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## Hybrid Contract Checking via Symbolic Simplification

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#### Abstract

Program errors are hard to detect and to prove absent. Contract checking allows us to (a) statically verify that a function satisfies its contract; (b) precisely blame functions at fault both statically and dynamically when there is a contract violation. Static contract checking catches all bugs but can only check restricted properties while dynamic checking can check more expressive properties, but is not complete. In this paper, we integrate static and dynamic contract checking for a subset of OCaml. We exploit a static checker as much as possible and leave the residual contract satisfaction checks to run-time. Thus, no (potential) bugs can escape and yet expressive properties can be expressed.


Key-words: contract semantics, static, dynamic, hybrid, contract checking, functional language, verification, debugging

## Vérification de contrats hybride par simplification symbolique

Résumé : Il est difficile de détecter des erreurs dans des programmes, ou de démontrer leur absence. Permettre aux programmeurs d'écrire des spécifications formelles et précises, en particulier sous la forme de contrats, est une approche commune pour vérifier des programmes et trouver des erreurs. Nous formalisons et proposons une implémentation d'un vérificateur hybride de contrats pour un sous-ensemble d'OCaml. La technique principale que nous mettons en œuvre est la simplification symbolique, qui permet de combiner facilement les vérifications statiques et dynamiques de contrats. La technique que nous proposons consiste à vérifier qu'une fonction satisfait son contrat ou indique quelle est la fonction à l'origine de sa violation. Quand la satisfaction d'un contrat n'est pas décidable statiquement, du code de test est ajouté au programme afin d'effectuer les vérifications à l'exécution.

Mots-clés : la sémantique du contrat, statique, dynamique, hybride, langage fonctionnel, vérification, débogage

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## 1 Introduction

Constructing reliable software is difficult even with functional languages. Formulating and checking (statically or dynamically) logical assertions [18, 15, 2, 55, 35, especially in the form of contracts [28, 13, 7, 14, 39, is one popular approach to error discovery. Static contract checking can catch all contract violations but may give false alarm and can only check restricted properties; dynamic checking can check more expressive properties but consumes run-time cycles and only checks the actual executed paths, thus is not complete. Static and dynamic checking can be complementary. In this paper, we formalize hybrid (i.e. static followed by dynamic) contract checking for a subset of OCaml. Thus, no (potential) contract violations can escape and yet expressive properties can be expressed.

Consider an OCaml program augmented with a contract declaration:

```
(* val f1 : int -> int -> int *)
contract \(f 1=(\{x \mid x>=0\}->\{y \mid y>=0\})\)
    -> \(\{z \mid z>=0\}\)
let \(\mathrm{f} 1 \mathrm{~g}=(\mathrm{g} 1)-1\)
let \(\mathrm{f} 2=\mathrm{f} 1(\mathrm{fun} \mathrm{x}->\mathrm{x}-1)\)
```

The contract of $f 1$ says that if $f 1$ takes a function that returns a non-negative number when given a non-negative number, the function $f 1$ itself returns a non-negative number. Both a static checker and a dynamic checker are able to report that f 1 fails its postcondition: the static checker relies on the invalidity of $\forall g$ : int $\rightarrow$ int, $(g 1) \geq 0 \Rightarrow(g 1)-1 \geq 0$ while the dynamic checker evaluates (( fun $x->x-1) 1)-1)$ to -1 , which violates the contract $\{z \mid z>=0\}$. However, a dynamic checker cannot tell that the argument (fun $x$-> $x-1$ ) fails f1's precondition because there is no witness at runtime, while a static checker can report this contract violation because $x-1 \geq 0$ does not hold for all $x$ of int to satisfy the postcondition $\{y \mid y \geq 0\}$. On the other hand, a static checker usually gives three outcomes: (a) definitely no bug; (b) definitely a bug; (c) possibly a bug. Here, a bug refers to a contract violation. If we get many alarms (c), it may take us a lot of time to check which one is a real bug and which one is a false alarm. We may want to invoke a dynamic checker when the outcome is (c).

Following the formalization in [39], but this time for a strict language. We first give a denotational semantics to contract satisfaction. That is to define what it means by an expression $e$ satisfies its contract $t$ (written $e \in t$ ) without knowing its implementation. Next, we define a wrapper $\triangleright$ that takes an expression $e$ and its contract $t$ and produces a term $e \triangleright t$ such that contract checks are inserted at appropriate places in $e$. If a contract check is violated, a special constructor $\mathrm{BAD}^{l}$ signals the violation. As the term $e \triangleright t$ is a term in the same language as $e$, all we have to do is to check the reachability of $\mathrm{BAD}^{l}$. If a BAD is reachable, we know a contract is violated and the label $l$ precisely captures the function at fault. We symbolically simplify the term $e \triangleright t$ aiming to simplify BADs away. In case there is any BAD left, we either report it as a compile-time error or leave the residual code for dynamic checking. We make the following contributions:

- We clarify the relationship between static contract checking and dynamic contract checking (82). A new observation is that, after static checking,
we should prune away some more unreachable code before go on dynamic checking. Such unreachable code however is essential during static checking. We prove the correctness of this pruning (86) with the telescoping property studied (but not used for such purpose) in [7, 39].
- We define $e \in t$ and $e \triangleright t$ and prove a theorem " $e \triangleright t$ is crash-free $\Longleftrightarrow e \in t$ " (\$4). The "crash-free" means "BAD is not reachable under all contexts". Such a formalization is tricky and its correctness proof is non-trivial. We re-do the kind of proofs in [40] for a strict language.
- We design a novel SL machine that augments symbolic simplification with contextual information synthesis for checking the reachability of BAD statically (\$5). The difficulty lies in the reasoning about non-total terms. The checking is automatic and modular and we prove is soundness. Moreover, the SL machine produces residual code for dynamic checking. We compare our framework with other approaches in $\$ 7$
- We design a logicization technique that transforms expressions to logical formulae, inspired by [20, 19] and axiomatization of functions that interactive theorem provers perform before calling SMT sovlers. However, we have to deal with non-total terms and that is the key contribution of the logicization (\$5).


## 2 Overview

Assertions [18] state logical properties of an execution state at arbitrary points in a program; contracts specify agreements concerning the values that flow across a boundary between distinct parts of a program (modules, procedures, functions, classes). If an agreement is violated, contract checking is supposed to precisely blame the function at fault. Contracts were first introduced to be checked at run-time [28, 13]. To perform dynamic contract checking (DCC), a function must be called to be checked. For example:

```
contract inc = {x | x > 0} -> {y | y > 0}
let inc = fun v -> v + 1
let t1 = inc 0
```

A dynamic checker wraps the inc in t 1 with its contract $t_{\text {inc }}$ :

$$
\text { let } \mathrm{t} 1=\left(\operatorname{inc} \underset{\mathrm{BAD}^{l^{\prime}}}{\stackrel{\mathrm{BAD}}{ }{ }^{l}} t_{\text {inc }}\right) 0
$$

where $l$ is ( 2,5 , "inc") indicating the source location where inc is defined (row:2,col:5) and $l^{\prime}$ is (3,10, "t1") indicating the location of the call site with caller's name. This wrapped t1 expands to:

$$
\begin{aligned}
& \left(\lambda x _ { 1 } \text { . let } y = \text { inc } \vdots \left(\text { let } x=x_{1}\right.\right. \text { in } \\
& \text { if } \left.x>0 \text { then } x \text { else } \operatorname{BAD}^{(3,10, " t 1 ")}\right) \\
& \text { in if } y>0 \text { then } y \text { else } \operatorname{BAD}^{(2,5, \text { "inc") })} 0
\end{aligned}
$$

In the upper box, the argument of inc is guarded by the check $x>0$; in the lower box, the result of inc is guarded by the check $y>0$. If a check succeeds, the
original term is returned; otherwise, the special constructor BAD is reached and a blame is raised. In this case, t1 calls inc with 0 , which fails inc's precondition. Running the above wrapped code, we get BAD ${ }^{(3,10, ~ " t 1 ")}$, which precisely blames t1.

The DCC algorithm is like this. Given a function $f$ and a contract $t$, to check that the callee $f$ and its caller agree on the contract $t$ dynamically, a checker wraps each call to $f$ with its contract:

$$
f \underset{\mathrm{BAD}^{\mathrm{BAD}}}{\bigotimes^{f}} t
$$

which behaves the same as $f$ except that (a) if $f$ disobeys $t$, it blames $f$, signaled by $\mathrm{BAD}^{f}$; (b) if the context uses $f$ in a way not permitted by $t$, it blames the caller of $f$, signaled by BAD? where "?" is filled with a caller name and the call site location.

Later, [7, 39] give formal declarative semantics for contract satisfaction that not only allow us to prove the correctness of DCC w.r.t. this semantics, but also to check contracts statically.

The essence of static contract checking (SCC) is:

The $\triangleright$ ("ensures") and the $\triangleleft$ ("requires") are dual to each other. The special constructor UNR (pronounced "unreachable"), does not raise a blame, but stops an execution. (One, who is familiar with assert and assume, can think of (if $p$ then $e$ else BAD ) as (assert $p ; e$ ) and (if $p$ then $e$ else UNR) as (assume $p ; e$ ).)

SCC is modular and performed at definition site of each function. For example, $(\lambda v \cdot v+1) \triangleright t_{\text {inc }}$ expands to:

$$
\begin{aligned}
& \lambda x_{1} . \text { let } y= \\
&(\lambda v \cdot v+1) \\
&\left(\text { let } x=x_{1} \text { in if } x>0 \text { then } x \text { else } \mathrm{UNR}^{?}\right) \text { in } \\
& \text { if } y>0 \text { then } y \text { else } \operatorname{BAD}^{(2,5, " i n c ") ~}
\end{aligned}
$$

At the definition site of a function, $f=e$, we assume $f$ 's precondition holds and assert its postcondition. If all BADs in $e \triangleright t$ are not reachable, we know $f$ satisfies its contract $t$. One way to check reachability of BAD is to symbolically simplify the fragment. In the above case, inlining $x$, we get:

$$
\begin{aligned}
& \lambda x_{1} . \text { let } y=(\lambda v \cdot v+1)\left(\text { if } x_{1}>0 \text { then } x_{1} \text { else UNR? }\right) \text { in } \\
& \text { if } y>0 \text { then } y \text { else } \operatorname{BAD}^{(2,5, \text { "inc" })}
\end{aligned}
$$

Unlike [37] in a lazy setting, we cannot apply beta-reduction in a strict language if an argument is not a value as it may not preserve the semantics. In this paper, besides symbolic simplification, we collect contextual information in logical formula form and consult an SMT solver to check the reachability of BAD. An SMT solver usually deals with formulae in first order logic (FOL), \$5 gives the details of the generation of formulae in FOL. As an overview, we present formulae in higher order logic (HOL). For the two subexpressions of the RHS of $y$, we have:

| $\lambda v . v+1$ | $\exists x_{2},\left(\forall v, x_{2}(v)=v+1\right)$ |
| :--- | ---: |
| if $x_{1}>0$ then $x_{1}$ else UNR? | $\exists x_{3},\left(x_{1}>0 \Rightarrow x_{3}=x_{1}\right) \vee$ |
|  | $\left(\operatorname{not}\left(x_{1}>0\right) \Rightarrow\right.$ false $)$ |

One can think of the existentially quantified $x_{2}$ (and $x_{3}$ ) denoting the expression itself. For the RHS of $y$, we have logical formula:

$$
\begin{array}{ll}
\forall y, \exists x_{2},\left(\forall v, x_{2}(v)=v+1\right) \wedge\left(\exists x_{3},\left(x_{1}>0 \Rightarrow\right.\right. & \left.x_{3}=x_{1}\right) \\
\left.\wedge\left(\operatorname{not}\left(x_{1}>0\right) \Rightarrow \text { false }\right) \wedge y=x_{2}\left(x_{3}\right)\right) & {[\mathrm{Q} 1]}
\end{array}
$$

We check the validity of $\forall x_{1}, \mathrm{Q} 1 \Rightarrow y>0$ by consulting an SMT solver. As $\forall x_{1}, \mathrm{Q} 1 \Rightarrow y>0$ is valid, we know the $\mathrm{BAD}^{(2,5, " \text { inc" })}$ is not reachable, thus inc satisfies its contract.

Consider the function f 1 and its contract $t_{\mathrm{f} 1}$ in $\S 1$. So $f 1 \triangleright t_{\mathrm{f} 1}$ is $(\lambda g .(g 1)-$ 1) $\triangleright(\{x \mid x \geq 0\} \rightarrow\{y \mid y \geq 0\}) \rightarrow\{z \mid z \geq 0\}$, which expands to:

$$
\left.\begin{array}{rl}
\lambda x_{1} . \text { let } z= & (\lambda g \cdot(g 1)-1) \\
& \left(\lambda x_{2} . \text { let } y=x_{1}\left(\text { let } x=x_{2}\right. \text { in }\right. \\
& \text { if } x \geq 0 \text { then } x \\
\text { else } \left.\operatorname{BAD}^{(4,5, "} f_{1} "\right)
\end{array}\right) \text { in } .
$$

After applying some conventional simplification rules, we have:

$$
\begin{aligned}
\text { R1: } \lambda x_{1} . & \text { let } z= \\
& \text { let } y=x_{1} 1 \text { in } \\
& \text { if } y \geq 0 \text { then } y-1 \text { else } \operatorname{UNR}^{?}
\end{aligned}
$$

We see that the inner $\operatorname{BAD}^{\left(4,5, "{ }_{1}{ }^{\prime}\right)}$ has been simplified away, because $x=x_{2}=1$ and (if $1 \geq 0$ then 1 else $\operatorname{BAD}^{\left(4,5, " f_{1} "\right)}$ ) is simplified to 1 . As we cannot prove $\forall x_{1}, \forall z,\left(\exists y, y=x_{1} 1 \wedge(y \geq 0 \Rightarrow z=y-1)\right) \Rightarrow z \geq 0$ to be valid, the other $\operatorname{BAD}^{\left(4,5, " f_{1} "\right)}$ remains. We can either report this potential contract violation at compile-time or leave this residual code R1 for DCC to achieve hybrid checking.

Hybrid contract checking (HCC) performs SCC first and runs the residual code as in DCC. In SCC, $f 1 \triangleright t_{f 1}$ checks whether $f 1$ satisfies its postcondition by assuming its precondition holds. At each call site of f1, we wrap the function with $\triangleleft$. For example:

```
contract f3 = {v | v >= 0}
let f3 = f1 zut
```

where zut is a difficult function for an SMT solver and zut's contract is $\{x \mid$ true $\}$. Say zut $\triangleleft\{x \mid$ true $\}=$ zut, we then have the term $f 3 \triangleright t_{f 3}$ to be:

$$
\left(\left(\mathrm{f} 1 \triangleleft t_{\mathrm{f} 1}\right) \text { zut }\right) \triangleright\{v \mid v>0\}
$$

which requires $f 3$ to satisfy $f 1$ 's precondition and assumes $f 1$ satisfies its postcondition because $f 1 \triangleright t_{f 1}$ has been checked. During SCC, a top-level function is never inlined. We do not have to know its detailed implementation at its call
site as it has been guarded by its contract with $f \triangleleft t$. The $\mathrm{f} 3 \triangleright t_{\mathrm{f} 3}$ expands to:

```
let v= let }z=\textrm{f}
    (\lambda\mp@subsup{x}{2}{}.let y = zut (let }x=\mp@subsup{x}{2}{}\mathrm{ in
    if }x\geq0\mathrm{ then }
    else UNR(7,10,"f}\mp@subsup{f}{1}{}\mp@subsup{}{}{\prime\prime})\mathrm{ ) in
        if }y\geq0\mathrm{ then }y\mathrm{ else BAD (7,10,"f}\mp@subsup{f}{3}{}\mp@subsup{}{}{\prime\prime}) ) in
    if z\geq0 then z else UNR (7,10," }\mp@subsup{f}{1}{\prime")
if v\geq0 then v else BAD (7,10,"f}\mp@subsup{f}{3}{\prime")
```

As $\triangleleft$ is dual to $\triangleright$, the RHS of $v$ is actually a copy of the earlier $f 1 \triangleright t_{f 1}$ but swapping the BAD and UNR and substituting $x_{1}$ with zut. We now know the source location of the call site of $f 1$ and its caller's name, the UNR? becomes $\operatorname{BAD}^{\left(7,10, " f_{3} "\right)}$ and the $\operatorname{BAD}^{\left(4,5, " f_{1} "\right)}$ becomes $\operatorname{UNR}^{\left(7,10, " f_{1} "\right)}$. At definition site where the caller is unknown, we use the location of $f 1$, i.e. $\left(4,5\right.$, " $f_{1}$ "). Once its caller is known, we use $\left(7,10, " f_{1} "\right)$. It is easy to get source location, which is for the sake of error message reporting. So we do not elaborate the source location further.

As an SMT solver says valid for $\forall v \cdot(\exists z . z \geq 0 \wedge v=z) \Rightarrow v \geq 0$, the $\mathrm{f} 3 \triangleright t_{\mathrm{f} 3}$ can be simplified to (say R2):

$$
\begin{aligned}
& \text { let } z=\mathrm{f} 1 \\
& \left(\lambda x_{2} \text {. let } y=\text { zut } \quad \text { (let } x=x_{2}\right. \text { in } \\
& \text { if } x>0 \text { then } x \\
& \text { else } \left.\operatorname{UNR}^{(7,10, "} f_{1} "\right) \text { in } \\
& \text { if } y \geq 0 \text { then } y \text { else } \operatorname{BAD}^{\left(7,10, " f_{3} "\right)} \text { ) in }
\end{aligned}
$$

One BAD remains. We can either report this potential contract violation at compile-time or continue a DCC. For SCC, we have checked $f 1 \triangleright t_{f 1}$, but for DCC, to invoke $f 1 \triangleright t_{f 1}$, we must use the residual code R1. However, the UNR clauses are useful for SCC, but redundant for DCC. We can remove UNRs with a simplification rule:

$$
\left(\text { if } e_{0} \text { then } e_{1} \text { else UNR }\right) \Longrightarrow e_{1} \quad[\mathrm{rmUNR}]
$$

(We shall explain why it is valid to apply this rule even if $e_{0}$ may diverge or crash in §6. Intuitively, UNR is indeed unreachable and $e_{0}$ has been checked before this program point.) Applying the rule [rmUNR] to R1 and R2 and simplify a bit, we get:

$$
\begin{aligned}
& \mathrm{f} 1 \sharp=\lambda x_{1} . \text { let } z=\left(\text { let } y=\left(x_{1} 1\right) \text { in } y-1\right) \text { in } \\
& \text { if } z \geq 0 \text { then } z \text { else } \operatorname{BAD}^{\left(4,5, " f_{1} "\right)} \\
& \mathrm{f} 2 \sharp=\mathrm{f} 1 \sharp \quad\left(\lambda x_{2} \cdot \operatorname{let} y=\operatorname{zut} x_{2}\right. \text { in } \\
& \text { if } \left.y \geq 0 \text { then } y \text { else } \operatorname{BAD}^{\left(7,10, " f_{3} "\right)}\right)
\end{aligned}
$$

respectively, which is the residual code being run. We show in $\$ 6$ that HCC blames a function $f_{i}$ iff DCC blames $f_{i}$.

Summary Given a definition $f=e$ and a contract $t$, to check $e$ satisfies $t$ (written $e \in t$ ), we perform these steps. (1) Construct $e \triangleright t$. (2) Simplify $e \triangleright t$ as much as possible to $e^{\prime}$, consulting an SMT solver when necessary. (3) If no

BAD is in $e^{\prime}$, then there is no contract violation; if there is a BAD in $e^{\prime}$ but no function call in $e^{\prime}$, then it is definitely a bug and report it at compile-time; if there is a BAD and function call(s) in $e^{\prime}$, then it is a potential bug. (4) For each function $f$, create its residual code $f \sharp$ by simplifying $e^{\prime}$ with the rule [rmUNR], and run the program with each $f$ being replaced by $f \sharp$.

## 3 The language

The language presented in this paper, named M , is pure and strict, a subset of OCaml, including parametric polymorphism.

### 3.1 Syntax

```
\(x, f \in\) Variables \(\quad T \in\) Type constructors
                                    \(K \in\) Data constructors
\(p g m \quad::=d e f_{1}, \ldots, d e f_{n} \quad\) Program
\(\tau \quad::=\vec{\tau} T \mid \tau_{1} \rightarrow \tau_{2} \quad\) Types
\(t \in\) Contracts
\(t \quad::=\{x \mid p\} \quad\) predicate contract
    \(\mid x: t_{1} \rightarrow t_{2} \quad\) dependent function contract
    | \(\left.x: t_{1}, t_{2}\right)\) dependent tuple contract
    Any polymorphic Anycontract
def \(\in\) Definitions
def \(::=\) type \(\overrightarrow{{ }^{\prime} \alpha} T=\overrightarrow{K \text { of } \vec{\tau}}\)
    | contract \(f=t\)
    let \(f \vec{x}=e \quad\) top-level function
    | let rec \(f \vec{x}=e\) top-level recursive function
\(a, e, p \in \operatorname{Exp} \quad\) Expressions
\(a, e, p \quad:=n \quad\) integers
        | \(r\) blame
        \(x\left|\lambda\left(x^{\tau}\right) . e\right| e_{1} \xrightarrow{e_{2}}\)
        match \(e_{0}\) with \(\xrightarrow{\text { alt }}\)
            pattern-matching
            constructor
```

```
r ::= BAD | UNR }\mp@subsup{}{}{l}\mathrm{ ( Blames
```

r ::= BAD | UNR }\mp@subsup{}{}{l}\mathrm{ ( Blames
l ::= ( }\mp@subsup{n}{1}{},\mp@subsup{n}{2}{},\mathrm{ String) Label
l ::= ( }\mp@subsup{n}{1}{},\mp@subsup{n}{2}{},\mathrm{ String) Label
alt ::= K( }\mp@subsup{x}{1}{\mp@subsup{\tau}{1}{}},···,\mp@subsup{x}{n}{\mp@subsup{\tau}{n}{}})->e\quad\mathrm{ Alternatives

```
alt ::= K( }\mp@subsup{x}{1}{\mp@subsup{\tau}{1}{}},\ldots,\mp@subsup{x}{n}{\mp@subsup{\tau}{n}{}})->e\quad\mathrm{ Alternatives
```




Figure 1: Syntax of the language M

Figure 1 gives the syntax of language M. A program contains a set of data type declarations, contract declarations and function definitions. Expressions include variables, lambda abstractions, applications, constructors and matchexpressions. Base types such as int and bool are data types with no parameter. Pairs are a special case of constructed terms, i.e. $\left(e_{1}, e_{2}\right)$ is Pair $\left(e_{1}, e_{2}\right)$ with type (' $\mathrm{a}, \mathrm{\prime} \mathrm{~b}$ ) product $=$ Pair of ' $\mathrm{a} *$ ' b . We have top-level let rec, but for the ease of presentation, we omit local let rec. (It is possible to allow local let rec by either assuming that a local recursive function is given a contract or using contract inference [21] to infer its contract. Even if [21] is not modular, it is good enough to infer a contract for a local function.) A local let-expression let $x=e_{1}$ in $e_{2}$ is a syntactic sugar for $\left(\lambda x . e_{2}\right) e_{1}$. An if-expression if $e_{0}$ then $e_{1}$ else $e_{2}$ is syntactic sugar for match $e_{0}$ with \{true $\rightarrow e_{1} ;$ false $\left.\rightarrow e_{2}\right\}$.

We assume all top-level functions are given a contract. Contract checking is done after the type checking phase in a compiler so we assume all expressions, contexts and contracts are well-typed and use its type information (presented as superscript, e.g. $e^{\tau}$ or $t^{\tau}$ ) whenever necessary.

The two contract exceptions (also called blames) $\mathrm{BAD}^{l}$ and $\mathrm{UNR}^{l}$ are adapted from [39]. They are for internal usage, not visible to programmers. The label $l$ contains information such as function name and source code location, which is useful for error reporting as well as for examination of the correctness of blaming. But we may omit the label $l$ when it is not the focus of the discussion.

It is possible for programmers to write:

```
let head xs = match xs with
    | [] -> raise Emptylist
    | x::l -> x
```

where raise : $\forall \alpha$. Exception $\rightarrow \alpha$. The Exception is a built-in data type for exceptions and Emptylist has type Exception. As we do not have try-with in language M (leaving it as future work), a preprocessing converts raise Emptylist to BADhead.

We have four forms of contracts. The $p$ in a predicate contract $\{x \mid p\}$ refers to a boolean expression in the same language M. Dependent function contracts allow us to describe dependency between input and output of a function. For example, $x:\{y \mid y>0\} \rightarrow\{z \mid z>x\}$ says that, the input is greater than 0 and the output is greater than the input. We can use a shorthand $\{x \mid x>0\} \rightarrow\{z \mid$ $z>x\}$ by assuming $x$ scopes over the RHS of $\rightarrow$. The $\rightarrow$ is right associative. Similarly, dependent tuple contracts allow us to describe dependency between two components of a tuple. For example, $(x:\{y \mid y>0\},\{z \mid z>x\})$ whose short hand is $(\{x \mid x>0\},\{z \mid z>x\})$. Contract Any is a universal contract that any expression satisfies. We support higher order contracts, e.g. $k:(\{x \mid$ $x>0\} \rightarrow\{y \mid y>x\}) \rightarrow\{z \mid k 5>-1\}$ for a function let $\mathrm{f} \mathrm{g}=\mathrm{g} 2$.

### 3.2 Type checking rules for expression

The language M is statically typed in the conventional way. Figure 2 gives type checking rules. A type judgement has the form

$$
\Gamma \vdash e^{\tau}
$$

which states that given $\Gamma$ (which is a mapping from variable to its type), $e$ has type $\tau$ assuming that any free variable in it has type given by $\Gamma$. If $\Gamma=\emptyset$, we omit the $\Gamma$, and write $\vdash e^{\tau}$.


Figure 2: Type Checking Rules
As we do type checking before contract checking, we assume all expressions are well-typed (i.e. no type error) in the rest of this paper. Note that nothing substantial in the paper depends delicately on the type system. The reason we ask that programs are well-typed is to avoid the technical inconvenience in designing the semantics of contracts if, say, evaluation finds an ill-typed expression (3 True).

### 3.3 Operational semantics

The semantics of our language is given by reduction rules in Figure 3. For a toplevel function, we fetch its definition from the evaluation envrionment $\Delta$. We adapt some basic definitions from [39. Definition 1 defines the usual contextual equivalence. Two expressions are said to be semantically equivalent, if under all (closing) contexts, if one evaluates to a blame $r$, the other also evaluates to the same $r$.

Definition 1 (Semantically Equivalent). Two expressions $e_{1}$ and $e_{2}$ are semantically equivalent, namely $e_{1} \equiv_{s} e_{2}$, iff for all closing $\mathcal{C}$, for all $r, \quad \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*}$ $r \quad \Longleftrightarrow \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} r$

Our framework only guarantees partial correctness. A diverging program does not crash.

Definition 2 (Diverges). A closed expression e diverges, written $e \uparrow$, iff either $e \rightarrow^{*}$ UNR, or there is no value val such that $e \rightarrow^{*}$ val.

$$
\begin{aligned}
& \frac{\text { let }(\text { rec }) f=e \in \Delta}{f \rightarrow e} \text { [E-top] } \\
& \text { ( } \lambda x . e) \mathrm{val} \rightarrow e[\mathrm{val} / \mathrm{x}] \quad \text { [E-beta] } \\
& \text { match } K \overrightarrow{v a l} \text { with } \overrightarrow{K \vec{x} \rightarrow e} \rightarrow e[\overrightarrow{v a l / x}] \quad \text { [E-match] } \\
& \frac{e_{1} \rightarrow e_{2}}{\mathcal{C} \llbracket e_{1} \rrbracket \rightarrow \mathcal{C} \llbracket e_{2} \rrbracket} \quad[\mathrm{E}-\mathrm{ctx}] \quad \mathcal{C} \llbracket r \rrbracket \rightarrow r \quad[\mathrm{E}-\mathrm{exn}] \\
& \text { Contexts } \mathcal{C}::=\llbracket \bullet \rrbracket|\mathcal{C} e| \operatorname{val} \mathcal{C} \mid K \overrightarrow{v a l} \mathcal{C} \vec{e} \\
& \text { | match } \mathcal{C} \text { with } \overrightarrow{a l t}
\end{aligned}
$$

Figure 3: Semantics of the language M

### 3.4 Crashing

We use BAD to signal that something has gone wrong in the program, which can be a program failure or a contract violation.

Definition 3 (Crash). A closed term e crashes iff $e \rightarrow^{*}$ BAD.
At compile-time, one decidable way to check the safety of a program is to see whether the program is syntactically safe.

Definition 4 (Syntactic safety). A (possibly-open) expression e is syntactically safe iff $\mathrm{BAD} \not \not_{s} e$. Similarly, a context $\mathcal{C}$ is syntactically safe iff BAD $\not s_{s} \mathcal{C}$.

The notation BAD $\not \not_{s} e$ means BAD does not syntactically appear anywhere in $e$, similarly for BAD $\not \otimes_{s} \mathcal{C}$. For example, $\lambda x \cdot x$ is syntactically safe while $\lambda x$. (BAD, $x$ ) is not.

Definition 5 (Crash-free expression). A (possibly-open) expression e is crashfree iff: for all $\mathcal{C}$ such that $\operatorname{BAD} \not \not_{s} \mathcal{C}$ and $\vdash \mathcal{C} \llbracket e \rrbracket::$ bool, $\mathcal{C} \llbracket e \rrbracket \nrightarrow^{*}$ BAD.

The notation $\vdash \mathcal{C} \llbracket e \rrbracket::$ bool means $\mathcal{C} \llbracket e \rrbracket$ is closed and well-typed. The quantified context $\mathcal{C}$ serves the usual role of a probe that tries to provoke $e$ into crashing. Note that a crash-free expression may not be syntactically safe, e.g. $\lambda x$.if $x * x \geq 0$ then $x+1$ else BAD.

Lemma 1 (Syntactically safe expression is crash-free).

$$
e \text { is syntactically safe } \Rightarrow \quad e \text { is crash-free }
$$

Proof. Since there is no BAD syntactically in $e$, for all context $\mathcal{C}$, such that there is no BAD syntatically in $\mathcal{C}$, then $\mathcal{C} \llbracket e \rrbracket \nrightarrow \rightarrow^{*}$ BAD. By definition 5 (Crash-free expression), $e$ is crash-free.

For ease of presentation, when we do not give label $l$ to BAD or UNR, we mean BAD or UNR for any $l$. Moreover, expressions $\mathrm{BAD}^{l}$ and $\mathrm{UNR}^{l}$ are closed expressions even if $l$ is not explicitly bound.

Lemma 2 (Neutering). If $e$ is crash-free, then $\lfloor e\rfloor \equiv_{s} e$.

Proof. Since $e$ is crash-free, all BADs in $e$ are not reachable so by converting all BADs in $e$ to UNR by $\lfloor$.$\rfloor does not change the semantics of e$. Formally, we prove this by induction on reduction rules.

Lemma 3 (Crash-free Preservation). Given $e_{1} \rightarrow e_{2}$,

$$
e_{1} \text { is crash-free } \Longleftrightarrow e_{2} \text { is crash-free }
$$

Proof. We prove two directions by contradiction.
$(\Rightarrow)$
Suppose $e_{2}$ is not crash-free. By Definition $5{ }^{120}$ (Crash-free Expression), there exists a $\mathcal{C}$ such that BAD $\notin_{s} \mathcal{C}$ and $\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow{ }^{*}$ BAD. By [E-ctx] and $e_{1} \rightarrow e_{2}$ and $\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD, we have: $\mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD. As we know $e_{1}$ is crash-free, we reach contradiction. Thus, we are done.
$(\Leftarrow)$
Suppose $e_{1}$ is not crash-free. By Definition $5^{112}$ (Crash-free Expression), there exists a $\mathcal{C}$ such that BAD $\not \otimes_{s} \mathcal{C}$ and $\mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*}$ BAD. By [E-ctx] and $e_{1} \rightarrow e_{2}$ and confluence of the language, we have $\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD. With the assumption that $e_{2}$ is crash-free, we reach contradiction. Thus, we are done.

Lemma 4 (Crash-free function). For all (possibly-open) terms $\lambda x$.e,

$$
\begin{aligned}
& \qquad \text { x.e is crash-free } \\
& \stackrel{\Longleftrightarrow}{\Longleftrightarrow} \text { for all (possibly-open) crash-free } e^{\prime}, e\left[e^{\prime} / x\right] \text { is crash-free. }
\end{aligned}
$$

Proof. We prove two directions separately.
$(\Rightarrow)$

$$
\begin{aligned}
& \lambda x . e \text { is crash-free } \\
& \Rightarrow \quad\left(\text { By Lemma } 2^{[12]}, e^{\prime} \text { is crash-free } \Rightarrow\left\lfloor e^{\prime}\right\rfloor \equiv_{s} e^{\prime}\right. \\
& \text { and by the definition of crash-free expression) } \\
& \text { for all crash-free } e^{\prime}, e\left[e^{\prime} / x\right] \text { is crash-free }
\end{aligned}
$$

$(\Leftarrow)$ We have the following proof.

> for all $\mathbf{c f} e^{\prime}, e\left[e^{\prime} / x\right]$ is crash-free
> $\Longleftrightarrow \quad$ (By Lemma $3^{[13]}$ )
> for all $\mathbf{c f} e^{\prime},(\lambda x . e) e^{\prime}$ is crash-free
> $\Longleftrightarrow \quad\left(\right.$ By Definition $5{ }^{12]}$ (Crash-free Expression))
> for all $\mathbf{c f} e^{\prime}, \forall \mathcal{C}, \operatorname{BAD} \not \not_{s} \mathcal{C}, \mathcal{C} \llbracket(\lambda x . e) e^{\prime} \rrbracket \nrightarrow^{*} \mathrm{BAD}$
> $\Rightarrow \quad\left(\right.$ By Lemma $2, e^{\prime}$ is crash-free $\left.\Rightarrow\left\lfloor e^{\prime}\right\rfloor \equiv_{s} e^{\prime}\right)$
> $\forall \mathcal{C}, \mathrm{BAD} \not$ s $_{s} \mathcal{C}, \mathcal{C} \llbracket(\lambda x . e)\left\lfloor e^{\prime}\right\rfloor \rrbracket \nrightarrow^{*} \mathrm{BAD}$
> $\Rightarrow \quad\left(\mathrm{By} \mathrm{BAD} \notin s\left\lfloor e^{\prime}\right\rfloor\right)$
> $\forall \mathcal{C}, \mathrm{BAD} \notin s \mathcal{C}, \mathcal{C} \llbracket(\lambda x . e) \rrbracket \nrightarrow^{*} \mathrm{BAD}$
> $\Longleftrightarrow \quad\left(\right.$ By Definition $5^{\sqrt[12]]{12}}$ (Crash-free Expression))
> $\lambda x . e$ is crash-free

### 3.5 Behaves-the-same

We define an ordering, named Behaves-the-same, which is useful in later sections.

Definition 6 (Behaves the same). Expression $e_{1}$ behaves the same as $e_{2}$ w.r.t. a set of exceptions $R$, written $e_{1}<_{R} e_{2}$, iff for all contexts $\mathcal{C}$, such that $\forall i \in$ $\{1,2\} . \vdash \mathcal{C} \llbracket e_{i} \rrbracket::$ bool

$$
\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} r \in R \quad \Rightarrow \quad \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} r
$$

Definition $6^{[14]}$ says that $e_{1}$ either behaves the same as $e_{2}$ or throws an exception from $R$. (The definition does not look as strong as that, but as every theorist knows, it is. For example, could $e_{1}$ produce true while $e_{2}$ produces false? No, because we could find a context $\mathcal{C}$ that would make $\mathcal{C} \llbracket e_{2} \rrbracket$ throw an exception while $\mathcal{C} \llbracket e_{1} \rrbracket$ does not.) In our framework, there are only two exceptional values in $R$ : BAD and UNR. Certainly, if $e_{2}$ itself throws an exception, then $e_{1}$ must throw the same exception.

As we only have two exceptional values BAD, UNR (which are dual to each other) in $R$, this yields Lemma ${ }^{5}{ }^{110}$. We omit $\}$ if there is only one element in $R$.

Lemma 5 (Properties of Behaves-the-same). For all closed $e_{1}$ and $e_{2}$,

$$
e_{1}<_{\text {UNR }} e_{2} \Longleftrightarrow e_{2}<_{\text {BAD }} e_{1}
$$

Proof. We prove two directions separately.
$(\Rightarrow)$ We have the following proof:

$$
\begin{array}{ll} 
& e_{1}<_{\text {UuR }} e_{2} \\
\Longleftrightarrow \quad & \left(\text { By defn of }<_{\text {UNR }}\right) \\
& \forall \mathcal{C} \cdot \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} \text { UNR } \Rightarrow \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} \text { UNR } \\
\Longleftrightarrow \quad & (\text { By logic }) \\
& \forall \mathcal{C} \cdot \mathcal{C} \llbracket e_{1} \rrbracket \nrightarrow^{*} \text { UNR } \Rightarrow \mathcal{C} \llbracket e_{2} \rrbracket \nrightarrow^{*} \text { UNR }
\end{array}
$$

We want to show that $\forall \mathcal{D} \cdot \mathcal{D} \llbracket e_{1} \rrbracket \rightarrow^{*} \mathrm{BAD} \Rightarrow \mathcal{D} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD.
Assume $\mathcal{D} \llbracket e_{1} \rrbracket \rightarrow^{*}$ BAD.
Let $\mathcal{C}=\operatorname{match}(\mathcal{D} \llbracket \bullet \rrbracket)$ with $\{$ DEFAULT $\rightarrow$ UNR $\}$
Now we have $\mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} \mathrm{BAD} \Rightarrow \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ UNR.
Since $\mathcal{C} \llbracket e_{2} \rrbracket=$ case $\mathcal{D} \llbracket e_{2} \rrbracket$ with $\{$ DEFAULT $\rightarrow$ UNR $\}$, we have $\mathcal{D} \llbracket e_{2} \rrbracket \rightarrow{ }^{*}$ BAD.
So we have

$$
\forall \mathcal{D} \cdot \mathcal{D} \llbracket e_{1} \rrbracket \rightarrow^{*} \mathrm{BAD} \Rightarrow \mathcal{D} \llbracket e_{2} \rrbracket \rightarrow^{*} \mathrm{BAD}
$$

$(\Leftarrow)$ By replacing BAD by UNR and UNR by BAD in the above proof for the direction $(\Rightarrow)$, we get the proof for the direction $(\Leftarrow)$.

### 3.6 Crashes-more-often

We study a specialized ordering crashes-more-often, which plays a crucial role in proving our main theorems.

Definition 7 (Crashes-more-often). An expression $e_{1}$ crashes more often than $e_{2}$, written $e_{1} \preceq e_{2}$, iff $e_{1}<_{\text {вар }} e_{2}$.

Informally, $e_{1}$ crashes more often than $e_{2}$ if they behave in exactly the same way except that $e_{1}$ may crash when $e_{2}$ does not. By Definition $7^{114]}$, Lemma $5^{1{ }^{114}}$ also says that:

$$
e_{1}<_{\text {UNR }} e_{2} \Longleftrightarrow e_{2} \preceq e_{1}
$$

Theorem 1 (Crashes-more-often is AntiSymmetric). For all expressions $e_{1}$ and $e_{2}, e_{1} \preceq e_{2}$ and $e_{2} \preceq e_{1}$ iff $e_{1} \equiv_{s} e_{2}$.
Proof. It follows immediately from the definition of $\equiv_{s}\left(\right.$ Definition ${ }^{11}$ ) and the definition of $\preceq$.

The crashes-more-often operator has many properties. Lemma $6^{\sqrt[15]{15}}$ says that BAD crashes-more-often then all expressions; all expressions crash more often then a diverging expression. Lemma $]^{\frac{1.50}{15}}$ gives more intuitive properties.

Lemma 6 (Properties of Crashes-more-often - I).
(a) $\mathrm{BAD} \preceq e_{2}$
(b) $e_{1} \preceq e_{2} \quad$ if $e_{2} \uparrow$

Proof. We prove each property separately (all by contradiction) and we assume type soundness.
(a) Assume there exists a context $\mathcal{C}$ such that $\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD and $\mathcal{C} \llbracket \mathrm{BAD} \rrbracket \nrightarrow^{*}$ BAD. There are two possibilities for $\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD: (1) the BAD is from the context $\mathcal{C}$; (2) the BAD is from the hole $e_{2}$. For case (1), we must have $\mathcal{C} \llbracket B A D \rrbracket \rightarrow{ }^{*}$ BAD since we use the same context $\mathcal{C}$. For case (2), if the hole is evaluated, we reach BAD immediately. So we reach a contradiction and we are done.
(b) Given $e_{2} \uparrow$, assume there exists a context $\mathcal{C}$ such that $\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD and $\mathcal{C} \llbracket e_{1} \rrbracket \nrightarrow^{*}$ BAD. Since $e_{2} \uparrow$ and $\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD, we know the BAD is from the context $\mathcal{C}$. So no matter what $e_{1}$ is, we have $\mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*}$ BAD. Thus, we again reach a contradiction and we are done.

Lemma 7 (Properties of Crashes-more-often - II). If $e_{1} \preceq e_{2}$

$$
\begin{aligned}
& \text { (a) } \quad e_{1} \rightarrow^{*} K \overline{f_{1}} \Rightarrow e_{2} \rightarrow^{*} K \overline{f_{2}} \text { or } e_{2} \uparrow \\
& \text { (b) } \quad e_{1} \uparrow \Rightarrow e_{2} \uparrow \\
& \text { (c) } e_{1} \text { is crash-free } \Rightarrow e_{2} \text { is crash-free } \\
& \text { (d) } e_{1} \rightarrow^{*} \lambda x . e_{1}^{\prime} \Rightarrow e_{2} \rightarrow^{*} \lambda x . e_{2}^{\prime} \text { or } e_{2} \uparrow
\end{aligned}
$$

Proof. We prove each property separately (all by contradiction):
(a) Given $e_{1} \rightarrow^{*} K \overline{f_{1}}$, assume neither $e_{2} \rightarrow^{*} K \overline{f_{2}}$ nor $e_{2} \uparrow$. Then we must have $e_{2} \rightarrow^{*}$ BAD. By the definition of $\preceq$ and the fact that $e_{1} \preceq e_{2}$, if $e_{2} \rightarrow^{*}$ BAD, then $e_{1} \rightarrow^{*}$ BAD. Since $e_{1} \rightarrow^{*} K \overline{f_{1}}$, we reach a contradiction and we are done.
(b) Given $e_{1} \uparrow$, assume $e_{2} \nmid$. Then $e_{2} \rightarrow^{*}$ val and there exists a syntactically safe context $\mathcal{C}$ such that $\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD. But $\mathcal{C} \llbracket e_{1} \rrbracket$ always diverges as $e_{1}$ diverges if $\operatorname{BAD} \not \oiint_{s} \mathcal{C}$. By the fact that $e_{1} \preceq e_{2}$ and by the definition of $\preceq$, we reach a contradiction and we are done.
(c) Given $e_{1}$ is crash-free, assume $e_{2}$ is not crash-free. By Definition $5^{\text {² }}$ (Crash-free Expression), there exists a syntactically safe context $\mathcal{C}$ such that $\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*}$ BAD. By the fact that $e_{1} \preceq e_{2}$ and by the definition of $\preceq$, we have $\mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*}$ BAD. This contradicts with another assumption that $e_{1}$ is crash-free. Since we reach a contradiction, we are done.
(d) The proof is similar to that in (a).

## 4 Contracts

Findler and Felleisen (FF) first introduced an algorithm for dynamic higher order contract checking [13]. Blume and McAllester [7] then define a semantics for contract satisfaction and show its sound-and-completeness with respect to the FF-algorithm. As the algorithm and the contract semantics are defined by two groups of people, there are some mismatches addressed in [12]. Later, [39] defines both a contract semantics and a (static) checking algorithm for a lazy language. In this paper, we follow the style in [39], design contract satisfaction and checking algorithm for a strict language. As diverging contracts make dynamic contract checking unsound (explained in Section 4.5) and we do hybrid checking, we focus on total contracts.

Definition 8 (Total contract). A contract $t$ is total iff

$$
\begin{array}{ll} 
& t \text { is }\{x \mid p\} \text { and } \lambda x . p \text { is total (i.e. crash-free, terminating) } \\
\text { or } & t \text { is } x: t_{1} \rightarrow t_{2} \text { and } t_{1} \text { is total and } \\
\text { or } t \text { is }\left(x: t_{1}, t_{2}\right) \text { and } t_{1} \text { is all valal and } \in t_{1}, t_{2}\left[v a l_{1} / x\right] \text { is total } \\
\text { or } t \text { is Any } \quad \text { for all val } l_{1} \in t_{1}, t_{2}\left[v a l_{1} / x\right] \text { is total } \\
\text { or }
\end{array}
$$

Our definition of total contract is different from that in [7], but close to the crash-free contract in [39] with an additional condition that $\lambda x . p$ is a terminating function. For example, contract $\{x \mid x \neq[]\} \rightarrow\{y \mid$ head $x>y\}$ is total in our framework because head $x$ does not crash for all $x$ satisfying $\{x \mid x \neq[]\}$. Such a contract is not total in [7] because a crashing function head is called in a predicate contract.

### 4.1 Type checking for contracts

A contract type judgement has the form

$$
\Gamma \vdash_{c} t \in \tau
$$

which states that given $\Gamma$ (a mapping from program variable to its type, and from type variable $\alpha$ to its kind $k$ ), $e$ has type $\tau$ assuming that any free variable in it has type given by $\Gamma$. Contract type checking rules are shown in Figure 4 .

$$
\begin{aligned}
& \frac{\Gamma, \alpha:: k \vdash_{c} t:: \tau}{\Gamma \vdash_{c}(\forall \alpha:: k . t):: \tau} \quad \text { [C-ForalL] } \\
& \overline{\Gamma \vdash_{c} \text { Any }:: \tau} \quad[\mathrm{C}-\mathrm{ANy}] \quad \frac{\Gamma, x:: \tau \vdash_{c} e:: \text { Bool }}{\Gamma \vdash_{c}\{x \mid e\}:: \tau} \quad \text { [C-ONE] } \\
& \frac{\Gamma \vdash_{c} t_{1}:: \tau_{1} \quad \Gamma, x:: \tau_{1} \vdash_{c} t_{2}:: \tau_{2}}{\Gamma \vdash_{c} x: t_{1} \rightarrow t_{2}:: \tau_{1} \rightarrow \tau_{2}} \quad[\mathrm{C}-\mathrm{FUN}] \\
& \frac{\Gamma \vdash_{c} t_{1}:: \tau_{i} \quad \Gamma, x:: \tau_{1} \vdash_{c} t_{2}:: \tau_{2}}{\Gamma \vdash_{c}\left(x: t_{1}, t_{2}\right)::\left(\tau_{1}, \tau_{2}\right)} \quad \text { [C-TUPLE] }
\end{aligned}
$$

Figure 4: Type Checking Rules for Contract

For a well-typed expression $e$, define $e \in t$ thus:

$$
\left.\left.\begin{array}{rl}
e \in\{x \mid p\} & \Longleftrightarrow \\
e \in x: t_{1} \rightarrow t_{2} & \Longleftrightarrow \begin{array}{l}
e \uparrow \text { or }(e \text { is crash-free and } \\
\left.p[e / x] \rightarrow^{*} \text { true }\right)
\end{array} \\
e \in\left(x: t_{1}, t_{2}\right) & \Longleftrightarrow \begin{array}{l}
e \uparrow \text { or }\left(e \rightarrow^{*} \lambda x . e_{2}\right. \text { and } \\
\left.\forall v a l_{1} \in t_{1} \cdot\left(e \operatorname{val}_{1}\right) \in t_{2}\left[v a l_{1} / x\right]\right)
\end{array} \\
{[\mathrm{A} 2]} \\
e \in \text { Any } & \Longleftrightarrow \begin{array}{l}
e \uparrow \text { or }\left(e \rightarrow^{*}\left(\text { val }_{1}, \text { val }_{2}\right)\right. \text { and } \\
\left.v a l_{1} \in t_{1} \text { and } \operatorname{val}_{2}\left[\operatorname{val}_{1} / x\right] \in t_{2}\left[\operatorname{val}_{1} / x\right]\right)
\end{array} \tag{A3}
\end{array}[\mathrm{A} 3]\right] \text { true } \quad[\mathrm{A} 4]\right] .
$$

Figure 5: Contract Satisfaction

### 4.2 A semantics for contract satisfaction

We give the semantics of contracts by defining " $e$ satisfies $t$ " (written $e \in t$ ) in Figure 5 inspired by [7, 39]. Here are some consequences: (1) a divergent expression satisfies any contract, hence all contracts are inhabited; (2) only crash-free expression satisfies a predicate contract; (3) any expression satisfies contract Any; (4) BAD only satisfies contract Any.

One difference from [39] is that, we do not allow $p[e / x]$ in [A1] to diverge while [39] allows because they only do static checking. We support dependent tuple contracts, that are not in [7, 39]. One difference from [7] is that, they say that a crashing expression does not satisifay any contract; we say that a crashing expression satisfy the universal contract Any. Having a top ordering contract is debated in [12] where a subcontract ordering is defined below. It is obvious that Any is useful in a lazy language [39] as we may want to ignore some subcomponents of a constructor. We explain why Any is also useful for a strict language in Section 4.6.

Definition 9 (Subcontract). For all closed contracts $t_{1}$ and $t_{2}, t_{1}$ is a subcontract of $t_{2}$, written $t_{1} \leqq t_{2}$, iff $\forall e . e \in t_{1} \Rightarrow e \in t_{2}$

### 4.3 The wrappers

$$
\begin{align*}
& e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}}\{x \mid p\}=\text { let } x=e \text { in if } p \text { then } x \text { else } r_{1} \quad[\mathrm{P} 1] \\
& e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} x: t_{1} \rightarrow t_{2}=\text { let } y=e \text { in } \\
& \lambda x_{1} \cdot\left(\left(y\left(x_{1} \underset{r_{1}}{\stackrel{r_{2}}{\diamond}} t_{1}\right)\right) \stackrel{r_{1}}{\stackrel{\rightharpoonup}{r_{2}}} t_{2}\left[\left(x_{1} \underset{\underline{r_{1}}}{\stackrel{r_{2}}{\diamond}} t_{1}\right) / x\right]\right) \quad[\mathrm{P} 2] \\
& e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}}\left(x: t_{1}, t_{2}\right)=\text { match } e \text { with } \\
& \left(x_{1}, x_{2}\right) \rightarrow\left(x_{1} \underset{r_{2}}{\left.\stackrel{r_{1}}{\otimes} t_{1}, x_{2} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{2}\left[\left(x_{1} \underset{\underline{r_{1}}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right) / x\right]\right) \quad \quad[\mathrm{P} 3]}\right. \\
& e \underset{r_{2}}{\stackrel{r_{1}}{\otimes}} \text { Any }=r_{2} \tag{P4}
\end{align*}
$$

Figure 6: Contract checking with the wrappers
As mentioned in Section 2, the essence of contract checking is the two wrappers $\triangleright$ and $\triangleleft$, which are dual to each other (defined in Figure 6). We omit the labels for $\triangleright$ and $\triangleleft$ whose full versions are $\triangleright_{l_{2}}^{l_{1}}$ and $\triangleleft_{l_{2}}^{l_{1}}$ respectively. The wrapped expression $e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t$ expands to a particular expression, which behaves the same as $e$ except that it raises blame $r_{1}$ if $e$ does not obey $t$ and raise $r_{2}$ if the wrapped term is used in a way disobeying $t$.

From [P1] to [P3], if $e$ crashes, the wrapped term crashes; if $e$ diverges, the wrapped term diverges. Whenever an $r_{i}$ is reached, we know the property $p$ does not evaluate to true (as in [P1]). The wrappers are defined such that Theorem 2 holds.

Theorem 2 (Sound-and-completeness of contract checking). For all closed expression $e^{\tau}$, closed and total contract $t^{\tau}$,

$$
(e \triangleright t) \text { is crash-free } \quad \Longleftrightarrow \quad e \in t
$$

The superscript $\tau$ says both $e$ and $t$ are well-typed and have the same type $\tau$. The full proof of Theorem 2 is in Appendix A, which is similar to that in [40]. In practice, we only need Thereom 3, i.e. one direction of Thereom 2,

Theorem 3 (Soundness of contract checking). For all closed expression $e^{\tau}$, closed and terminating contract $t^{\tau}$,

$$
(e \triangleright t) \text { is crash-free } \Rightarrow \quad e \in t
$$

Note that, if $t$ is terminating and $e \triangleright t$ is crash-free, then $t$ is total. Unlike [13, which assumes there is no exception from a contract itself, our contract checking algorithm helps programmers to ensure it by detecting exceptions in contracts themselves. The term $t_{2}\left[\left(v \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1} / x\right]\right.$ in [P2] and [P3] says that, we wrap each (function) call in a contract with its contract so that if there is any contract violation in a contract, we report this error. For example:

```
contract \(f=k:(\{x \mid x>0\}->\{y \mid y>0\})\)
    -> \(\{z|k|>-1\}\)
let \(\mathrm{f} \mathrm{g}=\mathrm{g} 2\)
let t2 = f (fun x -> x)
```

a contract violation occurs in $\{\mathrm{z} \mid \mathrm{k} 0>-1\}$ because the call k 0 fails k 's precondition $\{\mathrm{x} \mid \mathrm{x}>0\}$. As addressed in [10], we should blame the contract. We omit passing around the name of the contract in this paper as our focus is to check the reachability of BAD. Instead, we use $\underline{r_{1}}$ to indicate that the label of $r_{1}$ is replaced by the name of the contract.

### 4.4 Open expressions and contracts

For open expressions, we use the same idea in [39]. Suppose the declared contracts for f and g are $t_{f}, t_{g}$ respectively, and the definition of g is $\mathrm{g}=e_{g}$ where f is called in $e_{g}$. Then, instead of checking that $e_{g} \in t_{g}$, we check that

$$
\left(\lambda f . e_{g}\right) \in t_{f} \rightarrow t_{g}
$$

That means we simply lambda-abstract over any variables free in $e_{g}$. The same idea applies for the recursive functions. If the programmer specifies the contract $t_{f}$ for a definition $\mathrm{f}=e$, then it suffices to check that

$$
\lambda f . e \in t_{f} \rightarrow t_{f}
$$

which is easier because $\lambda$ f.e does not call f recursively. There is nothing new here - it is just the standard technique of loop invariants in another guise - but it is packaged very conveniently.

In other words, imagine we have a contract judgement:

$$
\Delta \vdash e \in t
$$

which states that given $\Delta$, which is a mapping from variable to its type, contract and definition.

Definition 10 (Contract judgement). We write $\Delta \vdash e \in t$ to mean that $e$ has contract $t$ assuming that any free variable in $e$ has contract given by $\Delta$ and any free variable in $t$ has definition given by $\Delta$. Suppose $\Delta=\left\{f_{1} \mapsto\right.$ $\left.\left(\tau_{1}, t_{1}, e_{1}\right), \ldots, f_{n} \mapsto\left(\tau_{n}, t_{n}, e_{n}\right)\right\}$, we define:

$$
\Delta \vdash e \in t \Longleftrightarrow \lambda f_{1} \ldots . . f_{n} . e \in t_{1} \rightarrow \cdots \rightarrow t_{n} \rightarrow t
$$

This means, in theory (i.e. in the formalization of the verification), we only need to deal with closed expressions; in practice (i.e. in the implementation), we may refer to the environment $\Delta$ when necessary. We can simply check crashfreeness of $e\left[\left(g \triangleleft t_{g}\right) / g\right] \triangleright t_{f}\left[\left(g \triangleleft t_{g}\right) / g\right]$ where a call to $g$ is replaced by $g \triangleleft t_{g}$. This idea holds for recursive calls of $f$ in $e$ as well, we check $e\left[f \triangleleft t_{f} / f\right] \triangleright t_{f}$. (Note that $f$ is not allowed to be used in $t_{f}$.)

### 4.5 Terminating contracts

We want $p$ in $\{x \mid p\}$ to be terminating because a divergent contract hides crashes. For example:

```
let rec loop x = loop x
contract fb = {x | loop x} -> {y | true}
let fb x = head []
```

$\mathrm{fb} \triangleright t_{\mathrm{fb}}$ is $\lambda x_{1} \cdot\left(\left(\lambda x\right.\right.$.head []) (if loop $x_{1}$ then $x_{1}$ else BAD)), which diverges whenever applied because of the loop. However, the function fb is not crashfree.

Consider the higher order function $f$ in Section 4.3, one might wonder whether we have to check the argument of the higher order function $f$ to be terminating because k is called in the contract. The answer is no. By inspecting [P1] and [P2], we can see that an argument is always evaluated earlier than the $x$ in $t_{2}$. So we will not encounter the situation that a divergent contract hides a crash.

We only have to prove termination of functions used in contracts, not all the functions in a program. We can adapt ideas in [26, 34, 4] to build an efficient automatic termination checker.

### 4.6 Contract Any

There is a debate in [12] on whether it is useful to have a top ordering contract Any. We want Any because we want to give a function, that always fails, a contract to satisfy, so that we do not blame it at its definition site during SCC because $\forall e, e \triangleright A n y=$ UNR, which is crash-free. Consider a popular OCaml library function:

```
contract failwith = {x | true} -> Any
let failwith str = raise (Failure str)
```

where Failure has type Exception. A caller of failwith always violates the contract Any because $\forall e, e \triangleleft$ Any $=$ BAD. For example:

```
let get a i = if i >= 0 and i < Array.length a - 1
    then a.(i) else failwith "Out of bound"
```

Whenever the else-branch is reached (either in SCC or DCC), the caller get is blamed because a safe program is meant not to invoke a function that fails. It is not useful to blame the failwith itself. Certainly, programmers' intention is not to have an index out of bound so they may give get a contract:

$$
\{a \mid \text { true }\} \rightarrow\{i \mid i \geq 0 \wedge i<\text { Array. length } a-1\} \rightarrow\{z \mid \text { true }\}
$$

so that a caller of get will be blamed if it fails get's precondition.
The example under debate in [12] is something like:

```
contract id = ({x | x /= 0} -> {y | true}) -> Any
let id x = x
let t3 = let invert y = 1/y in (id invert) 0
```

If programmers' intention is not to define a function that always fails, they should replace Any by $\{z \mid$ true $\}$, which never assigns blame because $\forall e, e \triangleright\{z \mid$ true $\}=e \triangleleft\{z \mid$ true $\}=e$. With this new contract, id is blamed in either SCC or DCC for violating its contract because id cannot guarantee a crash-free
result (required by $\{\mathrm{z} \mid$ true $\}$ ) when taking a non-crash-free function as its argument.

With the declarative semantics for contract satisfaction, contracts can be exported for separate compilation. An implementation of a function may change over time (e.g. having a more efficient implementation), but its exported contract may not change. In our framework, we respect a function's contract more than its implementation. This is different from the original purpose in [13], which only uses contracts for dynamic blaming.

We have a simple lemma for contract Any.
Lemma 8 (Contract Any). (a) If $\mathrm{BAD} \in t$, then $t=$ Any.
(b) If BAD $\triangleright t$ is crash-free, then $t=$ Any.

Proof. (a) By inspecting the definition of $\in$, the only contract that BAD satisfies is Any.
(b) By inspecting the definition of $\triangleright$, for all $t$ such that $t \neq$ Any, BAD $\triangleright t \rightarrow *$ BAD which is not crash-free. And we have BAD $\triangleright$ Any $=$ UNR which is crash-free, so we are done.

### 4.7 Contract ordering

the subcontract relation can be illustrated in rule-form shown in Figure 7, Each rule in Figure 7 is a theorem. The relation $p \Rightarrow_{e} q$ in rule [C-Pred] is defined in Definition 11. Rule [C-Any] follows directly from the definition of $\leqq$. We now study the rules [C-Pred], [C-DepFun] and [C-DepTup]. We assume the statement above the line is true, and prove the statement below the line is true. We leave the proof of other direction as a open problem.

$$
\begin{aligned}
& \frac{p \Rightarrow_{e} q}{\{x \mid p\} \leqq\{x \mid q\}} \quad[\mathrm{C}-\mathrm{PRED}] \quad t \leqq \text { Any } \quad[\mathrm{C}-\mathrm{ANY}] \\
& \frac{t_{1} \leqq t_{3} \quad \forall e \in t_{1}, t_{2}[e / x] \leqq t_{4}[e / x]}{\left(x: t_{1}, t_{2}\right) \leqq\left(x: t_{3}, t_{4}\right)} \\
& \text { [C-DEPTUP] } \\
& \frac{t_{3} \leqq t_{1} \quad \forall e \in t_{3}, t_{2}[e / x] \leqq t_{4}[e / x]}{x: t_{1} \rightarrow t_{2} \leqq x: t_{3} \rightarrow t_{4}} \\
& \text { [C-DEPFUN] }
\end{aligned}
$$

Figure 7: Subcontract Relation

Definition 11 (Boolean Expression Implication). For all boolean expressions $p$ and $q$, we say $p$ implies $q\left(\right.$ written $p \Rightarrow_{e} q$ ) iff $\binom{$ if $q$ then ()}{ else BAD }$\preceq\binom{$ if $p$ then () }{ else BAD }

From Definition 11$]^{[2]}$, for example, we know $\{x \mid x<10\} \Rightarrow_{e}\{x \mid x<12\}$. The substitution for contracts is defined in Figure 8. Here, we assume each bound variable has a unique name.

```
\(\{x \mid p\}[e / y]=\{x \mid p[e / y]\}\)
\(\left(x: t_{1} \rightarrow t_{2}\right)[e / y]=x: t_{1}[e / y] \rightarrow t_{2}[e / y]\)
\(\left(t_{1}, t_{2}\right)[e / y]=\left(t_{1}[e / y], e_{2}[e / y]\right)\)
\(\operatorname{Any}[e / y] \quad=\) Any
```

Figure 8: Substitution for Contracts

### 4.7.1 Predicate Contract Ordering

We prove that the rule [C-Pred] is sound; that is we prove Theorem $4^{[22]}$.
Theorem 4 (Predicate Contract Ordering). For all expressions $p$, $q$, if $p \Rightarrow q$ then $\{x \mid p\} \leqq\{x \mid q\}$.

Proof. We have the following proof for all $t_{1}, t_{2}, t_{3}, t_{4}$ :

$$
\begin{aligned}
& p \Rightarrow{ }_{e} q \\
& \Longleftrightarrow \quad \text { (By Definition } 11{ }^{[2]} \text { (Boolean Expression Implication), let } \\
& \left.e_{1}=\left(\begin{array}{l}
\text { case } p \text { of } \\
\text { True } \rightarrow() \\
\text { False } \rightarrow \text { BAD }
\end{array}\right) \text { and } e_{2}=\left(\begin{array}{l}
\text { case } q \text { of } \\
\text { True } \rightarrow() \\
\text { False } \rightarrow \text { BAD }
\end{array}\right)\right) \\
& e_{2} \preceq e_{1} \\
& \Longleftrightarrow \quad\left(\text { By Definition } 7^{[14]}\right. \text { (Crashes-more-often)) } \\
& \forall \mathcal{C} . \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} \mathrm{BAD} \Rightarrow \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} \mathrm{BAD} \\
& \Rightarrow \quad\left(\mathrm{By}\left({ }^{*}\right)\right. \text { below) } \\
& \forall e . e \text { is crash-free and }\left(e_{1}[e / x] \nrightarrow^{*}\{\text { BAD, False }\} \Rightarrow e_{2}[e / x] \not \nrightarrow^{*}\{\text { BAD, False }\}\right) \\
& \Longleftrightarrow \quad \text { (By logic and definition of } \in \text { in Figure 5) } \\
& \forall e . e \in\left\{x \mid e_{1}\right\} \Rightarrow e \in\left\{x \mid e_{2}\right\} \\
& \Longleftrightarrow \quad \text { (By Definition } 9^{177} \text { (Subcontract)) } \\
& \left\{x \mid e_{1}\right\} \leqq\left\{x \mid e_{2}\right\}
\end{aligned}
$$

(*) We know $\forall e, a, x . e[a / x] \equiv_{s}$ let $x=a$ in $e$.
Assuming for all crash-free $e$ :
(1) $\forall \mathcal{C} . \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} \mathrm{BAD} \Rightarrow \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} \mathrm{BAD}$
(2) (let $x=e$ in $\left.e_{1}\right) \nrightarrow^{*}\{$ BAD, False $\left.\}\right)$
we want to show (let $x=e$ in $e_{2}$ ) $\nrightarrow{ }^{*}\{\mathrm{BAD}$, False $\}$
Suppose (let $x=e$ in $\left.e_{2}\right) \rightarrow^{*}$ BAD
By (1), let $\mathcal{C}$ be let $x=e$ in $\bullet$, we have $\mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*}$ BAD.
That means (let $x=e$ in $e_{1}$ ) $\rightarrow^{*}$ BAD.
This contradicts with (2) so our assumption is wrong and we are done.
Suppose (let $x=e$ in $e_{2}$ ) $\rightarrow^{*}$ False
By (1), let $\mathcal{C}$ be case (let $x=e$ in $\bullet$ ) of $\{$ False $\rightarrow \mathrm{BAD}\}$, we have $\mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*}$ BAD.
That means (case (let $x=e$ in $e_{1}$ ) of $\{$ False $\rightarrow \mathrm{BAD}\}$ ) $\rightarrow^{*}$ BAD.
That means (let $x=e$ in $e_{1}$ ) $\rightarrow^{*}\{$ BAD, False $\}$.
This contradicts with (2) so our assumption is wrong and we are done.
End of proof.

### 4.7.2 Dependent Function Contract Ordering

We prove that the rule [C-DepFun] is sound; that is we prove Theorem $5{ }^{[23]}$.
Theorem 5 (Dependent Function Contract Ordering). For all $t_{1}, t_{2}, t_{3}, t_{4}$.

$$
\text { if } t_{3} \leqq t_{1} \text { and } \forall e \in t_{3} . t_{2}[e / x] \leqq t_{4}[e / x] \text {, then } x: t_{1} \rightarrow t_{2} \leqq x: t_{3} \rightarrow t_{4}
$$

Proof. We have the following proof for all $t_{1}, t_{2}, t_{3}, t_{4}$ :

$$
t_{3} \leqq t_{1} \text { and } \forall e_{3} \in t_{3} . t_{2}\left[e_{3} / x\right] \leqq t_{4}\left[e_{3} / x\right]
$$

$\Longleftrightarrow \quad\left(\right.$ By Definition $9^{177}$ (Subcontract))
$\left(\dagger_{1}\right) \quad \forall e_{1} \cdot e_{1} \in t_{3} \Rightarrow e_{1} \in t_{1}$ and $\forall e_{3} \in t_{3} . \forall e_{2} . e_{2} \in t_{2}\left[e_{3} / x\right] \Rightarrow e_{2} \in t_{4}\left[e_{3} / x\right]$
$\Rightarrow \quad$ (By the $\left(^{*}\right)$ below)
$\left(\dagger_{2}\right) \quad \forall e . \forall e_{1} \in t_{1} .\left(e e_{1}\right) \in t_{2}\left[e_{1} / x\right] \Rightarrow \forall e_{3} \in t_{3} .\left(e e_{3}\right) \in t_{4}\left[e_{3} / x\right]$
$\Longleftrightarrow \quad$ (By definition of $\in$ in Figure (5)
$\forall e . e \in x: t_{1} \rightarrow t_{2} \Rightarrow e \in x: t_{3} \rightarrow t_{4}$
$\Longleftrightarrow \quad\left(\right.$ By Definition $9^{177}$ (Subcontract))
$x: t_{1} \rightarrow t_{2} \leqq x: t_{3} \rightarrow t_{4}$
(*) For all $e$, assuming:
$\begin{array}{ll}\text { (1) } \forall e_{1} \cdot e_{1} \in t_{3} \Rightarrow e_{1} \in t_{1} & \left.\text { (first clause of the line } \dagger_{1}\right) \\ \text { (2) } \forall e_{3} \in t_{3}, \forall e_{2} \cdot e_{2} \in t_{2}\left[e_{3} / x\right] \Rightarrow e_{2} \in t_{4}\left[e_{3} / x\right] & \text { (second clause of the line } \dagger_{1} \text { ) } \\ \text { (3) } \forall e_{1} \in t_{1} \cdot\left(e e_{1}\right) \in t_{2}\left[e_{1} / x\right] & \text { (LHS of the line } \dagger_{2} \text { ) }\end{array}$
we show $\forall e_{3} . e_{3} \in t_{3} \Rightarrow\left(e e_{3}\right) \in t_{4}\left[e_{3} / x\right]$ as follows.

$$
\begin{array}{ll} 
& e_{3} \in t_{3} \\
\Longleftrightarrow & (\operatorname{By}(1)) \\
& e_{3} \in t_{1} \\
\Longleftrightarrow & (\operatorname{By}(3)) \\
& \left(e e_{3}\right) \in t_{2}\left[e_{3} / x\right] \\
\Longleftrightarrow & (\mathrm{By}(2)) \\
& \left(e e_{3}\right) \in t_{4}\left[e_{3} / x\right]
\end{array}
$$

We are done.

### 4.7.3 Dependent tuple contract ordering

We prove the rule [C-DepTup] is sound by showing:
For all $t_{1}, t_{2}, t_{3}, t_{4}$. if $t_{1} \leqq t_{3}$ and $t_{2} \leqq t_{4}$, then $\left(t_{1}, t_{2}\right) \leqq\left(t_{3}, t_{4}\right)$
Proof. For all $e$, if $e$ diverges, then for all $t_{1}, t_{2}, t_{3}, t_{4}, e \in\left(t_{1}, t_{2}\right)$ and $e \in\left(t_{3}, t_{4}\right)$ because a divergent expression satisfies all contracts. By the definition of $\leqq$, we have the desired result $\left(t_{1}, t_{2}\right) \leqq\left(t_{3}, t_{4}\right)$. Now, we prove the case when
$e \rightarrow^{*}\left(e_{1}, e_{2}\right)$ as follows.

```
            \(t_{1} \leqq t_{3}\) and \(t_{2} \leqq t_{4}\)
    \(\Longleftrightarrow \quad\) (By Definition \(9^{117}\) (Subcontract))
            \(\forall e_{1} . e_{1} \in t_{1} \Rightarrow e_{1} \in t_{3}\) and \(\forall e_{2} . e_{2} \in t_{2} \Rightarrow e_{2} \in t_{4}\)
    \(\Longleftrightarrow \quad(\) By logic \((\forall x . A) \wedge(\forall y . B) \equiv \forall x, y . A \wedge B\) if \(y \notin f v(A)\) and \(x \notin f v(B))\)
        \(\forall e_{1}, e_{2} . e_{1} \in t_{1} \Rightarrow e_{1} \in t_{3}\) and \(e_{2} \in t_{2} \Rightarrow e_{2} \in t_{4}\)
    \(\Rightarrow \quad(\) By logic \(((A \Rightarrow B) \wedge(C \Rightarrow D)) \Rightarrow((A \wedge C) \Rightarrow(B \wedge D)))\)
        \(\forall e . e \rightarrow^{*}\left(e_{1}, e_{2}\right)\) and \(\left(\left(e_{1} \in t_{1}\right.\right.\) and \(\left.e_{2} \in t_{2}\right) \Rightarrow\left(e_{1} \in t_{3}\right.\) and \(\left.\left.e_{2} \in t_{4}\right)\right)\)
    \(\Rightarrow \quad(\) By logic \((A \wedge(B \Rightarrow C)) \Rightarrow((A \wedge B) \Rightarrow(A \wedge C)))\)
        \(\forall e .\left(e \rightarrow^{*}\left(e_{1}, e_{2}\right)\right.\) and \(e_{1} \in t_{1}\) and \(\left.e_{2} \in t_{2}\right)\)
            \(\Rightarrow\left(e \rightarrow^{*}\left(e_{1}, e_{2}\right)\right.\) and \(e_{1} \in t_{3}\) and \(\left.e_{2} \in t_{4}\right)\)
    \(\Longleftrightarrow \quad\) (By definition of \(\in\) in Figure (5)
        \(\forall e . e \in\left(t_{1}, t_{2}\right) \Rightarrow e \in\left(t_{3}, t_{4}\right)\)
    \(\Longleftrightarrow \quad\left(\right.\) By Definition \(9^{177}\) (Subcontract))
        \(\left(t_{1}, t_{2}\right) \leqq\left(t_{3}, t_{4}\right)\)
```

Note that some tuple contracts are not comparable by $\leqq$, for example: ( 0 k, Any) $\notin$ (Any, 0 k ) and (Any, 0 k$) \notin(0 \mathrm{k}$, Any).

### 4.8 Contract equivalence

In this section we give formal definition of the equivalence of two contracts.
Definition 12 (Contract Equivalence). Two closed contracts $t_{1}$ and $t_{2}$ are equivalent, namely $t_{1} \equiv_{t} t_{2}$, iff

$$
\forall e . e \in t_{1} \Longleftrightarrow e \in t_{2}
$$

Contract equivalence $\equiv_{t}$ refers to semantic equivalence, not equality. For example, $\{x \mid$ false $\} \rightarrow\{x \mid$ true $\} \leqq\{x \mid$ false $\} \rightarrow\{x \mid$ false $\}$ and $\{x \mid$ false $\} \rightarrow\{x \mid$ false $\} \leqq\{x \mid$ false $\} \rightarrow\{x \mid$ true $\}$, and $\{x \mid$ false $\} \rightarrow\{x \mid$ true $\} \equiv_{t}\{x \mid$ false $\} \rightarrow\{x \mid$ false $\}$, but $\{x \mid$ false $\} \rightarrow\{x \mid$ true $\} \neq\{x \mid$ false $\} \rightarrow\{x \mid$ false $\}$.

Theorem 6 (Subcontract is antisymmetric). For all closed contracts $t_{1}$ and $t_{2}$, $t_{1} \leqq t_{2}$ and $t_{2} \leqq t_{1}$ iff $t_{1} \equiv_{t} t_{2}$.

## Proof.

$$
\begin{array}{ll} 
& t_{1} \leqq t_{2} \text { and } t_{2} \leqq t_{1} \\
\Longleftrightarrow & \left(\text { By Definition } 99^{117}(\text { Subcontract })\right) \\
& \forall e . e \in t_{1} \Rightarrow e \in t_{2} \text { and } \forall e . e \in t_{2} \Rightarrow e \in t_{1} \\
\Longleftrightarrow & (\text { By } \operatorname{logic}(\forall x . A(x) \Rightarrow B(x)) \wedge(\forall x . B(x) \Rightarrow A(x)) \equiv \forall x . A(x) \Longleftrightarrow B(x)) \\
& \forall e . e \in t_{1} \Longleftrightarrow e \in t_{2} \\
\Longleftrightarrow & \left(\text { By Definition } 10^{[24}(\text { Contract Equivalence })\right) \\
& t_{1} \equiv_{t} t_{2}
\end{array}
$$

End of proof.

For open contracts $t$, we assume implicitly that there is an environment $\Delta$, which is a mapping from variable to its type, contract and definition (See Definition 10 in Section 4.4).

Lemma 9 (Predicate Contract Equivalence). For all expressions $e_{1}$ and $e_{2}$, if $e_{1} \equiv_{s} e_{2}$, then $\left\{x \mid e_{1}\right\} \equiv_{t}\left\{x \mid e_{2}\right\}$.

Proof. We have the following proof:

$$
\begin{array}{ll} 
& e_{1} \equiv_{s} e_{2} \\
\Longleftrightarrow \quad & (\text { By Theorem }]^{[15]}(\text { Crashes-more-often is antisymmetric) }) \\
& e_{1} \preceq e_{2} \text { and } e_{2} \preceq e_{1} \\
\Longleftrightarrow & (\text { By Theorem }]^{[2]} \text { (Predicate contract ordering)) } \\
& \left\{x \mid e_{1}\right\} \leqq\left\{x \mid e_{2}\right\} \text { and }\left\{x \mid e_{2}\right\} \leqq\left\{x \mid e_{1}\right\} \\
\Longleftrightarrow & \text { (By Theorem }\left[\left._{6}\right|^{[2]}\right. \text { (Subcontract is antisymmetric)) } \\
& \left\{x \mid e_{1}\right\} \equiv_{t}\left\{x \mid e_{2}\right\}
\end{array}
$$

Lemma 10 (Dependent Function Contract Equivalence). For all contracts $t_{1}, t_{2}, t_{3}, t_{4}$, if $t_{1} \equiv_{t} t_{3}$ and $\forall e \in t_{1} . t_{2}[e / x] \equiv_{t} t_{4}[e / x]$, then $x: t_{1} \rightarrow t_{2} \equiv_{t}$ $x: t_{3} \rightarrow t_{4}$.

Proof. We have the following proof.

$$
\begin{aligned}
& t_{1} \equiv{ }_{t} t_{3} \text { and } \forall e \in t_{1} . t_{2}[e / x] \equiv{ }_{t} t_{4}[e / x] \\
& \Longleftrightarrow \quad \text { (By Theorem [6] }{ }^{[24} \text { (Subcontract is Antisymmetric)) } \\
& t_{1} \leqq t_{3} \text { and } t_{3} \leqq t_{1} \text { and } \\
& \left(\forall e \in t_{1} \cdot t_{2}[e / x] \leqq t_{4}[e / x] \text { and } \forall e \in t_{1} \cdot t_{4}[e / x] \leqq t_{2}[e / x]\right) \\
& \Longleftrightarrow \quad\left(\text { Since } t_{1} \equiv_{t} t_{3}, e \in t_{1} \Longleftrightarrow e \in t_{3}\right. \text {.) } \\
& t_{3} \leqq t_{1} \text { and } \forall e \in t_{1} . t_{2}[e / x] \leqq t_{4}[e / x] \text { and } \\
& t_{1} \leqq t_{3} \text { and } \forall e \in t_{1} . t_{4}[e / x] \leqq t_{2}[e / x] \\
& \Rightarrow \quad \text { (By [C-DepFun] in Figure 7) } \\
& x: t_{1} \rightarrow t_{2} \leqq x: t_{3} \rightarrow t_{4} \text { and } x: t_{3} \rightarrow t_{4} \leqq x: t_{1} \rightarrow t_{2} \\
& \Longleftrightarrow \quad\left(\text { By Theorem [6] }{ }^{[24]}\right. \text { (Subcontract is Antisymmetric)) } \\
& x: t_{1} \rightarrow t_{2} \equiv_{t} x: t_{3} \rightarrow t_{4}
\end{aligned}
$$

We are done.
Lemma 11 (Dependent Tuple Contract Equivalence). For all contracts $t_{1}, t_{2}, t_{3}, t_{4}$, if $t_{1} \equiv_{t} t_{3}$ and $\forall e \in t_{1} . t_{2}[e / x] \equiv_{t} t_{4}[e / x]$, then $\left(x: t_{1}, t_{2}\right) \equiv_{t}\left(x: t_{3}, t_{4}\right)$.

Proof. We have the following proof.

$$
\begin{array}{ll} 
& t_{1} \equiv_{t} t_{3} \text { and } \forall e \in t_{1} \cdot t_{2}[e / x] \equiv_{t} t_{4}[e / x] \\
\Longleftrightarrow \quad & \left(\text { By Theorem }{ }^{[6]]^{24]}}\right. \text { (Subcontract is Antisymmetric)) } \\
& t_{1} \leqq t_{3} \text { and } t_{3} \leqq t_{1} \text { and } \\
& \left(\forall e \in t_{1} \cdot t_{2}[e / x] \leqq t_{4}[e / x] \text { and } \forall e \in t_{1} \cdot t_{4}[e / x] \leqq t_{2}[e / x]\right) \\
\Longleftrightarrow \quad & \left(\text { Since } t_{1} \equiv_{t} t_{3}, e \in t_{1} \Longleftrightarrow e \in t_{3} \cdot\right) \\
& t_{3} \leqq t_{1} \text { and } \forall e \in t_{1} \cdot t_{2}[e / x] \leqq t_{4}[e / x] \text { and } \\
& t_{1} \leqq t_{3} \text { and } \forall e \in t_{1} \cdot t_{4}[e / x] \leqq t_{2}[e / x] \\
\Rightarrow \quad & (\text { By }[\mathrm{C}-\text { DepFun] in Figure } 7) \\
& \left(x: t_{1}, t_{2}\right) \leqq\left(x: t_{3}, t_{4}\right) \text { and }\left(x: t_{3}, t_{4}\right) \leqq\left(x: t_{1}, t_{2}\right) \\
\Longleftrightarrow \quad & \left(\text { By Theorem }[6]^{24]}(\text { Subcontract is Antisymmetric })\right) \\
& \left(x: t_{1}, t_{2}\right) \equiv_{t}\left(x: t_{3}, t_{4}\right)
\end{array}
$$

We are done.
Theorem 7 (Subcontract and Crashes-more-often Ordering). For all $t_{1}$ and $t_{2}$,

$$
\forall e . e \triangleright t_{1} \preceq e \triangleright t_{2} \quad \Rightarrow \quad t_{1} \leqq t_{2}
$$

Proof. We have the following proof:

$$
\begin{array}{ll} 
& \forall e . e \triangleright t_{1} \preceq e \triangleright t_{2} \\
\Rightarrow \quad & \left(\text { By Lemma } 7^{119}(\mathrm{c})\right. \text { (Properties of Crashes-more-often - II)) } \\
& \forall e . e \triangleright t_{1} \text { is crash-free } \Rightarrow e \triangleright t_{2} \text { is crash-free } \\
\Rightarrow \quad & \left(\text { By Theorem } \sqrt{2}^{118}(\text { grand theorem })\right) \\
& \forall e . e \in t_{1} \Rightarrow e \in t_{2} \\
\Longleftrightarrow \quad & \left(\text { By Definition } 9^{\sqrt{17]}}(\text { Subcontract })\right) \\
& t_{1} \leqq t_{2}
\end{array}
$$

## 5 Static contract checking and residualization

Thanks to the ground-breaking higher order contract wrappers $\bowtie$ (first introduced in [13]), which makes the analysis of higher order program much easier. From Theorem 3, all we need is to show that $e \triangleright t$ is crash-free. That is to check the reachability of BAD as each BAD signals a contract violation. We can symbolically simplify $e \triangleright t$ as much as possible to $e^{\prime}$ and check for occurrence of BAD in $e^{\prime}$.

We introduce an SL machine (Figure 10) which combines symbolic simplification and contextual information (ctx-info) synthesis with logical formulae. The novelty of our work is to combine them in a way to achieve verification, blaming and residualization in one-go. The SL machine takes an expression $e$ and produces its semantically equivalent and simplified version. A 4-tuple $\langle\mathcal{H} \| e| \mathcal{S}|\mathcal{L}\rangle$ is pronounced simplify and a 4 -tuple $\langle\langle\mathcal{H}\|e\| \mathcal{S} \mid \mathcal{L}\rangle\rangle$ is pronounced rebuild where

- $\mathcal{H}$ is an environment mapping variables to trivial values;

| $\langle\mathcal{H}\| n\|\mathcal{S}\| \mathcal{L}\rangle \rightsquigarrow\langle\langle\mathcal{H} \\| n\| \mathcal{S} \mid \mathcal{L}\rangle\rangle$ | [S-const] |
| :---: | :---: |
| $\langle\mathcal{H}\| r\|\mathcal{S} \\| \mathcal{L}\rangle \rightsquigarrow\langle\langle\mathcal{H} \\| r\| \mathcal{S} \mid \mathcal{L}\rangle\rangle$ | [S-exn] |
| $\langle\mathcal{H}[x \mapsto$ tval $]\| x\|\mathcal{S}\| \mathcal{L}\rangle \rightsquigarrow\langle\mathcal{H}[x \mapsto$ tval $]\|$ tval $\\| \mathcal{S}\|\mathcal{L}\rangle\rangle$ | [S-var1] |
| if $x \notin \mathcal{H}, \quad\langle\mathcal{H}\\|x\\| \mathcal{S} \mid \mathcal{L}\rangle \rightsquigarrow\langle\langle\mathcal{H}\| x \\| \mathcal{S} \mid \mathcal{L}\rangle\rangle$ | [S-var2] |
| $\left.\langle\mathcal{H}\| \lambda x^{\tau} . e\|\mathcal{S}\| \mathcal{L}\right\rangle \rightsquigarrow\langle\mathcal{H} \\| e\|(\lambda x . \bullet):: S\|\mathcal{L}, \forall x: \llbracket \tau \rrbracket\rangle$ | [S-lam] |
| $\left.\left.\langle\mathcal{H}\| e_{1} e_{2}\|\mathcal{S}\| \mathcal{L}\right\rangle \rightsquigarrow\langle\mathcal{H}\| e_{1}\left\|\left(\bullet e_{2}\right):: \mathcal{S}\right\| \mathcal{L}\right\rangle$ | [S-app] |
| $\langle\mathcal{H}\|$ match $e_{0}$ with alts $\left.\|\mathcal{S}\| \mathcal{L}\right\rangle$ <br> $\rightsquigarrow\langle\mathcal{H}\| e_{0} \mid$ (match • with alts) :: $\mathcal{S}\|\mathcal{L}\rangle$ | [S-match] |
| $\begin{aligned} & \langle\mathcal{H}\| K\left(a_{1}, \ldots, e_{i}, \ldots, e_{n}\right)\|\mathcal{S} \\| \mathcal{L}\rangle \\ & \left.\left.\rightsquigarrow\langle\mathcal{H}\| e_{i} \mid\left(K\left(a_{1}, \ldots, \bullet, \ldots, e_{n}\right)\right]\right):: \mathcal{S} \\| \mathcal{L}\right\rangle \end{aligned}$ | [S-K] |
| $\begin{aligned} & \text { if } x \notin f v(e), \\ & \left.\langle\mathcal{H}\| \operatorname{let} x=e_{1} \text { in } e_{2}\|(\bullet e):: \mathcal{S}\| \mathcal{L}\right\rangle \\ & \left.\sim\langle\mathcal{H}\| \text { let } x=e_{1} \text { in } e_{2} e\|\mathcal{S}\| \mathcal{L}\right\rangle \end{aligned}$ | [S-letL] |

if $f v(e) \cap \overrightarrow{x_{i}}=\emptyset$,
$\langle\mathcal{H}|\left(\right.$ match $e_{0}$ with $\left.\left.\xrightarrow\left[K \vec{x} \rightarrow e_{i}\right)|(\bullet e):: \mathcal{S}| \mathcal{L}\right\rangle\right]{\left.\rightsquigarrow\langle\mathcal{H}| \text { match } e_{0} \text { with } \overrightarrow{K \vec{x} \rightarrow e_{i} e}|\mathcal{S}| \mathcal{L}\right\rangle} \quad$ [S-matchL]
if $x \notin f v(a)$,
$\langle\mathcal{H}|$ val $\|\left(\bullet\left(\right.\right.$ let $x=e_{1}$ in $\left.\left.e_{2}\right)\right):: \mathcal{S}|\mathcal{L}\rangle$
$\rightsquigarrow\langle\mathcal{H}|$ let $x=e_{1}$ in val $\left.e_{2}|\mathcal{S}| \mathcal{L}\right\rangle$
[S-letR]
if $f v($ val $) \cap \vec{x}=\emptyset$,
$\langle\mathcal{H}|$ val $\|\left(\bullet\left(\right.\right.$ match $e_{0}$ with $\left.\left.\overrightarrow{K \rightarrow}\right)\right):: \mathcal{S}|\mathcal{L}\rangle$
$\rightsquigarrow\left\langle\mathcal{H} \|\right.$ match $e_{0}$ with $\left.\overrightarrow{K \vec{x} \rightarrow \text { val e }}\right| \mathcal{S}|\mathcal{L}\rangle$
[S-matchR]
if $f v($ alts $) \cap \vec{x}=\emptyset$,
$\langle\mathcal{H}| \xrightarrow[K \vec{x} \rightarrow e]{\text { match } e_{0} \text { with }} \|($ match $\bullet$ with alts $):: \mathcal{S}|\mathcal{L}\rangle$
$\rightsquigarrow\left\langle\mathcal{H} \| \xrightarrow{\text { match } e_{0} \text { with }} \quad\right.$ [S-match-match]
if $x \notin f v(a l t s)$,
$\left\langle\mathcal{H} \|\right.$ let $x=e_{1}$ in $e_{2} \|($ match $\bullet$ with alts $\left.):: \mathcal{S} \| \mathcal{L}\right\rangle$
$\rightsquigarrow\langle\mathcal{H}|$ let $x=e_{1}$ in match $e_{2}$ with alts $\left.\|\mathcal{S}\| \mathcal{L}\right\rangle$
[S-match-let]

Figure 9: SL machine part (a)

```
|\mathcal{H}|a|[]|\mathcal{L}\rangle>}\rightsquigarrow
if (s\not= match e with K \vec{x}->(\bullet,\mathcal{S},\mathcal{L})),
|\langle\mathcal{H}|r|s::\mathcal{S}|\mathcal{L}\rangle\rangle\rightsquigarrow\langle\langle\mathcal{H}|r|\mathcal{S}|\mathcal{L}\rangle\rangle
<\mathcal{H}|a|(\lambdax.\bullet)::\mathcal{S}|\mathcal{L}\rangle\rangle\rightsquigarrow\langle\langle\mathcal{H}|\lambdax.a|\mathcal{S}|\mathcal{L}\rangle\rangle
Rules below: }a\not\in{\mp@subsup{\textrm{BAD}}{}{l},\mp@subsup{\textrm{UNR}}{}{l}
[R-done]
\begin{tabular}{|c|c|}
\hline \(\left\langle\left\langle\mathcal{H} \mid a\left\|\left(\bullet e_{2}\right):: \mathcal{S}\right\| \mathcal{L}\right\rangle\right\rangle \rightsquigarrow\left\langle\mathcal{H} \mid e_{2}\|(a \bullet):: \mathcal{S}\| \mathcal{L}\right\rangle\) & [R-fun] \\
\hline \(\left\langle\langle\mathcal{H}|\right.\) val \(\left.\left.\|\left(\left(\lambda x . a_{1}\right) \bullet\right):: \mathcal{S} \mid \mathcal{L}\right\rangle\right\rangle \rightsquigarrow\left\langle\left\langle\mathcal{H}\left[x \mapsto\right.\right.\right.\) val] \(\left.\left|a_{1}\right| \mathcal{S}|\mathcal{L}\rangle\right\rangle\) & [R-beta] \\
\hline if \(a_{1} \neq \lambda x . a^{\prime}\) or \(a \neq v a l\),
\[
\left.\left.\langle\langle\mathcal{H}| a|\left(a_{1} \bullet\right):: \mathcal{S}|\mathcal{L}\rangle\right\rangle \rightsquigarrow\left\langle\langle\mathcal{H}| a_{1} a \| \mathcal{S} \mid \mathcal{L}\right\rangle\right\rangle
\] & [R-app] \\
\hline \(\left\langle\left\langle\mathcal{H} \mid a_{n}\left\|\left(K a_{1} \ldots \bullet\right):: \mathcal{S}\right\| \mathcal{L}\right\rangle\right\rangle \rightsquigarrow\langle\langle\mathcal{H}\|K \vec{a}\| \mathcal{S} \| \mathcal{L}\rangle\rangle\) & [R-K] \\
\hline \(\langle\langle\mathcal{H}| K \vec{a}|\) (match • with \(\{\ldots ; K \vec{x} \rightarrow e ; \ldots\}):: \mathcal{S} \| \mathcal{L}\rangle\rangle\) \(\rightsquigarrow\langle\mathcal{H}|\) let \(\overrightarrow{x=a}\) in \(e \| \mathcal{S}|\mathcal{L}\rangle\) & [R-K-match] \\
\hline \[
\begin{aligned}
& \text { if exists } \left.\left(K \overrightarrow{x^{f}}\right) \text { such that } \underset{\mathcal{L} \Rightarrow(\exists \overrightarrow{x:}: \llbracket \tau \rrbracket}{\vec{~}} \llbracket a \rrbracket_{(K} \vec{x}\right) \\
& \left\langle\left\langle\mathcal{H}\|a\|\left(\text { match } \bullet \text { with } K \overrightarrow{x^{7}} \rightarrow e\right):: \mathcal{S} \mid \mathcal{L}\right\rangle\right\rangle \\
& \rightsquigarrow\langle\mathcal{H}| e|\mathcal{S}| \mathcal{L}, \exists \overrightarrow{\left.\left.x: \llbracket \tau \rrbracket, \llbracket a \rrbracket_{(K} \vec{x}\right)\right\rangle}
\end{aligned}
\] & [R-s-match] \\
\hline
\end{tabular}
\(\langle\langle\mathcal{H}\|K \vec{a}\|(\) match • with \(\{\ldots ; K \vec{x} \rightarrow e ; \ldots\}):: \mathcal{S} \| \mathcal{L}\rangle\rangle\)
\(\rightsquigarrow\langle\mathcal{H}|\) let \(\overrightarrow{x=a}\) in \(e \| \mathcal{S}|\mathcal{L}\rangle\)
if exists \(\left(K \overrightarrow{x^{7}}\right)\) such that \(\left.\mathcal{L} \Rightarrow\left(\exists \overrightarrow{x: \llbracket \tau \rrbracket}, \llbracket a \rrbracket_{(K} \vec{x}\right)\right)\),
\(\left\langle\left\langle\mathcal{H}\|a\|\left(\right.\right.\right.\) match • with \(\left.\left.\left.\overrightarrow{K \overrightarrow{x^{f}} \rightarrow e}\right):: \mathcal{S} \| \mathcal{L}\right\rangle\right\rangle\)
\(\left.\left.\rightsquigarrow\langle\mathcal{H}| e|\mathcal{S}| \mathcal{L}, \exists \overrightarrow{x: \llbracket \tau \rrbracket}, \llbracket a \rrbracket_{(K} \vec{x}\right)\right\rangle \quad\) [R-s-match]
if for all \(\left(K \overrightarrow{x^{7}}\right)\) such that \(\left.\mathcal{L} \nRightarrow\left(\exists \overrightarrow{x: \llbracket \tau \rrbracket}, \llbracket a \rrbracket_{(K} \vec{x}\right)\right)\),
\(\langle\langle\mathcal{H}| a|\left(\right.\) match • with \(\left.\left.K \overrightarrow{x^{f}} \rightarrow e\right):: \mathcal{S}|\mathcal{L}\rangle\right\rangle\)
\(\rightsquigarrow\langle\mathcal{H}| e \| \begin{array}{ll}\left(\text { match } a \text { with } K \overrightarrow{x^{f}}\right. & \mathcal{L}, \exists \overrightarrow{x: \llbracket \tau \rrbracket}, \\ & \rightarrow(\bullet, \mathcal{S}, \mathcal{L}))::[]\end{array}\)
                                    [R-s-save]
\(\overline{\left.\left.\langle\mathcal{H}| a \mid\left(\text { match } a_{0} \text { with } K \vec{x} \rightarrow(\bullet, \mathcal{S}, \mathcal{L})\right):: \mathcal{S}^{\prime} \| \mathcal{L}^{\prime}\right\rangle\right\rangle}\)
\(\rightsquigarrow\left\langle\left\langle\mathcal{H} \|\right.\right.\) match \(a_{0}\) with \(\left.\left.\overrightarrow{K \vec{x} \rightarrow a}\|\mathcal{S}\| \mathcal{L}\right\rangle\right\rangle\) for some \(\mathcal{S}^{\prime}\) and \(\mathcal{L}^{\prime} \quad\) [R-match]
\(\langle\langle\mathcal{H}| a|\left(\operatorname{let} x^{\tau}=\bullet\right.\) in \(\left.\left.e_{2}\right):: \mathcal{S}|\mathcal{L}\rangle\right\rangle\)
\(\rightsquigarrow\langle\mathcal{H}| e_{2} \mid(\) let \(x=a\) in \(\left.\bullet):: \mathcal{S} \| \mathcal{L}, \exists x: \llbracket \tau \rrbracket, \llbracket a \rrbracket_{x}\right\rangle \quad\) [R-let-save]

Figure 10: SL machine part (b)
- \(e\) is the expression under simplification (or being rebuilt);
- \(\mathcal{S}\) is a stack which embodies the simplification context, or continuation that will consume a simplified expression;
```

$\left(\right.$ let $x=e_{1}$ in $\left.e_{2}\right) e \Longrightarrow$ let $x=e_{1}$ in $e_{2} e$
[letL]
if $f v(e) \cap \vec{x}=\emptyset$,
(match $e_{0}$ with $\overrightarrow{K \vec{x} \rightarrow e_{i}}$ ) $e$
$\Longrightarrow$ match $e_{0}$ with $\overrightarrow{K \vec{x} \rightarrow\left(e_{i} e\right)}$ [matchL]
if $x \notin f v(e)$,
tval (let $x=e_{1}$ in $\left.e_{2}\right) \Longrightarrow$ let $x=e_{1}$ in tval $e_{2} \quad[\operatorname{let} \mathrm{R}]$
if $f v($ tval $) \notin \vec{x}$,
val (match $e_{0}$ with $\xrightarrow{K \vec{x} \rightarrow e}$ )
$\Longrightarrow$ match $e_{0}$ with $\overrightarrow{K \vec{x} \rightarrow \text { val } e} \quad[$ matchR]
if $f v($ alts $) \cap \vec{x}=\emptyset$,
match (match $e_{0}$ with $\overrightarrow{K \vec{x} \rightarrow e}$ ) with alts
$\Longrightarrow$ match $e_{o}$ with $\vec{K} \rightarrow$ match $e$ with alts $\quad[$ match-match]
if $x \notin f v($ alts $)$,
match (let $x=e_{1}$ in $e_{2}$ ) with alts
$\Longrightarrow$ let $x=e_{1}$ in match $e_{2}$ with alts [match-let]
match $K a_{1} \ldots a_{n}$ with $\left\{\ldots ; K x_{1} \ldots x_{n} \rightarrow e ; \ldots\right\}$
$\Longrightarrow$ let $x_{1}=a_{1}$ in $\ldots$ let $x_{n}=a_{n}$ in $e \quad$ [scrut-match]

```

Figure 11: Simplification Rules
- \(\mathcal{L}\) is a logical store which contains the ctx-info in logical formula form; its syntax is
\[
\mathcal{L}::=\emptyset|\forall x: \tau, \mathcal{L}| \phi, \mathcal{L}
\]
where \(\phi\) is a predicate in Figure 12 ,
The job of SL machine is to simplify an expression as much as possible, consulting the logical store when necessary; when it cannot simplify the expression further, rebuilds the expression.

\subsection*{5.1 The SL machine}

In Figure 10, the constant \(n\) and blame \(r\) cannot be simplified further, thus being rebuilt as shown in [S-const] and [S-exn] respectively. One might ask why we rebuild rather than return a blame. There are two reasons: (a) it gives more information for static error reporting, i.e. we know conditions leading to a reachable BAD; (b) as we do hybrid contract checking, we want to send the residual code with undischarged blames to a dynamic checker.

As we perform symbolic simplification rather than evaluation (as in CEK machine [16]), we only put a variable in the environment \(\mathcal{H}\) if it denotes a trivial value. A variable denoting a top-level function is not put in \(\mathcal{H}\). Variables in \(\mathcal{H}\) are inlined by [S-var1] while variables not in \(\mathcal{H}\) are rebuilt by [S-var2].

Each element on the stack is called a stack frame where the hole • in a stack frame refers to the expression under simplification or being rebuilt. We use \(a\) to represent an expression that has been simplified. the syntax of a stack frame \(s\) in \(\mathcal{S}\) is
\[
\begin{aligned}
s::= & {[]|(\bullet):: s|(e \bullet):: s|(\lambda x . \bullet):: s| \text { let } x=\bullet \text { in } e } \\
& \mid(\text { match } \bullet \text { with alt) }:: s \mid \text { let } x=e \text { in } \bullet \\
& \mid\left(\text { match } e_{0} \text { with } \overrightarrow{K \vec{x} \rightarrow(\bullet, \mathcal{S}, \mathcal{L})}\right):: s
\end{aligned}
\]

The transitions [S-app], [S-match] and [S-K] implement the context reduction in Figure 3. The transitions [S-letL], [S-matchL], [S-letR], [S-matchR], [S-matchmatch], [S-match-let] implement the conventional simplification rules in Figure 11 Here, \(\vec{x}\) abbreviates a sequence of \(x_{1}, \ldots, x_{n}\). We use let instead of lambda for easy reading. Rules [letL] and [matchL] push the argument into the let-body and match-body respectively. Rules [letR] and [matchR] push the function into the let-body and match-body. The rules [match-match] and [match-let] are to make an expression less nested. Rule [K-match] allows us to simplify
\[
\text { match Some } e \text { with }\{\text { Some } x \rightarrow 5 \text {; None } \rightarrow \text { BAD }\}
\]
(where \(e\) is a crash-free expression, not a value) to let \(x=e\) in 5 which is crash-free.

What does rebuild do? If the stack is empty ([R-done]), which indicates the end of the whole simplification process, we return the expression. Otherwise, we examine the stackframe. By [E-exn], the transitions [R-r-match], [R-r-let], [R-r-fun] and [R-r-arg] rebuild UNR (or BAD) with the rest of the stack. After we finish simplifying one subexpression, we start to simplify another subexpression (e.g. [R-fun]). When all subexpressions are simplified, we rebuild the expression (e.g. [R-lam] and [R-app]). If current simplified expression is a value and we have stack frame lambda on \(\mathcal{S}\), we use [R-beta]; together with [S-var1], they implement a beta-reduction [E-beta]. Bound variables are renamed when necessary.

The logical store \(\mathcal{L}\) captures all the ctx-info up to the program point being simplified. (We use if-expression to save space, but refer to match-transitions.) Consider:

The [S-lam] puts \(\forall x:\) int in \(\mathcal{L}\), which is initially empty:
\[
\langle\mathcal{H}| \begin{aligned}
& \text { if } x>0 \\
& \text { then }(\text { if } x+1>0 \\
& \\
& \text { then } 5 \text { else BAD }) \\
& \text { else UNR) }
\end{aligned}
\]

The [S-match] starts to simplify the scrutinee \(x>0\), which is being rebuilt after a few trivial steps.
\[
\begin{aligned}
& \left\langle\langle\mathcal{H}| x>0 \| \quad \begin{array}{l}
\text { (if • then } \quad(\text { if } x+1>0 \\
\text { then } 5 \text { else BAD) } \quad \mid \forall x: \text { int }\rangle\rangle
\end{array}\right. \\
& \text { else UNR) :: }(\lambda x . \bullet)::[]
\end{aligned}
\]

Before applying the transition [R-s-save], we check whether \(x>0\) or \(\operatorname{not}(x>\) 0 ) is implied by \(\mathcal{L}\) to see whether the transition [R-s-match] can be applied. The transition [R-s-match] implements [E-match], where the side condition "if \(\left.\exists(K \vec{x}), \mathcal{L} \Rightarrow \llbracket a \rrbracket_{(K} \vec{x}\right)\) " checks if there is any branch \(K \vec{x}\) that matches the scrutinee. But the current information in \(\mathcal{L}\) is not enough to show the validity of either \(x>0\) or \(\operatorname{not}(x>0)\). By [R-s-save], we convert this scrutinee to logical formula with \(\left.\llbracket a \rrbracket_{(K} \vec{x}\right)\) (explained later) and put it in \(\mathcal{L}\) and simplify both branches. Note that, we put \(x>0\) in \(\mathcal{L}\) for the true branch while \(\operatorname{not}(x>0)\) for the false branch.
\[
\begin{array}{lll}
{\left[\left\langle\mathcal{H} \| \begin{array}{ll}
\text { if } x+1>0 & (\text { if } x>0 \text { then } \bullet)
\end{array}\right.\right.} & \forall x: \text { int }, \\
\text { then } 5 \text { else BAD } & ::(\lambda x \cdot \bullet)::[] & x>0
\end{array} ;
\]

In the true branch, after a few steps, we rebuild the scrutinee \(x+1>0\). In this case, \(\forall x\) : int, \(x>0 \Rightarrow x+1>0\) is valid. By [R-s-match], we take the true branch, which is a constant 5 . As both 5 and UNR cannot be simplified further, we rebuild them by [S-const] and [S-unr] respectively and obtain:
\[
\begin{aligned}
& {\left[\left\langle\mathcal{H}\|5\| \begin{array}{ll}
(\text { if } x>0 \text { then } \bullet\}) \\
::(\lambda x . \bullet)::[]
\end{array} \quad \begin{array}{l}
\forall x \text { int, } x>0, \\
(x+1>0)
\end{array}\right\rangle ;\right.} \\
& \left\langle\left\langle\mathcal{H} \| \text { UNR } \| \begin{array}{ll}
(\text { if } x>0 \text { else } \bullet\}) \\
::(\lambda x . \bullet)::[]
\end{array} \quad \begin{array}{l}
\forall x: \text { int, } \\
\operatorname{not}(x>0)
\end{array}\right\rangle\right]
\end{aligned}
\]

By [R-match], we combine both simplified branches to rebuild the matchexpression:
\[
\langle\langle\mathcal{H} \| \text { if } x>0 \text { then } 5 \text { else UNR }\|(\lambda x . \bullet)::[]\| \forall x: \text { int }\rangle\rangle
\]

We continue to rebuild the expression by [R-lam]:
\[
\langle\langle\mathcal{H} \| \lambda x \text {. if } x>0 \text { then } 5 \text { else UNR } \|[]| \forall x: \text { int }\rangle\rangle
\]
and terminate (by [R-done]) with a syntactically safe expression:
\[
\lambda x \text {. if } x>0 \text { then } 5 \text { else UNR. }
\]

Besides [R-s-save], another transition that saves ctx-info to \(\mathcal{L}\) is [R-let-save]. Consider an example:
\[
\lambda v . \text { let } y=v+1 \text { in if } y>v \text { then } y \text { else BAD }
\]

After a few simplification steps, we have:
\[
\left.\left.\begin{array}{rl}
\langle\langle\mathcal{H}\|v+1\| & (\text { let } y=\bullet \text { in if } y>v \\
& \text { then } y \text { else BAD })::(\lambda v \cdot \bullet)::[]
\end{array} \quad \forall v: \text { int }\right\rangle\right\rangle
\]

The rule [R-let-save] saves the information \(y=v+1\) to \(\mathcal{L}\), which allows us to check the validity of the scrutinee \(y>v\) later.
\[
\left.\begin{array}{l|lll} 
& \text { if } y>v \\
\text { then } y & \|\mathcal{H}\| & (\text { let } y=v+1 \text { in } \bullet) & \forall v: \text { int, } \\
\text { else } \operatorname{BAD} & ::(\lambda x \cdot \bullet)::[] & \exists y: \text { int, }
\end{array}\right\rangle
\]

Since \(\forall v\) : int, \(\exists y\) : int, \(y=v+1 \Rightarrow y>v\) is valid, by [R-s-match], we only need to simplify the true branch:
\[
\langle\mathcal{H}| y\left|\begin{array}{ll}
(\text { let } y=v+1 \text { in } \bullet) \\
::(\lambda v \cdot \bullet)::[]
\end{array} \quad \begin{array}{l}
\forall v: \text { int, } \exists y: \text { int, } \\
y=v+1, y>v
\end{array}\right\rangle
\]
which leads to the final result \(\lambda v\). let \(y=v+1\) in \(y\), which is syntactically safe.

Theorem 8 (SL machine terminates). For all expression \(e\), there exists an expression a such that \(\left\langle\emptyset\|e\|[] \| \emptyset \rightsquigarrow^{*} a\right.\).

Proof. See Appendix B.2.
Intuitively, SL machine behaves like CEK machine [16], but does not inline top-level functions and we do not have local let rec in our language. We also call SMT solver Alt-ergo with an option "-stop <time-bound>" or "-steps <bound>" to make sure the SMT solver terminates. So there is no element causing non-termination.

Theorem 9 (Correctness of SL machine). For all expression e, if \(\langle\emptyset| e \|[]|\emptyset\rangle \rightsquigarrow *\) \(a\), then \(e \equiv_{s} a\).

Proof. See Appendix B.2,
The SL is designed in a way such that the simplified \(a\) preserves the semantics of the original expression \(e\). The proof of Therem 9 (in Appendix B.2) uses the fact that, if there exists \(e_{3}\) such that \(\left\langle\mathcal{H}\left\|e_{1}|\mathcal{S} \| \mathcal{L}\rangle \rightsquigarrow^{*}\left\langle\mathcal{H} \mid e_{3}\|\mathcal{S}\| \mathcal{L}\right\rangle\right.\right.\) and \(\langle\mathcal{H}| e_{2}|\mathcal{S} \| \mathcal{L}\rangle \rightsquigarrow^{*}\left\langle\mathcal{H} \mid e_{3}\|\mathcal{S}\| \mathcal{L}\right\rangle\), then \(e_{1} \equiv_{s} e_{2}\).

Theorem 10 (Soundness of static contract checking). For all closed expression \(e\), and closed and terminating contract \(t\),
\[
\langle\emptyset\|e \triangleright t\|[] \| \emptyset\rangle \rightsquigarrow^{*} e^{\prime} \text { and } \operatorname{BAD} \not \not_{s} e^{\prime} \quad \Rightarrow \quad e \in t
\]

Proof. By Theorem 9, Lemma 1 and Theorem 3.

\subsection*{5.2 Logicization}

We now explain the mysterious convertion \(\llbracket . \rrbracket_{f}\), which we call logicization. Figure 12 gives the abstract syntax of the logical formula supported by an SMT solver named Alt-ergo [8], which is an automatic theorem prover for polymorphic first order logic modulo theories. It uses classical logic and assumes all types are inhabited. First, data type declaration in language M, e.g.
```

type 'a list = Nil | Cons of 'a * ('a list)

```
is converted to Alt-ergo code with type and logic declarations:
```

type 'a list
logic nil : 'a list
logic cons : 'a , 'a list _> 'a list

```
```

x,s,i,f \in Identifier
file ::= decl }1,···,\mp@subsup{\mathrm{ decl }}{n}{
bty ::= int | bool | i|,},i|\vec{bty}i\quad\mathrm{ Base type
lty ::= bty| 名 -> bty Logic type
ty ::= \alpha| (t\mp@subsup{y}{1}{},···,t\mp@subsup{y}{n}{})s\quad\mathrm{ Types}
decl ::= type }\vec{\prime
| logic }\vec{i}:lty| axiom i:\phi| goal i:\phi
\oplus ::= + |- |*|/
\odott ::= = |<> |< << |> |>=
\odot
m ::= n|x|m, m \oplus m}|\mp@code{|}|m|f\vec{m}\quad\mathrm{ Term
\phi ::= true |false |f \vec{m}\quad\mathrm{ Predicate}
| m
forall \vec{x}:ty.\phi| exists }\vec{x}\mathrm{ : ty. }

```

Figure 12: Syntax of logic declaration
Data type in language M :
\[
\text { type } \overrightarrow{\rightarrow a} s=K_{1} \text { of } \overrightarrow{t_{1}}|\cdots| K_{n} \text { of } \overrightarrow{t_{n}}
\]

Corresponding alt-ergo code: type \(\vec{a} s\)
logic \(K_{1}: \overrightarrow{t_{1}} \rightarrow \overrightarrow{{ }_{a}^{c}} s\)
logic \(K_{n}: \overrightarrow{t_{n}} \rightarrow \vec{a} s\)
Figure 13: Converting data type to Alt-ergo code

As Alt-ergo supports only first order logic (FOL), arguments of a logical function are a tuple, e.g. 'a , 'a list. The type variable 'a is assumed universally quantified at top-level. The convertion algorithm for an arbitrary user-defined data type is in Figure 13

Moreover, we introduce a first order function type:
```

type ('a, 'b) arrow

```
which allows us to encode the function type in the langugage M to Alt-ergo's first order type where the ' a and 'b refer to a function's input type and output type respectively. We also introduce a logical function apply:
logic apply : ('a, 'b) arrow , 'a -> 'b
where encoding with apply is conventional [22]. Converting types in the language \(M\) is straight forward (Figure 14).
\[
\begin{aligned}
\llbracket \tau_{1} \ldots \tau_{n} T \rrbracket & =\llbracket \tau_{1} \rrbracket \ldots \llbracket \tau_{n} \rrbracket T \\
\llbracket \tau_{1} \rightarrow \tau_{2} \rrbracket & =\left(\llbracket \tau_{1} \rrbracket, \llbracket \tau_{2} \rrbracket\right) \text { arrow }
\end{aligned}
\]

Figure 14: Converting higher order type to first order type

We now give an example showing that the SL machine is better than the unrolling approach in [37, 40] \({ }^{1}\).
```

(* val len : 'a list -> int *)
contract len $=\{x \mid$ true $\}->\{y|y|>=0\}$
let len $s=$ match $s$ with | [] $\quad$-> 0
| x::u -> $1+$ len u
(* val append : 'a list -> 'a list -> 'a list *)
contract append $=$ \{xs | true\} -> \{ys | true\}
-> \{len rs = len xs + len ys\}
let append xs ys = match xs with
| [] -> ys
| x::u -> x :: append u ys

```

The function len computes the length of a list and the function append appends two lists. Let \(e_{\mathbf{a}}\) and \(t_{\mathrm{a}}\) stand for the definition and contract of append respectively. Applying only simplification rules (including reduction rules) to \(e_{\mathbf{a}} \triangleright t_{\mathrm{a}}\), we get (R3):
\[
\begin{aligned}
& \lambda v_{1} \cdot \lambda v_{2} \text {.match } v_{1} \text { with } \\
& \mid[] \rightarrow \text { if len } v_{2}=\text { len } v_{1}+\text { len } v_{2} \text { then } v_{2} \text { else } \mathrm{BAD}^{l 1} \\
& \mid x:: u \rightarrow \text { if (len }(x:: \\
& \text { (if len (append } \left.u v_{2}\right)=\text { len } u+\text { len } v_{2} \\
& \text { then append } u v_{2} \text { else UNR)) } \\
& \left.=\text { len } v_{1}+\text { len } v_{2}\right) \\
& \text { then } x:: \text { append } u v_{2} \text { else } \mathrm{BAD}^{l_{2}}
\end{aligned}
\]

The simplification approach in [37] and the model checking approach in 32] involve inlining top-level functions, while we do not. Instead, we axiomatize toplevel function definitions called in contracts and lift expressions under checking to logic level and consult an SMT solver. The chanllenge is to deal with nontotal expressions (e.g. BAD) in our source code. In the literature of converting functional code (in an interactive theorem prover) to SMT formula [1, 9, 27, 6], they convert expression to a logical form directly. In [1], given a non-recursive function definition \(f=e\), they first \(\eta\)-expand \(e\) to get \(f=\lambda x_{1} \ldots x_{n} . e^{\prime}\) where \(e^{\prime}\) does not contain \(\lambda\); if it is a recursive function, they assume \(e\) is in a particular form such that all lambdas are at top-level and the function performing an immediate case-analysis over one of its arguments. Then, they form \(\forall \vec{x}, f\left(x_{1}, \ldots, x_{n}\right)=\llbracket e^{\prime} \rrbracket\) where \(\llbracket . \rrbracket\) converts an expression to logical form. (On the other hand, 6] uses \(\lambda\)-lifting method: \(\lambda\)-abstractions are translated from inside out, each \(\lambda\)-abstraction is replaced by a call to a newly defined functions. That is to form \(\left.\forall \vec{x}, f_{n}\left(x_{1}, \ldots, x_{n}\right)=\llbracket e^{\prime} \rrbracket ; \ldots ; \forall x_{1}, f=f_{1}\left(x_{1}\right).\right)\) This is fine for converting total terms, e.g. \(\llbracket 5 \rrbracket=5\) and \(\llbracket x \rrbracket=x\), etc., but what are \(\llbracket B A D \rrbracket\) and 【UNR】? Our key idea is not to convert an expression directly to a corresponding logical term, but form equality with \(\llbracket . \rrbracket_{f}\) recursively (defined in Figure [15). The subscript \(f\) in \(\llbracket e \rrbracket_{f}\) denotes the expression \(e\). Moreover, we perform neither \(\eta\)-expansion (which does not preserve semantics in the presence of non-total terms) nor \(\lambda\)-lifting, and yet we allow arbitrary forms of recursive functions. We have such flexibility because we convert \(\lambda\)-abstraction and partial

\footnotetext{
\({ }^{1}\) Unrolling approach may suit a lazy language better.
}
application directly with the help of apply. (Note that our logicization \(\llbracket . \rrbracket_{f}\) can also produce HOL formula for interactive proving by replacing (apply \((f, x)\) ) by \((f(x))\) and not converting the types.) No logicization work in the literature (including [9, 33, 27, 6]) deal with non-total terms. The work [6] uses approaches in [9, 27] to deal with polymorphism while Alt-ergo itself supports polymorphism.

Our framework can systematically generate Alt-ergo code, like below, to show that those BADs in R3 are unreachable.
```

logic len: ('a list, int) arrow
logic append: ('a list,
('a list,'a list) arrow) arrow
axiom len_def_1 : forall s:'a list. s = nil ->
apply(len,s) = 0
axiom len_def_2 : forall s:'a list. forall x:'a.
forall l:'a list. s = cons(x,l) ->
apply(len,s) = 1 + apply(len,l)
goal app_1 : forall v1,v2:'a list. v1 = nil ->
apply(len,v2) = apply(len,v1) + apply(len,v2)
goal app_2 : forall v1,v2,l:'a list.forall x:'a.
v1 = cons(x,l) ->
apply(len, apply(apply (append,l),v2))
= apply(len,l) + apply(len,v2) ->
(exists y:'a list. y = apply(apply(append,l),v2)
and apply(len,cons(x, y))
= apply(len,v1) + apply(len,v2))

```

To make an SMT solver's life easier (i.e. multiple small axioms are better than one big axiom), we have two axioms for len, one for each branch, which are self-explanatory. As a constructor is always fully applied, we do not encode its application with apply. The -> (in axioms and goals) is a logical implication. For example, in the goal app_1, the ctx-info v1=nil is from the pattern matching match v1 with \{[] -> ....\}; the query is the scrutinee apply (len,v2) \(=\operatorname{apply}(l e n, v 1)+\operatorname{apply}(l \mathrm{en}, \mathrm{v} 2)\). Alt-ergo says valid for both goals.

First, how to systematically convert a function definition to an axiom (e.g. len_def_1)? Figure 15 gives an operator \(\llbracket . \rrbracket_{f}\) that converts an expression to a logical formula. The subscript \(f\) in \(\llbracket e \rrbracket_{f}\) denotes the expression \(e\). For example, we can get len_def_1 thus:
\[
\begin{aligned}
& \llbracket \lambda s^{\prime} \text { a list } \text {. match } s \text { with }\{\text { Nil } \rightarrow 0\} \rrbracket_{\text {len }} \\
& =\forall s: ' \text { a list. } \llbracket \operatorname{match} s \text { with }\{\mathrm{Nil} \rightarrow 0\} \rrbracket_{(\operatorname{apply}(l e n, s))} \\
& =\forall s: ' \mathrm{a} \text { list. } \exists x_{0}: ' \mathrm{a} \text { list. } \llbracket s \rrbracket_{x_{0}} \wedge \\
& \left(x_{0}=\operatorname{nil}->\llbracket 0 \rrbracket_{(\operatorname{apply}(1 e n, s))}\right) \\
& =\forall s: ' \text { a list. } \exists x_{0}: ' \text { a list. } x_{0}=s \wedge \\
& \left(x_{0}=\text { nil }->\operatorname{apply}(\operatorname{len}, s)=0\right)
\end{aligned}
\]

Let \(x_{0}\) be \(s\), we get a more readable version (axiom len_def_1).
\[
\begin{aligned}
& \oplus \in[+,-, *, /] \quad \odot \in[>,<,=] \\
& \llbracket . \rrbracket_{f} \quad: \quad \text { Expression } \rightarrow \text { Formula } \\
& \llbracket \text { let (rec) } f=e \rrbracket_{f}=\llbracket e \rrbracket_{f} \quad \text { top-level defn } \\
& \llbracket \mathrm{BAD}^{l} \rrbracket_{f}= \begin{cases}\text { true } & \text { for axioms } \\
\text { false } & \text { for goals }\end{cases} \\
& \llbracket \mathrm{UNR}^{l} \rrbracket_{f}=\text { false } \\
& \llbracket x \rrbracket_{f}=f=x \\
& \llbracket n \rrbracket_{f}=f=n \\
& \llbracket e_{1}^{\tau} \oplus e_{2}^{\tau} \rrbracket_{f}=\exists x_{1}: \llbracket \tau \rrbracket, \exists x_{2}: \llbracket \tau \rrbracket \text {, } \\
& \left(\llbracket e_{1} \rrbracket_{x_{1}} \wedge \llbracket e_{2} \rrbracket_{x_{2}} \wedge f=x_{1} \oplus x_{2}\right) \\
& \begin{aligned}
\llbracket e_{1}^{\tau} \odot e_{2}^{\tau} \rrbracket_{f}= & \exists x_{1}: \llbracket \tau \rrbracket, \llbracket e_{1} \rrbracket_{x_{1}} \wedge \\
& \exists x_{2}: \llbracket \tau \rrbracket, \llbracket e_{2} \rrbracket_{x_{2}} \wedge
\end{aligned} \\
& \left(\left(x_{1} \odot x_{2} \wedge f=\text { true }\right) \vee\right. \\
& \left.\left(\operatorname{not}\left(x_{1} \odot x 2\right) \wedge f=\mathrm{false}\right)\right) \\
& \llbracket \lambda x^{\tau} \cdot e \rrbracket_{f}=\forall x: \llbracket \tau \rrbracket, \llbracket e \rrbracket_{(\operatorname{apply}(f, x))} \\
& \llbracket \text { let } x^{\tau}=e_{1} \text { in } e_{2} \rrbracket_{f}=\exists x: \llbracket \tau \rrbracket, \llbracket e_{1} \rrbracket_{x} \wedge \llbracket e_{2} \rrbracket_{f} \\
& \llbracket e_{1}^{\tau_{1}} e_{2}^{\tau_{2}} \rrbracket_{f}=\exists x_{1}: \llbracket \tau_{1} \rrbracket, \llbracket e_{1} \rrbracket_{x_{1}} \wedge \\
& \exists x_{2}: \llbracket \tau_{2} \rrbracket, \llbracket e_{2} \rrbracket_{x_{2}} \wedge \\
& f=\operatorname{apply}\left(x_{1}, x_{2}\right) \\
& \llbracket K e_{1}^{\tau_{1}} \ldots e_{n}^{\tau_{n}} \rrbracket_{f}=\exists x_{1}: \llbracket \tau_{1} \rrbracket, \llbracket e_{1} \rrbracket_{x_{1}} \wedge \cdots \wedge \\
& \exists x_{n}: \llbracket \tau_{n} \rrbracket, \llbracket e_{n} \rrbracket_{x_{n}} \wedge f=K\left(x_{1}, \ldots, x_{n}\right) \\
& \llbracket \xrightarrow[K \overrightarrow{x^{7}} \rightarrow e]{\text { match } e_{0}^{\tau_{0}}} \text { with } \rrbracket_{f}=\frac{\exists x_{0}: \llbracket \tau_{0} \rrbracket, \llbracket e_{0} \rrbracket_{x_{0}} \wedge}{\left(\bigwedge \forall \overrightarrow{x: \llbracket \tau \rrbracket},\left(x_{0}=K \vec{x}\right) \Rightarrow \llbracket e \rrbracket_{f}\right)}
\end{aligned}
\]

Figure 15: Convert expression to logical formula

Theorem 11 (Logicization for axioms). Given definition \(f=e^{\tau}, \forall f v(e), \exists f: \tau, \llbracket e \rrbracket_{f}\) is valid.

\section*{Proof. See Appendix B.1.}

Next, what query (i.e. goal) shall we make? All we want is to check the branch leading to BAD is reachable or not. So our task is to examine the scrutinee of a match-expression. For example, in the goal app_1, the ctxinfo v1=nil is from the pattern matching match v1 with \{[] -> ....\}; the query is apply (len, v2) \(=\) apply (len,v1) \(+\operatorname{apply}(l e n, v 2)\). The goal app_1 states the ctx-info \(\mathcal{L}\) implies the scrutinee. We have \(\mathcal{L}=\forall v_{1}\) : ' a list, \(\forall v_{2}\) : 'a list, \(v_{1}=\) nil by [S-lam] and [R-s-save]. The scrutinnee is \(\llbracket l \mathrm{en} v_{2}=\) len \(v_{1}+\) len \(\left.v_{2}\right\} \rrbracket_{\text {true. }}\) That is, we want to check whether len \(v_{2}=\) len \(v_{1}+\) len \(v_{2}\) is equivalent to true. Sending the Alt-ergo code in this paper to Alt-ergo solver, it replies valid for both goals. Thus, we know both \(\mathrm{BAD}^{l 1}\) and \(\mathrm{BAD}^{l 2}\) are not reachable.

Theorem 12 (Logicization for goals: validity preservation). For all (possibly open) expression \(e^{\tau}, \exists f: \tau\), if \(\forall f v(e): \tau, \llbracket e \rrbracket_{f}\) is valid and \(e \rightarrow e^{\prime}\) for some \(e^{\prime}\), then \(\forall f v\left(e^{\prime}\right), \llbracket e^{~^{\rrbracket}} \rrbracket_{f}\) is valid.

Proof. See Appendix B.1.
There are a few things to note about logicization.

Syntax abbreviation The Alt-ergo syntax
\[
\overrightarrow{\operatorname{logic} x: l t y} ; \quad \overrightarrow{\text { axiom } a_{i}: \phi_{i}} ; \quad \overrightarrow{\text { goal } g_{j}: \phi_{j}}
\]
is semantically the same as \(\forall \overrightarrow{x: l t y}, \overrightarrow{\phi_{i}} \Rightarrow \overrightarrow{\phi_{j}}\) where \(\vec{\phi}\) means a conjunction of a set of logical formulae.

Only functions called in contracts are converted to Alt-ergo axioms To check a function (say append) satisfies its contract, we do not convert its definition to axioms. As the wrappers \(\triangleright, \triangleleft\) have inserted contract checking obligation appropriately such that function calls (including recursive calls) are guarded by their contracts.

Crashing functions called in contracts In Figure 15, there are two convertions for BAD, true for axioms and false for goals. For example, we may have:
```

contract g = {x | x /= []} -> {y | head x > y}

```

In this case, the contract of \(g\) is crash-free even if a partial function head is called in the contract. The logicization of head gives:
```

logic head : ('a list, 'a) arrow
axiom head_def_1 : forall x:'a list. x=[] -> true
axiom head_def_2 : forall x,l:'a list.forall y:'a.
x = cons(y,l) -> apply(head, x) = y

```

The key thing is that the axiom head_def_1 is not a false axiom, it just does not give us any information, which is what we want.

Contracts that diverge Suppose divergent functions loop and nloop are used in a contract.
```

let rec loop x = loop x
let rec nloop x = not (nloop x)

```

Logicization gives:
```

logic loop : 'a -> 'a
axiom loop_def_1 : forall x:'a.
apply(loop, x) = apply(loop, x)
logic nloop : bool -> bool
axiom nloop_def_1 : forall x:bool.
apply(nloop, x) = not(apply(nloop, x))

```

Axiom loop_def_1 is same as stating true, which does not hurt. But axiom nloop_def_1 is same as stating false, which we must not allow. Fortunately, we only convert functions used in contracts that can be proved terminating (in Section 4.5) to axioms. We will not generate the axiom nloop_def_1.

BAD and UNR For goals, the \(\llbracket e \rrbracket_{f}\) collects ctx-info before a scrutinee of a match-expression, thus, \([\mathrm{BAD}]_{f}=[\mathrm{UNR}]_{f}=\) false, which implies everything. For example:
```

fun x -> let y = if x > 0 then x else UNR in
if y + 1 > 0 then y + 1 else BAD

```

The ctx-info \(\mathcal{L}\) before \(y+1>0\) is \(\forall x\) : int, \(\exists y\) : int, \((x>0 \Rightarrow y=x) \wedge(n o t(x>\) \(0) \Rightarrow\) false \()\). So \(\mathcal{L} \Rightarrow y+1>0\) is \(\forall x\) : int, \(\exists y\) : int, \((x>0 \Rightarrow y=x) \wedge(n o t(x>\) \(0) \Rightarrow\) false \() \Rightarrow y+1>0\), which is valid. It means, if \(\operatorname{not}(x>0)\) holds, \(y+1>0\) will not be reached. Similar reasoning applies if we replace the UNR by BAD in the above example.

\subsection*{5.3 Discussion and preliminary experiments}

One might notice that SL machine simplifies terms under lambda and the body of match-expression while we do not have such execution rules in Figure 3, As we rebuild blames and do not inline recursive functions (i.e. no crashing and no looping during simplification), SL machine does not violate call-by-value execution.
\[
\begin{array}{rlrl}
\Delta(n) & =n & & {[\mathrm{D} 1]} \\
\Delta(x) & =x \quad \text { if } x \notin \operatorname{dom}(\Delta) \text { or }[x \mapsto \perp] \subseteq \Delta & {[\mathrm{D} 2]} \\
\Delta[x \mapsto m](x) & =m & & {[\mathrm{D} 3]} \\
\Delta\left(\exists x: t y, x=m \wedge \phi_{1}\right) & =\Delta[x \mapsto \Delta(m)]\left(\phi_{1}\right) & & {[\mathrm{D} 5]} \\
\Delta\left(m_{1} \odot_{t} m_{2}\right) & =\Delta\left(m_{1}\right) \odot_{t} \Delta\left(m_{2}\right) & {[\mathrm{D} 6]} \\
\Delta\left(\phi_{1} \odot_{p} \phi_{2}\right) & =\Delta\left(\phi_{1}\right) \odot_{p} \Delta\left(\phi_{2}\right) & & \text { [D7] }
\end{array}
\]

Figure 16: Partial elimination of \(\exists\) quantifiers
One might notice that the logicization generates some existentially quantified variables and simple equalities which can be easily eliminated. By observing the conversion in Figure 15, we may encounter some sub-formula in this form: \(\exists x: t y, x=m \wedge \phi\), which can be simplified to \(\phi[m / x]\). A simple \(\exists\)-elimination algorithm in Figure 16 is good enough to eliminate some (but not all) existential quantifiers from the formula. The environment \(\Delta\) captures the maping from an \(\exists\)-bound variable to a term. For example:
\[
\begin{aligned}
& \Delta(\forall y: \text { int, } \exists x: \text { int }, x=y \wedge(\exists x: \text { int }, x=8 \wedge x>6)) \\
= & (\text { By }[\mathrm{D} 7]) \\
& \forall y: \text { int }, \Delta(\exists x: \text { int }, x=y \wedge(\exists x: \text { int }, x=8 \wedge x>6)) \\
= & (\text { By }[\mathrm{D} 4]) \\
& \forall y: \text { int, } \Delta[x \mapsto y](\exists x: \text { int }, x=8 \wedge x>6) \\
= & (\text { By }[\mathrm{D} 4]) \\
& \forall y: \text { int }, \Delta[x \mapsto 8](x>6) \\
= & (\text { By [D5] }) \\
& \forall y: \text { int, } \Delta[x \mapsto 8](x)>\Delta[x \mapsto 8](6) \\
= & (\text { By }[D 1] \text { and }[\mathrm{D} 0]) \\
& \forall y: \text { int }, 8>6
\end{aligned}
\]

The \(\Delta[x \mapsto \Delta(m)]\) means that, if \(x \notin \operatorname{dom}(\Delta)\), we extend the environment \(\Delta\) with \([x \mapsto \Delta(m)]\); if \(x \in \operatorname{dom}(\Delta)\), we update \(x\) with the term \(\Delta(m)\). The rest is self-explanatory.

Theorem 13 (Correctness of \(\exists\) quantifiers elimination). For all FOL formula \(\phi, \Delta(\phi)\) is valid if and only if \(\phi\) is valid.

Proof. The only change to the formula \(\phi\) is to substitute the existentially quantified \(x\) by \(m\). Since we have the equality \(x=m\) and the conjunction, it is immediate that the substitution is correct.

One might worry that the rule [match-match] causes exponential code explosion for static analysis (although no run-time overhead). For example, \(h_{1}=\) if (if \(a\) then \(b\) else \(c\) ) then \(d\) else \(e\), where \(a, b, c, d, e\) are expressions. At program point \(d\), the ctx-info is \((a \Rightarrow b) \wedge(\operatorname{not}(a) \Rightarrow c)^{2}\). Applying [match-match] to \(h_{1}\), we get: \(h_{2}=\) if \(a\) then (if \(b\) then \(d\) else \(e\) ) else (if \(c\) then \(d\) else \(e\) ). The \(d\) is duplicated and the ctx-info for the first \(d\) is \(a \wedge b\) while for the second \(d\) is \(\operatorname{not}(a) \wedge c\). With [match-match], we send smaller formula to an SMT solver (which is good for an SMT solver), but we may communicate with the SMT solver more often. From our current observation, it is quite often that the \(c\) is BAD or UNR, the SL machine immediately rebuilds the blame with the rest of the stack, and we get: if \(a\) then (if \(b\) then \(d\) else e) else \(c\). So \(d\) is not duplicated and we have smaller formula for the SMT solver.

One advantage of the SL machine is to allow adding or removing a rule easily. In the inc example in \$2, with rule [matchR], we can simplify
\[
(\lambda v \cdot v+1)\left(\text { if } x_{1}>0 \text { then } x_{1} \text { else UNR? }\right)
\]
to if \(x_{1}>0\) then \((\lambda v . v+1) x_{1}\) else \((\lambda v . v+1)\) UNR? As the variable \(x_{1}\) and the contract exception UNR? are values, performing beta-reduction, we get: if \(x_{1}>0\) then \(x_{1}+1\) else UNR? Now, we have a logical formula (denoted by Q2):
\[
\begin{equation*}
\exists y,\left(x_{1}>0 \Rightarrow y=x_{1}+1\right) \wedge\left(\operatorname{not}\left(x_{1}>0\right) \Rightarrow \text { false }\right) \tag{Q2}
\end{equation*}
\]
which is equivalent but smaller than the Q1 in \(\$ 2\),
We have implemented a prototyp \(\int^{3}\) based on the source code of ocamlc3.11.2. Table 1 shows the results of preliminary experiments, which are done on a PC running Ubuntu Linux with quadcore 2.93 GHz CPU and 3.2 GB memory. We take some examples from [25] and OCaml stdlib and time the static checking. The column Ann gives the LOC for contract annotations.

The preliminary result is promising: it checks a hundred lines of code (LOC) in a few seconds. This paper focuses on the theory of hybrid contract checking, we leave more optimization and rigorous experimentation on tuning the strength of symbolic simplification and the frequency of calling an SMT solver as future work.

\footnotetext{
\({ }^{2}\) To illustrate the idea with less cluttered form, we omit the conversion notation \(\llbracket \cdot \rrbracket_{f}\) for \(a\), \(b, c, d, e\).
\({ }^{3}\) http://gallium.inria.fr/ \({ }^{\sim}\) naxu/research/hcc.html
}

Table 1: Results of preliminary experiments
\begin{tabular}{|l|c|c|c|}
\hline program & total LOC & Ann LOC & Time (sec) \\
\hline intro123, neg & 23 & 4 & 0.08 \\
McCarthy's 91 & 4 & 1 & 0.02 \\
ack, fhnhn & 12 & 2 & 0.06 \\
arith, sum, max & 26 & 4 & 0.20 \\
zipunzip & 12 & 2 & 0.10 \\
OCaml stdlib/list.ml & 81 & 16 & 0.72 \\
\hline
\end{tabular}

\section*{6 Hybrid contract checking}

We have explained with examples how SCC, DCC, HCC work in Section 2. Programmers may choose to have SCC only, DCC only, or HCC. In this section, we summarize their algorithm. Given a program \(f_{i} \in t_{i}, f_{i}=e_{i}\) for \(1 \leq i \leq n\). Suppose \(f_{i}\) is the current function under contract checking; \(f_{j}\) is a function called in \(f_{i}\) (including \(f_{i}\) 's recursive call); sl is the SL machine; rmUNR implements the rule [rmUNR] (mentioned earlier in Section (2).
\[
\left(\text { if } e_{0} \text { then } e_{1} \text { else UNR }\right) \Longrightarrow e_{1} \quad[\mathrm{rmUNR}]
\]

We have:
\[
\begin{aligned}
& {[\mathrm{SCC}]: \operatorname{sl}\left(e_{i}\left[\left(f_{j} \triangleleft_{f_{i}}^{f_{j}} t_{f_{j}}\right) / f_{j}\right] \triangleright_{?}^{f_{i}} t\right)} \\
& {[\mathrm{DCC}]: e_{i}\left[\left(f_{j} \underset{\substack{\text { BaD } f_{j}}}{\text { BaD } f_{i}} t_{f_{j}}\right) / f_{j}\right]} \\
& {[\mathrm{HCC}]: f_{i} \sharp=\lambda ? . \operatorname{smUNR}\left(\operatorname{sl}\left(e_{i}\left[\left(\left(f_{j} \sharp " f_{i} "\right) \triangleleft_{f_{i}}^{f_{j}} t_{f_{j}}\right) / f_{j}\right] \triangleright_{?}^{f_{i}} t\right)\right)}
\end{aligned}
\]

In [HCC], the residual code \(f_{i} \sharp\) 's parameter "?" waits for a caller's name. For example, if an STM solver cannot prove the goal app_2 in Section 5.2 (although it can), recalling R3 in Section 5.2, the residual code append \(\#\) is:
\[
\begin{aligned}
& \lambda ? . \lambda v_{1} \cdot \lambda v_{2} \text {.match } v_{1} \text { with } \\
& \mid[] \rightarrow v_{2} ; \\
& \mid x:: l \rightarrow \text { if len }\left(x:: \text { append } t v_{2}\right)=\text { len } v_{1}+\text { len } v_{2} \\
& \quad \text { then } x:: \text { append } t v_{2} \text { else BAD }
\end{aligned}
\]
which says that we only have to check postcondition for the second branch. (If all BADs are simplified away during SCC, a residual code of a function is its original definition.)

Lemma 12 (Telescoping property [7, 39]). For all expression e, total contract \(t\), blames \(r_{1}, r_{2}, r_{3}, r_{4}, \quad\left(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t\right) \underset{r_{4}}{\stackrel{r_{3}}{\infty}} t=e \underset{r_{4}}{\stackrel{r_{1}}{\bowtie}} t\).

Precondition of a function is checked at caller sites. An \(f_{j} \sharp\) is the simplified \(f_{j} \triangleright_{f_{i}}^{f_{j}} t_{f_{j}}\), inspecting [HCC], each \(f_{j}\) at caller sites is replaced by \(\left(f_{j} \triangleright_{f_{i}}^{f_{j}} t_{f_{j}}\right) \triangleleft_{f_{i}}^{f_{j}} t_{f_{j}}\),

which is the same as in DCC. This shows that [HCC] blames \(f\) if and only if [DCC] blames \(f\).

Moreover, [T1] justifies the correctness of applying the rule [rmUNR] because all UNRs are indeed unreachable as \(\mathrm{BAD}^{l}\) is invoked before \(\mathrm{UNR}^{l}\) for the same \(l\). That is, (if \(p\) then \(e_{1}\) else \(\mathrm{BAD}^{l}\) ) is invoked before (if \(p\) then \(e\) else \(\mathrm{UNR}^{l}\) ) for the same \(p\), maybe different \(e\). So it is safe to apply the rule [rmUNR] even if \(p\) diverges or crashes because the same \(p\) in (if \(p\) then \(e_{1}\) else BAD) diverges or crashes first. It is easy to see if \(t=\{x \mid p\}\). If \(t=t_{1} \rightarrow t_{2}\), then


Focusing on the BADs and UNRs above \(\bowtie\), inspecting [P1] and [P2] in Figure 6, we can see that \(\mathrm{BAD}^{f_{j}}\) is invoked before \(\mathrm{UNR}^{f_{j}}\) and \(\mathrm{BAD}^{f_{i}}\) is invoked before \(\mathrm{UNR}^{f_{i}}\).

\section*{7 Related work}

Contract semantics were first formalized in [7, 12] for a strict language and later in [39] for a lazy language. This paper adapt and re-formalize some of their ideas on contract satisfaction and contract checking. Detailed design deference is explained in \(\$ 4\).

Pre/post-condition specification using logical formulae [18, 15, 2, 33] allows programmers to existentially quantify over infinite domains or express metaproperties that are not expressible in contracts. However, such property cannot be converted to program code for dynamic checking. As automatic static checking always has its limitation, being able to convert some difficult checks to dynamic checks is practical. Refinement types and contracts can be enhanced in many ways like we did for types, e.g. subcontract relation [12, 40], recursive contracts [7], polymorphic contracts [3]. Contracts also enjoy interesting mathematical properties [7, 12, 39, 38]. We like the idea of ghost refinement in [35] that separates properties that can be converted to program code from the meta-properties logical formulae.

One might recall the hybrid refinement type checking (HTC) [14, ?]. In theory, 17] shows that (picky/indy, i.e. our) contract checking is able to give more blame than refinement type checking in the presence of higher order dependent function contracts. That is partly why [35] invents a Kind checker to report ill-formed refinement types. As discussed in 84.3 , we check \(e \triangleright t\) to be crash-free in one-go and do not have to check \(t\) to be crash-free separately. In practice, the \(\mathcal{H}\) and \(\mathcal{L}\) in the SL machine serve the similar purpose as the typing environment in HTC. But the symbolic simplification gives more flexibility such as teasing out the path sensitivity analysis with the rule [match-match], etc. We hope this work opens a venue to compare HCC and HTC in practice, such as the kind of properties we can verify, the speed of static checking, the size and speed of the residual code generated, etc. Notably, VeriFast [?] (for verifying C and Java code) suggests that symbolic execution is faster than verification condition generation method [15, 2].

The work [23] mixes type checking and symbolic execution. However, [23] requires programmers to place block annotations \(\left\{_{t} t\right\}\) for type checking and
\(\left\{\begin{array}{ll}s & s\end{array}\right\}\) for symbolic execution while our SL machine systematically simplifies subterms and consults the logical store for checking at the appropriate program point. The [23] does not generate residual code while we do. Moreover, their symbolic expression is in linear arithmetics, which is more restrictive than ours.

Our approach is different from [35], which extracts proofs of refinement types from an SMT solver and injects them as terms in the generated bytecode RDCIL (like proof carrying code) during refinement type checking. It is for security purpose.

Some work [31, 24, 32, 25] suggest to convert program to higher order recursive scheme (HORS), which generates (possibly infinite) trees, and specify properties in a form of trivial automaton and do model checking to know whether HORS satisfies its desired property. Our approaches are completely different although we both do reachability checking. They work on automaton while we work on program directly. Our approach is modular (no top-level function is inlined) while theirs is not. They deal with local let rec (i.e. invariant inference) while we do not, but we could infer local contract with method in [21] or inline the local let rec function for a fixed number of times. They deal with protocol checking while we do not unless a protocol checking problem can be converted to checking the reachability of BAD. SL machine (in §5) can be used for any problem that checks the reachability of BAD in general.

The contextual information synthesis and conversion of expression to logical formula is inspired by the use of the application • in [20, 19], which makes conversion of higher order functions easier. But we use the technique in different contexts.

Many papers on program verification [36, 15, 2, 30, 29, 11] focus on memory leak, array bound checks, etc. and few handle higher order functions and recursive predicates. Our work focus on more advanced properties and blame precisely functions at fault. Contract checking in the imperative world is lead by [11, which statically checks contract satisfaction at bytecode CIL level and run dynamic checking separately. Residualization has not been done in [11. We may adapt some ideas in [?] to extend our framework for program with side effects.

\section*{8 Conclusion}

We have formalized a contract framework for a pure strict higher order subset of OCaml. We propose a natural integration of static contract checking and dynamic contract checking. With SL machine, our approach gives precise blame at both compile-time and run-time in the presence of higher order functions. In near future, besides rigorous experimentation and case-studies, we plan to add user-defined exceptions; allow side-effects in program and hidden side-effects in contracts; do contract or invariant inference as [11, 29, 21] are inspiring.

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\section*{A Proof for the main theorem}

The proof in this Section is similar to the one in [40] but for a call-by-value language.
\begin{tabular}{|lll|}
\hline\(||\). & \(::\) Contract \(\rightarrow\) Int \\
\(|\{x \mid p\}|\) & \(=1\) \\
\(\left|x: t_{1} \rightarrow t_{2}\right|\) & \(=\left|t_{1}\right|+\left|t_{2}\right|+1\) \\
\(\left|\left(t_{1}, t_{2}\right)\right|\) & \(=\left|t_{1}\right|+\left|t_{2}\right|+1\) \\
\(\mid\) Any \(\mid\) & \(=1\) \\
\hline
\end{tabular}

Figure 17: Size of Contract
As some of the proofs involve the structural induction on the size of contract, we define it in Figure 17 To make the proof look less clustered, we use the following shorthands:
\begin{tabular}{rll}
\(\mathbf{c f}\) & \(:\) & crash-free \\
\(\mathbf{s s}\) & \(:\) & syntatically safe \\
defn & \(:\) & definition \\
\(\mathbf{c l}\) & \(:\) & closed \\
\(\mathbf{t l}\) & \(:\) & total
\end{tabular}


Figure 18: Dependency of Theorems and Lemmas in Appendix A
To make the dependency of theorems and lemmas clear, a dependency diagram is shown in Figure 18. For many theorems and lemmas, we prove them by induction on the size of contract \(t\). The dashed directed edge shows that the size of the contract decreases, i.e. for a function contract \(x: t_{1} \rightarrow t_{2}\), we
call another lemma (or theorem) with \(t=t_{1}\) or \(t=t_{2}\). The solid directed edge shows the size of the contract is preserved. This makes the proof well-founded even though there are cycles in the dependencies (examined in Section A.3).

Theorem 2 (Soundness and Completeness of Contract Checking (grand theorem)) For all closed expression \(e^{\tau}\), closed and total contract \(t^{\tau}\),
\[
(e \triangleright t) \text { is crash-free } \Longleftrightarrow e \in t
\]

There are two directions to be proved:
- \(e \in t \Rightarrow e \triangleright t\) is crash-free. The difficulty lies in the proof for dependent function contracts. We appeal to a key lemma (Lemma \(14{ }^{[53]}\) [Key lemma] in Section A.2).
- \(e \triangleright t\) is crash-free \(\Rightarrow e \in t\). The difficulty also lies in the proof for dependent function contracts. We appeal to three things:
- definition and properties of crashes-more-often (Definition \(7^{\sqrt[144]{14}}\), Lemma \(7^{\sqrt[115]{15}}\) ).
- projection pair property of \(\triangleright\) and \(\triangleleft\) (Theorem \(15{ }^{55}\) in Section A.5);
- congruence of crashes-more-often (Theorem \(14{ }^{\sqrt{55}}\) in Section A.4).

Proof. The notation \(e^{\tau}\) and \(t^{\tau}\) mean that both the expression \(e\) and the contract \(t\) are well-typed and they have the same type \(\tau\). The proof begins by dealing with two special cases:
- Case \(e \rightarrow^{*}\) BAD: We prove the two directions separately.
\[
(\Rightarrow)
\]
\[
\begin{aligned}
& e \triangleright t \text { is } \mathbf{c f} \\
\Rightarrow & (\text { By Lemma } \sqrt{[1]}(\text { preservation of crash-freeness) } \\
& \text { and Lemma } \sqrt{[2]}(\mathrm{b}) \text { (about Any)) } \\
& t=\text { Any } \\
\Rightarrow & \text { (By defn of } \in, \text { every expression satisfies Any) } \\
& e \in t
\end{aligned}
\]
\((\Leftarrow)\)
\(e \in t\)
\(\Rightarrow \quad\) (By Lemma \(3^{[13]}\) (preservation of crash-freeness) and Lemma \(8{ }^{[21]}\) (a) (about Any))
\(t=\) Any
\(\Rightarrow \quad(\) By defn of \(\triangleright)\) \(e \triangleright\) Any is crash-free
- Case \(e \uparrow\) : By inspecting the definition of \(\triangleright\) and \(\in\), for all \(t\), if \(e \uparrow\), then \((e \triangleright t) \uparrow\) and \(e \in t\). Thus, we are done.

Hence, for the rest of the proof, we assume that \(e \rightarrow^{*}\) val \(\notin\{\mathrm{BAD}, \mathrm{UNR}\}\).
The rest of the proof is by induction on the size of \(t\).
- Case \(t\) is \(\{x \mid p\}\) :
\[
\begin{array}{ll} 
& e \triangleright\{x \mid p\} \text { is } \mathbf{c f} \\
\Longleftrightarrow & (\text { By defn of } \triangleright) \\
& \left(\begin{array}{l}
\text { let } x=e \text { in } \\
\text { match } p \text { with } \\
\mid \text { true } \rightarrow x \\
\mid \text { false } \rightarrow \text { BAD }
\end{array}\right) \text { is } \mathbf{c f} \\
& \left(\text { Since } e \rightarrow^{*} \text { val } \notin\{\text { BAD, UNR }\}\right) \\
& e \text { is cf and } p \nrightarrow^{*}\{\text { BAD, } \mathrm{false}\} \\
\Longleftrightarrow \quad & (\text { By defn of } \in) \\
& e \in\{x \mid p\}
\end{array}
\]
- Case \(t\) is \(x: t_{1} \rightarrow t_{2}\) : we want to prove that
\[
\left(e \triangleright x: t_{1} \rightarrow t_{2}\right) \text { is } \mathbf{c f} \Longleftrightarrow e \in x: t_{1} \rightarrow t_{2}
\]

We have the following induction hypotheses:
\[
\begin{array}{ll}
\forall \mathbf{c l} e_{1}, e_{1} \triangleright t_{1} \text { is } \mathbf{c f} \Longleftrightarrow e_{1} \in t_{1} & {[\mathrm{IH} 1]}  \tag{IH1}\\
\forall \mathbf{c l} e_{2}, \mathbf{c l} \mathbf{t l} e^{\prime} \cdot e_{2} \triangleright t_{2}\left[e^{\prime} / x\right] \text { is } \mathbf{c f} \Longleftrightarrow e_{2} \in t_{2}\left[e^{\prime} / x\right] & {[\mathrm{IH} 2]}
\end{array}
\]

We have the following proof:
```

        \(e \triangleright x: t_{1} \rightarrow t_{2}\) is \(\mathbf{c f}\).
    $\Longleftrightarrow \quad($ By defn of $\triangleright)$
let $y=e$ in $\lambda x_{1} \cdot\left(y\left(x_{1} \triangleleft t_{1}\right)\right) \triangleright t_{2}\left[\left(x_{1} \triangleleft t_{1}\right) / x\right]$ is $\mathbf{c f}$.
$\Longleftrightarrow \quad\left(\right.$ Since $e \rightarrow^{*}$ val $\notin\{$ BAD, UNR $\left.\}\right)$
$\lambda x_{1} .\left(e\left(x_{1} \triangleleft t_{1}\right)\right) \triangleright t_{2}\left[\left(x_{1} \triangleleft t_{1}\right) / x\right]$ is $\mathbf{c f}$.
$\Longleftrightarrow \quad$ (By Lemma $4^{[13]}$ (crash-free function))
(†) $\quad \forall \mathbf{c f} e^{\prime} .\left(e\left(e^{\prime} \triangleleft t_{1}\right)\right) \triangleright t_{2}\left[\left(e^{\prime} \triangleleft t_{1}\right) / x\right]$ is $\mathbf{c f}$.

```

Now the proof splits into two. In the reverse direction, we start with the assumption \(e \in x: t_{1} \rightarrow t_{2}\) :
```

            \(e \in x: t_{1} \rightarrow t_{2}\)
    $\Longleftrightarrow \quad($ By defn of $\in$ )
$\forall e_{1} \in t_{1} .\left(e e_{1}\right) \in t_{2}\left[e_{1} / x\right]$
$\Rightarrow \quad\left(\right.$ By Lemma $14{ }^{[53}$ (Key lemma), let $\left.e_{1}=e^{\prime} \triangleleft t_{1}\right)$
$\left.\forall \mathbf{c f} e^{\prime} .\left(e\left(e^{\prime} \triangleleft t_{1}\right)\right) \in t_{2}\left[\left(e^{\prime} \triangleleft t_{1}\right) / x\right]\right)$
$\Longleftrightarrow \quad(\mathrm{By}$ [IH2])
(†) $\quad \forall \mathbf{c f} e^{\prime} .\left(e\left(e^{\prime} \triangleleft t_{1}\right)\right) \triangleright t_{2}\left[\left(e^{\prime} \triangleleft t_{1}\right) / x\right]$ is $\mathbf{c f}$.

```

Now we have reached the desired conclusion ( \(\dagger\) ). The key step is the use of Lemma \(14{ }^{[53}\) (Key lemma) (see Section A.2).

In the forward direction, we start with ( \(\dagger\) ):
\[
\begin{aligned}
& \forall \mathbf{c f} e^{\prime} .\left(e\left(e^{\prime} \triangleleft t_{1}\right)\right) \triangleright t_{2}\left[\left(e^{\prime} \triangleleft t_{1}\right) / x\right] \text { is } \mathbf{c f} \text {. } \\
& \Rightarrow \quad\left(\mathrm{By}[\mathrm{IH} 1], e_{1} \in t_{1} \Rightarrow\left(e_{1} \triangleright t_{1}\right) \text { is } \mathbf{c f} \text { so we replace } e^{\prime} \text { by } e_{1} \triangleright t_{1}\right) \\
& \forall e_{1} \in t_{1} .\left(e\left(\left(e_{1} \triangleright t_{1}\right) \triangleleft t_{1}\right)\right) \triangleright t_{2}\left[\left(e_{1} \triangleright t_{1} \triangleleft t_{1}\right) / x\right] \text { is } \mathbf{c f} \\
& \Rightarrow \quad \text { (By (Theorem } 15{ }^{555} \text { (projection pair) and } \\
& \text { Theorem } 14{ }^{[55]} \text { (congruence of } \preceq \text { ) and } \\
& \text { Lemma } 7^{\frac{10}{15}} \text { (c) (property of } \preceq \text { )) twice) } \\
& \left.\forall e_{1} \in t_{1} \text {. }\left(e e_{1}\right) \triangleright t_{2}\left[e_{1} / x\right]\right) \text { is } \mathbf{c f} \\
& \Rightarrow \quad(\mathrm{By}[\mathrm{IH} 2]) \\
& \left.\forall e_{1} \in t_{1} .\left(e e_{1}\right) \in t_{2}\left[e_{1} / x\right]\right) \\
& \Longleftrightarrow \quad \text { (by definition of } \in \text { ) } \\
& e \in x: t_{1} \rightarrow t_{2}
\end{aligned}
\]

There are two key steps: one is to choose a particular crash-free \(e^{\prime}\), namely \(\left(e_{1} \triangleright t_{1}\right)\) where \(e_{1} \in t_{1}\); the other one is the appeal to Theorem \(15{ }^{550}\), the projection pair property of \(\triangleright\) and \(\triangleleft\) (see Section A.5).
- \(t\) is \(\left(x: t_{1}, t_{2}\right)\) : We have the following induction hypotheses:
\[
\begin{align*}
& \forall \mathbf{c l} e_{1} \cdot e_{1} \triangleright t_{1} \text { is } \mathbf{c f} \Longleftrightarrow e_{1} \in t_{1}  \tag{IH1}\\
& \forall \mathbf{c l} e_{2}, \mathbf{c l} \mathbf{t l} e^{\prime} \cdot e_{2} \triangleright t_{2}\left[e^{\prime} / x\right] \text { is } \mathbf{c f} \Longleftrightarrow e_{2}\left[e^{\prime} / x\right] \in t_{2}\left[e^{\prime} / x\right]
\end{aligned} \begin{aligned}
& {[\mathrm{IH} 1]} \\
& {[\mathrm{IH} 2]}
\end{align*}
\]

We prove it as follows.
```

            \(e \triangleright\left(x: t_{1}, t_{2}\right)\) is \(\mathbf{c f}\)
    $\Longleftrightarrow \quad($ By defn of $\triangleright)$
match $e$ with $\left\{\left(x_{1}, x_{2}\right) \rightarrow\left(x_{1} \triangleright t_{1}, x_{2} \triangleright t_{2}\left[x_{1} \triangleleft t_{1} / x\right]\right)\right\}$ is $\mathbf{c f}$
$\Longleftrightarrow \quad(\mathrm{By}[\mathrm{E}-\mathrm{match}]$ and defn of $\mathbf{c f})$
$e \rightarrow^{*}\left(e_{1}, e_{2}\right)$ and $e_{1}$ and $e_{2}$ are $\mathbf{c f}$ and
$\left(e_{1} \triangleright t_{1}\right)$ is $\mathbf{c f}$ and $\left(e_{2} \triangleright t_{2}\left[e_{1} \triangleleft t_{1} / x\right]\right)$ is $\mathbf{c f}$
$\Longleftrightarrow \quad(\mathrm{By}[\mathrm{IH} 1])$
$(\dagger) \quad e \rightarrow^{*}\left(e_{1}, e_{2}\right)$ and $e_{1}$ and $e_{2}$ are $\mathbf{c f}$ and
$e_{1} \in t_{1}$ and $\left(e_{2} \triangleright t_{2}\left[e_{1} \triangleleft t_{1} / x\right]\right)$ is $\mathbf{c f}$

```

Now the proof splits into two. In the forward direction, we start with ( \(\dagger\) ):
\[
\begin{aligned}
(\dagger) \quad & e \rightarrow^{*}\left(e_{1}, e_{2}\right) \text { and } e_{1} \text { and } e_{2} \text { are } \mathbf{c f} \text { and } \\
& e_{1} \in t_{1} \text { and } e_{2} \triangleright t_{2}\left[e_{1} \triangleleft t_{1} / x\right] \text { is } \mathbf{c f} \\
\Rightarrow \quad & (\text { By Lemma } \\
& \text { Theorem }{ }^{\left.16\right|^{[5]}}(\text { (congruence of } \preceq) \text { and } \\
& \text { Lemma } \left.\left.7]^{[5]}(\text { conditional }) \text { (property of } \preceq\right)\right) \\
& e \rightarrow^{*}\left(e_{1}, e_{2}\right) \text { and } e_{1} \in t_{1} \text { and } e_{2} \triangleright t_{2}\left[e_{1} / x\right] \text { is } \mathbf{c f} \\
\Longleftrightarrow & (\text { By }[\mathrm{IH} 1] \text { and }[\mathrm{IH} 2]) \\
& e \rightarrow^{*}\left(e_{1}, e_{2}\right) \text { and } e_{1} \in t_{1} \text { and } e_{2} \in t_{2}\left[e_{1} / x\right] \\
\Longleftrightarrow \quad & (\text { By definition of } \in) \\
& e \in\left(x: t_{1}, t_{2}\right)
\end{aligned}
\]

The key step is the use of Lemma \({ }^{16}{ }^{[57}\) (a) (see Section A.6).

Now we prove the reverse direction. We use the fact that \(\left(x: t_{1}, t_{2}\right)\) is total. By definition of total contract, \(t_{1}\) is total and for all \(e \in t_{1}, t_{2}[e / x]\) is total.
We have:
```

    \(e \in\left(x: t_{1}, t_{2}\right)\)
    \(\Longleftrightarrow \quad\) (By definition of \(\in\) )
    \(e \rightarrow^{*}\left(e_{1}, e_{2}\right)\) and \(e_{1} \in t_{1}\) and \(e_{2} \in t_{2}\left[e_{1} / x\right]\)
    \(\Longleftrightarrow \quad\) (By Lemma \(14{ }^{[53}\) (Key lemma), let \(\left.e_{1}=e^{\prime} \triangleleft t_{1}\right)\)
    \(e \rightarrow^{*}\left(e_{1}, e_{2}\right)\) and \(e_{1} \in t_{1}\) and \(\exists \mathbf{c f} e^{\prime}, e_{2} \in t_{2}\left[e^{\prime} \triangleleft t_{1} / x\right]\)
    \(\Longleftrightarrow \quad(\mathrm{By}[\mathrm{IH} 1])\)
    \(e \rightarrow^{*}\left(e_{1}, e_{2}\right)\) and \(e_{1} \triangleright t_{1}\) is \(\mathbf{c f}\) and \(\exists \mathbf{c f} e^{\prime}, e_{2} \in t_{2}\left[e^{\prime} \triangleleft t_{1} / x\right]\)
    \(\Rightarrow \quad\left(e_{1} \triangleright t_{1}\right.\) is \(\mathbf{c f}\) and by [IH2])
    \(e \rightarrow^{*}\left(e_{1}, e_{2}\right)\) and \(e_{1} \triangleright t_{1}\) is \(\mathbf{c f}\) and \(e_{2} \triangleright t_{2}\left[e_{1} \triangleright t_{1} \triangleleft t_{1} / x\right]\) is \(\mathbf{c f}\)
    \(\Longleftrightarrow \quad\) (By Lemma \({ }^{15}{ }^{56}\) (Idempotency)
    Theorem \(14{ }^{[55]}\) (congruence of \(\preceq\) ) and
    Lemma \(7^{\sqrt{15}}(\mathrm{c})(\) property of \(\preceq)\) )
    \(e \rightarrow^{*}\left(e_{1}, e_{2}\right)\) and \(e_{1} \triangleright t_{1}\) is \(\mathbf{c f}\) and \(e_{2} \triangleright t_{2}\left[e_{1} \triangleright t_{1} \triangleleft t_{1} \triangleleft t_{1} / x\right]\) is \(\mathbf{c f}\)
    $\Longleftrightarrow \quad\left(\right.$ By Theorem ${ }^{15}{ }^{[55}$ (Projection pair), $e_{1} \triangleright t_{1} \triangleleft t_{1} \preceq e_{1}$,
Theorem $14{ }^{[55]}$ (congruence of $\preceq$ ) and
Lemma $7^{\sqrt{15}}$ (c) (property of $\left.\preceq\right)$ )
$e \rightarrow^{*}\left(e_{1}, e_{2}\right)$ and $e_{1} \triangleright t_{1}$ is $\mathbf{c f}$ and $e_{2} \triangleright t_{2}\left[e_{1} \triangleleft t_{1} / x\right]$ is $\mathbf{c f}$

```

The key steps are using Lemma 14\(]^{\sqrt{53}}\) (Key lemma), apply Lemma 15\(]^{\sqrt{56}}\) (Idempotency) and use Theorem \(15{ }^{550}\) (Projection pair).
- \(t\) is Any: We have:
\[
\begin{array}{ll} 
& e \triangleright \text { Any is } \mathbf{c f} \\
\Longleftrightarrow \quad & (\text { By definition of } \triangleright) \\
& \text { UNR is } \mathbf{c f} \\
\Longleftrightarrow \quad & (\text { By definition of } \in, \text { and UNR } \in \text { Any }) \\
& e \in \text { Any }
\end{array}
\]

\section*{A. 1 Telescoping Property}

The telescoping property is adapted from [7] and we found that this property makes the proofs of many lemmas shorter. However, it is not used in any proof in [7].

Lemma 13 (Telescoping Property). For all expression e, and total contract \(t\), \(\left(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t\right) \stackrel{r_{3}}{\stackrel{r_{4}}{\bowtie}} t=e \underset{r_{4}}{\stackrel{r_{1}}{\bowtie}} t\)

Proof. Before we start the proof, by definition of let, [E-exn] and [E-match], we know two facts:
[Fact1] \(\forall e^{\prime}\). (let \(x=\operatorname{BAD}\) in \(\left.e^{\prime}\right) \rightarrow \mathrm{BAD}\)
[Fact2] \(\forall\) alts, (match BAD with alts) \(\rightarrow\) BAD
The proof begins by dealing with two special cases.
- Case \(e \rightarrow^{*}\) BAD: Based on [Fact1] and [Fact2], for all \(t \neq\) Any, by inspecting the definition of \(\bowtie\), we know \(\left(\underset{r_{j}}{\stackrel{r_{i}}{\bowtie}} t\right) \rightarrow^{*}\) BAD for all \(i, j\). So LHS \(=\) RHS \(=\) BAD for \(t \neq\) Any. In the case \(t=\) Any, we have:
\[
\begin{aligned}
& =r_{2} \stackrel{r_{4}}{\stackrel{r_{3}}{\triangleleft}} \text { Any } \\
& =r_{4} \\
& =e \underset{r_{4}}{\stackrel{r_{3}}{\infty}} \mathrm{Any}
\end{aligned}
\]
- \(e \uparrow\). Similar to the arguments in the case \(e \rightarrow^{*}\) BAD.

Hence for the rest of the proof we assume that \(e \rightarrow^{*}\) val \(\notin\{\mathrm{BAD}, \mathrm{UNR}\}\).
The rest of the proof is by induction on the size of \(t\).
- \(t\) is \(\{x \mid p\}\) :
```

    \(\left(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}}\{x \mid p\}\right) \stackrel{r_{r_{4}}}{r_{3}}\{x \mid p\}\)
    $=($ By definition of $\bowtie)$
let $x=\left(\right.$ let $x=e$ in if $p$ then $x$ else $\left.r_{1}\right)$
in if $p$ then $x$ else $r_{3}$
$=$ (We float let $x=e$ out)
let $x=e$ in if $p$ then (let $x=x$ in if $p$ then $x$ else $r_{3}$ )
else (let $x=r_{1}$ in if $p$ then $x$ else $r_{3}$ )
$=$ (This is not let rec, so inline $x$ in the then branch.
By [E-beta] and [Fact1].)
let $x=e$ in if $p$ then (if $p$ then $x$ else $r_{3}$ )
else $r_{1}$
$=$ (propagating the true value of $p$ to sub-branches)
let $x=e$ in if $p$ then $x$
else $r_{1}$
$=($ By defn of $\bowtie)$
$e \stackrel{r_{1}}{\stackrel{\rightharpoonup}{r_{4}}} t$

```
- \(t\) is \(x: t_{1} \rightarrow t_{2}\) : We have the following induction hypotheses:
\[
\begin{align*}
& \forall e, \mathbf{t l} t_{1},\left(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie} t_{1}}\right) \stackrel{r_{r_{4}}}{\stackrel{r_{3}}{\bowtie}} t_{1}=e \underset{r_{4}}{\stackrel{r_{1}}{\bowtie}} t_{1} \tag{IH1}
\end{align*}
\]

We have the following proof:
\[
\begin{aligned}
& \left(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} x: t_{1} \rightarrow t_{2}\right) \stackrel{r_{r_{4}}}{r_{3}} x: t_{1} \rightarrow t_{2} \\
& =(\text { By defn of } \bowtie) \\
& \text { let } y=e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} x: t_{1} \rightarrow t_{2} \text { in } \lambda x_{1} .\left(y \quad\left(x_{1} \underset{r_{3}}{r_{4}} t_{1}\right)\right) \stackrel{r_{3}}{\underset{r_{4}}{r_{3}}} t_{2}\left[\left(x_{1} \underset{r_{3}}{\stackrel{r_{4}}{\bowtie}} t_{1}\right) / x\right] \\
& =\text { (By defn of } \bowtie \text { again) } \\
& \text { let } y=e \text { in let } y=\lambda x_{2} \text {. }\left(\left(y\left(x_{2} \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right)\right) \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{2}\left[\left(x_{2} \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right) / x\right]\right) \text { in } \\
& \lambda x_{1} \cdot\left(\left(y \quad\left(x_{1} \underset{r_{3}}{r_{4}} t_{1}\right)\right) \stackrel{r_{4}}{r_{3}} t_{2}\left[\left(x_{1} \underset{r_{3}}{\stackrel{r}{4}_{\triangleleft}^{~}} t_{1}\right) / x\right]\right) \\
& =(\text { By } \beta \text {-reduction }) \\
& \text { let } y=e \text { in }
\end{aligned}
\]
\[
\begin{aligned}
& =\left(\text { By induction hypothesis with } t=t_{1}\right)
\end{aligned}
\]
\[
\begin{aligned}
& =\text { (By call-by-value, } r_{i} \text { in } t_{2} \text { (for all } i \text { ) are not reachable, replace } r_{3} \text { by } r_{1} \text { ) }
\end{aligned}
\]
\[
\begin{aligned}
& =\left(\text { By induction hypothesis [IH2]: } t=t_{2}\left[\left(x_{1} \stackrel{r_{4}}{r_{1}} t_{1}\right) / x\right]\right. \\
& t_{2}\left[\left(x_{1} \underset{r_{1}}{\stackrel{r_{4}}{\bowtie}} t_{1}\right) / x\right] \text { is } \mathbf{t l} \text { because } r_{i} \text { in } t_{2} \text { (for all } i \text { ) are not reachable) } \\
& \text { let } y=e \text { in } \lambda x_{1} .\left(y\left(x_{1} \underset{r_{1}}{\stackrel{r_{4}}{\bowtie}} t_{1}\right)\right) \underset{r_{4}}{\stackrel{r_{1}}{\otimes} t_{2}}\left[\left(x_{1} \underset{r_{1}}{\stackrel{r_{4}}{\otimes}} t_{1}\right) / x\right] \\
& =(\text { By defn of } \bowtie) \\
& e \underset{r_{4}}{\stackrel{r_{1}}{\bowtie} x: t_{1} \rightarrow t_{2}}
\end{aligned}
\]

Although the \(\beta\)-reduction is done in the body of a let-expression, it is valid because we know \(e \rightarrow^{*}\) val \(\notin\{\mathrm{BAD}, \mathrm{UNR}\}\) and it does not violate call-by-value execution.
- \(t\) is \(\left(x: t_{1}, t_{2}\right)\) : We have the following induction hypotheses:
\[
\begin{gather*}
\forall e, \mathbf{t l} t_{1},\left(e \underset{r_{r_{2}}}{\stackrel{r_{1}}{\bowtie}} t_{1}\right) \stackrel{r_{3}}{r_{3}} t_{1}=e e_{r_{4}}^{\stackrel{r_{1}}{\bowtie}} t_{1}  \tag{IH1}\\
\forall e, e^{\prime} \in t_{1}, \mathbf{t l} t_{2}\left[e^{\prime} / x\right],\left(e \underset{r_{2}}{r_{1}} t_{2}\left[e^{\prime} / x\right]\right) \underset{r_{4}}{r_{3}} t_{2}\left[e^{\prime} / x\right]=e \underset{r_{4}}{r_{1}} t_{2}\left[e^{\prime} / x\right] \tag{IH2}
\end{gather*}
\]

We have the following proof:
\[
\begin{aligned}
& \left(e \underset{r_{2}}{\stackrel{r_{1}}{\infty}}\left(x: t_{1}, t_{2}\right)\right) \stackrel{r_{r_{4}}}{r_{3}}\left(x: t_{1}, t_{2}\right) \\
& =(\text { By defn of } \bowtie) \\
& \text { (match } \left.e \text { with }\left(x_{1}, x_{2}\right) \rightarrow\left(x_{1} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{1}, x_{2} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{2}\left[\left(x_{1} \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right) / x\right]\right)\right) \underset{r_{4}}{\stackrel{r_{3}}{\bowtie}}\left(x: t_{1}, t_{2}\right) \\
& =\quad(\text { By defn of } \bowtie \text { again }) \\
& \operatorname{match}\left(\text { match } e \text { with }\left(x_{1}, x_{2}\right) \rightarrow\left(x_{1} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{1}, x_{2} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{2}\left[\left(x_{1} \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right) / x\right]\right)\right) \text { with } \\
& \left(x_{3}, x_{4}\right) \rightarrow\left(x_{3} \underset{r_{4}}{\stackrel{r_{3}}{\otimes}} t_{1}, x_{4} \underset{r_{4}}{\stackrel{r_{3}}{\bowtie}} t_{2}\left[\left(x_{3} \underset{r_{3}}{\stackrel{r_{4}}{\propto} t_{1}}\right) / x\right]\right) \\
& =(\text { By simpl rule [match-match] and [E-match] }) \\
& \text { match } e \text { with } \\
& \left(x_{1}, x_{2}\right) \rightarrow\left(\left(x_{1} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{1}\right) \stackrel{r_{3}}{r_{4}} t_{1},\left(x_{2} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{2}\left[\left(x_{1} \underset{r_{1}}{r_{2}} t_{1}\right) / x\right]\right) \underset{r_{4}}{\stackrel{r_{3}}{\bowtie}} t_{2}\left[\left(x_{1} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{1} \underset{r_{3}}{r_{4}} t_{1}\right) / x\right]\right) \\
& =\quad(\text { By induction hypothesis [IH1]. } \\
& \text { match } e \text { with } \\
& \left(x_{1}, x_{2}\right) \rightarrow\left(x_{1} \underset{r_{4}}{\stackrel{r_{1}}{\otimes}} t_{1},\left(x_{2} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{2}\left[\left(x_{1} \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right) / x\right]\right) \stackrel{r_{3}}{r_{4}} t_{2}\left[\left(x_{1} \underset{r_{3}}{\left.\left.\left.\stackrel{r_{1}}{\otimes} t_{1}\right) / x\right]\right)}\right.\right.\right. \\
& =\text { (Due to } x_{1} \underset{r_{4}}{\stackrel{r_{1}}{\bowtie}} t_{1} \text {, for all } i, j \text {, the } r_{i}, r_{j} \text { in }\left[x_{1} \underset{r_{j}}{\stackrel{r_{i}}{\bowtie}} t_{1} / x\right] \text { cannot be reached.) } \\
& \text { match } e \text { with } \\
& \left(x_{1}, x_{2}\right) \rightarrow\left(x_{1} \underset{r_{4}}{\stackrel{r_{1}}{\bowtie}} t_{1},\left(x_{2} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{2}\left[\left(x_{1} \underset{r_{1}}{\stackrel{r_{4}}{\bowtie}} t_{1}\right) / x\right]\right) \underset{r_{4}}{\stackrel{r_{3}}{\bowtie}} t_{2}\left[\left(x_{1} \underset{r_{1}}{r_{4}} t_{1}\right) / x\right]\right) \\
& =\left(\text { By induction hypothesis [IH2]: } t=t_{2}\left[\left(x_{1} \stackrel{r_{4}}{\stackrel{\wedge}{~}} \mathrm{r}_{1}\right) / x\right]\right. \text {.) } \\
& \text { match } e \text { with } \\
& \left(x_{1}, x_{2}\right) \rightarrow\left(x_{1} \underset{r_{4}}{\stackrel{r_{1}}{\bowtie}} t_{1}, x_{2} \underset{r_{4}}{\stackrel{r_{1}}{\bowtie}} t_{2}\left[\left(x_{1} \underset{r_{1}}{\stackrel{r_{4}}{\bowtie}} t_{1}\right) / x\right]\right) \\
& =(\text { By defn of projection }) \\
& e \underset{r_{4}}{{\underset{r}{1}}^{r_{1}}\left(x: t_{1}, t_{2}\right), ~(1)}
\end{aligned}
\]
- \(t\) is Any:

LHS
\[
\begin{aligned}
& \left(e \underset{\substack{r_{2} \\
r_{2}}}{r_{1}} \text { Any }\right) \stackrel{\underset{r_{4}}{r_{3}}}{\stackrel{r_{3}}{\triangleleft}} \text { Any } \\
& =r_{2} \stackrel{r_{3}}{\diamond} \text { Any } \\
& =r_{4}
\end{aligned}
\]

RHS
\[
\begin{aligned}
& e \stackrel{r_{3}}{\bowtie} \mathrm{Any} \\
= & r_{4}
\end{aligned}
\]

Since LHS \(\equiv\) RHS, we are done.

\section*{A. 2 Key Lemma}

Lemma 14 (Key lemma). For all crash-free e and total contract \(t\), such that \(\vdash e:: \tau\) and \(\vdash_{c} t:: \tau\),
\[
e \triangleleft t \in t
\]

Proof. First, we have the following derivation (named D1).
\[
\begin{aligned}
& (e \triangleleft t) \triangleright t \\
& =(\text { By defn of } \triangleleft \text { and } \triangleright) \\
& (e \underset{\text { BaD }}{\text { UnR }} t) \stackrel{\text { UuD }}{\text { UNR }} t \\
& =\left(\mathrm{By} \text { Lemma } \sqrt{13]^{[50}}(\text { Telescoping Property) })\right. \\
& e \underset{\mathrm{UNR}}{\bigotimes_{\mathrm{UNR}}} t
\end{aligned}
\]

Now, we have the following proof.
\[
\begin{aligned}
& e \text { is } \mathbf{c f} \\
& \Rightarrow \quad(\text { Since } t \text { is total, } t \equiv\lfloor t\rfloor \text {. By the defn of } \bowtie \text {, the context }(\bullet \underset{\text { UuR }}{\text { UuR }}\lfloor t\rfloor) \\
& \text { is syntactically safe. By defn of } \mathbf{c f} \text {, we have below) } \\
& e_{\substack{\mathrm{UNR}}}^{\substack{\mathrm{WR}}} \mathrm{is} \mathbf{c f} \\
& \Longleftrightarrow \quad \text { (By derivation D1) } \\
& (e \triangleleft t) \triangleright t \text { is } \mathbf{c f} \\
& \Longleftrightarrow \quad(\text { By Theorem }]^{118} \text { (grand theorem)) } \\
& (e \triangleleft t) \in t
\end{aligned}
\]

\section*{A. 3 Examination of Cyclic Dependencies}

Recall the dependency graph in Figure 18, there are two cycles:
(1) \(\mathrm{T} 2 \rightarrow \mathrm{~L} 15 \rightarrow \mathrm{~T} 2\)
(2) \(\mathrm{T} 2 \rightarrow \mathrm{~L} 17 \rightarrow \mathrm{~L} 19 \rightarrow \mathrm{~T} 2\)


Figure 19: Cyclic Dependency of Three Lemmas
Each cycle is shown in Figure 19, The dashed directed edge indicates a decrease in size of \(t\) while the solid directed edge shows a preservation of the size of \(t\). We can see that, in each cycle, there is an edge that decreases the size of \(t\). Cycle (1) is well-founded because the size of \(t\) (where \(t=x: t_{1} \rightarrow t_{2}\) ) decreases (to \(t_{1}\) ) when Theorem [2 \({ }^{[18]}\) calls Lemma 14\(]^{53}\). Cycle (2) is well-founded because the size of \(t\) (where \(t=x: t_{1} \rightarrow t_{2}\) ) decreases (to \(t_{1}\) ) when Theorem [2 \({ }^{118}\) calls Lemma \(16{ }^{[157}\). Although there are cyclic dependencies among these theorems and lemmas, on each cyclic path, there is a decrease in the size of \(t\). Thus, our proof on induction of the size of \(t\) is well-founded.

\section*{A. 4 Congruence of Crashes-More-Often}

Theorem 14 (Congruence of Crashes-More-Often).
\[
\forall e_{1}, e_{2} . \quad e_{1} \preceq e_{2} \quad \Longleftrightarrow \quad \forall \mathcal{C}, \quad \mathcal{C} \llbracket e_{1} \rrbracket \preceq \mathcal{C} \llbracket e_{2} \rrbracket
\]

Proof. We prove two directions separately:
\((\Rightarrow)\) For an arbitrary \(\mathcal{B}\), we prove \(\mathcal{B} \llbracket e_{1} \rrbracket \preceq \mathcal{B} \llbracket e_{2} \rrbracket\). We have the following proof:
\[
\begin{array}{ll} 
& e_{1} \preceq e_{2} \\
\Longleftrightarrow & (\mathrm{By} \text { definition } 7) \\
& \forall \mathcal{C} \cdot \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} \mathrm{BAD} \Rightarrow \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} \mathrm{BAD} \\
\Rightarrow & \forall \mathcal{C}, \mathcal{D} \cdot(\mathcal{C}=\mathcal{D} \llbracket \mathcal{B} \llbracket \bullet \rrbracket) \Rightarrow\left(\mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} \mathrm{BAD} \Rightarrow \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} \mathrm{BAD}\right) \\
\Rightarrow & \forall \mathcal{D} \cdot \mathcal{D} \llbracket \mathcal{B} \llbracket e_{2} \rrbracket \rrbracket \rightarrow^{*} \mathrm{BAD} \Rightarrow \mathcal{D} \llbracket \mathcal{B} \llbracket e_{1} \rrbracket \rightarrow^{*} \mathrm{BAD} \\
\Rightarrow & \forall \mathcal{B} \cdot \mathcal{B} \llbracket e_{1} \rrbracket \preceq \mathcal{B} \llbracket e_{2} \rrbracket
\end{array}
\]

Note that we assume for all \(i=1,2\) :
\[
\vdash \mathcal{C} \llbracket e_{i} \rrbracket:: \text { bool }, \vdash \mathcal{D} \llbracket e_{i} \rrbracket:: \text { bool and } \vdash \mathcal{E} \llbracket e_{i} \rrbracket:: \text { bool }
\]
\((\Leftarrow)\) It is trivially true, because we can choose an empty context (i.e. \(\mathcal{C}=\) -).

\section*{A. 5 Projection Pair and Closure Pair}

Recall the definition of projection pair. Let \(D\) and \(E\) be complete partial order's. If \(f: D \rightarrow E\) and \(g: E \rightarrow D\) are continuous functions such that \(f \circ g \subseteq i d\), then \((f, g)\) is called a projection pair. If \(i d \subseteq f \circ g\), then \((f, g)\) is called a closure pair. In this section, we are not going to explore the theory in depth. We only notice that in some way \((\bullet \triangleright t \triangleleft t \preceq i d)\) and \((i d \preceq \bullet \triangleleft t \triangleright t)\) match the definition of projection pair and closure pair respectively.

Theorem 15 (A projection pair). For all expression e and contract \(t\), such that \(\exists \Gamma . \Gamma \vdash e:: \tau\) and \(\Gamma \vdash_{c} t:: \tau\),
\[
(e \triangleright t) \triangleleft t \preceq e
\]

Proof. We have the following proof:
\[
\begin{aligned}
& (e \triangleright t) \triangleleft t \\
& =\quad(\text { By defn of } \triangleright \text { and } \triangleleft) \\
& (e \underset{\text { Bur }}{\mathrm{BaD}} t) \underset{\substack{\mathrm{VNR}}}{\mathrm{VNR}} t \\
& =\left(\text { By Lemma } 13{ }^{[50}\right) \\
& e \underset{\text { BaD }}{\text { ByD }} t \\
& \ll\left\{_{\text {вар }\}} \quad \text { (By Lemma 199 }{ }^{[58]}\right. \text { ) } \\
& e
\end{aligned}
\]

By definition of \(<_{\{\text {вар }\}}\), we get the desired result.

Theorem 16 (A Closure Pair). For all expression \(e\) and contract \(t\), such that \(\exists \Gamma . \Gamma \vdash e:: \tau\) and \(\Gamma \vdash_{c} t:: \tau\),
\[
e \preceq(e \triangleleft t) \triangleright t
\]

Proof. We have the following proof:
\[
\begin{aligned}
& (e \triangleleft t) \triangleright t \\
& =\quad(\text { By defn of } \triangleleft \text { and } \triangleright) \\
& (e \underset{\text { Ban }}{\text { ONR }} \uparrow \underset{\substack{\text { UNR }}}{\text { BAD }} t \\
& =\left(\text { By Lemma } 13{ }^{[50}\right) \\
& e \stackrel{\text { Wir }}{\substack{\text { Wr }}} \\
& \ll\left\{_ { \{ \mathrm { wnR } \} } \quad \left(\text { By Lemma } 19{ }^{[58}\right.\right. \text { ) } \\
& e
\end{aligned}
\]

By definition of \(<_{\{u n \mathrm{R}\}}\), we get the desired result.

\section*{A. 6 Contracts are Projections}

Recall the definition of projection, a projection \(p\) is a function that has two properties:
1. \(p=p \circ p\)
2. \(p \subseteq 1\)

The first one is called the retract property and says that projections are idempotent on their range. The second one says that the result of a projection contains no more information than its input.

We would like to show that if \(e \in t\), then \((\bullet \triangleleft t)\) is an error projection while \((\bullet \triangleright t)\) is a safe projection. By error projection, we mean \(e \triangleleft t\) either behaves the same as \(e\) or returns BAD. Similarly, by safe projection, we mean \(e \triangleright t\) either behaves the same as \(e\) or returns UNR.

Findler and Blume [12] are the first to discover that contracts are pairs of projections. However, they assume that the \(e\) is a non-crashing term and the only error raised are contract violations. We assume that a program may contain errors and may crash. We give error a contract Any. Moreover, we prove different theorems from 12 .

Theorem 17 (Error Projection). For all closed e and closed \(t\), if \(e \in t,(\bullet \triangleleft t)\) is a projection.
Proof. By Lemma \(15{ }^{56}\) (a) (Idempotency) and Lemma \(16{ }^{57}\) (a).
Theorem 18 (Safe Projection). For all closed \(e\) and closed \(t\), if \(e \in t,(\bullet \triangleright t)\) is a projection.
Proof. By Lemma \(\sqrt{15}^{\sqrt[56]{ }}\) (b) (Idempotency) and Lemma \(\sqrt{16}^{\sqrt[57]{57}}\) (b).
Lemma 15 (Idempotence). For all closed e, \(t\),
\[
e \stackrel{r_{1}}{\stackrel{r_{1}}{\bowtie}} t \stackrel{r_{r_{2}}}{\underset{r_{1}}{ }} t=e \stackrel{r_{r_{2}}}{\stackrel{r_{1}}{\bowtie}} t
\]

Proof. It follows directly from Lemma \(13{ }^{\sqrt{50}}\) (telescoping property).
Lemma 16 (Conditional projection). For all closed e, closed and total \(t\), if \(e \in t\), then
(a) \(e \triangleleft t \preceq e\)
(b) \(e \preceq e \triangleright t\)

Proof. We prove each of them separately.
(a) Given \(e \in t\), we have:
```

    \(e \triangleleft t\)
    \(=(\) By defn of \(\triangleright\) in Figure 6)
    \(e \stackrel{\text { vuR }}{\wedge} t\)
    \(\equiv_{s} \quad\left(\right.\) By Lemma \(18{ }^{[57}\) (Exception III))
        \(e_{\Perp}^{\mathrm{BaD}} t\)
    \(\preceq \quad(\text { By Lemma } 19]^{\sqrt[58]{58}}\) (Behaviour of projection) and Definition \(\left.6^{[14]}(\ll)\right)\)
        \(e\)
    ```
(b) Given \(e \in t\), we have:
\(e \triangleright t\)
\(=(\) By defn of \(\triangleright\) in Figure 6)
\(e{ }_{\bowtie}^{\text {BaD }} t\)
\(\equiv_{s} \quad(\text { By Lemma } 18]^{[57}\) (Exception III))
\(e \underset{\text { UNR }}{\substack{\text { UNR }}} t\)
\(\succeq \quad(\text { By Lemma }]^{19}\) [8] Behaviour of projection) and Definition \(\left.6^{[14]}(\ll)\right)\) \(e\)

Lemma 17 (Exception I). \(\forall \mathcal{C}\). ( \(\mathcal{C} \llbracket \mathrm{UNR}, \mathrm{BAD} \rrbracket\) is \(\mathbf{c f} \Rightarrow \forall r_{1}, r_{2} \in\{\mathrm{BAD}, \mathrm{UNR}\} . \mathcal{C} \llbracket \mathrm{UNR}, r_{1} \rrbracket \equiv_{s}\) \(\mathcal{C}\) 【UNR, \(\left.r_{2} \rrbracket\right)\)

Proof. The intuition is that the BAD in the hole cannot be reached, so we can replace it by any exceptional value. This reasoning in turn relies on the absence of a "catch" primitive that can transform BAD into something non-BAD.

Formally, we can prove the lemma by case splitting on whether \(\mathcal{C} \llbracket U N R, B A D \rrbracket\) terminates, and if it does, by induction on the number of steps of reduction.


Proof. For all expression \(e\), contract \(t\), we have:
\[
\begin{aligned}
& e \in t \\
& \Longleftrightarrow \quad\left(\text { By Theorem } 2^{[18}\right. \text { (Grand Theorem)) } \\
& e \triangleright t \text { is } \mathbf{c f} \\
& \Longleftrightarrow \quad \text { (By defn of } \triangleright \text { and } \mathbf{c f} \text { ) } \\
& \forall \mathcal{C}, \mathrm{BAD} \notin \mathcal{C} . \mathcal{C} \llbracket e \stackrel{\mathrm{BAD}}{\bowtie} t \rrbracket \not \nrightarrow^{*} \mathrm{BAD} \\
& \Longleftrightarrow \quad(\text { By Lemma } 17]^{[57}{ }^{r} \text { (Exception I)) }
\end{aligned}
\]
\[
\begin{aligned}
& \Rightarrow \quad(\text { Let } \mathcal{C}=\bullet)
\end{aligned}
\]

We are done.

\section*{A. 7 Behaviour of Projections}

We have seen that in Section A.5, we make use of the property of behaves-thesame (<<) (Lemma \({ }^{19}{ }^{[58]}\) ). In this section, we give its detailed proof. Lemma \(19{ }^{[58}\) says that an expression wrapped with a contract behaves either the same as the original expression or returns one of the exceptions which can be either BAD or UNR.

Lemma 19 (Behaviour of projection). For all \(r_{1}, r_{2}\), \(e\), total \(t\), such that \(\vdash e:: \tau\) and \(\vdash_{c} t:: \tau\), and \(r_{1}, r_{2} \in\{\) BAD, UNR \(\}\),
\[
e \underset{r_{2}}{{\underset{r}{1}}^{\bowtie}} t \lll\left\{r_{1}, r_{2}\right\}<
\]

Proof. The proof begins by dealing with two special cases: \(e \uparrow, e \rightarrow^{*}\) BAD. In both cases, by Definition of \(\bowtie\), we know \(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t \equiv_{s} e\) and we are done.

Hence, for the rest of the proof we assume that \(e \rightarrow^{*}\) val \(\notin\{\operatorname{BAD}, \mathrm{UNR}\}\). We prove it by induction on the size of \(t\). Let \(R\) be \(\left\{r_{1}, r_{2}\right\}\).
- \(t\) is \(\{x \mid p\}\) : we have
\[
\underset{r_{2}}{\stackrel{r_{1}}{\bowtie}\{x \mid p\}=\text { let } x=e \text { in } \begin{array}{l}
\text { match } p[e / x] \text { with } \\
\left\lvert\, \begin{array}{lr}
\text { true } \rightarrow e
\end{array}\right. \\
\mid \text { false } \rightarrow r_{1}
\end{array}}
\]

Since \(t\) is total, \(p[e / x] \nrightarrow^{*}\) BAD. So there are two cases to consider:
- If \(p[e / x] \rightarrow^{*}\) false, then \(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}}\{x \mid p\} \rightarrow^{*} r_{1}\) and we are done.
- If \(p[e / x] \rightarrow^{*}\) true, \(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}}\{x \mid p\} \rightarrow^{*} e\) and we are done.
- \(t\) is \(x: t_{1} \rightarrow t_{2}\) : We have
\[
e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} x: t_{1} \rightarrow t_{2}=\text { let } y=e \text { in } \lambda v .\left(\left(y\left(v \underset{r_{1}}{\left.\left.\stackrel{r_{2}}{\bowtie} t_{1}\right)\right)} \stackrel{r_{1}}{r_{1}} t_{2}\left[\left(v \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right) / x\right]\right)\right.\right.
\]

Since \(e \rightarrow^{*}\) val \(\notin\{\mathrm{BAD}, \mathrm{UNR}\}, e \rightarrow^{*} \lambda x . e^{\prime}\) and \(\left(e \underset{r_{2}}{{\underset{r}{1}}^{r_{2}}} x: t_{1} \rightarrow t_{2}\right) \rightarrow^{*}\) \(\lambda v .\left(\left(e\left(v \underset{r_{1}}{\left.\left.\stackrel{r_{2}}{\bowtie} t_{1}\right)\right)} \stackrel{r_{r_{2}}}{r_{1}} t_{2}\left[\left(v \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right) / x\right]\right)\right.\right.\).
We want to show that \(\forall \mathcal{C} . \mathcal{C} \llbracket e \rrbracket \rightarrow^{*} r \in R \Rightarrow \mathcal{C} \llbracket \lambda v .\left(\left(e\left(v \underset{r_{1}}{r_{2}} t_{1}\right)\right) \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{2}\left[\left(v \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}}\right.\right.\right.\) \(\left.\left.\left.t_{1}\right) / x\right] \rrbracket\right) \rightarrow^{*} r\). We prove it by induction on contexts. There are 3 cases to consider:
1. \(\mathcal{C}=\llbracket \bullet \rrbracket ;\)
2. \(\mathcal{C}=\mathcal{D}\) 【match - with alts \(\rrbracket\);
3. \(\mathcal{C}=\mathcal{D} \llbracket \bullet e_{3} \rrbracket\).

Case 1 and 2 are trivially true by inspecting the operational semantics of match. For Case 3, since we prove it by induction on the size of context, we have the following induction hypothesis:
\[
\forall \mathcal{D} \llbracket e \rrbracket \rightarrow^{*} r \Rightarrow \mathcal{D} \llbracket \bullet e_{3} \rrbracket \rightarrow^{*} r \quad[\mathrm{IH}]
\]

So all we need to prove is that for all \(e_{3}\),
\[
(\lambda v .(\left(e\left(v \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right)\right) \stackrel{r_{1}}{r_{2}} t_{2}[(v \stackrel{r_{2}}{\underbrace{}_{1}} t_{1}) / x])) e_{3} \ll R{ }_{R} e e_{3}
\]

By \(\beta\)-reduction, it means we want to show
\[
\begin{equation*}
\left(e\left(e_{3} \underset{r_{1}}{\stackrel{r_{2}}{\Perp}} t_{1}\right)\right) \underset{r_{2}}{\stackrel{r_{1}}{\Perp}} t_{2}\left[\left(e_{3} \underset{r_{1}}{\stackrel{r_{2}}{\bowtie}} t_{1}\right) / x\right]<_{R}\left(e e_{3}\right) \tag{*}
\end{equation*}
\]

By induction hypotheis where \(t=t_{2}\left[\left(e_{3} \underset{r_{1}}{\stackrel{r_{2}}{\otimes}} t_{1}\right) / x\right]\), we have
\[
\begin{equation*}
\left(e\left(e_{3} \underset{r_{1}}{\stackrel{r_{2}}{\diamond}} t_{1}\right)\right) \stackrel{r_{1}}{\stackrel{r_{2}}{\diamond}} t_{2}\left[\left(e _ { 3 } \underset { r _ { 1 } } { \stackrel { r _ { 2 } } { \diamond } t _ { 1 } ) / x ] \lll } \left(e \left(e_{3} \underset{r_{1}}{\left.\left.\stackrel{r_{2}}{\diamond} t_{1}\right)\right)}\right.\right.\right.\right. \tag{1}
\end{equation*}
\]

By induction hypothesis where \(t=t_{1}\), we have
\[
e_{3} \stackrel{r_{2}}{{\underset{r}{1}}^{\bowtie}} t_{1} \lll R e_{3}
\]

By Lemma 20 ( \({ }^{60}\) ( 0 gruence of \(<_{R}\) ), we have
\[
\begin{equation*}
e\left(e_{3} \underset{r_{1}}{\stackrel{r_{2}}{\propto}} t_{1}\right) \ll_{R} e e_{3} \tag{2}
\end{equation*}
\]

By (1) and (2) and Lemma \(21{ }^{60}\) (Transitivity of \(<_{R}\) ), we get \(\left(^{*}\right)\). By [IH], we have the desired result \(\forall \mathcal{C} . \mathcal{C} \llbracket e \rrbracket \rightarrow^{*} r \in R \Rightarrow \mathcal{C} \llbracket e_{r_{2}}^{r_{1}} x: t_{1} \rightarrow t_{2} \rrbracket \rightarrow^{*} r\).
- \(t\) is \(\left(x: t_{1}, t_{2}\right)\) : We have
\[
\begin{aligned}
& e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}}\left(t_{1}, t_{2}\right)=\operatorname{match} e \text { with } \\
& \left(x_{1}, x_{2}\right) \rightarrow\left(x_{1} \stackrel{r_{1}}{\stackrel{\bowtie}{r_{2}}} t_{1}, x_{2} \stackrel{r_{1}}{\stackrel{\bowtie}{r_{2}}} t_{2}\left[\left(x_{1} \stackrel{r_{2}}{\stackrel{\bowtie}{r_{1}}} t_{1}\right) / x\right]\right)
\end{aligned}
\]

If \(e \rightarrow^{*}\) val \(\notin\{\operatorname{BAD}, \mathrm{UNR}\}\), then \(e \rightarrow^{*}\left\{e_{1}, e_{2}\right\}\). By the induction hypotheses where \(t=t_{1}\) and \(t=t_{2}\) respectively, we know \(e_{1} \underset{r_{2}}{\aleph_{1}} t_{1}<_{R} e_{1}\) and \(e_{2} \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}} t_{2}<_{R} e_{2}\). Therefore, by Definition [6] \({ }^{[1]}\), we have \(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}}\left(t_{1}, t_{2}\right) \ll_{R} e\).
- \(t\) is Any: Since we have \(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}}\) Any \(=r_{2}\), we know \(e \underset{r_{2}}{\stackrel{r_{1}}{\bowtie}}\) Any \(\rightarrow^{*} r_{2}\). By Definition \(6^{\frac{14}{14}}\), we are done.

Lemma 20 (Congruence of Behaves-the-same). If \(e_{1} \ll R_{R} e_{2}\), then \(\forall \mathcal{C}, \mathcal{C} \llbracket e_{1} \rrbracket<_{R}\) \(\mathcal{C} \llbracket e_{2} \rrbracket\).

Proof. we have the following proof:
\[
\begin{array}{ll} 
& e_{1} \ll{ }_{R} e_{2} \\
\Longleftrightarrow & (\text { By definition (6) } \\
& \forall \mathcal{C}, \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} r \in R \Rightarrow \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} r \\
\Rightarrow \quad & (\text { Choose } \mathcal{C} \text { be } \mathcal{D} \llbracket \mathcal{C} \llbracket E \rrbracket \bullet \rrbracket) \\
& \forall \mathcal{D}, \forall \mathcal{E}, \mathcal{D} \llbracket \mathcal{E} \llbracket e_{2} \rrbracket \rrbracket \rightarrow^{*} r \in R \Rightarrow \mathcal{D} \llbracket \mathcal{E} \llbracket e_{1} \rrbracket \rrbracket \rightarrow^{*} r \\
\Longleftrightarrow & (\text { By definition } 6) \\
& \forall \mathcal{C}, \mathcal{C} \llbracket e_{1} \rrbracket<_{R} \mathcal{C} \llbracket e_{2} \rrbracket
\end{array}
\]

Note that we assume for all \(i=1,2\) :
\[
\vdash \mathcal{C} \llbracket e_{i} \rrbracket::(), \vdash \mathcal{D} \llbracket e_{i} \rrbracket::() \text { and } \vdash \mathcal{E} \llbracket e_{i} \rrbracket::()
\]

Lemma 21 (Transitivity of \(<_{R}\) ). If \(e_{1}<_{R} e_{2}\) and \(e_{2}<_{R} e_{3}\), then \(e_{1}<_{R} e_{3}\). Proof. By Definition \(6^{[1] 4}\), we have
\[
\text { (1) } \forall \mathcal{C} . \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} r \in R \Rightarrow \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} r
\]
(2) \(\forall \mathcal{C} . \mathcal{C} \llbracket e_{3} \rrbracket \rightarrow^{*} r \in R \Rightarrow \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} r\)

For all \(\mathcal{C}\), assuming \(\mathcal{C} \llbracket e_{3} \rrbracket \rightarrow^{*} r \in R\), we want to show \(\mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} r\). We have the following proof:
\[
\begin{array}{ll}
\forall \mathcal{C} . & \mathcal{C} \llbracket e_{3} \rrbracket \rightarrow^{*} r \in R \\
\Rightarrow & (\mathrm{By}(2)) \\
& \mathcal{C} \llbracket e_{2} \rrbracket \rightarrow^{*} r \in R \\
\Rightarrow & (\mathrm{By}(1)) \\
& \mathcal{C} \llbracket e_{1} \rrbracket \rightarrow^{*} r
\end{array}
\]

\section*{B Correctness of SL machine}

\section*{B. 1 Correctness of Logicization}

Theorem 11 (Logicization for axioms) Given a definition \(f=e^{\tau}\), the logical formula \(\forall f v(e), \exists f: \tau . \llbracket e \rrbracket_{f}\) is valid.
Proof. We prove it by structural induction on the size of the (possiblly open) expression \(e\). As UNR is for internal usage, we do not have UNR in \(e\).
- Case \(e\) is \(\mathrm{BAD}^{l}\). We have \(\llbracket \mathrm{BAD}^{l} \rrbracket_{f}=\) true, which is valid.
- Case \(e\) is \(x\). We have \(\exists f . f=x\). Let \(f\) be \(x\), we have \(x=x\), which is valid.
- Case \(e\) is \(n\). We have \(\exists f . f=n\). Let \(f\) be \(n\), we have \(n=n\), which is valid.
- Case \(e\) is \(e_{1}^{\tau} \oplus e_{2}^{\tau}\). It is semantically equivalent to let \(x_{1}=e_{1}\) in let \(x_{2}=\) \(e_{2}\) in \(x_{1} \oplus x_{2}\). From \(x_{1}=e_{1}\), by induction hypothesis, (1) \(\llbracket e_{1} \rrbracket_{x_{1}}\) is valid. From \(x_{2}=e_{1}\), by induction hypothesis, (2) \(\llbracket e_{2} \rrbracket_{x_{2}}\) is valid. Let the existentially quantified \(f\) be \(x_{1} \oplus x_{2}\), we have (3) \(x_{1} \oplus x_{2}=x_{1} \oplus x_{2}\). From (1), (2), (3), we know \(\exists f: \tau . \exists x_{1}: \llbracket \tau \rrbracket, \exists x_{2}: \llbracket \tau \rrbracket,\left(\llbracket e_{1} \rrbracket x_{x_{1}} \wedge \llbracket e_{2} \rrbracket x_{x_{2}} \wedge f=\right.\) \(\left.x_{1} \oplus x_{2}\right)\) is valid.
- Case \(e\) is \(e_{1}^{\tau} \odot e_{2}^{\tau}\). It is semantically equivalent to let \(x_{1}=e_{1}\) in let \(x_{2}=\) \(e_{2}\) in \(x_{1} \odot x_{2}\). From \(x_{1}=e_{1}\), by induction hypothesis, (1) \(\llbracket e_{1} \rrbracket_{x_{1}}\) is valid. From \(x_{2}=e_{1}\), by induction hypothesis, (2) \(\llbracket e_{2} \rrbracket_{x_{2}}\) is valid. If \(e_{1}^{\tau_{1}} \odot e_{2}^{\tau_{2}}\) evaluates to true, \(x_{1} \odot x_{2}\) is valid and \(\operatorname{not}\left(x_{1} \odot x_{2}\right)\) is invalid. So \(\exists f: \tau, \exists x_{1}: \llbracket \tau \rrbracket, \llbracket e_{1} \rrbracket_{x_{1}} \wedge \exists x_{2}: \llbracket \tau \rrbracket, \llbracket e_{2} \rrbracket_{x_{2}} \wedge\left(\left(x_{1} \odot x_{2} \wedge f=\right.\right.\) true \() \vee\) \(\left(\operatorname{not}\left(x_{1} \odot x 2\right) \wedge f=\right.\) false \(\left.)\right)\) deduces to \(\exists f: \tau, \exists x_{1}: \llbracket \tau_{1} \rrbracket\), \(\llbracket e_{1} \rrbracket x_{x_{1}} \wedge \exists x_{2}:\) \(\llbracket \tau_{2} \rrbracket, \llbracket e_{2} \rrbracket_{x_{2}} \wedge\left(x_{1} \odot x_{2} \wedge f=\right.\) true \()\). Let the existentially quantified \(f\) be true. From (1), (2) and true \(=\) true, we know \(\llbracket e_{1}^{\tau} \odot e_{2}^{\tau} \rrbracket_{f}\) is valid. If \(e_{1}^{\tau_{1}} \odot e_{2}^{\tau_{2}}\) evaluates to false, we apply the similar reasoning as above with the exitentially quantified \(f\) being false.
- Case \(e\) is \(\lambda x^{\tau_{1}} . e_{2}^{\tau_{2}}\). We have \(\exists f: \tau_{1} \rightarrow \tau_{2}, \forall x: \llbracket \tau \rrbracket\), \(\llbracket e \rrbracket_{(\operatorname{apply}(f, x))}\). Let the existentially quantified \(f\) be \(\lambda x . e_{2}\).
- Case \(e\) is let \(x^{\tau_{1}}=e_{1}\) in \(e_{2}^{\tau_{2}}\). It is semantically equivalent to let \(x^{\tau_{1}}=\) \(e_{1}\) in let \(x_{2}^{\tau_{2}}=e_{2}\) in \(x_{2}\). We have \(\llbracket\) let \(x^{\tau_{1}}=e_{1}\) in let \(x_{2}^{\tau_{2}}=\) \(e_{2}\) in \(x_{2} \rrbracket_{f}=\exists x: \llbracket \tau \rrbracket, \llbracket e_{1} \rrbracket_{x} \wedge \exists x_{2}: \llbracket \tau \rrbracket, \llbracket e_{2} \rrbracket_{x_{2}} \wedge f=x_{2}\). From definitions \(x^{\tau}=e_{1}\) and \(x_{2}^{\tau_{2}}=e_{2}\), by induction hypothesis, (1) \(\exists x: \tau_{1}, \llbracket e_{1} \rrbracket_{x}\) is valid and (2) \(\exists x_{2}: \tau_{2}, \llbracket e_{2} \rrbracket_{x_{2}}\) is valid. Let \(x_{2}\) be \(f\). From (1), (2) and \(f=f\), we know \(\exists f: \tau_{2}, \exists x: \llbracket \tau \rrbracket, \llbracket e_{1} \rrbracket_{x} \wedge \exists x_{2}: \llbracket \tau \rrbracket, \llbracket e_{2} \rrbracket_{x_{2}} \wedge f=x_{2}\) is valid.
- Case \(e\) is \(\left(e_{1}^{\tau_{1}} e_{2}^{\tau_{2}}\right)\). It is semantically equivalent to let \(x_{1}=e_{1}\) in let \(x_{2}=\) \(e_{2}\) in \(x_{1} x_{2}\). We have 【let \(x_{1}=e_{1}\) in let \(x_{2}=e_{2}\) in \(x_{1} x_{2} \rrbracket_{f}=\) \(\exists x_{1}: \tau_{1}, \llbracket e_{1} \rrbracket_{x_{1}} \wedge \exists x_{2}: \tau_{2}, \llbracket e_{2} \rrbracket_{x_{2}} \wedge f=\operatorname{apply}\left(x_{1}, x_{2}\right)\). From definitions \(x_{1}=e_{1}\) and \(x_{2}=e_{2}\), by induction hypothesis, (1) \(\exists x_{1}: \tau_{1}, \llbracket e_{1} \rrbracket_{x_{1}}\) is valid and (2) \(\exists x_{2}: \tau_{2}, \llbracket e_{2} \rrbracket_{x_{2}}\) is valid. Let the existentially quantified \(f\) be \(\operatorname{apply}\left(x_{1}, x_{2}\right)\). From (1), (2) and \(\operatorname{apply}\left(x_{1}, x_{2}\right)=\operatorname{apply}\left(x_{1}, x_{2}\right)\), we know \(\exists x_{1}: \tau_{1}, \llbracket e_{1} \rrbracket_{x_{1}} \wedge \exists x_{2}: \tau_{2}, \llbracket e_{2} \rrbracket_{x_{2}} \wedge f=\operatorname{apply}\left(x_{1}, x_{2}\right)\) is valid.
- Case \(e\) is \(K^{\tau} e_{1}^{\tau_{1}} \ldots e_{n}^{\tau_{n}}\). It is semantically equivalent to let \(x_{1}=e_{1}\) in... let \(x_{n}=e_{n}\) in \(K x_{1} \ldots x_{n}\). We have \(\llbracket\) let \(x_{1}=e_{1}\) in...let \(x_{n}=\) \(e_{n}\) in \(K x_{1} \ldots x_{n} \rrbracket_{f}=\exists x_{1}: \tau_{1}, \llbracket e_{1} \rrbracket_{x_{1}} \wedge \cdots \wedge \exists x_{1}: \tau_{1}, \llbracket e_{1} \rrbracket_{x_{1}} \wedge f=\) \(K\left(x_{1}, \ldots, x_{n}\right)\). From definitions \(x_{i}=e_{i}\) for \(1 \leq i \leq n\), by induction hypothesis, we know (i) \(\exists x_{i} \cdot \llbracket e_{i} \rrbracket_{x_{i}}\) is valid. Let \(f\) be \(K\left(x_{1}, \ldots, x_{n}\right)\). From (i) and \(K\left(x_{1}, \ldots, x_{n}\right)=K\left(x_{1}, \ldots, x_{n}\right)\), we know \(\exists f: \tau, \exists x_{1}\) : \(\tau_{1}, \llbracket e_{1} \rrbracket_{x_{1}} \wedge \cdots \wedge \exists x_{1}: \tau_{1}, \llbracket e_{1} \rrbracket_{x_{1}} \wedge f=K\left(x_{1}, \ldots, x_{n}\right)\) is valid.
- Case \(e\) is match \(e_{0}^{\tau_{0}}\) with \(\overrightarrow{K \overrightarrow{x^{\tau_{x}}} \rightarrow e^{\tau}}\). It is semantically equivalent to let \(x_{0}^{\tau_{0}}=e_{0}\) in match \(x_{0}\) with \(\overrightarrow{K \overrightarrow{x^{\tau_{x}}} \rightarrow \text { let } y=e \text { in } y}\). We have \(\llbracket\) let \(x_{0}^{\tau_{0}}=\) \(e_{0}\) in match \(x_{0}\) with \(\overrightarrow{K \overrightarrow{x^{\tau_{x}}}} \rightarrow\) let \(y=e\) in \(y \rrbracket_{f}=\exists x_{0}: \tau_{0}, \llbracket e_{0} \rrbracket_{x_{0}} \wedge\)
\[
\begin{aligned}
& \left(\bigwedge \overrightarrow{\forall x: \llbracket \tau \rrbracket},\left(x_{0}=K \vec{x}\right) \Rightarrow \exists y: \tau, \llbracket e \rrbracket_{y} \wedge f=y\right) \text {. From definitions } x_{0}=e_{0} \\
& \text { and } y=e, \text { by induction hypothesis, (1) } \exists x_{0}: \tau_{0}, \llbracket e_{0} \rrbracket_{x_{0}} \text { is valid and (2) } \\
& \exists y: \tau, \llbracket e \rrbracket_{y} \text { is valid. Let } y \text { be } f \text {. From (2) and } f=f, \text { the RHS of } \\
& \Rightarrow \text { in the logical formula is valid. Together with }(1) \text {, we know } \exists x_{0} \text { : } \\
& \left.\tau_{0}, \llbracket e_{0} \rrbracket_{x_{0}} \wedge\left(\bigwedge \forall \overrightarrow{x: \llbracket \tau \rrbracket,\left(x_{0}=K\right.} \vec{x}\right) \Rightarrow \exists y: \tau, \llbracket e \rrbracket_{y} \wedge f=y\right) \text { is valid. }
\end{aligned}
\]

Theorem 12 (Logicization for goals: validity preservation) For all (possibly open) expression \(e^{\tau}\), if \(\exists f: \tau, \llbracket e \rrbracket_{f}\) is valid and \(e \rightarrow e^{\prime}\) for some \(e^{\prime}\), then \(\llbracket e^{\prime} \rrbracket_{f}\) is valid.

Proof. We prove it by structural induction on the size of \(e\). The lemma holds vacuriously for expressions BAD, UNR, \(x, n, e_{1} \oplus e_{2}\). We focus on two cases where a redex occurs. The rest of the cases can be proved easily by applying induction hypotheses.
- Case \(e\) is \(\left(\lambda x^{\tau} . e_{1}\right) e_{2}\). We have
\[
\begin{aligned}
& \llbracket\left(\lambda x^{\tau} . e_{1}\right)^{\tau_{1}} e_{2}^{\tau_{2}} \rrbracket_{f} \text { is valid } \\
& \Longleftrightarrow \quad\left(\text { By definition of } \llbracket \cdot \rrbracket_{f}\right) \\
& \exists x_{1}: \llbracket \tau_{1} \rrbracket, \llbracket\left(\lambda x^{\tau} . e_{1}\right) \rrbracket_{x_{1}} \wedge \exists x_{2}: \llbracket \tau_{2} \rrbracket, \llbracket e_{2} \rrbracket x_{x_{2}} \wedge \\
& f=\operatorname{apply}\left(x_{1}, x_{2}\right) \text { is valid } \\
& \Longleftrightarrow \quad \text { (By definition of } \llbracket . \rrbracket_{x_{1}} \text { ) } \\
& \exists x_{1}: \llbracket \tau_{1} \rrbracket, \forall x^{\tau}, \llbracket e_{1} \rrbracket_{\left(\operatorname{apply}\left(x_{1}, x\right)\right)} \wedge \exists x_{2}: \llbracket \tau_{2} \rrbracket, \llbracket e_{2} \rrbracket_{x_{2}} \wedge \\
& f=\operatorname{apply}\left(x_{1}, x_{2}\right) \text { is valid } \\
& \Longleftrightarrow \quad \text { (By Logic: } P \wedge \exists x, Q(x) \Longleftrightarrow \exists x, P \wedge Q(x) \text { where } x \text { is not in } P \text { ) } \\
& \exists x_{1}: \llbracket \tau_{1} \rrbracket, \exists x_{2}: \llbracket \tau_{2} \rrbracket, \forall x^{\tau}, \llbracket e_{1} \rrbracket\left(\operatorname{apply}\left(x_{1}, x\right)\right) \wedge \llbracket e_{2} \rrbracket_{x_{2}} \wedge \\
& f=\operatorname{apply}\left(x_{1}, x_{2}\right) \text { is valid } \\
& \Rightarrow \quad\left(\text { Let } x \text { be } x_{2}\right) \\
& \exists x_{1}: \llbracket \tau_{1} \rrbracket, \exists x_{2}: \llbracket \tau_{2} \rrbracket, \llbracket e_{1} \rrbracket_{\left(\operatorname{apply}\left(x_{1}, x_{2}\right)\right)}\left[x_{2} / x \rrbracket \wedge \llbracket e_{2} \rrbracket_{x_{2}} \wedge\right. \\
& f=\operatorname{apply}\left(x_{1}, x_{2}\right) \text { is valid } \\
& \Longleftrightarrow \quad\left(\text { Since } f=\operatorname{apply}\left(x_{1}, x_{2}\right) \text {, replace } \operatorname{apply}\left(x_{1}, x_{2}\right) \text { by } f\right) \\
& \exists x_{1}: \llbracket \tau_{1} \rrbracket, \exists x_{2}: \llbracket \tau_{2} \rrbracket, \llbracket e_{1} \rrbracket_{f}\left[x_{2} / x\right\rceil \wedge \llbracket e_{2} \rrbracket x_{2} \text { is valid } \\
& \left.\Longleftrightarrow \quad \text { (Rename } x_{2} \text { to } x\right) \\
& \exists x_{1}: \llbracket \tau_{1} \rrbracket, \exists x: \llbracket \tau_{2} \rrbracket, \llbracket e_{1} \rrbracket_{f} \wedge \llbracket e_{2} \rrbracket_{x} \text { is valid } \\
& \Longleftrightarrow \quad \text { (By Logic: } \exists x, P \Longleftrightarrow P \text { where } x \text { is not in } P \text { ) } \\
& \exists x: \llbracket \tau_{2} \rrbracket, \llbracket e_{1} \rrbracket_{f} \wedge \llbracket e_{2} \rrbracket_{x} \text { is valid } \\
& \Longleftrightarrow \quad\left(\text { By definition of } \llbracket . \rrbracket_{f}\right) \\
& \llbracket \text { let } x=e_{2} \text { in } e_{1} \rrbracket_{f} \text { is valid } \\
& \Longleftrightarrow \quad\left(\text { let } x=e_{2} \text { in } e_{1} \text { is semantically equivalent to } e_{1}\left[e_{2} / x\right]\right) \\
& \llbracket e_{1}\left[e_{2} / x\right] \rrbracket_{f} \text { is valid }
\end{aligned}
\]
- Case \(e\) is match \(K \overrightarrow{a_{i}}\) with \(\overrightarrow{K \overrightarrow{x^{7}} \rightarrow e_{i}}\). We have
\[
\begin{aligned}
& \llbracket \operatorname{match}(K \overrightarrow{v a l})^{\tau_{0}} \text { with } \overrightarrow{K \vec{x} \rightarrow e_{i}} \rrbracket_{f} \text { is valid } \\
& \Longleftrightarrow \quad\left(\text { By definition of } \llbracket \cdot \rrbracket_{f}\right) \\
& \exists x_{0}: \llbracket \tau_{0} \rrbracket, \llbracket K \overrightarrow{v a l} \rrbracket_{x_{0}} \wedge\left(\bigwedge \overrightarrow{\forall x: \llbracket \tau \rrbracket},\left(x_{0}=K \vec{x}\right) \Rightarrow \llbracket e_{i} \rrbracket_{f}\right) \text { is valid } \\
& \Longleftrightarrow \quad\left(\text { By definition of } \llbracket \cdot \rrbracket_{x_{0}}\right) \\
& \exists x_{0}: \llbracket \tau_{0} \rrbracket, \exists \overrightarrow{y: \llbracket \tau \rrbracket}, \llbracket v a l \rrbracket_{y} \wedge x_{0}=K \vec{y} \wedge \\
& \left(\bigwedge \forall \overrightarrow{x: \llbracket \tau \rrbracket},\left(x_{0}=K \vec{x}\right) \Rightarrow \llbracket e_{i} \rrbracket_{f}\right) \text { is valid } \\
& \Rightarrow \quad(\text { Let } \vec{x} \text { be } \vec{y}) \\
& \left.\begin{array}{l}
\exists x_{0}: \llbracket \tau_{0} \rrbracket, \overrightarrow{\exists y: \llbracket \tau \rrbracket, \llbracket v a l \rrbracket_{y}} \wedge x_{0}=K \vec{y} \wedge \\
\left(\bigwedge\left(x_{0}=K \vec{y}\right) \Rightarrow \llbracket e_{i} \rrbracket_{f}[\overrightarrow{y / x}]\right.
\end{array}\right) \text { is valid } \\
& \Longleftrightarrow \quad(\text { By Logic: } P \wedge(P \Rightarrow Q) \wedge(\neg P \Rightarrow R) \Longleftrightarrow P \wedge Q) \\
& \exists x_{0}: \llbracket \tau_{0} \rrbracket, \overrightarrow{\exists>: \llbracket \tau \rrbracket}, \llbracket v a l \rrbracket_{y} \wedge x_{0}=K \vec{y} \wedge \llbracket e_{i} \rrbracket_{f}[\overrightarrow{y / x}] \text { is valid } \\
& \Rightarrow \quad \xrightarrow{(\text { By Logic: } \exists x, \exists y, P(y) \wedge P(x, y) \Longleftrightarrow \exists y, P(y) \wedge \exists x, P(x, y)), ~} \\
& \exists \overrightarrow{y: \llbracket \tau \rrbracket}, \llbracket v a l \rrbracket_{y} \wedge \exists x_{0}: \llbracket \tau_{0} \rrbracket, x_{0}=K \vec{y} \wedge \llbracket e_{i} \rrbracket_{f}[\overrightarrow{y / x}] \text { is valid } \\
& \left.\Longleftrightarrow \quad \xrightarrow{\left(\text { Let } x_{0} \text { be } K\right.} \vec{y} \text {. By Logic: true } \wedge P \Longleftrightarrow P\right) \\
& \exists \overrightarrow{y: \llbracket \tau \rrbracket}, \llbracket v a l \rrbracket_{y} \wedge \llbracket e_{i} \rrbracket_{f}[\overrightarrow{y / x}] \text { is valid } \\
& \Longleftrightarrow \xrightarrow{\exists \overrightarrow{x: \llbracket \tau \rrbracket}, \llbracket v a l \rrbracket_{x}} \wedge \llbracket e_{i} \rrbracket_{f} \text { is valid } \\
& \Longleftrightarrow \quad\left(\text { By definition of } \llbracket \cdot \rrbracket_{f}\right) \\
& \llbracket \text { let } \overrightarrow{x=v a l} \text { in } e_{i} \rrbracket_{f} \\
& \Longleftrightarrow \quad\left(\operatorname{let} \overrightarrow{x=v a l} \text { in } e_{i} \text { is semantically equivalent to } e_{i}[\overrightarrow{v a l / x}]\right) \\
& \llbracket e_{i}\left[\overrightarrow{\mathrm{val} / \mathrm{x}} \rrbracket_{f}\right. \text { is valid }
\end{aligned}
\]

\section*{B. 2 Transition rules}

The SL machine does not inline top-level functions. We do not have local let rec in our language and we only inline trivial values. Moreover, we set a stop-bound for the SMT solver Alt-ergo with an option "-stop \(<\mathrm{n}>\) " (which restrict the total amount of time) or "-steps \(\langle\mathrm{n}>\) " (which restrict the total number of steps) so that the SMT solver always terminates. Thus, there is no element in the SL machine causing non-termination.

Theorem 8 (SL machine terminates) For all \(\mathcal{H}, e, \mathcal{S}, \mathcal{L}\), there exists an expression \(a\) such that \(\langle\mathcal{H}\|e \mid S\|\)
\(\lg c\rangle \rightsquigarrow^{*} a\).
Proof. The rebuilding rules either lead to the end state ([R-done]) or reduce the number of stack frames ([R-r], [R-lam], [R-beta], [R-app], [R-K], [R-K-match], [R-s-match], [R-s-save]) or reduce the size of the stack frame on top of the stack ([R-fun]. [R-match], [R-let-save]).

The simplification rules either lead directly to a rebuild rule ([R-const], [Rexn], [R-var1], [R-var2]) or lead to a simplification rule that reduces the size of the expression under simplification ([S-lam], [S-app], [S-match], [S-K]) or lead to a simplification rule that reduces the size of the stack ([S-letL], [S-matchL], [S-letR], [S-matchR], [S-match-match], [S-match-let]).

For the cases that corresponding to simplification rules in Figure 11, we use the fact: [EqFact] \(e_{1} \equiv_{s} e_{2}\) if \(\exists e_{3}, e_{1} \rightarrow^{*} e_{3}\) and \(e_{2} \rightarrow^{*} e_{3}\). Moreover, if any of the subexpression is an exception \(r\), it is easy to show that both sides evaluate to the same \(r\). So we only consider the case that none of the subexpression is an exception \(r\).

Theorem 9 (Correctness of SL machine) For all closed expression \(e\), if \(\langle\emptyset \mid e\|[]\|\rangle \rightsquigarrow^{*} a\), then \(e \equiv_{s} a\).

Proof. We prove it by induction on the number of transition steps. We have the following induction hypothesis: for all \(\mathcal{H}, e, \mathcal{S}, \mathcal{L}\), there exists \(\mathcal{H}_{2}, e_{2}, \mathcal{S}_{2}, \mathcal{L}_{2}\), such that \(\langle\mathcal{H}\|e\| \mathcal{S} \mid \mathcal{L}\rangle \rightsquigarrow\left\langle\mathcal{H}_{2}\left\|e_{2}\right\| \mathcal{S}_{2} \mid \mathcal{L}_{2}\right\rangle\) or \(\langle\mathcal{H}\|e\| \mathcal{S} \mid \mathcal{L}\rangle \rightsquigarrow\left\langle\left\langle\mathcal{H}_{2} \mid e_{2}\left\|\mathcal{S}_{2}\right\| \mathcal{L}_{2}\right\rangle\right\rangle\),
\[
\left\langle\mathcal{H}_{2}\left\|e_{2}\right\| \mathcal{S} \mid \mathcal{L}_{2}\right\rangle \rightsquigarrow^{*} a \wedge e_{2} \equiv_{s} a \quad[\mathrm{IH}]
\]

By Lemma \(22{ }^{[68]}\) (Correctness of rebuilding), we know
\[
\left\langle\left\langle\mathcal{H}_{2} \mid e_{2}\left\|\mathcal{S}_{2}\right\| \mathcal{L}_{2}\right\rangle\right\rangle \rightsquigarrow^{*} a \wedge e_{2} \equiv_{s} a \quad[\mathrm{RB}]
\]

For cases [S-const], [S-exn], [S-var1] [S-var2], by induction hybothesis, we get the desired result. We now focus on slightly non-obvious transitions.
- Case [S-lam]. We first have:
\[
\begin{array}{ll} 
& \left\langle\mathcal{H} \mid \lambda x^{\tau} . e\|[]\| \emptyset\right\rangle \\
\rightsquigarrow \quad & (\mathrm{By}[\mathrm{~S}-\mathrm{lam}]) \\
& \langle\mathcal{H}\|e\|(\lambda x . \bullet)::[] \mid \forall x: \tau\rangle \\
\rightsquigarrow^{*} \quad\left(\mathrm{By}[\mathrm{IH}],\langle\mathcal{H}\|e\|(\lambda x . \bullet):: S \| \mathcal{L}, \forall x: \tau\rangle \rightsquigarrow^{*} a \wedge e \equiv_{s} a\right) \\
& \langle\langle\mathcal{H}\|a|(\lambda x \cdot \bullet)::[] \| \forall x: \tau\rangle\rangle \\
\rightsquigarrow \quad & (\mathrm{By}[\mathrm{R}-\mathrm{lam}]) \\
& \langle\langle\mathcal{H}\|\lambda x . a\|[] \| \forall x: \tau\rangle\rangle \\
\rightsquigarrow \quad & (\mathrm{By}[\mathrm{R} \text {-done]) } \\
& \lambda x . a
\end{array}
\]

We now have:
\[
\begin{array}{ll} 
& e \equiv_{s} a \\
\Longleftrightarrow & \left.(\text { By Definition }]^{\boxed{10}} \equiv{ }_{s}\right) \\
& \forall \mathcal{C}, r, \mathcal{C} \llbracket e \rrbracket \rightarrow^{*} r \Longleftrightarrow \mathcal{C} \llbracket a \rrbracket \rightarrow^{*} r \\
\Longleftrightarrow & (\mathcal{C}=\mathcal{D} \llbracket \lambda x \cdot \bullet \rrbracket) \\
& \forall \mathcal{D}, r, \mathcal{D} \llbracket \lambda x . e \rrbracket \rightarrow^{*} r \Longleftrightarrow \mathcal{D} \llbracket \lambda x . a \rrbracket \rightarrow^{*} r \\
\Longleftrightarrow & \left(\text { By Definition } \prod^{\llbracket 1} \equiv_{s}\right) \\
& \lambda x . e \equiv_{s} \lambda x . a
\end{array}
\]
- Case [S-app]. If \(e_{1}\) is \(r\), it is easy. By [S-app] and [R-r-fun], we get \(\left\langle\mathcal{H}\left\|r e_{2}\right\|[] \| \emptyset\right\rangle \rightsquigarrow^{*} r\), which is semantically equivalent to \(r e_{2}\). We now consider the case where \(e_{1}\) is not \(r\). We have:
```

                \(\left\langle\mathcal{H}\left\|e_{1} e_{2}\right\|[] \mid \emptyset\right\rangle\)
    $\rightsquigarrow \quad(\mathrm{By}[\mathrm{S}-\mathrm{app}])$
$\left\langle\mathcal{H}\left\|e_{1}\right\|\left(\bullet e_{2}\right)::[] \| \emptyset\right\rangle$
$\rightsquigarrow^{*} \quad\left(\operatorname{By}[\mathrm{IH}],\left\langle\mathcal{H} \mid e_{1}\left\|\left(\bullet e_{2}\right)::[]\right\| \emptyset\right\rangle{ }^{*} a_{1} \wedge e_{1} \equiv_{s} a_{1}\right)$
$\left\langle\left\langle\mathcal{H}\left\|a_{1}\right\|\left(\bullet e_{2}\right)::[] \| \emptyset\right\rangle\right\rangle$
$\rightsquigarrow \quad(\mathrm{By}[\mathrm{R}-\mathrm{fun}])$
$\left\langle\mathcal{H}\left\|e_{2}\right\|\left(a_{1} \bullet\right)::[] \| \emptyset\right\rangle$
$\rightsquigarrow^{*}\left(\mathrm{By}[\mathrm{IH}],\left\langle\mathcal{H} \mid e_{2}\left\|\left(a_{1} \bullet\right)::[]\right\|\right\rangle \rightsquigarrow a_{2} \wedge e_{2} \equiv_{s} a_{2}\right)$
$\left\langle\left\langle\mathcal{H}\left\|a_{2}\right\|\left(a_{1} \bullet\right)::[] \| \emptyset\right\rangle\right\rangle$
$\leadsto \quad(\mathrm{By}[\mathrm{R}-\mathrm{app}])$
$\left.\left\langle\langle\mathcal{H}| a_{1} a_{2}\right|[]|\emptyset\rangle\right\rangle$
$\leadsto \quad(\mathrm{By}[\mathrm{R}$-done] $)$
$a_{1} a_{2}$

```

Given \(e_{1} \equiv_{s} a_{1}\) and \(e_{2} \equiv_{s} a_{2}\), by congruence of \(\equiv_{s}\), we know \(e_{1} e_{2} \equiv_{s} a_{1} a_{2}\).
- Case [S-match].
```

            \(\langle\mathcal{H}|\) match \(e_{0}\) with alts \(\left.\|[]\|\right\rangle\)
    $\rightsquigarrow \quad($ By $[\mathrm{S}-\mathrm{match}])$
$\langle\mathcal{H}| e_{0} \|($ match • with alts) :: []\| $\|\rangle$
$\rightsquigarrow^{*}\left(\mathrm{By}[\mathrm{IH}],\left\langle\mathcal{H}\left\|e_{0}\right\|(\right.\right.$ match $\bullet$ with alts $\left.\left.)::[] \mid \emptyset\right\rangle \rightsquigarrow^{*} a_{0} \wedge e_{0} \equiv_{s} a_{0}\right)$
(†) $\left\langle\left\langle\mathcal{H}\left\|a_{0}\right\|(\right.\right.$ match • with alts) :: [] \| Ø $\left.\rangle\right\rangle$

```

There are two subcases: either [R-s-match] or [R-s-save] is applied. Let alts be \(\overrightarrow{K \overrightarrow{x^{7}} \rightarrow e_{i}}\).
- there exists a branch \(\left(K \overrightarrow{x^{7}}\right)\) such that \(\left.\mathcal{L} \Rightarrow\left(\exists \overrightarrow{x: \llbracket \tau \rrbracket}, \llbracket a_{0} \rrbracket_{(K} \vec{x}\right)\right)\). We continue from ( \(\dagger\) ):
\[
\begin{aligned}
& \left.\left\langle\left\langle\mathcal{H} \| a_{0}\right|\left(\text { match • with } \overrightarrow{K \overrightarrow{x^{f}} \rightarrow e_{i}}\right)::[] \mid \emptyset\right\rangle\right\rangle \\
& \leadsto \quad(\mathrm{By}[\mathrm{R}-\mathrm{s}-\mathrm{match}]) \\
& \left\langle\mathcal{H} \mid e_{i}\|[]\| \exists \overrightarrow{x^{7}}, \llbracket a_{0} \rrbracket_{K} \overrightarrow{\vec{x}^{\prime}}\right\rangle \\
& \left.\left.\rightsquigarrow^{*} \quad\left(\mathrm{By}[\mathrm{IH}],\left\langle\mathcal{H}\left\|e_{i}\right\|[]\right| \exists \overrightarrow{x^{7}}, \llbracket a_{0} \rrbracket_{(K} \vec{x}\right)\right\rangle \rightsquigarrow^{*} a_{i} \wedge e_{i} \equiv_{s} a_{i}\right) \\
& \left.\left\langle\left\langle\mathcal{H}\left\|a_{i}\right\|[] \| \exists \overrightarrow{x^{7}}, \llbracket a_{0} \rrbracket_{(K} \vec{x}\right)\right\rangle\right\rangle \\
& \rightsquigarrow \quad(\mathrm{By}[\mathrm{R} \text {-done }]) \\
& a_{i}
\end{aligned}
\]

Given \(\left.\mathcal{L} \Rightarrow\left(\exists \overrightarrow{x: \llbracket \tau \rrbracket}, \llbracket a_{0} \rrbracket_{(K} \vec{x}\right)\right)\), by Theorem \(\mathbb{1 2}^{[36]}\), we know \(a_{0} \equiv_{s}\) \(K \overrightarrow{x^{f}}\) for some \(\overrightarrow{x^{f}}\). Together with \(e_{0} \equiv_{s} a_{0}\) and \(e_{i} \equiv_{s} a_{i}\), by congruence of \(\equiv_{s}\), we have match \(e_{0}\) with \(\overrightarrow{K \overrightarrow{x^{7}} \rightarrow e_{i}} \equiv_{s} a_{i}\).
- there is no branch \((K \vec{x})\) such that \(\left.\mathcal{L} \Rightarrow \llbracket a_{0} \rrbracket_{(K} \vec{x}\right)\).

We continue from ( \(\dagger\) ):
\[
\begin{aligned}
& \left.\left\langle\langle\mathcal{H}| a_{0} \|\left(\text { match • with } \overrightarrow{K \overrightarrow{x^{7}} \rightarrow e_{i}}\right)::[] \mid \emptyset\right\rangle\right\rangle \\
& \rightsquigarrow \quad \text { (By [R-s-save]) } \\
& \begin{array}{l}
\left\langle\mathcal{H}\left\|e_{i}\right\|\left(\text { match } a \text { with } K \overrightarrow{x^{f}} \rightarrow(\bullet, \mathcal{S}, \mathcal{L})\right)::[] \| \begin{array}{c}
\mathcal{L}, \exists \overrightarrow{x: \llbracket \tau \rrbracket} \\
\llbracket a \rrbracket(K \vec{x})
\end{array}\right\rangle
\end{array} \\
& \rightarrow(\bullet, \mathcal{S}, \mathcal{L}))::[] \\
& \left.\wedge e_{i} \equiv_{s} a_{i}\right) \\
& \xrightarrow[{\langle\mathcal{H}| a_{i} \|\left(\text { match } a \text { with } K \overrightarrow{x^{f}} \rightarrow(\bullet, \mathcal{S}, \mathcal{L})\right)::[] \| \underset{~}{\left.\mathbb{L}, \exists \overrightarrow{x: \llbracket \tau \rrbracket} \rrbracket_{(K} \vec{x}\right)}}]{ } \\
& \rightsquigarrow \quad(\mathrm{By}[\mathrm{R}-\text { match] }) \\
& \left\langle\langle\mathcal{H}| \text { match } a_{0} \text { with } \overrightarrow{K \vec{x} \rightarrow a_{i}}\|[]\| \mathcal{L}, \exists \overrightarrow{x: \llbracket \tau \rrbracket}, \llbracket a \rrbracket_{(K \quad \vec{x})\rangle}\right\rangle \\
& \rightsquigarrow \quad(B y[R-d o n e]) \\
& \text { match } a_{0} \text { with } \overrightarrow{K \vec{x} \rightarrow a_{i}}
\end{aligned}
\]

From \(e_{0} \equiv_{s} a_{0}\) and \(e_{i} \equiv_{s} a_{i}\), by congruence of \(\equiv_{s}\), we have match \(e_{0}\) with \(\overrightarrow{K \vec{x} \rightarrow e_{i}} \equiv_{s}\) match \(a_{0}\) with \(\overrightarrow{K \vec{x} \rightarrow a_{i}}\).
- Case [S-K]. The proof is similar to the case [S-app]. Simplification of each component \(e_{i}\) to \(a_{i}\) is semantically preserving. After applying induction hypothesis, we apply [R-K]. Given \(e_{i} \equiv_{s} a_{i}\), by congruence of \(\equiv_{s}\), \(K e_{1} \ldots e_{n} \equiv_{s} K a_{1} \ldots a_{n}\).
- Case [S-letL]. We want to show that (let \(x=e_{1}\) in \(\left.e_{2}\right) e \equiv_{s}\) let \(x=\) \(e_{1}\) in \(e_{2} e\). We have:
\[
\begin{aligned}
& \left(\text { let } x=e_{1} \text { in } e_{2}\right) e \\
\rightarrow & \left(\text { let } x=\text { val }_{1} \text { in } e_{2}\right) e \\
\rightarrow & e_{2}\left[\text { val }_{1} / x\right] e \\
\rightarrow & \left(\lambda y \cdot a\left[\text { val }_{1} / x\right]\right) e \\
\rightarrow & \left(\lambda y \cdot a\left[v a l_{1} / x\right]\right) \text { val } \\
\rightarrow & a\left[\text { val }_{1} / x, \text { val } / y\right]
\end{aligned}
\]
and
\[
\begin{array}{ll} 
& \text { let } x=e_{1} \text { in } e_{2} e \\
\rightarrow^{*} & \text { let } x=\text { val }_{1} \text { in } e_{2} e \\
\rightarrow & \left(e_{2} e\right)\left[\text { val }_{1} / x\right] \\
\rightarrow & ((\lambda y \cdot a) e)\left[v a l_{1} / x\right] \\
\rightarrow^{*} & ((\lambda y \cdot a) \mathrm{val})^{2}\left[v a l_{1} / x\right] \\
\rightarrow^{*} & a\left[\mathrm{val}^{2} / y, \mathrm{val}_{1} / x\right] \\
= & a\left[\mathrm{val}_{1} / x, v a l / y\right]
\end{array}
\]

By [EqFact], we are done.
- Case [S-matchL]. We want to show that if \(f v(e) \cap \vec{x}=\emptyset\), then (match \(e_{0}\) with \(\left.\overrightarrow{K \vec{x} \rightarrow e_{i}}\right) e \equiv_{s}\) match \(e_{0}\) with \(\overrightarrow{K \vec{x} \rightarrow\left(e_{i} e\right)}\). We have:
\[
\begin{aligned}
& \left(\text { match } e_{0} \text { with } \overrightarrow{K \vec{x} \rightarrow e_{i}}\right) e \\
\rightarrow^{*} & \left(\text { match } K \overrightarrow{v a l_{x}} \text { with } \overrightarrow{K \vec{x} \rightarrow e_{i}}\right) e \\
\rightarrow & e_{i}\left[\overrightarrow{v a l_{x} / x}\right] e \\
\rightarrow & \left(\lambda y \cdot e_{2}\left[\overrightarrow{v a l_{x} / x}\right]\right) e \\
\rightarrow^{*} & \left(\lambda y \cdot e_{2}\left[\operatorname{val}_{x} / x\right]\right) \mathrm{val} \\
\rightarrow & e_{2}\left[\overrightarrow{v a l_{x} / x}, v a l / y\right]
\end{aligned}
\]
and
\[
\begin{aligned}
& \text { match } e_{0} \text { with } \vec{K} \vec{x} \rightarrow\left(e_{i} e\right) \\
\rightarrow & \\
\rightarrow & \text { match } K \overrightarrow{v a l_{x}} \text { with } \overrightarrow{K \vec{x} \rightarrow\left(e_{i} e\right)} \\
\rightarrow & \left(e_{i} e\right)\left[\overrightarrow{v a l_{x} / x}\right] \\
\rightarrow^{*} & \left(\lambda y \cdot e_{2} e\right)\left[\overrightarrow{v a l_{x / x}}\right] \\
\rightarrow^{*} & \left(\lambda y \cdot e_{2} \text { val }\right)\left[\overrightarrow{v a l_{x} / x}\right] \\
\rightarrow^{*} & e_{2}\left[\mathrm{val}_{x} / x, v a l / y\right]
\end{aligned}
\]

By [EqFact], we are done.
- Case [S-letR]. We want to show that if \(x \notin f v(e)\), then \(\lambda y\).e (let \(x=\) \(e_{1}\) in \(\left.e_{2}\right) \equiv_{s}\) let \(x=e_{1}\) in \(\lambda\).e \(e_{2}\). We have:
\[
\begin{array}{ll} 
& \lambda y \cdot e\left(\text { let } x=e_{1} \text { in } e_{2}\right) \\
\rightarrow^{*} & \lambda y \cdot e\left(\text { let } x=\text { val }_{1} \text { in } e_{2}\right) \\
\rightarrow & \lambda y \cdot e\left(e_{2}\left[\text { val }_{1} / x\right]\right) \\
\rightarrow & \lambda y \cdot e\left(\text { val }_{2}\left[\operatorname{val}_{1} / x\right]\right) \\
\rightarrow & e\left[\text { val }_{2}\left[\text { val }_{1} / x\right] / y\right] \\
= & e\left[\text { val }_{2} / y\right]\left[\text { val }_{1} / x\right]
\end{array}
\]
and
\[
\begin{array}{ll} 
& \text { let } x=e_{1} \text { in }(\lambda y . e) e_{2} \\
\rightarrow^{*} & \text { let } x=\operatorname{val}_{1} \text { in }(\lambda y . e) e_{2} \\
\rightarrow & \left((\lambda y . e) e_{2}\right)\left[\text { val }_{1} / x\right] \\
\rightarrow & \left((\lambda y . e) \text { val }_{2}\right)\left[\text { val }_{1} / x\right] \\
\rightarrow & e\left[\text { val }_{2} / y\right]\left[\text { val }_{1} / x\right]
\end{array}
\]

By [EqFact], we are done.
- Case [S-match-match]. We want to show that if \(f v(\) alts \() \cap \vec{x}=\emptyset\), then match (match \(e_{0}\) with \(\overrightarrow{K \vec{x} \rightarrow e}\) ) with alts \(\equiv_{s}\)
match \(e_{o}\) with \(\overrightarrow{K \vec{x} \rightarrow \text { match } e \text { with alts. We have: }}\)
\[
\begin{aligned}
& \text { match (match } e_{0} \text { with } \overrightarrow{K \vec{x} \rightarrow e} \text { ) with alts } \\
\rightarrow^{*} & \text { match }\left(\underset{\text { match } K}{v_{\text {val }}} \text { with } \overrightarrow{K \vec{x} \rightarrow e}\right) \text { with alts } \\
\rightarrow & \text { match } e[\text { valolx}] \text { with alts }
\end{aligned}
\]
and
\[
\begin{aligned}
& \text { match } e_{o} \text { with } \vec{K} \vec{x} \rightarrow \text { match } e \text { with alts } \\
& \rightarrow^{*} \text { match } K \overrightarrow{v_{01}} \\
& \rightarrow \quad \text { with } \overrightarrow{K \vec{x} \rightarrow \text { match } e \text { with alts }} \\
&=(\text { match } e \text { with alts })\left[\overrightarrow{v a l_{0} / x}\right] \\
&(\text { By fv }(\text { alts }) \cap \vec{x}=\emptyset) \\
& \text { match } e\left[\overrightarrow{v a l_{0} / x}\right] \text { with alts }
\end{aligned}
\]

By [EqFact], we are done.
- Case [S-match-let]. We want to show if \(x \notin f v(\) alts ), then match (let \(x=\) \(e_{1}\) in \(e_{2}\) ) with alts \(\equiv_{s}\) let \(x=e_{1}\) in match \(e_{2}\) with alts. We have:
\[
\begin{array}{ll} 
& \text { match }\left(\text { let } x=e_{1} \text { in } e_{2}\right) \text { with alts } \\
\rightarrow^{*} \quad \text { match }\left(\text { let } x=\text { val }_{1} \text { in } e_{2}\right) \text { with alts } \\
\rightarrow \quad & \text { match } e_{2}\left[\text { val } l_{1} / x\right] \text { with alts }
\end{array}
\]
and
\[
\begin{array}{ll} 
& \text { let } x=e_{1} \text { in match } e_{2} \text { with alts } \\
\rightarrow^{*} & \text { let } x=\text { val in match } e_{2} \text { with alts } \\
\rightarrow \quad & \left(\text { match } e_{2} \text { with alts }\right)[\text { val } 1 / x] \\
=\quad & (\text { By } x \notin \text { fv(alts) }) \\
& \text { match } e_{2}[\text { val } / x] \text { with alts }
\end{array}
\]

By [EqFact], we are done.

Lemma 22 (Correctness of rebuilding). For all \(\mathcal{H}, a_{1}, \mathcal{S}, \mathcal{L}\), if \(\left\langle\langle\mathcal{H}| a_{1} \| s::\right.\) \(\mathcal{S} \| \mathcal{L}\rangle>\rightsquigarrow^{*} a\), then \(a_{1} \equiv_{s} a\).

Proof. We prove it by induction on the number of transition steps. We have the following induction hypothesis: for all \(\mathcal{H}, a_{1}, \mathcal{S}, \mathcal{L}\), there exists \(\mathcal{H}_{2}, a_{2}, \mathcal{S}_{2}, \mathcal{L}_{2}\), such that \(\left.\left\langle\left\langle\mathcal{H} \| a_{1}\right| \mathcal{S} \mid \mathcal{L}\right\rangle\right\rangle \rightsquigarrow\left\langle\mathcal{H}_{2}\left\|a_{2}\right\| \mathcal{S}_{2} \| \mathcal{L}_{2}\right\rangle\) or \(\left.\left\langle\left\langle\mathcal{H} \| a_{1}\right| \mathcal{S} \mid \mathcal{L}\right\rangle\right\rangle \rightsquigarrow\) \(\left.\left\langle\left\langle\mathcal{H}_{2} \| a_{2}\right| \mathcal{S}_{2} \mid \mathcal{L}_{2}\right\rangle\right\rangle\),
\[
\left\langle\left\langle\mathcal{H}_{2}\left\|a_{2}\right\| \mathcal{S}_{2} \| \mathcal{L}_{2}\right\rangle\right\rangle \rightsquigarrow^{*} a \wedge a_{2} \equiv_{s} a \quad[\mathrm{IH}]
\]

The base case is [R-done]. As two expressions \(a\) at both LHS and RHS of \(\rightsquigarrow\) are syntactically the same, they are semantically equivalent, so we have the desired result. By [E-exn], [E-ctx], definition of contexts and induction hypothesis [IH], we get the desired result for [R-r-match], [R-r-let], [R-r-fun], [R-r-arg], [R-r-K]. The • in a stack frame indicates the original position of the expression being simplified. It is easy to check that [R-lam], [R-fun], [R-app] and [R-K] just put the simplifed expression back to the - so they are correct. By [E-beta] and [S-var1], [R-beta] is correct. We now consider those slightly non-obvious transitions.
- Case [R-K-match]. This transition implements the simplification rule [Kmatch] in Figure [11. We want to show that match \(K a_{1} \ldots a_{n}\) with \(\left\{\ldots ; K x_{1} \ldots x_{n} \rightarrow e ; \ldots\right\} \equiv_{s}\) let \(x_{1}=a_{1}\) in \(\ldots\) let \(x_{n}=a_{n}\) in \(e\). We have:
\[
\begin{aligned}
& \operatorname{match} K a_{1} \ldots a_{n} \text { with }\left\{\ldots ; K x_{1} \ldots x_{n} \rightarrow e ; \ldots\right\} \\
\rightarrow^{*} & \operatorname{match} K \operatorname{val}_{1} \ldots \text { val }_{n} \text { with }\left\{\ldots ; K x_{1} \ldots x_{n} \rightarrow e ; \ldots\right\} \\
\rightarrow & e[\overrightarrow{v a l / x}]
\end{aligned}
\]
and
\[
\begin{aligned}
& \quad \text { let } x_{1}=a_{1} \text { in } \ldots \text { let } x_{n}=a_{n} \text { in } e \\
& \rightarrow^{*} \quad \text { let } x_{1}=\operatorname{val}_{1} \text { in } \ldots \text { let } x_{n}=\operatorname{val}_{n} \text { in } e \\
& \rightarrow \quad e[v a l / x]
\end{aligned}
\]

By [EqFact], we are done.
- Case [R-s-match]. Given \(\mathcal{L} \Rightarrow \exists \overrightarrow{x: \llbracket \tau \rrbracket}, \llbracket a \rrbracket_{K} \vec{x}\) is valid and \(a \rightarrow^{*} K_{i} \overrightarrow{v a l}\) for some \(\overrightarrow{v a l}\), by Theorem \(\left[12{ }^{[36}, \mathcal{L} \Rightarrow \exists \vec{x}, \llbracket K_{i} \overrightarrow{v a l} \rrbracket_{K} \vec{x}\right.\) is valid. From Figure 15, we know \(K_{i}=K\). By [E-match], we get the body \(e\) in the branch \(K\). Since \(\mathcal{L} \Rightarrow \exists \vec{x}, \llbracket a \rrbracket_{K} \vec{x}\) implies \(\mathcal{L} \wedge \exists \vec{x}, \llbracket a \rrbracket_{K} \vec{x},[\) R-s-match] is correct.
- Case [R-s-save]. This transition simplifies each branches with the as-
 \(a \rightarrow^{*} K_{i} \overrightarrow{v a l}\) for some \(\overrightarrow{v a l}\), by Theorem \([12]^{\frac{136}{|c|}} \mathcal{L} \wedge \exists \vec{x}, \llbracket K_{i} \overrightarrow{v a l} \rrbracket_{K} \vec{x}\) is valid. From Figure 15, we know \(K_{i}=K\). By [E-match], we get the body \(e\) in the branch \(K\). So [R-s-save] is correct.
- Case [R-match]. This rule just put back each simplified branch to its original position indicated by the \(\bullet\). The \(\mathcal{S}\) and \(\mathcal{L}\) keep the stack and logical store before each branches are simplified. So [R-match] is correct.
- Case [R-let-save]. The local let defines \(x\), by Theorem \(11{ }^{[36}, \exists x: \llbracket \tau \rrbracket, \llbracket a \rrbracket_{x}\) is valid. So [R-let-save] is correct.

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