## A NOTE ON TREE MEDIANS

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# ABSTRACT

The median invariance property of trees is described in this paper. Tree structures that are weighted ( nonnegative edge weights ) and unweighted ( unit edge weights ) are considered. It is established that the location of median(s) in trees is an invariant with respect to the weights on each tree edge and that the median of a tree T is the same if the tree T were weighted or unweighted.

#### I. Introduction

Network location deals with the problem of selecting one node of a network that optimizes some functions which are distance-dependent with respect to all other nodes of the network. These problems include the location of centers and medians of networks[3]. A node v of a connected graph G(V,E) is a central node if its distance to any other node in G is a minimum. The center of a graph is the set of all central nodes. The *status* of a node v in G(V,E) is the sum of distances from v to every other node in G. The median of a graph G is the set of nodes with minimum status.

With respect to facility location, the center of a network optimizes the distance to/from every other node in the network whereas the median optimizes the total distance traversed from every other node. Network location theory and problems have been discussed in great detail by Handler and Mirchandani[1]. A number of interesting results are summarized in [2,3].

In this paper, we present the median invariance property of trees. We consider median location on unweighted trees and weighted trees (trees with a nonnegative weight assigned to each tree edge) and show that the median of a tree is invariant with respect to the weights on each edge. In other words, the median of a tree T is the same if T were weighted or unweighted. The same property however, is not true for tree centers as their location in a tree is sensitive to the edge weights.

The median property is illustrated in figures 1a and 1b. The numbers marked next to each node indicate the node status. The numbers along each edge denote the edge weights in figure 1b. The median is marked by a solid circle.

The notations and definitions are described in the following section. The main result and relevent



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previous results are described in section III. The results and their significance are summarized in the section on conclusions.







Figure 1b.

έ.

### **II.** Notations and Definitions

Let T(V,E) denote an unweighted tree and let  $T_w(V,E)$  denote a weighted tree that is otherwise identical to T. By weighted, we imply a nonnegative number w(u,v) associated with each edge  $(u,v) \in E(T_w)$ . In this paper, we explicitly refer to  $T_w$  whenever necessary, otherwise we refer to the tree T in general. The distance d(u,v) denotes the length of the shortest path between nodes u and v. The status  $S_u$  of a node u in T is the sum of distances from v to every other node in T or  $T_w$ .

$$S_u = \sum_{v \in V(T)} d(u, v)$$

A node  $x \in V(T)$  (or  $\in V(T_w)$ ) is a median if  $S_x$  is the minimum over all nodes. Let  $(u,v) \in E$ , then T(u,v) refers to the subtree of T rooted at v containing the node u. Let N(u) represent the set of neighbors of the node u.

#### **III.Median Invariance**

We summarize relevent results in this section and present the main result. It is known that every tree has one two medians in a tree and if there are two medians, then they must be neighbors [3].

The following theorem relates the status of neighboring nodes to the number of nodes in the subtrees that includes each of them. We present the theorem and proof for the general case of weighted trees which is an extension of a similar result described in [4,5].

#### Theorem 1.:

Let i,j be two distinct, adjacent nodes in  $T_w$ . Then,  $S_i = S_j + w(i,j) [|V(T(j,i))| - |V(T(i,j))|]$ . **Proof:** 

By definition of  $S_i$ , we have,

$$S_i = \sum_{k \in V(T)} d(i,k) =$$

$$\sum_{k \in V(T(i,j)) - \{i\}} d(i,k) + \sum_{k \in V(T(j,i)) - \{i\}} d(i,k)$$
However, V(T) = V(T(i,j)) UV(T(j,i)) - {i,j}.

$$d(i,k) = \begin{cases} d(j,k) + w(i,j) & \text{for } k \in V(T(j,i)) - \{i\} \\ d(j,k) - w(i,j) & \text{for } k \in V(T(i,j)) - \{j\} \end{cases}$$

Hence, 
$$S_i = \sum_{k \in V(T(i,j)) - \{i\}} d(j,k) + w(i,j) [|V(T(j,i))| - 1] + \sum_{k \in V(T(j,i)) - \{i\}} d(j,k) - w(i,j) [|V(T(i,j))| - 1]$$

$$= S_j + w(i, j) [[V(T(j, i))] - [V(T(i, j))]].$$

Hence, the lemma holds.

## Theorem 2:

Median location in a tree is independent of edge weights.

## **Proof:**

Suppose  $v_x$  is a median in T and  $v_y$  in  $T_w$ , and that  $v_x \neq v_y$ . If  $v_x \in N(v_y)$ , then there exists a path  $P = v_y$ ,  $v_{i1}$ ,  $v_{i2}$ , ...,  $v_{ik}$ ,  $v_x$ , k > 0, between  $v_y$  and  $v_x$ .

Since  $v_x$  and  $v_y$  are medians in T and  $T_w$  respectively, it is clear that

$$S_{v_x} \le S_{v_{at}} < \dots < S_{v_y} \text{ in T and,}$$
$$S_{v_y} \le S_{v_{at}} < S_{v_{at}} < \dots < S_{v_x}, \text{ in } T_w$$

This implies that  $S_{v_x} > S_{v_k}$  in T, and  $S_{v_x} \le S_{v_k}$ in  $T_w$ ; a contradiction from theorem 1 since  $S_{v_x} = S_{v_k} + w(v_x, v_{ik})[|\nabla(T(v_{ik}, v_x))| - |\nabla(T(v_x, v_{ik}))|]$ and  $w(v_x, v_{ik}) > 0$ .

If  $v_x$  and  $v_y$  are neighbors, then both must be the medians of T and  $T_w$  or else the above contradiction holds.  $\Box$ .

### **Conclusion:**

The property of median invariance is of significance in communication networks . besides others. In a communication network, the cost of communication between a pair of nodes depends upon several factors such as the distance between them, link reliability, and bandwidth. As such, they are generally represented as edge weighted graphs. The location of centers and medians is important in communication networks for optimizing network activities. There are several sequential and distributed algorithms for determining centers medians for both weighted and and unweighted graphs representing the network.

The median invariance property of trees suggests that a median finding algorithm in such a network can ignore the edge weights and simply treat the tree as unweighted.

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