is a disk pair of our triangulation of $[0, 1] \times [0, \infty)$ and some vertex y of D, is such that $\mathcal{D}(f(y)) > 2L + 2\delta + 1$ then there is a filter vertex z of D with $\mathcal{D}(f(z)) > L + 2\delta + 1$.

Proof: Since $\mathcal{D}(f(y) > 2L+2\delta+1$, Lemma 7.2 (with $K = 3\delta$ and $E = 2\delta+1$) implies that in our triangulation of $[0,1] \times [0,\infty)$ there is an edge path ϕ (of length $\leq L = A_{5.6(7\delta+1)}$ from y to a filter vertex z of $[0,1] \times [0,\infty)$ such that $H(\phi)$ is in the horoball containing f(y) (and so z is a vertex of D) and such that $\mathcal{D}(f(z)) > L + 2\delta + 1$. \Box

If (D, α) is a disk pair of our triangulation of $[0, 1] \times [0, \infty)$ and D does not contain a vertex of v of F with $\mathcal{D}(f(v)) \geq L + 2\delta + 1$, then Claim 2 implies that $H(D) \subset X_{2L+2\delta+1}$. Suppose (D, α) is a disk pair and D contains a

vertex v of F such that $\mathcal{D}(f(v)) \geq L + 2\delta + 1$. Then the disk D is removed from the domain of H_1 (the part of $[0,1] \times [0,\infty)$ above ψ). Say α has image in hP_j . Let H be the horoball above hP_j and let c be a closest vertex of $H(\delta) = \mathcal{D}^{-1}(\delta) \cap H$ to *. Claim 1 implies that D contains a vertex w from the filter F such that $d(f(w), c) \leq 2L + 5\delta + 3$. Since H_1 avoids $B_{K_1}(*)$, and $B_{2L+5\delta+3}(c_i) \subset B_{K_1}(*)$ for $i \in \{1, \ldots, m\}$ our peripheral hP_j cannot be in $\mathcal{A} = \{A_1, \ldots, A_m\}$. This implies that hP_j avoids $B_N(*)$. Hence if D is bounded, then any homotopy killing α in $\Gamma(hP_i)$ avoids $B_N(*)$. If D is unbounded (and α is a line) then any proper homotopy in $\Gamma(hP_i)$ of two opposing rays of this line avoids $B_N(*)$ (such a homotopy exists since P_i is 1-ended and has semistable fundamental group at ∞). Define \hat{H} on D to be such a homotopy. It suffices to show the resulting homotopy is proper. Given any compact set $C \subset X$ only finitely many peripheral subgroups intersect C. Hence only finitely many of the extensions of H_1 intersect C so that $\hat{H}^{-1}(C)$ is contained in the compact set $H^{-1}(C)$ union the inverse image of finitely many extensions of H_1 to (finitely many) disks. Since each such extension (on the closed disk) is proper H is a proper map with image in $X_{2L+2\delta+1} (= X_{M_0})$. This concludes the proof of Case 1.

Before we consider the second case, we prove part (1) the lemma. We build the homotopy \hat{H} in a similar way, but less care is necessary. The paths β'_v and β'_w are not necessary. Instead use the paths β_v and β_w (geodesic edge paths in X from * to v and w respectively) to define $s'_v = (\beta_v, r_v)$ and $s'_w = (\beta_w, r_v)$. Build a filter homotopy between $Qs_v = (Q\beta_v, Qr_v)$ and Qs_w and use relative simplicial approximation to obtain a proper simplicial homotopy Hbetween Qs_v and Qs_w with image in X. (See Figure 4.) Next use Theorem 8.3, Claim 1 and Claim 2 (as before) to obtain a proper homotopy H_1 of $Qs_v = (Q\beta_v, Qr_v)$ to $Qs_w = (Q\beta_w, Qr_w)$ rel{*}, with image in X_{M_0} .

Since the loop $(Q\beta_v^{-1}, Q\beta_w, e^{-1})$ is homotopically trivial in Y, we can combine H_1 with such a homotopy and replace $(Q\beta_v^{-1}, Q\beta_w)$ by e. We obtain a proper homotopy \hat{H} of Qr_v to (e, Qr_w) with image in X_{M_0} . This finishes part (1) of the lemma.

For the final case, we follow much of our earlier notation. Assume that $K' \ge N + 19\delta + 1$ and for $j \in \{1, \ldots, m\}$

$$B_{2L+5\delta+3}(c_j) \subset B_{K'}(*).$$

Let $t_1 = K' + L + \delta$ and $M' = M_{6.1}(t_1)$.

Case 2. Assume $gP_i \notin \{A_1, \ldots, A_m\}$ and e is an edge of gP_i in $X - B_{M'}(*)$.

Say our edge path ray r_v (at v) converges to $x \in \partial X$ and r_w converges to $y \in \partial X$. Let α_v be a geodesic from * to v. By Lemma 8.2, the vertex $s_v(n)$ is within δ of the n^{th} vertex of (α_v, r_v) . Similarly for s_w . The vertex of s_v that is d(v, *) from * and the vertex of s_w that is d(w, *) from * are within $2\delta + 1$ of one another. Since M' < d(v, *), we have $d(s_v(M'), s_w(M')) \leq 2\delta + 1$. By Lemma 6.1, there is a path γ in ∂X from x to y such that for any two points w_1 and w_2 in the image of γ and any geodesic edge paths q_1 and q_2 at * converging to w_1 and w_2 respectively, $d(q_1(k), q_2(k)) \leq \delta$ for all $k \leq t_1 (= K' + L + \delta)$.

Let $f: [0,1] \times [0,\infty) \to X$ be a filter homotopy for a filter $F(s_v, s_w, \gamma, 0)$ of Lemma 6.3. Recall that on each rectangle R of $[0,1] \times [0,\infty) - F$ we have $f(\bar{R}) \subset St_L(z)$ where z is the upper left vertex of R. Let f_1 be the restriction of f to $[0,1] \times [K'+L,\infty)$ and let τ be f_1 restricted to $[0,1] \times \{t_1\}$. Let F_1 be a proper simplicial approximation to f_1 that agrees with f_1 on the filter F and with image in the St_L neighborhood of the part of the filter in $[0,1] \times [t_1,\infty)$. (The map F_1 is obtained by combining simplicial approximations to f_1 on closed rectangles.) Since f_1 restricted to the part of the filter in $[0,1] \times [t_1,\infty)$ avoids $B_{K'+L}(*)$, the image of F_1 is in $X - B_{K'}(*)$. By Lemma 6.1, the path τ has image in $N_{\delta}(s_v(t_1))$. Next we define a proper simplicial homotopy Hof $Q(r_v)$ to $(e, Q(r_w), \operatorname{rel}\{v\}$ in $X - B_N(*)$ by combining F_1 with six other proper simplicial homotopies (see Figure 6).

Let α'_v be the tail of α_v beginning at $\alpha_v(t_1)$. Let β_v be an edge path of length $\leq \delta$ from $\alpha_v(t_1)$ to $s_v(t_1)$. For $m \geq t_1$, consider the edges $\alpha_v([m, m+1])$ and $s_v([m, m+1])$, and paths of length $\leq \delta$ from $\alpha_v(m)$ to $s_v(m)$ and from $\alpha_v(m+1)$ to $s_v(m+1)$, forming loops. These loops are homotopically trivial in $St_{A_{5.6(\delta+1)}}(s_v(m)) \subset St_L(s_v(m))$ and so by Theorem 7.1 we may assume these homotopies are simplicial. Combining these homotopies, there is a proper simplicial homotopy H_1 between $(\beta_v, s_v|_{[t_1,\infty)})$ and (α'_v, r_v) with image in $St_L(s_v([t_1,\infty))) \subset X - B_{K'}(*)$. Similarly for H_2 and w.

By Lemma 7.4 there is a simplicial homotopy H_3 of r_v to a projection Qr_v , rel $\{v\}$ with image in the $19\delta + 1$ neighborhood of $im(r_v)$. Similarly for H_4 and r_w . Consider the geodesic triangle formed by α_v , α_w and e = (v, w). The m^{th} vertex of α_v is within δ of the m^{th} vertex of α_w for all m. Let ψ be an edge path of length $\leq \delta$ from $\alpha_v(t_1)$ to $\alpha_w(t_1)$. (For simplicity, assume that d(*, v) = d(*, w).) For each integer $t_1 \leq m \leq d(*, v)$ there is an edge path ψ_m from $\alpha_v(m)$ to $\alpha_w(m)$ (with $\psi_{t_1} = \psi$ and $\psi_{d(*,v)} = e$). The loops formed by

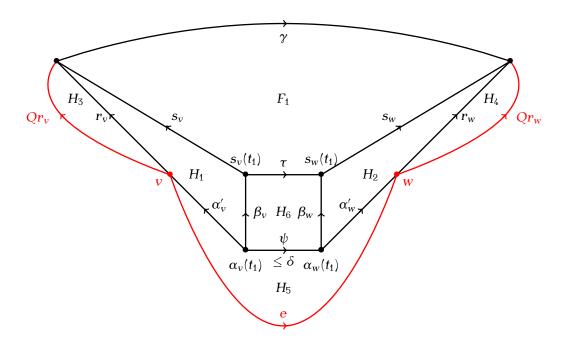


Figure 6: Combining Homotopies

 ψ_m, ψ_{m+1} and the corresponding edge from α'_v and α'_w is homotopically trivial by a simplicial homotopy in $St_{5.6(\delta+1)}(\alpha(m))$. Combining these homotopies gives the homotopy H_5 , a simplicial homotopy of (α'_v, e) to (ψ, α'_w) in the $A_{5.6(\delta+1)}$ star neighborhood of α'_v . Hence H_5 has image in $X - St_{K'}(*)$. The loop $(\beta_v, \tau, \beta_w^{-1}, \psi^{-1})$ has image in $B_{2\delta}(s_v(t_1))$ and so is homotopically trivial (by the simplicial homotopy H_6) in $St_L(s_v(t_1)) \subset X - St_{K'}(*)$.

Combining these homotopies, we have H, a proper simplicial homotopy rel $\{v\}$ of Qr_v to (e, Qr_w) (see Figure 6), with image in $X - St_{K'}(*)$. Now, use Theorem 8.3 (to cut out the disks of $[0, 1] \times [0, \infty)$ that H does not map into X_{M_0}). Define \hat{H} to agree with H on the compliment of the removed disks. Suppose (D, α) is such a disk pair and $H(\alpha)$ has image in the peripheral hP_j . Let \tilde{H} be the horoball over hP_j in X and let c be a closest point of $\tilde{H}(\delta)$ to *. Claims 1 and 2 imply D contains a filter vertex within $2L + 5\delta + 3$ of c. Since $B_{2L+5\delta+3}(c_i) \subset B_{K'}(*)$ for $i \in \{1, \ldots, m\}$, we have $hP_j \notin \{A_1, \ldots, A_m\}$.

We proceed just as before. If D is bounded, then any homotopy killing α in $\Gamma(hP_j)$ avoids $B_N(*)$. If D is unbounded (and α is a line) then any proper homotopy in $\Gamma(hP_j)$ of two opposing rays of this line avoids $B_N(*)$. Define \hat{H} on D to be such a homotopy. Just as before, \hat{H} is proper with image in $X_{M_0} - B_N(*)$. This completes the proof of Case 2 and Lemma 9.1. \Box

The proof of our Main Theorem will be derived from the next result by a homotopy "stacking" argument.

Lemma 9.2 If d = (w, q) is an edge of Y then Qr_w is properly homotopic rel $\{w\}$ to (d, Qr_q) in X_{M_0} . Furthermore, for each integer N there is an integer $M_{9,2}(N)$ such that if d has image in $Y - B_{M_{9,2}(N)}$ then Qr_w is properly homotopic rel $\{w\}$ to (d, Qr_q) by a homotopy in $X_{M_0} - B_N(*)$.

Proof: If d belongs to a peripheral coset then Qr_w is properly homotopic rel{w} to (d, Qr_q) in X_{M_0} by Lemma 9.1. Otherwise, let e = (v, w) be an edge of a peripheral coset. By Lemma 9.1, the ray Qr_v is properly homotopic rel{v} to (e, Qr_w) in X_{M_0} . Equivalently, Qr_w is properly homotopic rel{w} to (e^{-1}, Qr_v) in X_{M_0} . Again by Lemma 9.1 Qr_v is properly homotopic rel{v} to (e, d, Qr_q) in X_{M_0} . Equivalently, (e^{-1}, Qr_v) is properly homotopic rel{v} to (d, Qr_q) in X_{M_0} . Equivalently, (e^{-1}, Qr_v) is properly homotopic rel{w} to (d, Qr_q) in X_{M_0} . Since both (d, Qr_q) and Qr_w are properly homotopic rel{w} to (e^{-1}, Qr_v) in X_{M_0} , the first part of the lemma is proved.

For the second part, we will show that Qr_w and (d, Qr_q) are properly homotopic rel $\{w\}$ to 'far out' proper rays at w that have image in a peripheral coset. Since peripheral subgroups are semistable, these rays are in turn properly homotopic rel $\{w\}$ to one another in $X_{M_0} - B_N(*)$. Combining homotopies will finish the proof of the lemma.

Without loss, assume the integers $M_{9.1}(k)$ are strictly increasing in k. We choose $P_1 \in \mathbf{P}$ (any other peripheral would do as well). Let \mathcal{A}_N be the (finite) set of all peripheral cosets vP_1 such that $v \in B_N(*)$. Since P_1 has semistable fundamental group at ∞ , Theorem 3.1(3) implies there is an integer $M_1(N)$ such that if $A \in \mathcal{A}_N$ and r and s are proper edge path rays in $A - St_{M_1(N)}(*)$, both based at the vertex v, then r and s are properly homotopic rel $\{v\}$ in $\Gamma(A) - St_N(*)$. Let $M_2(N) = M_{9.1}(M_1(N))$. Let \mathcal{B}_N be the (finite) set of all peripherals vP_1 such that $v \in B_{M_2(N)}(*)$. Let $M_3(N)$ be such that if $B \in \mathcal{B}_N$ then the bounded components of $\Gamma(B) - St_{M_2(N)}(*)$ belong to $B_{M_3(N)}(*)$. We will show that $M_3(N)$ satisfies the role of $M_{9.2}(N)$.

Let d = (w, q) be an edge in $Y - B_{M_3(N)}(*)$ and let A be the peripheral coset wP_1 . The constant $M_3(N)$ has been chosen so that whether or not $A \in \mathcal{B}_N$, there is an proper edge path ray $r = (e_1, e_2, \ldots)$ based at w and with image in $\Gamma(A) - B_{M_2(N)}(*)$. Label the consecutive vertices of r as $v_0 = w, v_1, v_2, \ldots$

For $k \geq 1$ let N_k be the largest integer such that e_k is in $Y - B_{M_{9,1}(N_k)}(*)$. By the definition of $M_2(N)$, we have $N_k \geq M_1(N)$ for all k. By Lemma 9.1 there is a proper homotopy rel $\{v_{i-1}\}$ (call it H_i) of $Qr_{v_{i-1}}$ to (ψ_i, Qr_{v_i}) in $X_{M_0} - B_{N_k}(*)$ where ψ_i is an edge path in $A - B_{N_k}(*) \subset A - B_{M_1(N)}(*)$ from v_{i-1} to v_i .

$$H_i: Qr_{v_{i-1}} \sim_{v_{i-1}} (\psi_i, Qr_{v_i}).$$

Since r is proper, the e_k converge to infinity and so the N_k converge to infinity. This means that the images of only finitely many H_i intersect any given compact set. Hence combining the H_i as in Figure 7 gives \hat{H}_1 , a proper homotopy rel $\{w\}$ of $Qr_{v_0} = Qr_w$ to $r_1 = (\psi_1, \psi_2, \ldots)$ with image in $X_{M_0} - B_{M_1(N)}(*)$.

$$\hat{H}_1: Qr_{v_0} = Qr_w \sim_w r_1 = (\psi_1, \psi_2, \ldots) \to X_{M_0} - B_{M_1(N)}(*).$$

Lemma 9.1 also gives a proper homotopy rel $\{v_1\}$ (call it \hat{H}_2) of Qr_{v_1} to (ϕ, d, Qr_q) in $X_{M_0} - B_{M_1(N)}(*)$, where ϕ is an edge path in $A - B_{M_1(N)}(*)$ from v_1 to v_0 . Equivalently \hat{H}_2 is a proper homotopy rel $\{w\}$ of (d, Qr_q) to (ϕ^{-1}, Qr_{v_1}) in $X_{M_0} - B_{M_1(N)}(*)$.

$$\hat{H}_2: (d, Qr_q) \sim_w (\phi^{-1}, Qr_{v_1}) \to X_{M_0} - B_{M_1(N)}(*).$$

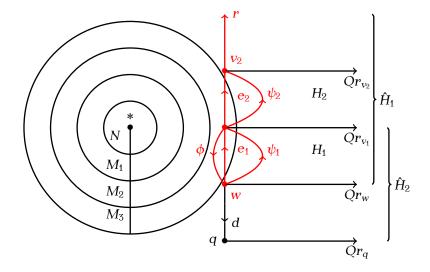


Figure 7: Multiple Homotopies

Combining the homotopies H_2, H_3, \ldots gives \hat{H}_3 , a proper homotopy \hat{H}_3 rel $\{v_1\}$ of Qr_{v_1} to (ψ_2, ψ_3, \ldots) in $X_{M_0} - B_{M_1(N)}(*)$.

$$\dot{H}_3: Qr_{v_1} \sim_{v_1} (\psi_2, \psi_3, \ldots) \to X_{M_0} - B_{M_1(N)}(*).$$

Combining \hat{H}_2 and \hat{H}_3 gives \hat{H}_4 a proper homotopy rel $\{w\}$ of (d, Qr_q) to $(\phi^{-1}, \psi_2, \psi_3, \ldots)$ in $X_{M_0} - B_{M_1(N)}(*)$.

$$\hat{H}_4: (d, Qr_q) \sim_w (\phi^{-1}, \psi_2, \psi_3, \ldots) \to X_{M_0} - B_{M_1(N)}(*).$$

Whether or not $A \in \mathcal{A}_N$, the definition of $M_1(N)$, implies there is a proper homotopy rel $\{w\}$ (call it \hat{H}_5) of $(\phi^{-1}, \psi_2, \psi_3, \ldots)$ to (ψ_1, ψ_2, \ldots) in $\Gamma(A) - St_N(*)$.

$$\hat{H}_5: (\phi^{-1}, \psi_2, \psi_3, \ldots) \sim_w (\psi_1, \psi_2, \ldots) \to \Gamma(A) - St_N(*).$$

Combining \hat{H}_1 , \hat{H}_5 and \hat{H}_4 gives a proper homotopy rel $\{w\}$ of Qr_w to (d, Qr_q) by a homotopy in $X_{M_0} - B_N(*)$.

$$Qr_w \sim_w (\psi_1, \psi_2, \ldots) \sim_w (\phi^{-1}, \psi_2, \psi_3, \ldots) \sim_w (d, Qr_q)$$

Theorem 9.3 Suppose G is a 1-ended finitely presented group that is hyperbolic relative to \mathbf{P} a finite collection of 1-ended finitely presented proper subgroups of G. If each $P \in \mathbf{P}$ has semistable fundamental group at ∞ , then G has semistable fundamental group at ∞ .

Proof: If r is a proper edge path ray in X_{M_0} and based at *, then r is properly homotopic to any projection Qr of r to Y. Hence we need only consider proper edge path rays based at * and with image in Y. Let $r_* = l^+$. We show for any proper edge path ray s at * and with image in Y, s is properly homotopic rel{*} to Qr_* in X_{M_0} . Then, if s_1 and s_2 are arbitrary proper edge path rays at * and with image in Y we have both are properly homotopic rel{*} to r_* in X_{M_0} and hence s_1 is properly homotopic to s_2 rel{*} in X_{M_0} . This means X_{M_0} has semistable fundamental group at ∞ .

Write s as the edge path $(e_1, e_2, ...)$ and say that v_i is the initial vertex of e_i . Let $0 < N_1 < N_2 < \cdots$ be a sequence of integers such that $M_{9,2}(N_i) < N_{i+1}$ for all $i \ge 1$. Since s is proper, there is an integer K_2 such that for all $i \ge K_2$, e_i has image in $Y - B_{N_2}(*)$. Given an integer j > 2 there is an integer $K_j \ge K_{j-1}$ such that for all $i \ge K_j$, e_i has image in $Y - B_{N_j}(*)$. For $1 \le i < K_2$, Lemma 9.2 implies there is a proper homotopy H_i rel $\{v_i\}$ of Qr_{v_i} to $(e_i, Qr_{v_{i+1}})$.

For $j \geq 2$ and $K_j \leq i < K_{j+1}$, the edge e_i has image in $Y - B_{N_j}(*)$. For such *i*, we use Lemma 9.2 to obtain a proper homotopy H_i rel $\{v_i\}$ of Qr_{v_i} to $(e_i, Qr_{v_{i+1}})$ with image in $X_{M_0} - B_{N_{j-1}}(*)$. Let *H* be the homotopy obtained by combining the homotopies H_i as in Figure 8.

For $j \ge 2$ and $K_j \le i < K_{j+1}$, the edge e_i has image in $Y - B_{N_j}(*)$. For such *i*, we use Lemma 9.2 to obtain a proper homotopy H_i rel $\{v_i\}$ of Qr_{v_i} to $(e_i, Qr_{v_{i+1}})$ with image in $X_{M_0} - B_{N_{j-1}}(*)$. Let *H* be the homotopy obtained by combining the homotopies H_i as in Figure 8.

It suffices to show that H is proper. Let C be compact in X_{M_0} and j such that $C \subset B_{N_j}(*)$. Then for all $k \geq K_{j+1}$, H_k has image in $X_{M_0} - B_{N_j}(*) \subset X_{M_0} - C$. Then $H^{-1}(C) = \bigcup_{i=1}^{K_{j+1}} H_i^{-1}(C)$ is a finite union of compact sets and H is proper. \Box

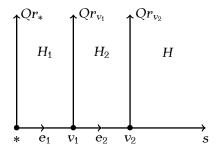


Figure 8: Final Homotopies

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