Big Data Analytics for Smart Cities: The H2020 CLASS Project

Eduardo Quiñones

Barcelona Supercomputing Center Barcelona, Spain eduardo.quinones@bsc.es

Ana Juan Ferrer

Atos Research Barcelona, Spain ana.juanf@atos.net

Marko Bertogna University of Modena

University of Modena Modena, Italy marko.bertogna@unimore.it

Luca Chiantore

City of Modena Modena, Italy luca.chiantore@comune.modena.

it

Erez Hadad IBM Research - Haifa Haifa, Israel erezh@il.ibm.com

Alfredo Reboa

Maserati Modena, Italy alfredo.reboa@arproject.com

CCS CONCEPTS

- Computer systems organization \to Cloud computing; Embedded systems; Software and its engineering
- \rightarrow Real-time schedulability; \bullet Theory of computation
- → MapReduce algorithms;

1 INTRODUCTION

Applying big-data technologies to field applications has resulted in several new needs. First, processing data across a compute continuum spanning from cloud to edge to devices, with varying capacity, architecture etc. Second, some computations need to be made predictable (real-time response), thus supporting both data-in-motion processing and larger-scale data-at-rest processing. Last, employing an event-driven programming model that supports mixing different APIs and models, such as Map/Reduce, CEP, sequential code, etc.

2 THE H2020 CLASS PROJECT

CLASS aims to create a platform that allows users to develop and execute their applications efficiently. At the resource level, fog[3] principles are applied, of distributing computation across the continuum using COMPSs [1], and taking decisions closer to the data origin to reduce communication. On the edge, new embedded architectures (e.g., GPUs, manycore) are used. On the cloud side CLASS aims to maximize throughput while maintaining latency requirements. Last, CLASS aims to explore a serverless polyglot event-driven platform of Apache OpenWhisk [2] and extend it with real-time requirements, both for analytics foundation and for the programming model.

3 SMART CITY USE-CASE

CLASS software will be evaluated in the *Modena Automotive Smart Area* (MASA), a real urban laboratory in Modena,

Italy, equipped with sensors, cellular and optic connectivity. Maserati provides prototypes of highly-connected cars with sensors, such as radars. The use-case consists of the following set of CLASS applications:

- Intelligent traffic management, dynamically controlling traffic lights and smart road signals based on traffic conditions, e.g., to reduce fuel consumption and providing "green routes" for emergency vehicles.
- Advanced driving assistance providing obstacle avoidance, dynamic path/route planning and parking assistance.

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