COMBINING ADA 95, JAVA BYTE CODE, AND THE DISTRIBUTED SYSTEMS ANNEX

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Abstract .

This paper describes a prototype client/server system which combines two technologies: the ability to compile Ada 95 code into Java Byte Code (JBC) running on the Java Virtual Machine via Intermetrics AppletMagic¹⁴ product and the Ada 95 Distributed Systems Annex. The paper sets out the goals of the prototype effort and then illustrates the concepts, design, and techniques used to create the system. Finally, the trade-offs, alternatives, benefits and conclusions from the prototype effort are presented.

Overview

Recently, two new and interesting — but separate — technologies have emerged in the Ada community. The first is the ability to compile Ada 95 code into Java Byte Code (JBC) running on the Java Virtual Machine via Intermetrics AppletMagic product. This brings Ada developers the many benefits of Internet based client/server applications. The second technology is the Ada 95 Distributed Systems Annex (Annex E). This also allows the creation of client/ server software, but is even more flexible in allowing many different configurations of distributed software. As of Spring 1997, these technologies had not yet been combined nor even shown to be able to work together.

The AJPO sponsored' the author's previous company to produce a software prototype which combined Ada 95, the Java Virtual Machine (JVM), and the Distributed Systems Annex (DSA) in one demonstration. In addition, the AJPO directed that the software prototype be representative of the type of applications which will be a part of the forthcoming Defense Information Infrastructure (DII) and its Common Operating Environment (COE).

This paper will illustrate the concepts, techniques and benefits which arise from the successful combination of Ada 95, Java Byte Code and the Distributed Systems Annex.

The Prototype's Goals

The use of Java Byte Code technology inspired the project to strive for three goals:

- Demonstrate Client Neutrality: The client software must run (without change) on Sun/Solaris, Macintosh/System 7.5.5, PC/ Windows NT 4.0, and PC/Windows 95 environments.
- Ensure that no physical distribution and/or installation of client software is needed: The demonstration application must run on any machine preconfigured with a web browser. There will be no

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 Provide instant update of clients: If the demonstration application is updated from v1.0 to v1.1, then all clients must automatically run the latest version the next time they launch their web browser.

The use of the Distributed Systems Annex inspired the project to strive for an additional goal:

Ensure Scalability: The server software must be able to be configured and run on more than one Sun system. Repartitioning the distributed server system must not require any modification of the Server's Ada 95 software. Achieving this goal will provide the ability to distribute the server over multiple machines to achieve corresponding performance gains without Ada 95 source code modifications.

Specific Tools Used in Prototype Demonstration

All new software written for the prototype was written in Ada 95. The client software was compiled using Intermetrics AppletMagic v1.38 compiler for Macintosh. The client software makes extensive use of the standard Java toolkits and libraries via the Ada 95 bindings supplied with AppletMagic. The resulting JavaByteCode (or J-code) has been run on Java Virtual Machine (JVM) clients on a Macintosh (using four different JVM implementations), a PC running Windows 95 and Windows NT, and on a Sun^{**}. The server software was compiled with ACT's GNAT v3.09 for Sparc/Solaris 2.5.1 and GLADE v1.01 (the GNAT implementation of the Ada 95 Distributed Systems Annex). The server software has been run on a series of Sparcstation 4 and Sparcstation 2 machines under Solaris 2.5.1.

Specific Software Requirements

Basic Concept

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The prototype client/server pair represents a hypothetical Command, Control, Communications, Computers and Intelligence (C4I) application which could be built on top of the DII COE using Ada 95/JBC and the DSA. For this effort, the server would simulate a series of sensors which were monitoring the locations of enemy troops on the battlefield. The client would collect the data reported by all of the sensors and display it on a map on the user's screen. The server's three (3) sensors would simulate the reporting of simplified information on enemy troop locations and troop types with which a commander might be presented during a battle. This data would be broadcast in near real-time and displayed as military icons on a simulated texture map by the client software.

Server Capabilities

The server software simulares three independent sensors all observing a common Battlefield. The sensors are:

- Ground Sensor (e.g., an Artillery Forward Observer [FO]),
- ◆ Air Sensor (e.g., an Unmanned Aerial Vehicle [UAV]), and
- Satellite Sensor.

Each of these sensors is located in a different place on/over the common Battlefield. Each sensor looks at the Battlefield and returns observations to main sensor server (which then relays them to the client software via a socket connection). Each sensor introduces

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[&]quot;Observed differences in client software behavior for identical .class files appear to be due to differences in JVM implementations. The behavior of the Ada 95 client is no different than a Java client — both run identically on different machines within the known differences/bugs present on those JVM implementations.

map window, disconnect from the server, and return to the login screen. The server software remains active in the background and awaits additional client connections.

Overall Architecture

This section describes the software and hardware architecture for both the client and server pieces. In addition, the flow of information among the client(s) and distributed servers is illustrated for a typical user scenario (or use case).

The client(s) and server are connected via a TCP/IP network (e.g., the Internet). The client machine is running some implementation of the Java Virtual Machine (JVM) (e.g., a Java enabled web browser). Once the Sensor Server has been launched, one or more clients may connect to it. Both the HTML server (providing the web page and the downloadable JBC client applet) and the Sensor Server application *must* be hosted on the same machine.

Figure 3 shows the overall architecture for both the client and server machines and a typical use-case interaction. Details on this architecture are provided in the next two sections. The remainder of this section provides an architectural description of the components base on the most typical Use Case.

*This is due to a "limitation" of the security software which is part of the Java Virtual Machine. A web-based applet (client) is only allowed to open up a network connection to the same host machine from which the applet was downloaded (i.e., the html server).

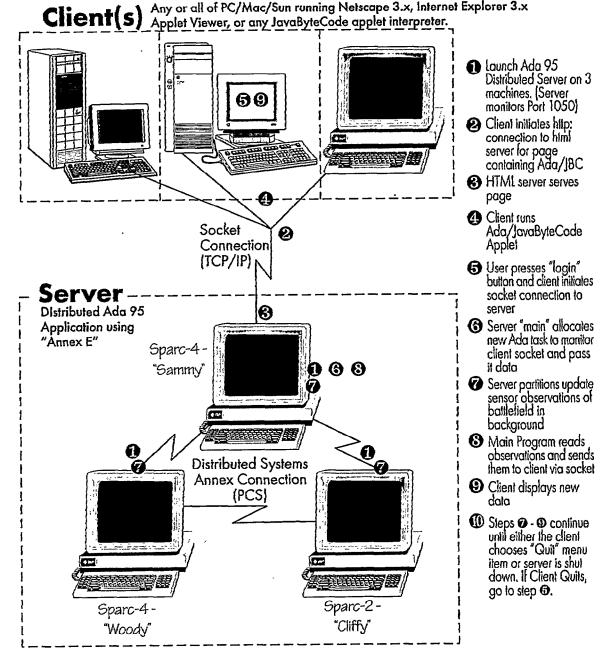


Figure 3: Overall Client/Server Architecture

Upon launch, the Sensor Server main program begins to monitor socket port 1050 for a client connection. At the same time, the separate server partitions for the Sensors and the Battlefield begin to monitor the battlefield and record troop positions.

The client connects to the web server html page that contains the Sensor Demo applet. The html server downloads the applet to the client machine as part of the web page. The Ada 95/JBC client run and then initially displays the screen that was shown in Figure 1.

When the user presses the "login" button, then the client software to initiate a TCP/IP Socket connection to port 1050 onto the Server. Upon detecting a new connection from a client, the server spawns off a new Ada task dedicated to polling each Sensor Partition for its readings and sending sensor updates to the tasks client. In parallel, the Sensor Server main program then awaits either a new client connection or control-C from the server console. The client software displays a blank map in a new window and then begins to monitor socket port 1050 for new sensor data to read. As the server sends new data, the client software displays updated icons in the new map window on the client machine. An example of this map was shown in Figure 2. The user may select "Quit" from the "File" menu at any time in order to close the map window and return to the login screen. The user quits the browser session to rerminate all client/server interaction. The server software continues to await additional client connections. Once the server receives a control-C, it is interrupted and performs an orderly shutdown of all distributed partitions.

Several elements of this architecture are dictated by the use of the Java Virtual Machine. These include the co-location of the HTML server and the sensor server, the use of a socket connection back to the server machine, and the use of a new window on the client to contain the map and the menu bar (only JVM Frames may have menus). The automatic startup and shutdown of the server software and all associated partitions is enabled by functionality provided by the Glade implementation of the DSA. Most other partitioning decisions enumerated in this section and the following two sections were design decisions by the author.

Client Design

The client software consists of nine (9) new Ada 95 packages. These packages make use of many pieces of the standard Java Library. The basic architecture for the client software is shown in the dependency diagram in Figure 4.

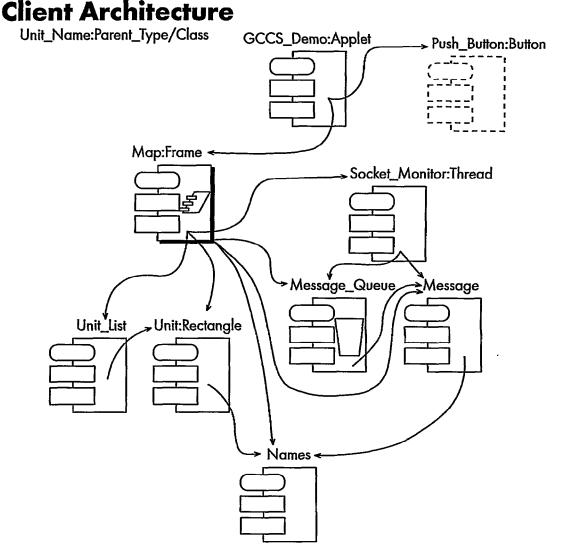


Figure 4: Client Dependency Architecture

Inheritance Relationships

Five of the new types defined in the client program inherit from standard Java types:

- The GCCS_Demo class (the "Client main program") inherits from Applet (which enables it to be embedded in a web page).
- The Map class inherits from Frame (which provides a separate window and menu bar).
- The Push_Button class inherits from Button (which provides a call-back on a GUI button).
- The Unit class inherits from Rectangle because a unit adds Armed Forces information to a GUI concept of a rectangle class that has a location and a size. This design allows easy determination of when the user has clicked within a unit or when units overlap on the screen as this functionality is provided by the Java APIs for Rectangle.
- The Socket_Monitor class inherits from Thread (which provides a separate thread that runs in parallel to the main class) and reads data from the TCP/IP socket. AppletMagic v1.38 did not implement Ada tasking semantics. If it had, these could have been used. Instead, the design falls back on Java's thread semantics which are provided. This is less intuitive for the experienced Ada programmer, but it helps the program fit more directly with the use of JavaByteCode and the Java APIs.

The other packages do not inherit from pre-existing Java structutes, but represent other design abstractions. In this small example none of the newly defined abstractions inherit from each other.

Aggregation Relationships

The GCCS_Demo class is composed of instances of the Map and Push_Button classes as well as instances of several predefined Java AWT GUI classes. The Map class is composed of instances of the Socket_Monitor, Message_Queue and Unit_List classes. Message_Queue and Unit_List are aggregates of the Message and Unit classes respectively.

Table 1 contains a brief description of each of the Ada packages.

Working with the Java APIs: The Learning Curve

When writing Java applets in Ada 95 using AppletMagic, the effort of learning Java's syntax is reduced but not eliminated. Unfortunately, in order to follow any of the examples in many books or articles, one must know enough of Java's syntax and semantics to read and understand them. Since Java's semantics are very similar to Ada 95's, this is not difficult. Rather, when learning Java, the biggest hurdle is that of mastering the vast APIs that are part of Java. In this sample application, the design draws heavily upon the nervork APIs (java.net) and the GUI APIs (java.awt). Due to the complexity of these APIs, there was a substantial learning curve involved. Several sets of Java books and on-line tutorials were consulted. In fact, approximately seven incremental iterations of the design and implementation were performed in order to master the complexity of the APIs and building this type of applet for the first time. The final appler, though, is very much a Java applet - done in Ada 95 syntax and semantics. It makes full use of the Java APIs and, except for the Algol/Pascal syntax, resembles most other applets.

Working with the Java APIs: Advantages and Disadvantages

In general, the advantages of using the Java APIs far outweighed the single biggest disadvantage: the complex learning curve. The advantages include: a rich set of functionality to choose from; plentiful examples in books and magazines; and a uniform GUI look and feel on all platforms from a single, standard, set of source code. An additional minor disadvantage was the fact that the implementa-

GCCS_Demo	Contains the applet and housekeeping code. It starts the applet and presents the user with a login screen. It makes use of Push_Button to invoke the right action when the user pushes the "Login" button.	
Push_Button	A generic package that provides a subclass of the Java Button class and an associated action routine that is called when the button is pushed. In the Sensor Demo, the action is to create a new map frame and display it. Map and its associated thread take over from there.	
Мар	Map Brings up a separate window (a Java Frame) along with a menu bar and menu. Map contains an instance of the Socket_Monitor class which is responsible for getting data from the server. Map contains an additional thread that depends o the Message_Queue class and reads each new message from the queue. Based on the message, the thread then creates new units and adds them to the Unit_List. The Paint() method then makes use of the Unit_List and Unit Paint() methods to display these new units.	
Socket_Monitor	Responsible for getting data from the server. Is a subclass of Thread so it operates in parallel with other threads in the applet. Each new line of data read from the socket is converted to a message via the Message class's constructor. The new message is then added to the Message_Queue.	
Message	e Parses the raw text string from the server into its component information.	
Message_Queue	ssage_Queue A FIFO list of Messages that have been retrieved from the server. It is "synchronized" because it is a shared data structure which is access by both the Socket_Monitor and Map "threads".	
Unit	Unit A single observation from a single sensor. It has a location on the map and a unit kind.	
Unit_List	Unit_List An array of three Singly-Linked Lists of Units. Each list corresponds to a different sensor and its unit observations.	
Name A pair of enumerated types listing the Sensor names and the kinds of Enemy units.		

Table 1: Description of each Client application package

tions are not yet implemented in a uniform and bug free way. Although the code does not need to change in order to produce a portable GUI, the resulting application is unlikely to be 100% identical among platforms. Many JVM GUI bugs are well documented on the internet and are of a minor nature.

The Use of Java APIs and Concepts in the Client Design

In order to produce a JavaByteCode based applet which would meet the goals listed at the beginning of this paper, it was necessary to make use of several of the features of Java. Foremost among these is Java's platform independent GUI toolkit: AWT (Abstract Windowing Toolkit). AppletMagic provides a full set of Ada interfaces to these predefined routines. It is typical, as seen in Figure 4, to design ones application by inheriting from these predefined classes. In addition, it was a critical requirement that the Client Applet be able to simultaneously display sensor results, accept user input and receive new results from the server. This necessitated the use of multi-threading in the Applet. Ada 95 tasks and protected types could have been used to implement this requirement. Unfortunately, version 1.38 of AppletMagic did not yet provide support for these features. Java does provide a very similar

Server Architecture

multithreading capability, and it was available through the use of standard Java APIs and AppletMagic supported pragmas. Although the final design is not the same as if Ada tasking were used, it is very close — proof of the similarity between Ada's semantics and those of Java.

Creating Client Applets in Ada 95

Overall, some things about creating a client applet are made simpler by the use of Ada 95. As has been mentioned, the learning curve is simpler because of the use of Ada. However there are also difficulties in using Ada 95 for an applet. For example, a translation must be made when using most common references, examples or books. Certainly this is mitigated by the excellent examples supplied by AppletMagic, but they don't replace a book or article. In the same way, it is difficult to ask questions in forums such as comp.lang.java.programmer without first translating one's question and example code into Java syntax and/or translating a response. This is offset by the willingness of the AppletMagic development team — especially lead developer Tucker Taft — to directly answer questions from users. Certainly, this design effort shows that it is feasible and practical to create thin client applets using Ada 95.

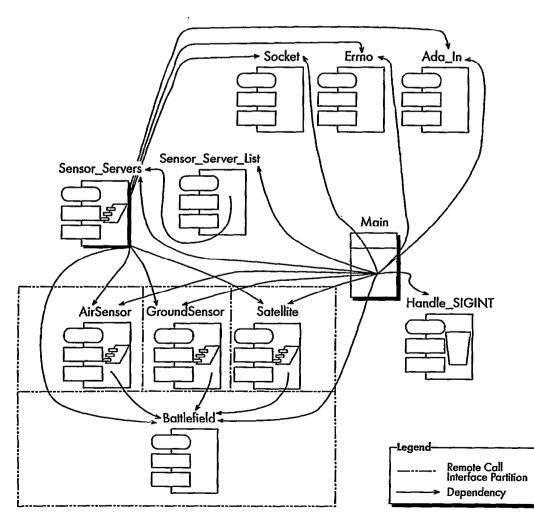


Figure 5: Server Dependency Architecture

Server Design

The server software consists of eleven (11) Ada 95 packages. The basic architecture for the server software is shown in the dependency diagram in Figure 5.

There are five separate distributed components in the server software:

- The "Main" Program: Package Main and the Sensor_Server_List and Sensor_Server components are the main pieces in the Data Server partition. This partition initiates communication with the other partitions but is never called on by any others.
- The Air Sensor: A Remote Call Interface partition. This partition responds to requests for the Air Sensor's observations. It also contains a separate task whose thread simulates the sensors it updates readings from the Battlefield Partition on a continuous basis.
- The Ground Sensor: A Remote Call Interface partition. This partition responds to requests for the Ground Sensor's observations. It also contains a separate task whose thread simulates the sensors it updates readings from the Battlefield Partition on a continuous basis.
- The Satellite Sensor: A Remote Call Interface partition. This partition responds to requests for the Satellite Sensor's observations. It also contains a separate task whose thread simulates the sensors it updates readings from the Battlefield Partition on a continuous basis.
- The Bottlefield: A Remote Call Interface partition. This partition contains the locations of all enemy units. It responds to requests for the list of locations. Ourrently, units on the battlefield are static.

Table 2 contains a brief description of each of the Ada packages.

Communicating Between Client and Server

In this prototype system, simplicity was the primary driver in choosing the mechanism to connect the client and server pieces. Although both parts are written in Ada 95, the client compiles into JavaByteCode running on any client machine with a JVM or Web Browser. The server runs on one or more Sun workstations. Therefore, some network communication mechanism must be chosen. Several alternatives exist: a socket connection, Remote Procedure Calls (RPCs), Common Object Request Broker Architecture (CORBA), and a heterogeneous implementation of the DSA (see the section on Alternative Architectures for the trade-offs). Of all of these, only a simple socket connection had been proven in a similar context. While simplicity is a chief advantage of a socket connection, it's low level nature brings along some disadvantages. The socket connection is a narrow interface - it can only communicate a simple character or binary based data stream. It is up to the developer(s) of the client and server to determine the messaging protocol (semantics) the are to be used and to convert any and all data to be sent to the low level format supported ("marshalling the data"). For this simple prototype system, this kind of communication worked well. However, it does not scale well to larger systems.

Creating Servers Using Ada 95's Distributed Systems Annex (DSA)

It would certainly have been possible to create the Ada 95 server as a single Ada 95 program containing multi-threaded tasks representing each Sensor. In fact, that design is *not* very different from the actual design shown in *Figure 5*. However, that design does not exactly model the real-world simulation that was desired in this prototype. The goal was to implement a system where each Sensor was located on a different computer and all of these computers communicated to exchange readings about the battlefield. Ada 95's DSA enabled the simplicity of a single program, single language, multi-threaded approach to be combined with the scalability and realism of a design that ran on multiple computers.

The actual piototype server was created as a single Ada 95 program and then made to run as a distributed system by adding only the appropriate categorization pragmas defined in the Ada 95 RM. If compilation and linking proceed normally, then the result is a single Ada 95 program. However, by making use of the post compilation GLADE tool "gnatdist" (ACT's implementation of the DSA which works with GNAT), the program can be made to run on multiple

	An infinite loop server program. Opens the socket connection on port 1050 and waits at the Socket.Accept() call for clients to connect. Uses the Sensor_Server_List package to keep track of tasks spawned to handle socket connections. Its code contains an Asynchronous Transfer of Control that handles the SIGINT (^C) interrupt if the user presses control-C to stop the server.
Sensor_Servers	A package containing a task type. One new task is allocated for each client socket connection. The task repeatedly gathers the most recent observation from the AirSensor, GroundSensor, and Satellite and passes them to the client via the socket connection.
Sensor_Server_List A Singly Linked List of Sensor_Servers. Used to allow the Main to signal all Sensor_Server tasks to shutd when the server program is interrupted/terminated.	
Handle_SIGINT	A protected procedure/interrupt handler. Traps the SIGINT signal (control-C) and allows Main to conduct an orderly shutdown.
AirSensor, GroundSensor, Satellite	A Remote Call Interface package. Each provides an identical interface to return to the caller the most recent set of observations. Each also contains a task that works in the background to observe the Battlefield and update the internal list of observed enemies.
Battlefield	A Remote Call Interface package. The Battlefield contains the true list of enemy unit positions. Each sensor receives this true data and adds its own sensor error adjustments to make a sensor observation.
Socket, Ada_In, Errno Bindings to the Unix Socket, Socket Address, and Error Number facilities.	

Table 2: Description of each Server application package

computers via the DSA. No further source code changes are needed. In the design shown in *Figure 5*, there is one active partition (the main partition) and four Remote Interface Partitions (one for each sensor and one for the battlefield). This allows the resulting program to run on anywhere from one (1) to five (5) different computers without recompilation or relinking. The distribution of partitions to computing nodes is strictly a post compliation process.

Workarounds: Creating Better Designs Accidentally

Due to a bug in GNAT v3.09, the prototype application would receive an incorrect SIGPIPE Unix signal whenever a client socket connection closed. ACT provided a workaound for this problem in the form of a protected object which associated a protected procedure as the interrupt handler for the SIGPIPE signal.

This code succinctly illustrated how to trap and react to a Unix signal. As a result, a similar protected type was designed to handle SIGINT, the signal generated when the user interrupts the running program with a control-c (^c) keystroke (*see Listing 1*). This protected type is then used by the server main program in conjunction with an Asynchronous Transfer of Control:

begin

-- startup/initialization code select Handle_SIGINT.SIGINT_Handler.Interrupted; -- got ^c, now shutdown then abort loop -- normal server processing end loop; end select; end;

The main program starts up and then enters an infinite loop within the ATC. While in that loop it handles client connections and serves sensor data. Upon receiving a ^C generated SIGINT signal, the select part of the ATC is activated and causes the abort of the normal sensor loop. This code then shuts down all partitions and terminates the server. The result is a simple, clean mechanism to have a server which runs in the background until interrupted.

```
package Handle_SIGINT is
  pragma Elaborate_Body;
  protected SIGINT_Handler is
    entry Interrupted; -- wait for SIGINT (^C)
procedure Signal; -- handle SIGINT & set flag
     pragma Interrupt_Handler (Signal);
  private
    Interrupt_Received : Boolean := False;
  end SIGINT_Handler;
end Handle_SIGINT;
with Ada. Interrupts. Names;
package body Handle_SIGINT is
  protected body SIGINT_Handler is
    entry Interrupted when Interrupt_Received is
    begin
      null:
             -- release caller
    end Interrupted;
    procedure Signal is
    begin
      Interrupt_Received := True;
    end Signal;
  end SIGINT_Handler;
begin
  Ada.Interrupts.Attach_Handler
   (SIGINF_Handler.Signal'Access, Ada.Interrupts.Names.SIGINT);
end Handle_SIGINT;
```

```
Listing 1: Handling SIGINT
```

Alternative Architectures

Sockets - A Narrow Interface

The design presented in this prototype application uses standard sockets to communicate between the client and server. These are supported in a very similar fashion by the Solaris operating system used on the Server and by the Java. Net package supplied with the JVM.

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As previously mentioned, this provides only a narrow pipeline between the client and server. The API consists of little more than two operations — one to read bytes of data and one to write bytes of data. All information in the application must be converted from Ada datatypes to characters/bytes. All actions to be communicated from the client to the server must be changed from procedure call oriented actions into message oriented events and back again. This places much of the responsibility for the infrastructure of a distributed client/server application onto the programmer. Two higher level alternatives exist, however neither of these was employed in this prototype application due to a lack of time, resources, and the fact that neither alternative had yet been tried.

CORBA - A Wider Option

An approach which reflects the high level software design more directly is that of CORBA. Via the use of IDL (Interface Definition Language), an object-oriented API between the client and server can be defined. This API consists of the operations, data arguments and exceptions that represent each interface (or class). The IDL interface is then mapped into the implementation language for the client and server (e.g., Ada 95). Both the client and server developers work as if they are writing code that makes use of local packages. Underneath, these packages define stubs and skeletons that marshal the data, communicate it across the network (similar to RPCs) and unmarshal the data on the server side. This hides all of the communications detail under the simple API.

This interface is wider than that of sockets because it allows the expression of a complex API as the direct communication path between client and server. As far as the programmer is concerned, the server is just another package in the local client program — even though the server actually runs on a remote machine across the network. This raises the level of abstraction between client and server to a much higher level and provides many benefits over direct socket programming.

For this prototype application, the only current drawback to the use of CORBA would be the fact that the client is running on a JVM with code written in Ada 95. CORBA ORBs exist for both Ada 95 code applications and for the Java JVM. However, the code targeted to the JVM, which would be created from the IDL, would likely be Java source code. Therefore, extra steps would be needed to (a) compile the generated code, and (b) make use of Intermetrics auxiliary tool to create an Ada interface to the generated Java code.

RMI to DSA - Another Wide Option

Just as the prototype was nearing completion, Texas A&M University (TAMU) announced ADEPT/JxA, an upgrade to ADEPT that would connect the Java Remote Method Invocation (RMI) and Ada's Distributed Systems Annex. RMI is Java 1.1's technology for creating Java to Java distributed applications. Using this technology, one could hypothetically have created the Applet Client using Ada 95 code which made use of RMI. This code would then be connected to the server code using the DSA via TAMU's JxAgent. So far as the author knows, no one has yet attempted this connection. Both AppletMagic and Glade worked well in this prototype application. Although a small number of bugs were present in both tools, these bugs were easily worked around. Both Intermetrics and ACT were highly responsive to questions and bug reports and their assistance enabled the prototype effort to go smoothly. Based on the experiences in this small prototype effort, the author would recommend the use of either or both tools on a full scale development effort.

Results/Conclusions

The Sensor Client/Server prototype has successfully demonstrated that Ada 95 can be used to create distributed Client/Server applications in the same way as other technologies, based on both the Java Virtual Machine and Distributed Applications (e.g., Remote Procedure Calls). It has also demonstrated that it is possible to combine the Ada 95 DSA (Annex E) type of distributed software with Java-based Client/Server distributed software.

The construction on this prototype system proved that Ada 95 could be used to successfully create both a client and a server which combine the best features of both the Java Virtual Machine and the Distributed Systems Annex. It was also demonstrated that it is possible to use these technologies to produce a realistic client/server system which simulates a simplified C4I sensor display application.

The prototype has successfully shown several of the advantages of the Java Virtual Machine for any large client/server environment: Client Neutrality: The client software runs (without change) on Sun/Solaris, Macintosh/System 7.5.5, PC/Windows NT 4.0, and PC/Windows 95 environments.

- No physical distribution and/or installation of client software necessary: In order to run the prototype, the user needs only to have a machine configured with a web browser.
- The goal of illustrating the automatic download of a new version of the software was not met during the time of the prototype. There was not enough time in the project to modify the software after the deployment of version 1.0. However, the goal was partially demonstrated since new client versions were constantly deployed as incremental prototype versions were built. Therefore, the author has confidence that a subsequent system would easily demonstrate this goal.

The prototype has also successfully shown a strong advantage of the Ada 95 Distributed Systems Annex approach:

 Scalability: The server software is able to be configured and run on anywhere from 1 to 5 Sun systems without changes to the Ada source code and without recompilation of the software. (Repartitioning the software only required a simple edit of the .cfg file and rerunning "gnatdist".)

With regards to the Ada community, the existence of this prototype serves as a proof-of-concept that Ada 95 software can be used in contexts where developers might naturally think of the use of Java. For an experienced Ada 95 developer who is *not* familiar with Java, the lower learning curve might well prove to be an advantage. Additionally, the demonstration of the ability to combine a JBC applet with a DSA server drives the state of Ada based client/server development forward another notch.

Appendix A – Client Software Source Code Listings

 * AJPO GCCS Demo
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 * * This program is free software; you can redistribute it and/or modify * it under the terms of the GNU General Public License as published by * the Free Software Foundation; either version 2 of the License, or * (at your option) any later version *
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with java.applet.Applet; use java.applet.Applet; with Interfaces.java; use Interfaces.java; with java.lang.String; use java.lang.String; with java.awt.Component; use java.awt.Component; use java.awt.Container; with java.awt.Container; with java.awt.Image; use java.awt.Image; with Map: use Map: package GCCS_Demo is type GCCS Demo_Obj is new Applet_Obj with private: type GCCS_Demo_Ptr is access all GCCS_Demo_Obj; procedure main(Argv : String_Array); -- called as entry point to applet procedure init (This : access GCCS_Demo_Obj); -- called before start for one time initialization private type GCCS_Demo_Obj is new Applet_Obj with record Login_Button : Component_Ptr ; --button to connect to verify user : Component_Ptr ; --user name Name_Field Password_Field : Component_Ptr ; --user password Imq : Image_ptr ; --the map The_Map_Frame : Map_Ptr : -- the window to display the map : String_Ptr := +"192.190.177.181"; host -- the default address to Sammy end record: end GCCS_Demo; -- Body of GCCS_Demo S with java.io.PrintStream with java.lang.System; with java.io.PrintStream; use java.io.PrintStream; use java.lang.System; with java.lang.Integer; use java.lang.Integer; with java.awt.Button; use java.awt.Button; with java.awt.Label; use java.awt.Label; with java.awt.TextField: use java.awt.TextField: with java.awt.GridLayout; use java.awt.GridLayout; with java.awt.LayoutManager; use java.awt.LayoutManager; with java.net.URL; use java.net.URL; -- for codebase with Push_Button; -- generic push button with Ada. Characters. Latin_1; package body GCCS_Demo is -- instantiate the generic button & set up its call back type PressedButtonInfo is record Parent : GCCS_Demo_ptr; -- what applet is button inside of? end record: procedure ConnectButtonPress(info : PressedButtonInfo); package ConnectButton is new push_button (PressedButtonInfo, ConnectButtonPress); use ConnectButton; procedure ConnectButtonPress(info: PressedButtonInfo) is -- make a frame or just show already made frame begin println(stdout, +*Button was pressed)*); println(stdout, +"Bringing up map window"); Info.Parent.The_Map_Frame := new_Map(+*Battlefield Map*, Info.Parent.Img, Info.Parent.Host); -- a side effect of creating a new map frame is to also -- launch two threads in that frame: (1) to read the socket -- and (2) to read messages from the queue and modify the unit list setResizable(Info.Parent.The_Map_Frame, False); resize(Info, Parent. The Map Frame, 880, 656); -- should really wait for the image to be ready before the show, but ...

show(Info.Parent.The_Map_Frame); println(stdout, +"Map window up."); end ConnectButtonPress; -- Initialize the applet. procedure init(This : access GCCS_Demo_Obj) is HC_Parameter : String_Ptr; LB_Info : PressedButtonInfo := (Parent => GCCS_Demo_ptr(this)); N_Field : TextField_Ptr := new_TextField(8); P_Field : TextField_Ptr := new_TextField(8); A_Label : Component_Ptr; RIGHT : Integer renames Java.AWT.Label.Right; begin • setLayout(this, new_GridLayout(rows=>3, cols=>2, hgap=>10, vgap=>3) .LayoutManager'access); -- add username and password fields to applet A_Label := Add(container_ptr(this), Component_Ptr(new_Label(+"Name", RIGHT))); This.Name_Field := Add(container_ptr(this), Component_Ptr(N_Field)); Show(This.Name_Field); A_Label := Add(container_ptr(this), Component_Ptr(new_Label(+"Password", RIGHT))); SetEchoCharacter(P_Field, '*'); This.Password_Field := Add(container_ptr(this), Component_Ptr(P_Field)); Show(This.Password_Field); -- add null label for spacing in grid A_Label := Add(container_ptr(this), Component_Ptr(new_Label(+**, RIGHT))); -- add button to applet This.Login_Button := ConnectButton.New_push_button (container_ptr(this), LB_Info, +"Login"); Show(This.Login_Button); resize(This, preferredSize(container_ptr(this))); -- deal with the (hidden) Frame's Imaage This.Img := getImage(This, getCodeBase(This), +*map_gifs/map6.gif*); --map#6 is 880x656 --grid from sever is 110x82 each cell is 8x8 (8:1 ratio) -- read parameter from HTML file HC_Parameter := getParameter(This, +"HC"); if HC_Parameter /= null and then not equalsIgnoreCase(HC_Parameter, +*True*) then -- figure out which machine we came from and pass that along to the map This.Host := getHost(getCodeBase(This)); else null; -- use the default value set in private part end if; end init; -- Main Program procedure main(Argv : String_Array) is This : aliased GCCS_Demo_Obj; begin GCCS_Demo.init(This'access); GCCS_Demo.start(This'access); end main; end GCCS_Demo; pragma Suppress(Elaboration_Check); with java.lang.String; use java.lang.String; with Interfaces.java; use Interfaces.java; with java.awt.Event; use java.awt.Event; with java.lang; use java.lang; with java.awt.Container; use java.awt.Container; with java.awt.Component; use java.awt.Component; with java.awt.Button; use java.awt.Button; generic type callbackInfo is private: with procedure handlepress(info : callbackInfo);

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package push_button is type push_button_Obj is new Button_Obj with record cb : callbackInfo; end record; type push_button_Ptr is access all push_button_Obj'class; function New_push_button (Parent : Container_Ptr: info : callbackInfo; B_Name : String_Ptr; Obj : push_button_Ptr := null) return component ptr: -- function "+" (S:String) return String_Ptr renames Interfaces.Java. "+"; function action (Obj : access push_button_Obj; Event : Event Ptr; what Obj ; Object Ptr) return Boolean; end push_button; with java.lang.System; use java.lang.System; with java.io.PrintStream; use java.io.PrintStream; package body push_button is -- creates a new push button and returns it to the parent object function New_push_button (Parent : Container_Ptr; info : callbackInfo: B_Name : String_Ptr; Obj : push_button_Ptr := null) return component_ptr is new_button : push_button_Ptr := new push_button_obj; begin setLabel(Button_ptr(new_button), B_Name); new_button.cb := info; return add (parent, Component_Ptr(new_button)); end New push button: -- Handles a button push event for this object and sends it somewhere function action(Obj: access push_button_Obj; Event : Event_Ptr; What_Obj : Object_Ptr) return Boolean is begin handlepress(Obj.cb); return true: -- put code here to call Orbix client? end action; end push button; * AJPO GCCS Demo * Map Window Frame

with java.lang.String;	use java.lang.String;	
with Interfaces.java;	use Interfaces.java;	
with java.awt.Frame;	use java.awt.Frame;	
with java.awt.Component;	use java.awt.Component;	
with java.awt.Container;	use java.awt.Container;	
with java awt.Event:	use java.awt.Event;	needed for handleEvent
with java.net.URL;	use java.net.URL;	
with java.awt.Graphics;	use java.awt.Graphics;	needed for overriding paint
with java.awt.Image;	use java.awt.Image;	needed for storing Map
with java.awt.MenuBar;	use java.awt.MenuEar;	
with java.lang.Runnable;	use java.lang.Runnable;	needed to provide second
thread		-
with java.lang.Thread:	use java.lang.Thread;	- needed to provide second
thread		-
with INT:	use Wil-	
with Unit:	use Unit:	

use Unit_List: with Unit_List; with Socket_Monitor; use Socket Monitor: package Map is type Map_Obj is new Frame_Obj with private; -- eventually add runable component for "implements runnable" type Map_Ptr is access all Map_Obj; function handleEvent (This : access Map_Obj; evt : Event_Ptr) return Boolean; -- handle window close event procedure paint(This : access Map_Obj; G : Graphics_ptr); -- use to draw map in frame and animate icons procedure update (This : access Map_Obj; G : Graphics_ptr); -- override to avoid total redraw, use clipping regions. procedure run(This : access Map_Obj); pragma Convention (Java, run); -- so matches Runable, Run -- called when thread is started -- Implements Runnable function new_Map(title : String_Ptr; The_Map : Image_Ptr; : String_Ptr; Host_Addr Obj : Map_Ptr := null) return Map_Ptr; pragma Convention(Java_Constructor, new_Map); private type Map_Obj is new Frame_Obj with record Our_Map : Image_Ptr; Menu_Bar : MenuBar_Ptr; NYI_Dialog : NYI_Ptr; Positions : Unit_List_Ptr; SM : Socket_Monitor_Ptr; -- thread related data Runnable : aliased Runnable_Obj; -- means 'implements Runnable' The_Thread : Thread_Ptr := null; -- points to the thread we kicked off. If it is null, then make a new thread. end record; end Map; with java.io.PrintStream; use java.io.PrintStream; -- needed for println with java.lang.System: use java.lang.System; -- needed for stdout with java.awt.Menu; use java.awt.Menu: with java.awt.MenuItem; use java.awt.MenuItem; with Names: use Names: with Message; use Message; with Message_Queue; use Message_Queue; pragma Elaborate All (Message Queue); package body Map is procedure Create_Menus (The_Menu_Bar : MenuBar_Ptr) is File_Menu : Menu_Ptr := new_Menu(+"File"); begin File_Menu := Add (The_Menu_Bar, File_Menu); Add(File_Menu, +*Observe Sensors*); Add(File_Menu, +*Quit*); end Create_Menus; function new_Map(title : String_Ptr; The Map : Image Ptr: Host Addr : String Ptr; : Map_Ptr := null) 0bj return Map_Ptr is -- constructor operation Lew_Map : Map_Ptr := Map_Ptr(new_Frame(title, Frame_Ptr(Obj))); regin Lew_Map.Our_Map := The_Map;

Lew_Map.Menu_Par := new_MenuPar;

SetMenuBar(New_Map, New_Map.Menu_Bar); Create_Menus(New_Map.Menu_Bar); New_Map.NVI_Dialog := new_NVI(parent => Frame_Ptr(New_Map), title => +"Not Yet Implemented", modal => True); println(stdout, +'after nyi constructor in New_Map'); println(stdout, +"before unit_list constructor in New_Map"); New_Map.Positions := new_Unit_List; println(stdout, +'after unit_list constructor in New_Map'); New Map.SM := new_Socket_Monitor(+*Map Socket Monitor*, Host_Addr); setPriority (New_Map.SM, java.lang.thread.Min_Priority); -- to avoid deadlock Socket_Monitor.Start(New_Map.SM); println(stdout, +"after Socket Monitor start New_Map"); New_Map.The_Thread := new_Thread(New_Map.Runnable'Access, +"Map Frame thread"); setPriority(New_Map.The_Thread, java.lang.thread.Min_Priority+2); -- to avoid deadlock start(New_Map.The_Thread); println(stdout, +"after Map Frame Thread start in New_Map"); return New Map: end new_Map; function handleEvent (This : access Map_Obj; evt : Event_Ptr) return Boolean is -- handle window close event Super : Frame_Obj renames Frame_Obj (This.all) ; -- non dispatching view of "parent" begin if evt.id = java.awt.Event.Window_Destroy then done(This,SM); Stop(This.The_Thread); hide(This): dispose(This); return true; elsif (evt.target.all in MenuItem_Obj'Class) then -- selected some menu item declare Item : MenuItem_Ptr := MenuItem_Ptr(evt.Target); Label : String_Ptr := GetLabel(Item); begin if Label.all = Ada_To_Java_String("Quit").all then -- kill the frame -- same logic as Event.Window_Destroy socket_monitor.done(This.SM); --stop our thread by setting This. The_Thread to null -- the loop in run finishes so Run exits and the thread dies stop(This.The_Thread); hide (This) ; dispose(This); -- close down the frame and return to the login screen return true; elsif Label.all = Ada_To_Java_String("Observe Sensors").all then -- toggle this & call socket_monitor.suspend() or .resume() -- ?? or should we suspend our thread that reads from the queue? show(this.NYI_Dialog); return True; else -- some other menu? this is an error print (stdout, +"ERROR: Other menu selected. Label: "); println(stdout, Label); return java.awt.Frame.handleEvent(Super'access, evt); end if; end: elsif evt.id = java.awt.Event.Mouse_Up then declare Handled : Boolean; begin Handled := Unit_List.MouseUp(This.Positions, evt, evt.x, evt.y); -- delegate click if Handled then repaint (This); end if; -- click did something so update screen return Handled; end; else -- not window destroy and not menu item. Pass on to super & container return java.awt.Frame.handleEvent(Super'access, evt);

end if; end handleEvent;

procedure paint(This : access Map_Obj; G : Graphics_ptr) is Result : Boolean ; -- stores drawImage result. True if all bits avail. else false begin

-- temporary. replace with double buffering Result := drawImage(G, This.Our_Map, 0, 0, This.ImageObserver'access); print(stdout, +'Redrawing Map Image. All bits avilable: *); println(stdout, Result); Unit_List.Paint(This.Positions, G);

end paint;

procedure update(This : access Map_Obj; G : Graphics_ptr) is --!! in the future avoid total redraw. --!! in the future use clipping regions. begin paint(This, G); --don't clear background first end update; procedure run(This : access Map_Obj) is

-- called when thread is started -- Implements Runnable A Msg : Message_Ptr: begin -- new_Frame() set the thread to /= null -- Suspend() will set thread to null when we should pause -- then we'll just reallocate in Resume() which will call Run again while This. The_Thread /= null loop -- get next message from the queue (may block) -- add message to the Unit_List. -- this will cause it to be displayed next time the frame is repainted -- yield() so that other threads get the CPU yield; -- so that other threads get the CPU A_Msg := Remove; -- synchronized call may block -- 11 if message kind is start, then clear out unit_list for that sensor --!! since a new set of positions is arriving if A_Msg.Kind = Message.Start then Clear (This_List => This.Positions, For_This_Sensor => A_Msg.Sensor); elsif A_Msg.Kind = Message.Observation then Add(To_List => This.Positions, For_Sensor => A_Msg.Sensor, => new_Unit(A_Msg.Enemy, x=> A_Msg.X, y=> A_Msg.Y)); Item else -- A_Msg.Kind = Message.Stop repaint(This); -- processed a new set of observations so make sure they -- show up on the screen (minimal refresh) end if; yield; -- so that other threads get the CPU end loop;

end run;

procedure stop(This : access Map_Obj) is begin This.The_Thread := null; -- will cause run to exit its loop & stop end stop; --add in suspend() and resume() to Map --applet calls suspend() and resume() when it gets called --suspend sets the_thread = null

--resume allocates it again end Map;

-- * AJPO GCCS Demo

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-- * Socket Monitor -- reads messages from socket and adds them to queue

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use java.lang.String; with java.lang.String; with Interfaces.java; use Interfaces.java; with java.lang.Thread; use java.lang.Thread; use java.net.Socket; with java.net.Socket; use java.io.InputStream; with java.io.InputStream: with java.io.DataInputStream; use java.io.DataInputStream; use java.net.URL; with java.net.URL; use Message; with Message; with Message_Queue; use Message_Queue; pragma Elaborate_All(Message_Queue); package Socket_Monitor is type Socket_Monitor_Obj is new Thread_Obj with private; type Socket_Monitor_Ptr is access all Socket_Monitor_Obj; function new_Socket_Monitor(title : String_Ptr; Host Addr : String_Ptr; : Socket_Monitor_Ptr := null) Obi return Socket_Monitor_Ptr; pragma Convention (Java_Constructor, new_Socket_Monitor); procedure run(Obj : access Socket_Monitor_Obj); procedure done (This : access Socket_Monitor_Obj); private type Socket_Monitor_Obj is new Thread_Obj with record : Socket_Ptr; Sock : DataInputStream_Ptr; in_stream Base_Host_Addr : String_Ptr; end record; end Socket_Monitor; with java.lang.System; use java.lang.System; -- for stdout use java.io.PrintStream; with java.io.PrintStream; with java.net.URL; use java.net.URL: with java.net.InetAddress; use java.net.InetAddress; with Ada.Characters.Latin_1; use Ada.Characters.Latin_1; with Ada.Text_IO; use Ada.Text_IO; with Ada.Integer_Text_IO; use Ada.Integer_Text_IO; package body Socket_Monitor is function Open_Socket(This : access Socket_Monitor_Obj) return DataInputStream_Ptr; function new_Socket_Monitor(title : String_Ptr; Host_Addr : String_Ptr; : Socket_Monitor_Ptr := null) Obj return Socket_Monitor_Ptr is New_SM : Socket_Monitor_Ptr := Socket_Monitor_Ptr(new_Thread(title, Thread_Ptr(Obj))); begin New_SM.Base_Host_Addr := Host_Addr; return New SM: end new_Socket_Monitor; function Open Socket(This : access Socket_Monitor Obj) return DataInputStream_Ptr is host_inet : InetAddress_ptr; port : integer := 1050; begin println(stdout, +"before new socket call"); host_inet := getbyName(This.Base_Host_Addr); -- translate string inet # This.Sock := new_Socket(host_inet, port); -- make socket println(stdout, +'after new socket call.'); print(Stdout, +*Now Connected to: *); println(stdout, getHostName(getInetAddress(This.Sock))); println(stdout, +"about to return input stream"); -- initiate the input stream return new_DataInputStream(getInputStream(This.Sock)); end Open_Socket; procedure done (This : access Socket_Monitor_Obj) is hegin println(stdout, +"Closing InputStream");

close(This.in_stream); close(This.Sock); stop(This); end done; procedure run(Obj : access Socket_Monitor_Obj) is -- never terminates by itself. the done() method is called to shut it down. str_ptr : String_Ptr := new String_Obj; A Msg : Message Ptr: use type String_Ptr; begin Obj.in stream := Open_Socket(Obj): --open socket and set input stream to socket While_More_Data: 1000 Str_ptr := readline(Obj.in_stream); Yield: -- let other threads proceed exit when str_ptr = null; print(stdout, +("Socket Message: ")); println(stdout, str_ptr); print(stdout, +"This socket message is "); print(stdout, length(str_ptr)); println(stdout, " characters long"); A_Msg := new_Message(str_ptr); Yield; -- let other threads proceed Message_Queue.Add(Item => A_Msg); Yield; -- let other threads proceed end loop While_More_Data; done(Obj); exception when java.io.IOException => println(stdout, + "Got a Java.io.IOException inside of Socket_Monitor.Run"); done(Obj); end run; end Socket_Monitor; _____ -- * AJPO GCCS Demo -- * Message Queue -- & Queue (FIFO style) of Messages -- * The queue will block on Remove calls until new messages are added -- * Calls to Add never block with java.lang; use java.lang; -- for InterruptedException and type Object with Message; use Message; package Message_Queue is --only one message_queue. This is an ASM pragma Elaborate_Body; -- This class is intended to run in a Multi-Threaded environment procedure Add(Item : access Message_Obj); function Remove return Message_Ptr; -- will block if queue is empty procedure Clear: private -- these must be declared in the spec's private part to be -- primitive operations on the tagged type type Node: type Node_Ptr is access Node; type Node is record Msg : Message_Ptr; Next : Node_Ptr; Prev : Node_Ptr; end record; type Message_Oueue_Obj is new Object with record Head : Node_Ptr; Last : Node_Ptr; end record: type Message_Queue_Ptr is access all Message_Queue_Obj'class; procedure QAdd(To : access Message_Queue_Obj; Item : access Message_Obj); function QRemove(From : access Message_Queue_Obj) return Message_Ptr: -- will block if queue is eroty procedure QClear(This : access Message_Queue_Obj); -- This class is intended to run in a Multi-Threaded environment pragma Convention(Ada_Synchronized, QAdd); pragra Convention (Ada_Synchronized, QRemove); pragma Convention (Ada_Synchronized, OClear); end Message_Queue;

-- * AJFO GCCS Demo

-- * Message -- Sensor observations from the server use java.lang; with java.lang; with java.lang.String; use java.lang.String; with Names; use Names; package Message is type Kinds_Of_Messages is (Start, Stop, Observation); type Message_Obj is tagged limited record : Kinds_Of_Messages; - Which kind of message did the sensor send Kind : Names.Sensors; - Which sensor recorded this enemy Sensor - these three are only valid if Kind = Observation - should be variant record, but these aren't yet supported - X coord of enemy : Integer; x - Y coord of enemy v : Integer: : Names.Enemy_Kinds: - Which type of enemy was seen Enemy -workaround for broken exceptions: Valid : Boolean := True; - set to true if a valid message was built - if false, all fields are invalid end record; type Message_Ptr is access all Message_Obj; function new_Message(Str : String_Ptr) return Message_Ptr; Incomplete_String : exception; - raised if New_Message is given an incomplete string end Message;

- * AJPO GCCS Demo
- * Names :Sensors and Targes common types across Client & Server

with java.lang.String; use java.lang.String; package Names is Illegal_Value : exception ; type Sensors is (Air, Gnd, Sat) ; function To_String (S : Sensors) return String_Ptr; function To_Sensor (Str : String_Ptr) return Sensors; type Enemy_Kinds is (Tank, Infantry, Artillery); function To_String (EK : Enemy_Kinds) return String_Ptr; function To_Enemy (Str : String_Ptr) return Enemy_Kinds;

end Names;

- * AJPO GCCS Demo

* Unit List - an SLL (LIFO style) of Units

with java.lang; use java.lang; with java.awt.Graphics; use java.awt.Graphics; with java.awt.Event; use java.awt.Event; with Unit; use Unit: with Names; use Names; package Unit List is type Unit_List_Obj is tagged limited private; type Unit_List_Ptr is access all Unit_List_Obj; function new_Unit_List return Unit_List_Ptr; type Iterator is private; procedure Initialize(This_Iterator : in out Iterator; To_This_List : access Unit_List_Obj; For_This_Sensor : Names.Sensors) ; function Current(In This_Iterator : in Iterator) return Unit_Ptr; procedure Next(In_This_Iterator : in out Iterator); function Is_Done(This_Iterator : in Iterator) return Boolean; procedure Add (To_List : access Unit_List_Obj; For_Sensor : Names.Sensors; : access Unit Obi): Item procedure Clear(This_List : access Unit_List_Obj; For_This_Sensor : Names.Sensors); procedure paint (This : access Unit_List_Obj; G : Graphics_ptr); - use to draw Unit List in frame function mouseUp(Obj : access Unit_List_Obj; evt : Event_Ptr; x : Integer: y : Integer) return Boolean: - convenience function called when mouse is released inside a unit_list

- called from map's handleEvent() private

end Unit_List;

- * AJPO GCCS Demo * Abstract Unit Icon (to be overlayed on Map frame) * all units are 32x18 icons set in the top left of a 32x32 cell - * currently the grid is 8x8 pixels to server grid - * so all unit icons take up 4x4 cells and can overlap with java.awt.Event; use java.awt.Event; - needed for handleEvent with java.awt.Image: use java.awt.Image; - needed for storing Map with java.lang.String; use java.lang.String; with Interfaces.java; use Interfaces.java; with java.awt.Graphics; use java.awt.Graphics; - needed for overriding paint with java.awt.Rectangle: use java.awt.Rectangle; with java.awt.Color; use java.awt.Color; with NYI; use NYI; with Names; use Names: package Unit is type Unit_Obj is new Rectangle_Obj with record Selected : Boolean := False; Kind : Names.Enemy_Kinds; end record; type Unit_Ptr is access all Unit_Obj; function new_Unit(Kind : Names.Enemy_Kinds; x : integer; y : integer; Obj : Unit_Ptr := null) return Unit_Ptr; pragma Convention(Java_Constructor, new_Unit); procedure paint (This : access Unit_Obj; This_Color : Color_Ptr; G : Graphics_ptr); - use to draw Unit in frame function mouseUp(Obj : access Unit_Obj; evt : Event_Ptr; x : Integer; y : Integer) return Boolean; - convenience function called when mouse is released inside a unit - called from map's handleEvent() procedure highlight (This : access Unit_Obj); - toggles the selection state - causes paint to draw an outset rectangle in black 1 pixel - called when mouseUp happens end Unit:

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Appendix B - Server Software Source Code Listings with Battlefield; -- Stores current battlefield data with AirSensor; -- remote observation sensor with Satellite; -- remote observation sensor with GroundSensor; -- remote observation sensor with Ada.Text_IO; use Ada.Text_IO; with Socket; -- Socket constants and functions with Ada_In; -- Internet Socket constants and functions with Interfaces.C; with Interfaces.C.Strings; with Errno; -- provides socket error messages with Ada Unchecked_Conversion; with Ada.Characters.Latin_1; -- to obtain the NL/LF character 16#10# with Sensor_Servers; with Sensor_Server_List; with Block_SIGPIPE; with Handle_SIGINT: -- to allow graceful shutdown on ^C procedure Main is use type Interfaces.C.Int; use type Battlefield.Target; package C renames Interfaces.C; --Converts Internet style address to 'generic' socket address function To_Sockaddr is new Ada.Unchecked_Conversion (Ada_In.Sockaddr_In, Socket.Sockaddr); --Socket will be bound to the local port : C.Unsigned_Short := 1050; Local_Port : C.Int; -- Socket created locally The_Socket Client_Socket : C.Int; -- Socket connection from client --Variables for Internet to 'generic' address conversion : Ada_In.Sockaddr_In; Temp_Address : Socket.Sockaddr_ptr; The Address : C.Int :=10;--Maximum number of Clients that will MaxClients --be accepted for socket connection in one execution of program One : Socket.const_char_ptr := new C.Signed_Char'(1); SSL : Sensor_Server_List.Sensor_Server_List_Obj; begin Put_Line("Main is Running!!!"); Put_Line("Creating Socket!!!"); The_Socket := Socket.Socket(Socket.AF_Inet, Socket.Sock_Stream, 0); Put_Line("Socket Number: " & C.Int'Image(The_Socket)); if Socket.setsockopt(s => The_Socket, level => Socket.SOL_SOCKET, optname => Socket.SO_REUSEADDR, optval ⇒ One, optlen => 4) = -1 then Put_Line("setsockopt Failed!!! with Error No: "& C.unsigned'image(C.Unsigned((Errno.Get_Errno)))); Errno.perror(C.Strings.New_String("setsockopt")); raise Program_Error; end if: --Create Adress to bind to Socket Temp_Address.Sin_Family := C.Short(Socket.Af_Inet); Temp_Address.Sin_Addr.S_Addr := C.Unsigned_Long(Ada_In.Inaddr_Any); Temp_Address.Sin_Fort := Ada_In.htons(Local_Port); The_Address := new Socket.Sockaddr'(To_Sockaddr(Temp_Address)); Put_Line("Binding to Address"); if Socket.Bind(The_Socket, The_Address, 16) /= -1 then Put_Line('Bind Successful!!'); else Put_Line("Bind Failed!!!"); Errno.perror(C.Strings.New_String("Bind")); raise Program_Error; end if: -begin listening for socket connections if Socket.Listen(The_Socket, MaxClients) /=-1 then Put_Line("Server Listening!!"); etse Put_Line("Listen Failed!!!");

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--Start Sensors Airsensor. Init: GroundSensor.Init: Satellite.Init; select Handle_SIGINT.SIGINT_Handler.Interrupted; New_Line; Put_Line("Received a ^C. Beginning Shutdown of Servers"); Ada.Text_IO.Flush; -- if received ^c, then shutdown all servers & tasks gracefully Put_Line("Shutting Down Air Sensor"); Ada.Text_IO.Flush; Airsensor.Finish; Put_Line("Shutting Down Ground Sensor"); Ada.Text_IO.Flush; Groundsensor.Finish; Put_Line("Shutting Down Satellite Sensor"); Ada.Text_IO.Flush; Satellite.Finish; Put_Line("All Sensors Shut Down. Now Killing Server Tasks"); Ada.Text_IO.Flush; Sensor_Server_List.Close_All(SSL); Put_Line("Program Terminating Normally"); Ada.Text_IO.Flush; then abort --put into loop and spawn new task and add to list 1000 Ada.Text_IO.Flush; Client_Socket := Socket.Ada_Accept(The_Socket, null, 0); Ada.Text_IO.Flush; if Client_Socket /= -1 then Ada.Text_IO.Flush; Put_Line("Connection Accepted(!"); Put Line ("Spawning new task for socket " & C.Int'Image (Client_Socket)); Sensor_Server_List.Add (To_List => SSL, Item => new Sensor_Servers.Sensor_Server(Client_Socket)); olse Ada.Text_10.Flush; Put Line("Connection Error on Accept!!"); Errno.perror(C.Strings.New_String("Accept")); end if; end loop; end select; --exit if ^c trapped exception when Others => Put_Line("Shutting Down Air Sensor"): Ada.Text_IO.Flush; Airsensor.Finish; Put_Line("Shutting Down Ground Sensor"); Ada.Text_IO.Flush; Groundsensor.Finish; Put_Line('Shutting Down Satellite Sensor'); Ada.Text_IO.Flush; Satellite.Finish; Put_Line("All Sensors Shut Down. Now Killing Server Tasks"); Ada. Text_IO.Flush; Sensor_Server_List.Close_All(SSL); Put_Line("Program Terminating Hormally"); Ada.Text_IO.Flush; end Main;

Errno.perror(C.Strings.New_String("Listen"));

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end if:

--Initialize Battlefield

Battlefield.Init;

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