

LETTER

A Visibility-Based Upper Bound for Android Unlock Patterns*

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SUMMARY The Android pattern unlock is a popular graphical password scheme, where a user is presented a 3×3 grid and required to draw a pattern on the onscreen grid. Each pattern is a sequence of at least four contact points with some restrictions. Theoretically, the security level of unlock patterns is determined by the size of the pattern space. However, the number of possible patterns is only known for 3×3 and 4×4 grids, which was computed by brute-force enumeration. The only mathematical formula for the number of possible patterns is a permutation-based upper bound. In this article, we present an improved upper bound by counting the number of “visible” points that can be directly reached by a point.

key words: user authentication, graphical password, Android unlock patterns, upper bound

1. Introduction

To keep strangers from checking out personal information, people often lock their smartphone screens with text-based or graphical passwords. The Android pattern password has been widely used for screen lock technology in Android devices since its first introduction on Android version 1.0. To unlock a locked screen, a user needs to draw a secret pattern that connects a sequence of four or more contact points. For a 3×3 grid, there are 389,112 patterns, which can provide more choices than 5-digit PINs [1]. However, humans do not choose a pattern uniformly at random and have some bias in the pattern selection process, e.g., the upper left corner and three-point long straight lines are very typical selection strategies [2]. Hence, the entropy of patterns is rather low and to increase the security of patterns, schemes with larger grids have been proposed. For example, Cyan-LockScreen [3] allows users to select from grid sizes ranging from 3×3 to 6×6 . The largest grid that we can find in the real life is perhaps the 25×25 grid by Security Lock

Screen [4].

Whereas the practical security of unlock patterns should be evaluated by an extensive user study, the theoretical security of unlock patterns can be measured by counting the total number of possible patterns. Currently, it is known that there are 389,112 ($\approx 2^{19}$) patterns in a 3×3 grid and 4,350,069,823,024 ($\approx 2^{42}$) patterns in a 4×4 grids [5]. Note that these values were computed by brute-force enumeration because a mathematical formula for the number of patterns is not known even for the simplest case of the 3×3 grid [6]. Can we compute the number of patterns in a large grid (e.g., 10×10) by brute-force enumeration? Even a 5×5 grid is expected to have more than 2^{60} patterns and thus the brute-force enumeration does not seem to be a feasible method for calculating the size of pattern space in a large grid.

The only mathematical formula that can be applied to a large grid is a permutation-based upper bound, which simplifies the counting by ignoring an important restriction on a valid pattern; unvisited points in a valid pattern cannot be jumped over but the permutation-based upper bound allows all kinds of jumps. In this article, we present an improved upper bound by reducing the number of jumps. To refrain from jumping over unvisited points, we use the concept of visibility, i.e., the maximum number of points that are directly reachable from a point. Our numerical data show that the visibility-based upper bound outperforms the permutation-based upper bound.

2. Permutation-Based Upper Bound

In the Android pattern unlock scheme, a user can select a pattern according to the following rules [2]:

- (i) At least four points must be chosen,
- (ii) No point can be used twice,
- (iii) Only straight lines are allowed, and
- (iv) One cannot jump over points not visited before.

If we use the Cartesian coordinate system where the origin is the point at the lower left corner, a pattern p can be denoted by a sequence of points as $\langle (x_1, y_1), (x_2, y_2), \dots \rangle$. For example, the Z-shaped pattern in Fig. 1 is the sequence $\langle (0, 2), (1, 2), (2, 2), (1, 1), (0, 0), (1, 0), (2, 0) \rangle$.

Suppose the first point of a pattern p in a 3×3 grid is $(0, 0)$. Which point can be the second point of the pattern p ? If $(0, 2)$ becomes the second point, the unvisited point $(0, 1)$ must be jumped over and thus, by rule (iv), $(0, 2)$ cannot

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$\mathcal{V}((0,0);G) = 9$ in the 4×4 grid G . For the invisible point $(3,3)$ and the visible points $(1,0)$, $(3,1)$ in Fig. 2, we have $\mathcal{V}((0,0);G \setminus \{(3,3)\}) = 9$, $\mathcal{V}((0,0);G \setminus \{(1,0)\}) = 9$, and $\mathcal{V}((0,0);G \setminus \{(3,1)\}) = 8$. Because removing a (visited) point from a grid does not increase the visibility, we have

$$\mathcal{V}(G^{-i}) \leq \mathcal{V}(G^{-(i-1)}) \leq \dots \leq \mathcal{V}(G). \quad (8)$$

From Eq. (7) and Eq. (8), $\mathcal{V}(G^{-i})$ satisfies

$$\mathcal{V}(G^{-i}) \leq \min(\mathcal{V}(G), |G| - i - 1), \quad (9)$$

where $0 \leq i \leq |G| - 2$ and $\mathcal{V}(G^0) = \mathcal{V}(G)$.

Since any point can be the first point of a pattern, there are $|G|$ ways to choose the first point. The number of ways to choose the second point is bounded by $\mathcal{V}(G) = \mathcal{V}(G^0)$ and the number of ways to choose the third point is bounded by $\mathcal{V}(G^{-1})$. In general, the number of ways to choose the i th point is bounded by $\mathcal{V}(G^{-(i-2)})$. Now, we can derive the visibility-based upper bound as follows:

$$\begin{aligned} \mathcal{N}(G) &= \sum_{k=4}^{|G|} \mathcal{N}_k(G) \\ &\leq \sum_{k=4}^{|G|} |G| \cdot \mathcal{V}(G) \cdot \mathcal{V}(G^{-1}) \cdot \dots \cdot \mathcal{V}(G^{-(k-2)}) \\ &= |G| \sum_{k=4}^{|G|} \mathcal{V}(G) \cdot \mathcal{V}(G^{-1}) \cdot \dots \cdot \mathcal{V}(G^{-(k-2)}) \\ &= |G| \sum_{k=4}^{|G|} \prod_{i=0}^{k-2} \mathcal{V}(G^{-i}) \\ &\leq |G| \sum_{k=4}^{|G|} \prod_{i=0}^{k-2} \min(\mathcal{V}(G), |G| - i - 1), \end{aligned} \quad (10)$$

where the last inequality is by Eq. (9).

The computation of $\mathcal{V}(G)$ is the most time-consuming part in Eq. (10). Since $\mathcal{V}(G) = \max_{(x,y) \in G} \mathcal{V}((x,y);G)$ is the maximum value $\mathcal{V}((x,y);G)$ over the choice of $(x,y) \in G$, we first compute $\mathcal{V}((x,y);G)$ as follows.

- Compute the multiset of slopes $S = \{\frac{y'-y}{x'-x} \mid (x',y') \in G \text{ and } (x',y') \neq (x,y)\}$ where the slope of any upward (or downward) vertical line is defined by $+\infty$ (or $-\infty$)
- Sort the elements of the multiset S and leave only one instance for each slope by removing repeated instances.
- Count the (distinct) elements of S in (b).

In step (a), we compute the slopes from (x,y) . If multiple points have the same slope, only one point is visible. Therefore, we remove invisible points by removing repeated slopes in (b) and then count the number of visible points in (c). Step (a) and (c) can be done in linear time. Step (b) can be done in $O(|G| \log |G|)$ time by using merge sort or heap-sort. $\mathcal{V}(G)$ can be obtained by computing $\mathcal{V}((x,y);G)$ for each $(x,y) \in G$ and finding the maximum value. Therefore, $\mathcal{V}(G)$ can be computed in $O(|G|^2 \log |G|)$ time. In practice, $\mathcal{V}(G)$ for the largest grid of the real life (e.g., 25×25) can be

Table 1 Upper bound on the number of patterns: visibility-based vs. permutation-based.

Grid	Visibility-based	Permutation-based
3×3	9.86E+05	9.86E+05
4×4	3.60E+13	5.69E+13
5×5	1.48E+25	4.22E+25
6×6	9.24E+40	1.01E+42
7×7	1.08E+62	1.65E+63
8×8	2.99E+87	3.45E+89
9×9	5.60E+118	1.58E+121
10×10	5.68E+154	2.54E+158
11×11	3.13E+197	2.20E+201
12×12	2.18E+244	1.51E+250
13×13	1.84E+299	1.16E+305
14×14	3.45E+358	1.38E+366
15×15	4.74E+425	3.42E+433
16×16	2.61E+497	2.33E+507
17×17	1.86E+577	5.65E+587
18×18	2.50E+661	6.22E+674
19×19	2.47E+755	3.91E+768
20×20	6.90E+852	1.74E+869
21×21	2.20E+960	6.75E+976
22×22	9.17E+1071	2.77E+1091
23×23	6.37E+1192	1.45E+1213
24×24	7.52E+1317	1.16E+1342
25×25	2.55E+1454	1.67E+1478

computed less than one second with a desktop PC. Table 1 presents numerical data of upper bounds for up to 25×25 grids. Except for 3×3 grid, the visibility-based upper bound is always lower than the permutation-based upper bound.

4. Conclusion

The Android pattern unlock has been widely adopted but very little is known about the mathematical analysis of its security. Except for the “unfinished” work in [6], our upper bound is the first rigorous analysis of the theoretical security of patterns. We invite readers to the research on an exact formula or a tighter bound for the security of patterns.

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