Lecture Notes in Computer Science

4000

Commenced Publication in 1973
Founding and Former Series Editors:
Gerhard Goos, Juris Hartmanis, and Jan van Leeuwen

Editorial Board

David Hutchison

Lancaster University, UK

Takeo Kanade

Carnegie Mellon University, Pittsburgh, PA, USA

Josef Kittler

University of Surrey, Guildford, UK

Jon M. Kleinberg

Cornell University, Ithaca, NY, USA

Friedemann Mattern

ETH Zurich, Switzerland

John C. Mitchell

Stanford University, CA, USA

Moni Naor

Weizmann Institute of Science, Rehovot, Israel

Oscar Nierstrasz

University of Bern, Switzerland

C. Pandu Rangan

Indian Institute of Technology, Madras, India

Bernhard Steffen

University of Dortmund, Germany

Madhu Sudan

Massachusetts Institute of Technology, MA, USA

Demetri Terzopoulos

University of California, Los Angeles, CA, USA

Doug Tygar

University of California, Berkeley, CA, USA

Moshe Y. Vardi

Rice University, Houston, TX, USA

Gerhard Weikum

Max-Planck Institute of Computer Science, Saarbruecken, Germany

Sławomir Stańczak Marcin Wiczanowski Holger Boche

Resource Allocation in Wireless Networks

Theory and Algorithms



Authors

Sławomir Stańczak

Fraunhofer German-Sino Lab for Mobile Communications

Einsteinufer 37, 10587 Berlin, Germany

E-mail: stanczak@hhi.fhg.de

Marcin Wiczanowski

Heinrich-Hertz Chair, Faculty of EECS Technical University of Berlin

Einsteinufer 25, 10587 Berlin, Germany

E-mail: marcin.wiczanowski@tu-berlin.de

Holger Boche

Heinrich-Hertz Chair, Faculty of EECS Technical University of Berlin Einsteinufer 25, and Fraunhofer German-Sino Lab for Mobile Communications and Fraunhofer-Institute for Telecommunications, Heinrich-Hertz-Institut (HHI)

Einsteinufer 37, 10587 Berlin, Germany

E-mail: boche@hhi.fhg.de

Library of Congress Control Number: 2006934732

CR Subject Classification (1998): C.2, F, G.2.2, D.4.4

LNCS Sublibrary: SL 1 – Theoretical Computer Science and General Issues

ISSN 0302-9743

ISBN-10 3-540-46248-1 Springer Berlin Heidelberg New York ISBN-13 978-3-540-46248-4 Springer Berlin Heidelberg New York

This work is subject to copyright. All rights are reserved, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, re-use of illustrations, recitation, broadcasting, reproduction on microfilms or in any other way, and storage in data banks. Duplication of this publication or parts thereof is permitted only under the provisions of the German Copyright Law of September 9, 1965, in its current version, and permission for use must always be obtained from Springer. Violations are liable to prosecution under the German Copyright Law.

Springer is a part of Springer Science+Business Media

springer.com

© Springer-Verlag Berlin Heidelberg 2006 Printed in Germany

Typesetting: Camera-ready by author, data conversion by Markus Richter, Heidelberg Printed on acid-free paper SPIN: 11818762 06/3142 5 4 3 2 1 0



Der König hat viele Gnade für meine geringen Dienste, und das Publikum viel Nachsicht für die unbedeutenden Versuche meiner Feder; ich wünschte, dass ich einigermaßen etwas zu der Verbesserung des Geschmackes in meinem Lande, zur Ausbreitung der Wissenschaften beitragen könnte. Denn sie sind's allein, die uns mit anderen Nationen verbinden, sie sind's, die aus den entferntsten Geistern Freunde machen, und die angenehmste Vereinigung unter denen selbst erhalten, die leider durch Staatsverhältnisse öfters getrennt werden.

Clavigo, Johann Wolfgang von Goethe

Nader wiele łaski raczy mi okazywać król za moje skromne służby, publiczność zaś zbyt jest wyrozumiała dla niepozornych płodów mego pióra, byłbym wszelako szczęśliwy mogąc się nieco przyczynić do urobienia literackiego smaku w moim kraju, do rozprzestrzenienia nauk. Jedynie to bowiem może nas zbliżyć do innych nacji, tylko dzięki temu zdobywamy w najdalszych stronach przyjaciół pośród przodujących umysłów, przyczyniając się do utrwalenia najcenniejszych więzów, które niestety jakże często zrywają interesa państwowe.

Clavigo, Johann Wolfgang von Goethe (Tłumaczenie: Wanda Markowska)

Preface

The wireless industry is in the midst of a fundamental shift from providing voice-only services to offering customers an array of multimedia services, including a wide variety of audio, video and data communications capabilities. Future wireless networks will be integrated into every aspect of daily life, and therefore could affect our life in a magnitude similar to that of the Internet and cellular phones. However, the emerging applications and directions require fundamental understanding on how to design and control wireless networks that lies far beyond what the currently existing theory can provide. We are deeply convinced that mathematics is the key technology to cope with central technical problems in the design of wireless networks since the complexity of the problem simply precludes the use of engineering common sense alone to identify good solutions.

The main objective of this book is to provide tools for better understanding the fundamental tradeoffs and interdependencies in wireless networks, with the goal of designing resource allocation strategies that exploit these interdependencies to achieve significant performance gains. The book consists of three largely independent parts: theory, applications and appendices. The first part ends with some bibliographical comments and the second part starts with a short introduction to the problem of resource allocation in wireless networks. Below we briefly summarize the content of each part.

Theory: Chapters 1 and 2 deal with some fundamental problems in the theory of nonnegative matrices and provide a theoretical basis for the resource allocation problem addressed in the second part of the book. It should be emphasized that our intent is *not* to provide a thorough treatment of this wide subject. Instead, we focus on problems that naturally appear in the design of resource allocation strategies for wireless networks. When developing such strategies, different characterizations of the Perron root of nonnegative irreducible matrices turn out to be vital to better understanding of fundamental tradeoffs between diverse optimization objectives. Our main attention will be directed to the Perron root of nonnegative irreducible matrices whose entries

continuously depend on some parameter vector. In this case, the Perron root can be viewed as a map from a convex parameter set into the set of positive reals. The book is concerned with the properties of this map and, in particular, with the question under which conditions it is a convex function of the parameter vector. With few exceptions, we focus on a special structure of matrix-valued functions that is particularly relevant to applications in wireless networks. We provide necessary and sufficient conditions for the Perron root to be a convex function of the parameter vector as well as address a closely related problem of convexity of the so-called feasibility set. Chapter 2 is devoted to some properties of a positive solution to a system of linear equations with nonnegative coefficients. Applications that involve systems of linear equations with nonnegative coefficients are numerous, ranging from the physical and engineering sciences to other mathematical areas like graph theory and optimization. Such systems also occur in the power control problem for power-constrained wireless networks.

Applications: The second part of the book (Chaps. 4-6) deals with the problem of resource allocation in wireless networks. Roughly speaking, the objective is to maximize the sum of utilities of link rates for best-effort (elastic) traffic. This is equivalent to the problem of joint power control and link scheduling, which has been extensively investigated in the literature and is known to be notoriously difficult to solve, even in a centralized manner. Although the book provides some interesting insights into this problem, the main focus will be on the power control part. In particular, a class of utility functions is identified for which the power control problem can be converted into an equivalent convex optimization problem. The convexity property is a key ingredient in the development of powerful and efficient power control algorithms.

Appendices: The main purpose of the appendices is to make the book more understandable to readers who are not familiar with some basic concepts and results from linear algebra and convex analysis. The treatment is very superficial and formal proofs are presented only for the most important results such as the Perron–Frobenius theorem. Moreover, the presentation is limited to results used somewhere in the book. However, we hope that this collection of basic results will help some readers to better understand the material covered by the book. Finally, the presentation introduces the notation and terminology used throughout the book.

Acknowledgments: The work of Holger Boche and Sławomir Stańczak was supported in part by the *Bundesministerium für Bildung und Forschung (BMBF)* under grants 01BU150 (Hyeff), 01BU350 (3GET) and 01BU566 (ScaleNet). Marcin Wiczanowski was supported by the *Deutsche Forschungsgemeinschaft (DFG)* under grant BO1734/7-1. The authors also acknowledge

support from Alcatel SEL Forschungszentrum in Stuttgart, and Siemens CT in München, as well as valuable suggestions and comments from colleagues.

And finally, we would like to thank our families for their patience, support and understanding. This book is dedicated to you.

Berlin, June 2006

Sławomir Stańczak Marcin Wiczanowski Holger Boche

Contents

Pa	rt I '	Theor	у	
1	On	the P	erron Root of Irreducible Matrices	3
	1.1		Basic Definitions	3
	1.2	Some	Bounds on the Perron Root and Their Applications	4
		1.2.1	Concavity of the Perron Root on Some Subsets of	
			Irreducible Matrices	11
		1.2.2	Kullback-Leibler Divergence Characterization	14
		1.2.3	Some Extended Perron Root Characterizations	15
		1.2.4	Collatz–Wielandt-Type Characterization of the	
			Perron Root	18
	1.3	Conve	exity of the Perron Root	22
		1.3.1	Some Definitions	22
		1.3.2	Sufficient Conditions	24
		1.3.3	Convexity of the Feasibility Set	26
		1.3.4	Necessary Conditions	28
	1.4	Specia	al Classes of Matrices	
		1.4.1	Symmetric Matrices	31
		1.4.2	Symmetric Positive Semidefinite Matrices	32
	1.5 The Perron Root Under the Linear Mapping		34	
		1.5.1	Some Bounds	35
		1.5.2	Disproof of the Conjecture	38
	1.6	Some	Remarks on Arbitrary Nonnegative Matrices	41
		1.6.1	Log-Convexity of the Spectral Radius	42
		1.6.2	Characterization of the Spectral Radius	43
		1.6.3	Collatz–Wielandt-Type Characterization of the	
			Spectral Radius	46
	17	Riblic	ograpical Notes	47

2	\mathbf{On}	On the Positive Solution to a Linear System with				
	Nonnegative Coefficients 5					
	2.1					
	2.2	Feasil	pility Sets	53		
	2.3		exity Results	56		
		2.3.1	Log-Convexity of the Positive Solution	56		
		2.3.2	Convexity of the Feasibility Set	59		
		2.3.3	Strict Log-Convexity	60		
		2.3.4	Strict Convexity of the Feasibility Sets	65		
	2.4	_	Linear Case	66		
Pa	rt II	Appli	cations and Algorithms			
3	Inti	roduct	ion	71		
4	Net	Network Model				
	4.1	Basic	Definitions	75		
	4.2	Mediu	ım Access Control	76		
	4.3	Wirel	ess Communication Channel	79		
		4.3.1	Signal-to-Interference Ratio	81		
		4.3.2	Power Constraints	83		
		4.3.3	Data Rate Model	84		
		4.3.4	Two Examples	85		
5			Allocation Problem in Communications			
	Net			91		
	5.1	End-t	o-End Rate Control in Wired Networks	91		
		5.1.1	Fairness Criteria	92		
		5.1.2	Algorithms	95		
	5.2 Problem Formulation for Wireless Networks			97		
		5.2.1	Joint Power Control and Link Scheduling	98		
		5.2.2	Feasible Rate Region	101		
		5.2.3	End-to-End Window-Based Rate Control for Wireless			
			Networks	103		
		5.2.4	MAC Layer Fair Rate Control for Wireless Networks.	105		
		5.2.5	Utility-Based Power Control	107		
	5.3		pretation in the QoS Domain	112		
	5.4		rks on Joint Power Control and Link Scheduling	115		
		5.4.1	Optimal Joint Power Control and Link Scheduling	115		
		5.4.2	High SIR Regime	118		
		5.4.3	Low SIR Regime	119		
		5.4.4	Wireless Links with Self-Interference	122		
	5.5	Rema	rks on the Efficiency–Fairness Trade Off	123		
		5.5.1	Efficiency of the Max-Min Fair Power Allocation	125		

		5.5.2 Axiom-Based Interference Model	128		
6	Pov	ver Control Algorithm	129		
	6.1 Some Basic Definitions				
	6.2	Convex Statement of the Problem	131		
	6.3	Strong Convexity Conditions	133		
	6.4	Gradient Projection Algorithm	137		
		6.4.1 Global Convergence	138		
		6.4.2 Rate of Convergence	140		
		6.4.3 Diagonal Scaling	142		
		6.4.4 Projection on a Closed Convex Set	142		
	6.5	Distributed Implementation	143		
		6.5.1 Local and Global Parts of the Gradient Vector	143		
		6.5.2 Adjoint Network	145		
		6.5.3 Distributed Handshake Protocol	148		
		6.5.4 Noisy Measurements	150		
Par	rt II]	I Appendices			
A	Son	ne Concepts and Results from Matrix Analysis	155		
	A.1	Vectors and Vector Norms	155		
	A.2	Matrices and Matrix Norms	157		
	A.3	Square Matrices and Eigenvalues	158		
		A.3.1 Spectral Radius and Neumann Series	159		
		A.3.2 Orthogonal, Symmetric and Positive Semidefinite			
		Matrices	160		
	A.4	Perron–Frobenius Theory	161		
		A.4.1 Perron–Frobenius Theorem for Irreducible Matrices	162		
		A.4.2 Perron–Frobenius Theorem for Primitive Matrices	165		
		A.4.3 Some Remarks on Reducible Matrices	166		
		A.4.4 The Existence of a Positive Solution p to			
		$(\alpha \mathbf{I} - \mathbf{X})\mathbf{p} = \mathbf{b} \dots$	168		
В		ne Concepts and Results from Convex Analysis	171		
	B.1		171		
	B.2	Convex Sets and Functions	175		
		B.2.1 Strong Convexity	176		
	B.3	Log-Convex Functions	177		
		B.3.1 Inverse Functions of Monotonic Log-Convex Functions	179		
	B.4	Convergence of Gradient Projection Algorithms	180		
\mathbf{Re}	feren	ices	185		

List of Figures

1.1	The feasibility set F for some $\mathbf{X} \in \mathcal{X}_{K,\Gamma}^p(\Omega)$ with $\gamma(x) = x, x > 0, K = 2$ and $\Omega = \mathbb{Q}^2$	34
2.1	Illustration of Example 2.3: The feasibility set $F(P_t; P_1, P_2)$ with $\mathbf{X}(\boldsymbol{\omega}) \equiv 0, \ \gamma(x) = e^x - 1, x > 0,$ and $\mathbf{u}(\boldsymbol{\omega}) = (e^{\omega_1} - 1, e^{\omega_2} - 1)$. The constraints P_1, P_2 and P_t	
2.2	are chosen to satisfy $0 < P_1, P_2 < P_t$ and $P_t < P_1 + P_2$ The l^1 -norm $\ \mathbf{p}(\boldsymbol{\omega}(\mu))\ _1$ as a function of $\mu \in [0,1]$ for some fixed $\hat{\boldsymbol{\omega}}, \check{\boldsymbol{\omega}} \in \mathbf{Q}^K$ chosen such that $\ \mathbf{p}(\hat{\boldsymbol{\omega}})\ _1$ and $\ \mathbf{p}(\check{\boldsymbol{\omega}})\ _1$ are	55
2.3	independent of the choice of γ	65 67
4.1	union of these sets is not convex in general	
	node 4	77

5.1	Three flows compete for access to two links [58, 1]. Whereas flows 1 and 2 are one-link flows going through links 1 and	
	2, respectively, flow 3 uses both links. The links have fixed	
	capacities C_1 and C_2 , respectively. Clearly, the maximum	
	total throughput is $C_1 + C_2$ and, in the maximum, the	
	longer flow must be shut off $(\nu_3 = 0)$ so that the one-link	
	flows can be allocated rates of $\nu_1 = C_1$ and $\nu_2 = C_2$.	
	In contrast, if $C_1 \leq C_2$, the max-min fair allocation is	
	$\nu_1 = C_1/2, \nu_2 = C_2 - C_1/2$ and $\nu_3 = C_1/2$. Thus, the total	
	throughput is $C_2 + C_1/2$ which is strictly smaller than	
	$C_1 + C_2$. Note that if $C_1 = C_2$, then all source rates are equal	
	under the max-min fair solution.	93
5.2	Assuming $\Phi^{-1}(x) = e^x - 1, x \in \mathbb{R}$, the figure compares	
J	the modified utilities $U(x) = \Psi(\Phi^{-1}(x)), x > 0$,	
	with the traditional ones $U(x) = \Psi(x), x > 0,$	
	for $\Psi(x) = \log(x), \Psi(x) - 1/x, x > 0$, and	
	$\Psi(x) = \log x/(1+x), x > 0.$	110
5.3	The feasible rate region for two mutually orthogonal links	
	subject to a sum power constraint. The region is a strictly	
	convex set so that link scheduling between arbitrary points	
	on the boundary of the feasible rate region is suboptimal	117
5.4	The feasible SIR region for two users under total power	
-	constraint $P_{\rm t}$ and individual power constraints on each link	
	$P_1 < P_t$ and $P_2 < P_t$. If there were no individual power	
	constraints, a MAC policy involving a time sharing protocol	
	between the points E and F , corresponding to power vectors	
	$(0, P_t)$ and $(P_t, 0)$, respectively, would be optimal. In contrast,	
	when in addition individual power constraints are imposed, a	
	time sharing protocol between A and D (that correspond to	
	power vectors $(0, P_2)$ and $(P_1, 0)$, respectively) is suboptimal.	
	In this case, it is better to schedule either between A and B	
	or between B and C or between C and D depending on the	
	target signal-to-interference ratios.	121
	000 00000000000000000000000000000000000	
6.1	In the primal network, the received signal samples	
	at E1 and E2 are $y_1 = h_{1,1}X_1 + h_{1,2}X_2$ and	
	$y_2 = h_{2,2}X_2 + h_{2,1}X_1$, respectively, where X_1, X_2 are	
	zero-mean independent information-bearing symbols with	
	$E[X_1 ^2] = p_1, E[X_2 ^2] = p_2$. In the adjoint network, E1	
	and E2 transmits $X_1/h_{1,1}$ and $X_2/h_{2,2}$, respectively, so that	
	the received signal samples are $\tilde{y}_1 = X_1 + h_{2,1}/h_{2,2}X_2$ and	
	$\tilde{y}_2 = X_2 + h_{1,2}/h_{1,1}X_1$	147

List of Symbols

$a, b, c, \alpha, \beta, \mu,$ $\mathbf{A}, \mathbf{B}, \mathbf{X}, \mathbf{Y}$ $\mathbf{A} \leq \mathbf{B}$ \mathbf{A}^{-1} \mathbf{A}^{T} $\mathbf{A}_{K}(\mathbf{X})$ $\mathbf{A} \times \mathbf{B}$ \mathbf{A} $\mathbf{A} \circ \mathbf{B}$	Scalars over \mathbb{R} or \mathbb{C} Matrices; Sect. A.2 Partial ordering; Sect. A.2 Matrix inverse; Sect. A.3 Transpose matrix; Definition A.3 Eq. (1.8) Cartesian product Sect. 5.2.1 Hadamard product; Sect. A.2
$\frac{\mathrm{B}_K}{\mathrm{\overline{B}}_K}$ B	Sect. 1.6.2 Sect. 1.6.2 Sects. 4.3 and 5.2.1
\mathbb{C} $\mathrm{cl}(A)$ C $\mathrm{\tilde{C}}$	Sect. A.1 Closure Eq. (5.11) Eq. (5.15)
$egin{aligned} \operatorname{diag}(\mathbf{u}) \ \operatorname{det}(\mathbf{A}) \ \delta_l \end{aligned}$	Diagonal matrix; Sect. A.2 Matrix determinant; Sect. A.3 The Kronecker delta
$egin{aligned} \mathbf{e}_i \ & \mathbf{E}_K(\mathbf{X}) \ & \mathbf{E}_K^+(\mathbf{X}) \ & \boldsymbol{\eta}(\mathbf{p}) \end{aligned}$	Sect. A.1 Sect. 1.6.2 Sect. 1.6.2 Eq. (6.30)
$egin{array}{c} { m F} \\ \partial { m F} \\ { m F}^c \end{array}$	Eq. (1.53) and Eq. (2.5) Eq. (1.55) Eq. (1.60)

$F(P_t)$ $F(P_1,, P_K)$ $F_k(\alpha)$ $F(P_t; P_1,, P_K)$ $\partial F(P_t)$ $\partial F(P_1,, P_K)$ $F^c(P_t)$ F_{γ} $F_{\gamma}(P)$ $\partial F_{\gamma}(P)$ $f'(x), x \in \mathbb{R}$ $f''(x), x \in \mathbb{R}$ $F(\mathbf{p})$ $F_e(\mathbf{s})$	Eq. (2.9) Eq. (2.11) Eq. (2.12) Eq. (2.13) Definition 2.15 Definition 2.15 Sect. 2.4 Eq. (5.32) Eq. (5.31) Eq. (5.34) The first derivative; Sect. B.1 The second derivative; Sect. B.1 Eq. (6.2) Eq. (6.12)
$egin{aligned} oldsymbol{\Gamma}(oldsymbol{\omega}) \ g_k(\mathbf{p}) \end{aligned}$	Eqs. (1.48) and (5.12) (6.21)
$h_k(\mathbf{s})$	Eq. (6.14)
$egin{aligned} \mathbf{I} \ I_k(\mathbf{p}) \end{aligned}$	Identity matrix; Sect. A.2 Eq. (6.5)
$K \ K(n)$	Sect. 4.1 Sect. 4.1
$\lambda_p(\boldsymbol{\omega}) \ \mathrm{LC}_K(\Omega) \ \mathrm{lc}(\Omega) \ L$	Sect. 1.3.1 Definition 1.34 Sect. 2.3 Sect. 4.1
$\begin{array}{l} \mathbb{N} \\ \mathbb{N}_0 \\ \mathbb{N} \\ \mathbb{N}_K = \mathbb{R}_+^{K \times K} \\ \mathbb{N}_K^+ \\ \mathbb{N}_K(\Omega) \\ \mathbb{N}_{K,\Gamma}(\Omega) \\ \ \mathbf{u}\ \\ \ \mathbf{X}\ \\ \nabla_k f(\mathbf{x}) \\ \nabla^f(\mathbf{x}) \\ \nabla^2 f(\mathbf{x}) \end{array}$	Natural numbers Nonnegative integers Sect. 4.1 Definition A.18 Sect. 1.6.2 Definition 1.32 Eq. (2.8) Vector norms; Sect. A.1 Matrix norms; Sect. A.2 Definition B.9 Eq. (B.3) Definition B.12

$\Omega \subset \mathbb{R}^K$	Sect. A.1 Eq. (1.45)
$egin{aligned} \Pi_K & \Pi_K^+ & \Pi_K^+ & \mathbb{P}_K = \mathbb{R}_{++}^{K imes K} & \mathbb{P}_K(\Omega) & & & & & \\ \mathbf{p}(\mathbf{X}) & & & & & & \\ \mathbf{p}(\mathbf{X}) & & & & & & \\ \mathbf{p}(\boldsymbol{\omega}) & & & & & & \\ \boldsymbol{\Phi} & & & & & & \\ \boldsymbol{\Psi} & & & & & & \\ \boldsymbol{\Psi}_e & & & & & & \\ \boldsymbol{\psi} & & & & & & \\ \boldsymbol{\psi}_e & & & & & & \\ \boldsymbol{H}_{\mathrm{S}} & & & & & & \\ \mathbf{P} \subset \mathbb{R}_+^K & & & & & \\ \mathbf{P}_n & & & & & & \\ \mathbf{P}_+ & & & & & & \\ \end{aligned}$	Sect. 1.1 Sect. 1.1 Definition A.18 Sect. Sect. Sect. 1.3.1 Eq. (1.2) Eq. (2.4) Eq. (4.7) Definition 5.5 Definition 5.5 Eq. (5.36) Definition 6.1 Eq. (B.19) Eq. (4.6) Eq. (4.6) Eq. (6.10)
$\mathbf{q}(\mathbf{X})$ $Q \subset \mathbb{R}$	Eq. (1.2) Sect. 1.3.1
$\mathbb{R} \\ \mathbb{R}_{+} \subset \mathbb{R} \\ \mathbb{R}_{++} \subset \mathbb{R}_{+} \\ \mathbb{R}^{K} \\ \mathbb{R}^{K \times K} \\ \mathbb{R}^{K}_{++}(\Omega)$	Real numbers Sect. A.4 Sect. A.4 Sect. A.1 Sect. A.2 Sect. 2.1
$\sigma(\mathbf{A})$ $ ho(\mathbf{X})$ S_K $S_K(\mathbf{X})$ $\mathrm{SIR}_k(\mathbf{p})$ $S \subset \mathbb{R}^K$ S	Matrix spectrum; Definition A.7 Spectral radius; Definition A.7 Sect. 1.2 Eq. (1.3) Eq. (4.2) Eq. (6.11) Sect. 4.1
$egin{aligned} & ext{trace}(\mathbf{X}) \ & oldsymbol{ heta}(\mathbf{p}) \end{aligned}$	Matrix trace; Sect. A.2 Eq. (6.30)
$\mathbf{u} \leq \mathbf{v}$	Partial ordering; Sect. A.1
p,q,s,u,v,z,	Vectors; Sect. A.1

XXII List of Symbols

\mathbf{V}	Eq. (4.4)
$W_K(\mathbf{X})$	Eq. (1.14)
$\begin{aligned} \mathbf{X}_K &\subset \mathbf{N}_K \\ \mathbf{X}_K(\Omega) \\ \mathbf{X}_{K,\Gamma}(\Omega) \\ \mathbf{X}_{K,\Gamma}^s(\Omega) \\ \mathbf{X}_{K,\Gamma}^p(\Omega) \\ \mathbf{X}_{K,\Gamma}^p(\Omega) \end{aligned}$	Definition A.21 Definition 1.32 Eq. (1.49) Sect. 1.4.1 Sect. 1.4.2 Sect. 1.5

O Zero vector; Sect. A.1