On Syntax-Directed Transduction and Tree Transducers
by
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## SUMMARY

Several topics of theoretical and practical importance to the field of translator writing systems are presented in this paper. These are
(1). implementation of generalized syntaxdirected transduction (GSDT) on a finitestate tree transducer;
(2). implementation of GSDI on a tree-walking pushdown store transducer;
(3). transformation of the context-free grammar underlying a GSDT and the resulting transformation of the transduction elements of that GSDT;
(4). tree transduction of parse trees between equivalent context-free grammars.

## 1. Introduction

Studies of theoretical models of the translation of computer programming languages have led to a better understanding of the nature and design of the compilation process. The study of syntax-directed transduction [1, 2] has been particularly fruitful in this respect. Models of transformational grammar such as tree transductions [3] have related uses.

The following topics are covered in this paper:
(1) relation between generalized syntaxdirected transduction (GSDT) and tree transduction;
(2) implementation of GSDT on a tree-walking pushdown store transducer;
(3) transformation of the context-free granmar underlying a GSDT and the resulting transformation of the transduction elements of that GSDT;
(4) tree transductions of parse trees between equivalent context-free grammars.

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2. Definitions and Notation

A context-free grammar is a system $G=\left(V_{N}, V_{T}, P, S\right)$, where $V_{N}$ and $V_{T}$ are respectively the nonterminal and terminal alphabets, $S \in V_{N}$ is the distinguished symbol, and $P$, the set of productions, is a finite subset of $\mathrm{V}_{\mathrm{N}} \times \mathrm{V}^{*}$. The symbol $\Phi$ denotes the empty set, and $\lambda$ denotes the null string. When $x$ is a string, $\lg (x)$ denotes the length of $x$; $\lg (\lambda)=0$.

A stratified alphabet is a pair ( $\Sigma, r$ ), where $\Sigma$ is a finite, nonempty set of symbols and $r: \Sigma \rightarrow\{0,1,2, \ldots\}$ associates a non-negative integer with each element of $\Sigma$. The function $r$ partitions $\Sigma$ into a finite number of subsets $\Sigma_{0}, \Sigma_{1}, \ldots, \Sigma_{k}$, where $\Sigma_{i}=\{\sigma \varepsilon \Sigma \mid r(\sigma)=1\}$. Often only $\Sigma$ will denote a stratified alphabet, $r$ being understood. The set of trees $\mathrm{T}_{\Sigma}$ generated
by a stratified alphabet $\Sigma$ is defined inductively as the smallest set containing $\Sigma_{0}$ and such that whenever $\sigma \in \Sigma_{n}$ and $t_{0}, t_{1}, \ldots$, $t_{n-1} \varepsilon T_{\Sigma}$, then $\sigma\left(t_{0} t_{1} \ldots t_{n-1}\right) \in T_{\Sigma}$. It is convenient to introduce variable leaf labels for trees, and this is done following Rounds [3]. Let $A$ be a set. The set of trees $T_{\Sigma}(A)$, where
$\Sigma$ is a stratified alphabet, is the smallest set containing $\Sigma_{0} \cup A$ and such that whenever
$\sigma \varepsilon \Sigma_{n}$ and $t_{0}, t_{1}, \ldots, t_{n-1} \varepsilon T_{\Sigma}(A)$, then $\sigma\left(t_{0} t_{1} \ldots t_{n-1}\right) \varepsilon T_{\Sigma}(A)$. Thus $T_{\Sigma}=T_{\Sigma}(\Phi)=$ $T_{\Sigma}\left(\Sigma_{0}\right)$. When $t$ is a tree, $\|t\|_{C}$ is the string composed of a left-to-right concatenation of the leaf labels of $t$.

$$
\begin{aligned}
& A= A \text { tree } \frac{\text { transducer }}{}(T T) \text { is a system } \\
&\left.Q=X, \delta, Q_{0}, F\right), \text { where } \\
&=\text { finite, nonempty set of states }
\end{aligned}
$$

$\Sigma=$ stratified alphabet
$X=$ set of variables
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$q_{0} \in Q$ is the initial state
$F \subseteq Q$ is the set of final states
$\delta$, the direct transition function, is in its most general form, a mapping of $T_{\Sigma}\left(Q \times T_{\Sigma}\right.$ ( $\left.\left\{x_{0}, x_{1}, \ldots, x_{k-1}\right\}\right)$ ) into the finite subsets of $\mathrm{T}_{\Sigma}\left(\mathrm{Q} \times \mathrm{T}_{\Sigma}\left(\left\{\mathrm{x}_{0}, \mathrm{x}_{1}, \ldots, \mathrm{x}_{\mathrm{k}-1}\right\}\right)\right)$, where $\mathrm{x}_{0}, \mathrm{x}_{1}, \ldots$, $x_{k-1} \in X$. In general tree transducers can operate nondeterministically, although only deterministic ones will be used here. Certain restrictions can be placed on the direct transition function:
(1). If $\delta: Q \times\left\{\sigma\left(x_{0} x_{1} \ldots x_{k-1}\right)\right\} \rightarrow T_{\Sigma}$
( $\mathrm{Q} \times\left\{\mathrm{x}_{0}, \mathrm{x}_{1}, \ldots, \mathrm{x}_{\mathrm{k}-1}\right\}$ ), where
$\sigma \in \Sigma_{k}$, then $A=\left(Q, \Sigma, X, q_{0}, F\right)$ is a
(deterministic) finite-state tree transducer ( FSTIT ).
(2). If $\delta: Q \times\left\{\sigma\left(x_{0} x_{1} \ldots x_{k-1}\right)\right\} \rightarrow T_{\Sigma}$
$\left.\left(\left\{x_{0}, x_{1}, \ldots, x_{k-1}\right\}\right)\right)$, then $A=(Q, \Sigma, x$, $\left.q_{0}, F\right)$ is called a context-free tree transducer.
These tree transducers are almost the same as Rounds' tree grammars [3], except that a transition function rather than tree rewriting rules is used, and the set of trees accepted (and transduced) by the device may be infinite. Viewing the components of $\delta$ as tree rewriting rules, the tree transducers opeate in the same manner as the tree grammars of Rounds [3].

An instantaneous description (ID) of a tree transducer is a representation of the partially transformed input tree plus the state symbols labeling the roots of its subtrees, i.e., an element of $\mathrm{T}_{\Sigma}\left(\mathrm{Q} \times \mathrm{T}_{\Sigma}(\Phi)\right)$. Informally, an atomic move $F_{\bar{A}}$ of a tree transducer A relates two ID's separated by a single direct transition. The set $Y(A)$ of trees accepted by a finitestate tree transducer $\bar{A}=\left(Q, \Sigma, X, q_{0}, F\right)$ is

$$
\begin{aligned}
& Y(A)=\left\{x \in T_{\Sigma}(\Phi) \mid\left(q_{0}, x\right) \vdash^{*} y, y \in T_{\Sigma}\right. \\
& \left.\quad\left(F \times \Sigma_{0}\right)\right\} .
\end{aligned}
$$

Final states will not come into play in this paper, but are included here for completeness. The set $Z(A)$ of trees output by a finite-state tree transducer $A=\left(Q, \Sigma, X, q_{0}, F\right)$ is just the set of accepting ID's of $A$, i.e.,

$$
\begin{aligned}
& Z(A)=\left\{y \varepsilon T_{\Sigma}\left(F \times \Sigma_{0}\right) \mid\left(a_{0}, x\right) \stackrel{\vdash_{A}^{*}}{y}\right. \\
& x \in Y(A)\} .
\end{aligned}
$$

A generalized syntax-directed transduction (GSDI) [2] is a system $G_{t}=(G, \Gamma, \overline{\Delta, R) \text {, where }}$ $\mathrm{G}=\left(\mathrm{V}_{\mathrm{N}}, \mathrm{V}_{\mathrm{T}}, \mathrm{P}, \mathrm{S}\right)$ is a context-free grammar; $\Gamma$ is a finite, nonempty set of translation symbols of the form $t_{j}(A), A \varepsilon \bar{V}_{N}-\{S\}$, plus the symbol $t_{1}(S)$;
$\Delta=$ output alphabet
$R: P \rightarrow$ finite subsets of $(\Gamma \cup \Delta)$ *, such that if
$h_{0} B_{1} h_{1} B_{2} \ldots h_{m-1}{ }^{B_{m}} h_{m} \varepsilon R\left(C+g_{0} A_{1} g_{1} A_{2} \ldots g_{n-1}\right.$
$A_{n} g_{n}$ ),
then $g_{1} \varepsilon V_{T^{*}}{ }^{*}, h_{1} \varepsilon \Delta^{*}, A_{i} \in V_{N}, B_{i} \in \Gamma$, where the $B_{i}$ are of the form $t_{j}(A), A \varepsilon$ $\left\{A_{1}, A_{2}, \ldots, A_{n}\right\}$. Implying an ordering on the elements of $R(A \rightarrow x)=\left\{y_{1}, \ldots, y_{k}\right\}$, the notation used in [2] and here is

$$
\begin{array}{ll}
A \rightarrow x \quad t_{1}(A) & =y_{1} \\
t_{2}(A) & =y_{2} \\
t_{k}(A) & =y_{k}
\end{array}
$$

where $y_{1}, y_{2}, \ldots, y_{k}$ are the transduction elements associated with $A \rightarrow x$. The translation induced by $G_{t}=(G, \Gamma, \Delta, R)$ is a mapping
$t: L(G) \rightarrow$ subsets of $\Delta^{*}$.

## 3. GSDT's and Finite-State Tree Iransducers

Theorem 1
Corresponding to each GSDT $G_{\mathrm{t}}=(G, \Gamma, \Delta$,
R) there exists a deterministic FSTT A such that $\| Z(A)| |_{C}=t(L(G))$.
Proof:
Let $G_{t}=(G, \Gamma, \Delta, R)$ be the given GSDT, where $G=\left(V_{N}, V_{T}, P, S\right)$. Let
$P=\left\{P_{1}, P_{2}, \ldots, P_{n}\right\}$, and form
$\overline{\mathrm{P}}=\left\{\overline{\mathrm{P}}_{11}, \overline{\mathrm{P}}_{12}, \ldots, \overline{\mathrm{P}}_{1 k_{1}}\right.$,
$\bar{P}_{21}, \bar{P}_{22}, \ldots, \overline{\mathrm{P}}_{2 k_{2}}$,
$\left.\bar{P}_{n l}, \bar{P}_{n 2}, \ldots, \bar{P}_{n k}\right\}$,
where $k_{1}$ is the number of transduction elements associated with $P_{i}$.
Let

$$
p=\max _{t_{j}(A) \varepsilon \Gamma}(j) \quad \max _{i}\left(k_{i}\right)
$$

construct the FSTT $A=\left(\left\{q_{1}, \ldots, q_{p}\right\} \times V_{N}\right.$, $P \cup \bar{P} \cup V_{T} \cup\{\lambda\} \cup \Delta,\left\{x_{0}, x_{1}, \ldots\right\}$, $\left.\delta,\left[q_{1}, S\right], \Phi\right)$.

The stratified alphabet $P \cup \bar{P} \cup V_{T} \cup\{\lambda\} \cup \Delta$ is partitioned as follows:
$\Sigma_{0}=V_{T} \cup\{\lambda\} \cup \Delta$
$\Sigma-\Sigma_{0}=P \cup \bar{P}$, where
$r\left(P_{i}\right)=r(A \rightarrow x)=\max (1, \lg (x))$, where
$P_{1}=A+x$ is the i-th production;
$r\left(\bar{P}_{i j}\right)=\max \left(1, \lg \left(y_{j}\right)\right)$, where $P_{i}=A \rightarrow x$ and

$$
t_{f}(A)=y_{f}
$$

To construct $\delta$, let, for each production
$P_{1}=A \rightarrow g_{0} A_{1} g_{1} \cdots g_{n-1} A_{n} g_{n}$ in $P$, the $j$-th
translation of $A$ be $t_{j}(A)=h_{0} B_{1} h_{1} \cdots h_{m-1} B_{m} h_{m}$.
Corresponding to the above, include in $\delta$ the transition

$$
\begin{aligned}
& \delta\left(\left[q_{j}, A\right], P_{1}\left(x_{0} x_{1} \cdots x_{k-1}\right)\right)= \\
& \quad \bar{P}_{1 j}\left(h_{0}\left(\left[q_{j_{1}}, A_{k_{1}}\right], x_{\ell_{1}}\right) h_{1}\left(\left[q_{j_{2}}, A_{k_{2}}\right], x_{L_{2}}\right) \ldots\right. \\
& \left.\quad h_{m-1}\left(\left[q_{j_{m}}, A_{k_{m}}\right], x_{l_{2}}\right) h_{m}\right),
\end{aligned}
$$

where if $B_{i}=t_{r}\left(A_{s}\right)$, then

$$
\begin{aligned}
& j_{1}=r \\
& k_{i}=\max \left(1, \lg \left(g_{0} A_{1} g_{1} \cdots g_{S-1} A_{s}\right)-1\right) \\
& \ell_{1}=s
\end{aligned}
$$

The translation of the input tree by the FSTT corresponds to the "top-to-bottom" interpretation of the corresponding GSDT along the lines suggested by Lewis and Stearns [1]. The states of the FSIT act as "marks" which pass through the tree, directing the translation in the same manner as the tree grammars of [3]. Once this and the above construction are understood, the proof becomes straightforward without additional details.

## Example 1

The GSDT in Example 3.1 of [2] is implicitly defined by

$$
\begin{aligned}
& \text { 1. } S+A \quad t_{1}(S)=t_{2}(A) c t_{1}(A) \\
& \text { 2. } A+a A \quad t_{1}(A)=t_{2}(A) c t_{1}(A) \\
& t_{2}(A)=a t_{2}(A) \\
& \text { 3. } A \rightarrow B A \quad t_{1}(A)=t_{2}(A) c t_{1}(A) \\
& t_{2}(A)=b t_{2}(A) \\
& \text { 4. } A \rightarrow a \quad t_{1}(A)=\lambda \\
& t_{2}(A)=a \\
& \text { 5. } \mathrm{A} \rightarrow \mathrm{~b} \quad \mathrm{t}_{1}(\mathrm{~A})=\lambda \\
& t_{2}(A)=b
\end{aligned}
$$

This GSDT produces, for each $w \in\{a, b\}^{+}$, a string composed of the suffixes of $w$ separated by c's. The corresponding FSTT is

$$
A=\left(\left\{a_{1}, q_{\phi}\right\} \times\{S, A\}, \Sigma,\left\{x_{0}, x_{1}\right\}, \delta,\left[a_{1}, S\right],\right.
$$

where

$$
\begin{aligned}
& \Sigma=\left\{P_{1}, \ldots, P_{5}, \bar{P}_{11}, \bar{P}_{21}, \bar{P}_{22}, \ldots, \bar{P}_{51}, \bar{P}_{52}\right\} \text { and } \\
& \delta \delta \text { consists of } \\
& \delta\left(\left[q_{1}, S\right], P_{1}\left(x_{0}\right)\right)= \bar{P}_{11}\left(\left(\left[q_{2}, A\right], x_{0}\right) c\right. \\
&\left.\left(\left[q_{1}, A\right], x_{0}\right)\right) \\
& \delta\left(\left[q_{1}, A\right], P_{2}\left(x_{0} x_{1}\right)\right)= \bar{P}_{21}\left(\left(\left[q_{2}, A\right], x_{1}\right) c\right. \\
&\left.\left(\left[q_{1}, A\right], x_{1}\right)\right) \\
& \delta\left(\left[q_{2}, A\right], P_{2}\left(x_{0} x_{1}\right)\right)= \bar{P}_{22}\left(a\left(\left[q_{2}, A\right], x_{1}\right)\right) \\
& \delta\left(\left[a_{1}, A\right], P_{3}\left(x_{0} x_{1}\right)\right)= \bar{P}_{31}\left(\left(\left[q_{2}, A\right], x_{1}\right) c\right. \\
&\left.\left(\left[q_{1}, A\right], x_{1}\right)\right) \\
& \delta\left(\left[q_{2}, A\right], P_{3}\left(x_{0} x_{1}\right)\right)= \bar{P}_{32}\left(b\left(\left[q_{2}, A\right], x_{1}\right)\right) \\
& \delta\left(\left[q_{1}, A\right], P_{4}\left(x_{0}\right)\right)= \bar{P}_{41}(\lambda) \\
& \delta\left(\left[q_{2}, A\right], P_{4}\left(x_{0}\right)\right)=\bar{P}_{42}(a) \\
& \delta\left(\left[q_{1}, A\right], P_{5}\left(x_{0}\right)\right)=P_{51}(\lambda) \\
& \delta\left(\left[q_{2}, A\right], P_{5}\left(x_{0}\right)\right)=\bar{P}_{52}(b)
\end{aligned}
$$

## Theorem 2 (Rounds [3])

Deterministic finite-state tree transductions are effectively closed under composition. Immediately from theorems 1 and 2 we have

## Corollary

GSDI's are effectively closed under composition.

## 4. Tree-Walking Pushdown Store Transducers

A tree-walking pushdown store transducer
(TPDT) is a system $A=\left(Q, G, \Gamma, \Delta, \delta, q_{0}\right.$, $\left.Z_{0}, F\right)$, where
$Q=$ finite, nonempty set of states
$G=\left(V_{N}, V_{T}, P, S\right)$ is a context-free grammar
$\Gamma=$ pushdown store alphabet
$\Delta=$ output alphabet
$\delta=Q \times\left(P \cup V_{T} \cup\{\lambda\}\right) \times \Gamma \rightarrow Q \times$ $\{-1,0,1, \ldots, p\} \times \Gamma^{*} \times \Delta^{*}$ is the direct transition function
$\mathrm{q}_{0} \in \mathrm{Q}$ is the initial state
$\mathrm{Z}_{0} \varepsilon \Gamma$ is the initial pushdown store symbol
$F \subseteq Q$ is the set of final states

The TPDT operates similarly to the tree automata of [2], except that a pushdown store is involved. Another view of the TPDT is a pushdown store transducer whose input is a parse tree on $G$ and whose input head executes a "two-way" movement over this tree.

The TPDT makes an atomic move as follows. If ( $p, d, w, y$ ) $\varepsilon \delta(q, A, Z)$, the TPDT is in state $q$, its input head is located at a node labeled A in the input tree, and $Z$ is the topmost symbol of the pushdown store. The TPDT then changes to state $p$, replaces $Z$ by $w$, outputs y , and moves its input head in direction d. If $\mathrm{d}=0$, no head movement is made. If $\mathrm{d}=-1$, the head moves to the ancestor of the node where it previously resided. If d $=1$, $i>0$, the head moves to the i-th descendent of the node previously read. The symbols of $w$, read left-to-right, are the topmost symbols of the pushdown store read top-to-bottom.

## Theorem 3

Each GSDT can be implemented on a one-state, deterministic TPDT.

## Proof:

Let $G_{t}=(G, \Gamma, \Delta, R), G=\left(V_{N}, V_{T}, P, S\right)$ be the given GSDT. A one-state, deterministic TPDT will be constructed that simulates a preorder traversal [4] of the output tree corresponding to the given GSDT, as if it were implemented on a FSITT. As the leaves of this output tree are "visited," their labels are output by the TPDI. Construct
$A=(\{q\}, G, \Gamma \times\{1,2, \ldots, p\}, \Delta, \delta, q$, $\left.\left[t_{1}(S), 1\right], \Phi\right)$, where
$p=1+$ maximum value of $m$ attained in a
transduction element $h_{0} B_{1} h_{1} \cdots h_{m-1} B_{m} h_{m}$.
Let $P=\left\{P_{1}, P_{2}, \ldots, P_{k}\right\}$. The transition
function $\delta$ is constructed as follows. Let

$$
P_{i}=A+g_{0} A_{1} g_{1} \cdots g_{n-1} A_{n} g_{n},
$$

and let the j -th transduction element associated with this production be

$$
t_{j}(A)=h_{0} B_{1} h_{1} \cdots h_{m-1} B_{m} h_{m}
$$

Corresponding to the above, include in $\delta$ the transitions
$\begin{aligned} & \delta\left(q, P_{i},\left[t_{j}(A), 1\right]\right)=\left(a, 1_{1},\left[B_{1}, 1\right]\left[t_{j}(A), 2\right], h_{0}\right) \\ & \delta\left(a, P_{i},\left[t_{j}(A), 2\right]\right)=\left(q, 1_{2},\left[B_{2}, 1\right]\left[t_{j}(A), 3\right], h_{1}\right) \\ & \vdots \\ & \delta\left(q, P_{i},\left[t_{j}(A), m\right]\right)=\left(q, 1_{m},\left[B_{m}, 1\right]\left[t_{j}(A), m+1\right],\right. \\ &\left.h_{m-1}\right)\end{aligned}$
$\delta\left(q, P_{i},\left[t_{j}(A), m+1\right]\right)=\left(q,-1, \lambda, h_{m}\right)$.
If $B_{r}=t_{v}\left(A_{\ell}\right)$, then $i_{r}=\lg \left(g_{0} A_{1} g_{1} \cdots g_{\ell-1} A_{\ell}\right)$.

The above transitions break up the computation of $t_{j}(A)$ into $m+1$ "phases":

1. Output $h_{0}$; compute $B_{1}$;
m. Output $h_{m-1}$; compute $B_{m}$;
$m+1$. Output $h_{m}$; return to predecessor node.
The reader can readily convince hinself that the recursively applied rules for preonder tree traversal
"visit the root;
"visit the subtrees in left-to-right order"
are indeed being applied to the output tree, and the leaves of this tree are being output in left-to-right order.

## Example 2

Let $G_{t}$ be the GSDT of Example 1. The corresponding TPDT is
$M=\left(\{q\}, G,\left\{t_{1}(S), t_{1}(A), t_{2}(A)\right\} \times\{1,2,3\}\right.$, $\left.\{\mathrm{a}, \mathrm{b}, \mathrm{c}\}, \delta, \mathrm{q},\left[\mathrm{t}_{1}(\mathrm{~S}), 1\right], \Phi\right)$, where $\delta$
consists of

```
\(\delta\left(\mathrm{a}, \mathrm{P}_{1},\left[\mathrm{t}_{1}(\mathrm{~S}), 1\right]\right)=\left(\mathrm{a}, 1,\left[\mathrm{t}_{2}(\mathrm{~A}), 1\right]\left[\mathrm{t}_{1}(\mathrm{~S}), 2\right], \lambda\right)\)
\(\delta\left(q, P_{1},\left[t_{1}(S), 2\right]\right)=\left(q, 1,\left[t_{1}(A), 1\right]\left[t_{1}(S), 3\right], c\right)\)
\(\delta\left(\square, P_{1},\left[t_{1}(S), 3\right]\right)=(q,-1, \lambda, \lambda)\)
\(\delta\left(\mathrm{q}, \mathrm{P}_{2},\left[\mathrm{t}_{1}(\mathrm{~A}), 1\right]\right)=\left(\mathrm{q}, 1,\left[\mathrm{t}_{2}(\mathrm{~A}), 1\right]\left[\mathrm{t}_{1}(\mathrm{~A}), 2\right], \lambda\right)\)
\(\delta\left(q, P_{2},\left[t_{1}(A), 2\right]\right)=\left(a, 1,\left[t_{1}(A), 1\right]\left[t_{1}(A), 3\right], c\right)\)
\(\delta\left(q, P_{2},\left[t_{1}(A), 3\right]\right)=(q,-1, \lambda, \lambda)\)
\(\delta\left(a, P_{2},\left[t_{2}(A), 1\right]\right)=\left(a, 1,\left[t_{2}(A), 1\right]\left[t_{2}(A), 2\right], a\right)\)
\(\delta\left(q, P_{2},\left[t_{2}(A), 2\right]\right)=(q,-1, \lambda, \lambda)\)
\(\delta\left(q, P_{3},\left[t_{1}(A), 1\right]\right)=\left(q, 1,\left[t_{2}(A), 1\right]\left[t_{1}(A), 2\right], \lambda\right)\)
\(\delta\left(q, P_{3},\left[t_{1}(A), 2\right]\right)=\left(q, 1,\left[t_{1}(A), 1\right]\left[t_{1}(A), 3\right], c\right)\)
\(\delta\left(q, P_{3},\left[t_{1}(A), 3\right]\right)=(q,-1, \lambda, \lambda)\)
\(\delta\left(\mathrm{a}, \mathrm{P}_{3},\left[\mathrm{t}_{2}(\mathrm{~A}), 1\right]\right)=\left(\mathrm{q}, 1,\left[\mathrm{t}_{2}(\mathrm{~A}), 1\right]\left[\mathrm{t}_{2}(\mathrm{~A}), 2\right]\right.\),
\(\delta\left(q, P_{3},\left[t_{2}(A), 2\right]\right)=(q,-1, \lambda, \lambda)\)
\(\delta\left(q, P_{4},\left[t_{1}(A), 1\right]\right)=(q,-1, \lambda, \lambda)\)
\(\delta\left(q, P_{4},\left[t_{2}(A), 1\right]\right)=(q,-1, \lambda, a)\)
\(\delta\left(q, P_{5},\left[t_{1}(A), 1\right]\right)=(q,-1, \lambda, \lambda)\)
\(\delta\left(\mathrm{q}, \mathrm{P}_{5},\left[\mathrm{t}_{2}(\mathrm{~A}), 1\right]\right)=(\mathrm{a},-1, \lambda, \mathrm{~b})\)

\section*{5. Transformations of the Grammaris} Underlying Syntax-Directed Transductions
Transforming the grammar underlying a syntax-directed transduction generally changes the transduction elements associated with the new productions. Only transformations that result in weakly equivalent grammans will be considered in this section.

\section*{(1). Substitution of Productions}

Let \(G=\left(V_{N}, V_{T}, P, S\right)\) be a context-free grammar. Let \(A \rightarrow z_{1} B z_{2} \varepsilon P, B \varepsilon V_{N}\), and let \(B \rightarrow y_{1}, i=1,2, \ldots, k\) be all the B-productions in P. Let \(G^{\prime}=\left(V_{N}, V_{N}, P^{\prime}, S\right)\), where \(P^{\prime}=\left(P-\left\{A \rightarrow z_{1} B z_{2}\right\}\right) \cup\left\{A \rightarrow z_{1} y_{i} z_{2}\right.\) ) \(1=1,2, \ldots, k\}\); clearly \(L\left(G^{1}\right)=L(G)\). Theorem 4
GSDT's are effectively closed under substitution of productions.

\section*{Proof:}

Let \(G_{t}=(G, \Gamma, \Delta, R), G=\left(V_{N}, V_{T}, P, S\right)\) be the given GSDT. Let \(A \rightarrow z_{1} \mathrm{Br}_{2}\) be the production to be deleted, via replacement of \(B\) by \(B \rightarrow y_{1}, \ldots\),
\(B \rightarrow y_{k}\). Construct \(G_{t}^{\prime}=\left(G^{\prime}, \Gamma, \Delta, R^{\prime}\right)\),
\(G^{\prime}=\left(V_{N}, V_{T}, P^{\prime}, S\right)\), where
\(P^{\prime}=\left(P-\left\{A \rightarrow z_{1} B z_{2}\right\}\right) \cup\left\{A \rightarrow z_{1} y_{1} z_{2} \mid\right.\)
\(1=1,2, \ldots, k\}\).
To construct \(R^{\prime}\), define homomorphisms \(h_{1}\) :
\((\Gamma \cup \Delta)^{*} \rightarrow(\Gamma \cup \Delta)^{*}\) such that if
\[
R\left(B \rightarrow y_{i}\right)=\left\{x_{i 1}, x_{i 2}, \ldots, x_{i k_{1}}\right\},
\]
then \(h_{i}\left(t_{j}(B)\right)=x_{1 j}, j=1,2, \ldots, k_{i}\)
\[
\begin{gathered}
h_{1}(x)=x, x \neq t_{j} \\
1 \leq j \leq k_{1} .
\end{gathered}
\]
(B) for some

Obtain \(\mathrm{R}^{\prime}\) via
\[
\begin{aligned}
& R^{\prime}(X)=X, X \in P-\left\{A \rightarrow z_{1} B z_{2}\right\} \\
& R^{\prime}(A\left.\rightarrow z_{1} y_{k} z_{2}\right)=\left\{h_{i}\left(x_{1}\right), \ldots, h_{i}\left(x_{m}\right)\right\} \\
&=h_{1}\left(R\left(A \rightarrow z_{1} B z_{2}\right)\right),
\end{aligned}
\]
where \(R\left(A \rightarrow z_{1} B z_{2}\right)=\left\{x_{1}, \ldots, x_{m}\right\}\).
Clearly \(G_{t}^{\prime}\) and \(G_{t}\) produce the same transduction. Example 3
\[
\begin{array}{ll}
S \rightarrow E & t_{1}(S)=t_{1}(E) \# t_{2}(E) \\
E \rightarrow E+T & t_{1}(E)=t_{1}(E) t_{1}(T)+ \\
& t_{2}(E)=+t_{2}(E) t_{2}(T) \\
E \rightarrow T & t_{1}(E)=t_{1}(T) \\
& t_{2}(E)=t_{2}(T) \\
T \rightarrow T^{*} a & t_{1}(T)=t_{1}(T) a^{*} \\
& t_{2}(T)=t_{2}(T) a \\
T \rightarrow a & t_{1}(T)=a \\
& t_{2}(T)=a
\end{array}
\]

Eliminating the production \(S \rightarrow E\) through substitution of \(E \rightarrow E+T\) and \(E \rightarrow T\) yields the GSDT
```

$S \rightarrow E+T \quad t_{1}(S)=t_{1}(E) t_{1}(T)+\#+t_{2}(E) t_{2}(T)$
$S \rightarrow T$
$E \rightarrow E+T$
$t_{1}(S)=t_{1}(T) \# t_{2}(T)$
$t_{1}(E)=t_{1}(E) t_{1}(T)+$
$t_{2}(E)=+t_{2}(E) t_{2}(T)$
$E \rightarrow T \quad t_{1}(E)=t_{1}(T)$
$t_{2}(E)=t_{2}(T)$
$T \rightarrow T^{*} a \quad t_{1}(T)=t_{1}(T) a^{*}$
$t_{2}(T)=*_{2}(T) a$
$T+a \quad t_{1}(T)=a$
$t_{2}(T)=a$

```

Corollary
Syntax-directed transductions (SDT's) and simple SDT's are closed under substitution of productions. Simple Polish SDT's are not closed under substitution of productions.
(2). Redefinition

Let \(G=\left(V_{N}, V_{T}, P, S\right)\) be a context-free grammar, and let \(A \rightarrow y_{1} y_{2} y_{3}\) be a production of P. Construct \(G^{\prime}=\left(V_{N} \cup\{Z\}, V_{T}, P^{\prime}, S\right)\),
where \(Z\) is a new nonterminal and
\[
\begin{aligned}
P^{\prime}= & \left(P-\left\{A \rightarrow y_{1} y_{2} y_{3}\right\}\right) \cup\left\{A \rightarrow y_{1} z_{3},\right. \\
& \left.Z \rightarrow y_{2}\right\} .
\end{aligned}
\]

Clearly \(L\left(G^{\prime}\right)=L(G)\).
Theorem 5
GSDT's are effectively closed uder redefinition.
Proof: Let \(G_{t}=(G, \Gamma, \Delta, R)\),
\(G=\left(V_{N}, V_{T}, P, S\right)\) be the given GSDT, and let \(\mathrm{A} \rightarrow \mathrm{y}_{1} \mathrm{y}_{2} \mathrm{y}_{3}\) be the production that participates in the redefinition.
Construct \(G_{t}^{\prime}=\left(G^{\prime}, \Gamma^{\prime}, \Delta, R^{\prime}\right), G^{\prime}=\)
\(\left(V_{N} \cup\{Z\}, V_{T}, P^{\prime}, S\right)\), where \(P^{\prime}=\left(P-\left\{A \rightarrow y_{1}\right.\right.\) \(\left.\left.y_{2} y_{3}\right\}\right) \cup\left\{A \rightarrow y_{1} z_{3}, z \rightarrow y_{2}\right\}\).
\(\Gamma^{\prime}\) and \(R^{\prime}\) are obtained as follows. Let \(A \rightarrow y_{1}\)
\[
y_{2} y_{3}=A \rightarrow g_{0} A_{1} g_{1} \cdots g_{n-1} A_{n} g_{n} .
\]

Let \(y_{2} \in\left(W \cup V_{T}\right)^{*}\), where \(W \leq\left\{A_{1}, A_{2}, \ldots, A_{n}\right\}\).
In particular, suppose \(W=\left\{A_{1_{1}}, \ldots, A_{1_{m}}\right\}\).
Let \(R\left(A+y_{1} y_{2} y_{3}\right)=\left\{x_{1}, x_{2}, \ldots, x_{k}\right\}\). Then
\(\begin{aligned} & R^{\prime}\left(Z \rightarrow y_{2}\right)=\left\{t_{1}\left(A_{1_{1}}\right), t_{2}\left(A_{1_{1}}\right), \ldots, t_{k_{1}}\left(A_{1_{1}}\right), \ldots\right. \\ & \vdots \\ &\left.t_{1}\left(A_{1_{m}}\right), t_{2}\left(A_{1_{m}}\right), \ldots, t_{k_{m}}\left(A_{1_{1}}\right)\right\},\end{aligned}\)
and hence \(\Gamma^{\prime}=\Gamma u\left\{t_{l}(z), \ldots, t_{\ell}(z)\right\}\), where \(\ell=k_{1}+k_{2}+\ldots+k_{m}\). Define a homomorphism
\(\mathrm{h}:(\Gamma \cup \Delta)^{*} \rightarrow\left(\Gamma^{\prime} \cup \Delta\right)^{*}\) such that

\(h(X)=X\), otherwise.
Then \(R^{\prime}\left(A+y_{1} Z y_{2}\right)=h\left(R\left(A \rightarrow y_{1} y_{2} y_{3}\right)\right)\).
\[
R^{\prime}(X)=R(X), X \varepsilon P-\left\{A+y_{1} y_{2} y_{3}\right\}
\]

The above construction is based upon the fact that in the redefinition transformation replacing \(A \rightarrow y_{1} y_{2} y_{3}\) by \(A \rightarrow y_{1} Z_{3}\) and \(Z+y_{2}\), the nonterminal \(A\) "loses control" of the translations of the nonterminals in \(y_{2}\), and must "pass them on" to Z. Careful scrutiny of the example below will convince the reader that \(G_{t}^{\prime}\) and \(G_{t}\) induce the same transduction.

\section*{Example 4}

Consider the trivial GSDT defined implicitly by
\(A \rightarrow a B a b c C D \quad t_{1}(A)=t_{2}(C) x y t_{1}(B) t_{1}(D) t_{1}(C) x_{2}(B)\)
\(B \rightarrow b\)
\[
t_{1}(B)=\lambda
\]
\[
t_{2}(B)=b
\]
\(c+c \quad t_{1}(C)=c\)
\(t_{2}(c)=\lambda\)
\(D=d \quad t_{1}(D)=d\)
Let \(y_{1}=a, y_{2}=B a b c C, y_{3}=D\). Then
\(W=\{B, C\} \subseteq\{B, C, D\}\), and the translation symbols \(t_{f}(Z), \ldots, t_{4}(Z)\) are added, where the homomorphism of the proof is
\[
\begin{aligned}
& h\left(t_{1}(B)\right)=t_{1}(Z) ; h\left(t_{2}(B)\right)=t_{2}(Z) ; \\
& h\left(t_{1}(C)\right)=t_{3}(Z) ; h\left(t_{2}(C)\right)=t_{4}(Z) ; \\
& h(X)=x, \text { otherwise. }
\end{aligned}
\]

The following GSDT results:
\(A \rightarrow a Z D \quad t_{1}(A)=t_{4}(Z) x y t_{1}(Z) t_{1}(D) t_{3}(Z) x t_{2}(Z)\)
\(Z \rightarrow B a b c C \quad t_{1}(Z)=t_{1}(B) ; t_{2}(Z)=t_{2}(B)\) \(t_{3}(Z)=t_{1}(C) ; t_{4}(Z)=t_{2}(C)\)
\(B \rightarrow b \quad t_{1}(B)=\lambda ; t_{2}(B)=b\)
\(c \rightarrow c \quad t_{1}(C)=c ; t_{2}(c)=\lambda\)
\(D \rightarrow d \quad t_{1}(D)=d\)
Corollary
GSDT's are effectively closed under transformation to Chomsky normal form.

Proof: Transformation to Chomsky normal form consists of a finite number of redefinition
transformations.

\section*{(3). Arden's Transformation}

Let \(G=\left(V_{N}, V_{T}, P, S\right)\) be a context-free grammar. Let \(A \rightarrow A \alpha_{1} i=1,2, \ldots, r\) be the left-recursive \(A\)-productions in P , and let \(A \rightarrow \beta_{1}, i=1,2, \ldots, s\) be the remaining A-productions.
Construct \(G^{\prime}=\left(V_{N} \cup\{Z\}, V_{T}, P^{\prime}, S\right)\), where
\[
\begin{aligned}
P^{\prime}= & \left(P-\left\{A+A \alpha_{1}, \ldots, A \rightarrow A \alpha_{r}\right\}\right) u \\
& \left\{A \rightarrow B_{i} Z \mid i_{1}=1,2, \ldots, s\right\} \\
& u\left\{Z \rightarrow \alpha_{i} \mid i=1,2, \ldots, r\right\} \cup\left\{Z \rightarrow \alpha_{i} Z \mid\right. \\
& 1=1,2, \ldots, r\} .
\end{aligned}
\]

Then \(L\left(G^{\prime}\right)=L(G) \quad\).

\section*{Arden's Transformation of Syntax-Directed}

\section*{Transductions}

Let \(G_{t}=(G, \Gamma, \Delta, R), G=\left(V_{N}, V_{T}, P, S\right)\) be given, where \(G_{t}\) is not a GSDT, but rather the simpler SDT of [I]. Construct \(G_{t}=\) ( \(G^{\prime}, \Gamma, \Delta, R^{\prime}\) ), where \(G^{\prime}\) is the grammar constructed above. Let \(R\left(A \rightarrow A \alpha_{i}\right)=\)
\(\left\{x_{1} A \bar{x}_{i}\right\}, i=1,2, \ldots, r\)
\(R\left(A+\beta_{1}\right)=y_{1}, 1=1,2, \ldots, s\).
Then \(R^{\prime}\left(A \rightarrow \beta_{1}\right)=R\left(A \rightarrow \beta_{1}\right), i=1,2, \ldots, s\)
\(R^{\prime}\left(A \rightarrow \beta_{1} Z\right)=\left\{t_{1}(Z) y_{1} t_{2}(Z)\right\}, 1=1\),
2, ..., s
\(R^{\prime}\left(Z \rightarrow \alpha_{1} Z\right)=\left\{t_{1}(Z) x_{1}, \bar{x}_{i} t_{2}(Z)\right\}, i=1\),
\(2, \ldots, r\)
\(R^{\prime}\left(Z \rightarrow \alpha_{i}\right)=\left\{x_{i}, \bar{x}_{1}\right\}, i=1,2, \ldots, r\) \(R^{\prime}(X)=R(X)\), all other \(X \in P^{\prime}\).
\(G_{t}^{\prime}\) and \(G_{t}\) induce the same transduction. Note that \(G_{t}^{\prime}\) is a GSDT.

\section*{Conjecture}

GSDT's are not closed under Arden's transformation or transformation to Greibach. normal form.

\section*{6. Transformations of Parse Trees}

Suppose a GSDT \(G_{t}=(G, \Gamma, \Delta, R)\) is given. Supnose further that it is more convenient to parse strings of \(L(G)\) according to grammar \(G^{\prime}\), where \(L\left(G{ }^{\dagger}\right)=L(G)\). It may not always be possible to transform \(G\) to an equivalent syntax-directed transduction of the same class. Rather than transform \(G_{t}\), the parse trees on \(G^{\prime}\) could be transformed back to their counterparts on \(G\), and \(G\) applied. A preliminery result is presented in this section.

Inverse Chomsky Normal Form
Let \(G=\left(V_{N}, V_{T}, P, S\right)\) be a context-free grarmar and \({ }_{G}{ }^{T}=\left(V_{N}^{\prime}, V_{T}, P^{\prime}, S\right)\) be a Chomsky normal form granmar such that \(L\left(G^{\prime}\right)=\) L (G). A tree transduction can be used to transform parse trees on \(G^{\prime}\) to their counterparts on G. Consider the P-production
\(P_{k}=A \rightarrow a A b B A b, A, B \in V_{N}, a, b \varepsilon V_{T}\)
and its counterparts in \(\mathrm{P}^{\prime}\)
\(P_{1}^{\prime}=A \rightarrow N_{a} X_{1}\)
\(P_{i+1}^{\prime}=X_{1} \rightarrow A X_{2}\)
\(P_{i+2}^{\prime}=X_{2} \rightarrow N_{b} X_{3}\)
\(P_{i+3}^{\prime}=X_{3}+B X_{4}\)
\(P_{i+4}=X_{4} \rightarrow A N_{b}\)
\(P_{i+5}^{\prime}=N_{a}+a\)
\(P_{i+6}=N_{b} \rightarrow b\)
The corresponding direct transitions of an Inverse Chomsky normal form general tree transduction are
\(\delta\left(\mathrm{q}, \mathrm{P}_{1+5}\left(\mathrm{x}_{0}\right)\right)=\mathrm{a}\)
\(\delta\left(q, P_{i+6}\left(x_{0}\right)\right)=b\)
\(\delta\left(q, P_{i}^{\prime}\left(x_{0} P_{i+1}^{\prime}\left(x_{1} x_{2}\right)\right)\right)=\left(q, P_{i+1}\left(x_{0} x_{1} x_{2}\right)\right)\)
\(\delta\left(q, \bar{P}_{i+1}^{i}\left(x_{0} x_{1} P_{i+2}^{\prime}\left(x_{2} x_{3}\right)\right)\right)=\left(q, \bar{P}_{i+2}^{\prime}\left(x_{0} x_{1} x_{2} x_{3}\right)\right)\)
\(\delta\left(q, \bar{P}_{i+3}\left(x_{0} x_{1} x_{2} x_{3} P_{i+4}\left(x_{4} x_{5}\right)\right)\right)=P_{k}\left(\left(q, x_{0}\right) \ldots\right.\)
( \(\mathrm{q}, \mathrm{x}_{5}\) ))
Other inverse transformations can be accomplished using tree transductions, including inverse Arden's transformation and inverse Greibach normal form. This and other work is currently being continued.

\section*{7. Conclusion}

Several topics of theoretical and practical importance to the field of translator writing systems were presented in this paper. It is instructive to note the practical difference between the two implementations of GSDT presented in Sections 3 and 4. The FSTT implementation (Section 3) results in a "program" (transition function) of moderate size, but requires a relatively complex memory management system for manipulating tree structures. On the other hand, the TPDT implementation (Section 4) requires a relatively simple memory management system, since the input tree is fixed and the output can be written into a sequential file. As payment, the TPDT requires a relatively large program.

Much more work than appears in this paper has been done [5]. The properties of a syntaxdirected transduction scheme more general than GSDI, and equivalent to the scheme of [6], have been investigated.
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