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# Search-Based Software Engineering

15th International Symposium, SSBSE 2023  
San Francisco, CA, USA, December 8, 2023  
Proceedings

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# Preface

## Message from the General Chair

We are very excited to bring you the proceedings of the 15th edition of the International Symposium on Search-Based Software Engineering (SSBSE 2023). SSBSE is a premier event for all who are interested in the intersection of search optimization and difficult software engineering problems spanning numerous domains. This year SSBSE was held as a hybrid event; physically located in San Francisco, California, USA and remote for those that were unable to attend in person. We continue to be co-located with ESEC/FSE and are grateful for their support of our symposium.

Thank you to Tao Yue and Paolo Arcaini for putting together an exciting research track program; without your constant feedback and support planning this event would have been extremely difficult! I would also like to thank the track chairs for their hard work supporting SSBSE as well: Rebecca Moussa and Thomas Vogel (Hot Off the Press track), Gregory Gay and Max Hort (RENE/NIER track), and Bobby Bruce, José Miguel Rojas, and Vali Tawosi (Challenge track). I would also like to thank Alexander Lalejini for his work on the SSBSE website and Emeraldalda Sesari for her work on publicizing our event. Many thanks to our multiple Program Committees as well for their tireless work on reviewing papers and suggesting improvements and to our Steering Committee for continuing to oversee and support this event.

Very special thanks to our sponsor, Grand Valley State University. I would also like to thank Satish Chandra from Google for his support as the general chair of ESEC/FSE 2023, as well as Federica Sarro at University College London as a point of contact in the Steering Committee for continuing support whenever an issue arose that I did not have an answer for.

I enjoyed seeing you all at SSBSE 2023 and hope you enjoyed the program!

December 2023

Erik Fredericks

## Message from the Program Chairs

Speaking for the SSBSE 2023 Program Committee, we are delighted to introduce the proceedings of the 15th International Symposium on Search-Based Software Engineering. Search-Based Software Engineering (SBSE) focuses on formulating various optimization problems in software engineering as search problems and then addressing them with search techniques, intending to automate complex software engineering tasks. A wide class of software engineering challenges can be formulated into SBSE problems, including test optimization, design and code refactoring, software/system development process optimization, and many more, which have been addressed with various search techniques. The community continuously advances the field by identifying, formulating, and solving new challenges such as searching for critical driving scenarios for testing autonomous vehicles, optimizing the energy consumption of software applications, and automating hyperparameter tuning of machine learning models.

SSBSE 2023 upheld the longstanding tradition of SSBSE by gathering the SBSE community yearly to share and discuss advancements in the field. This year, we welcomed submissions showcasing innovative contributions across all SBSE domains. Specifically, we received 13 submissions to the main Research track, four to the Replications and Negative Results (RENE)/New Ideas and Emerging Results (NIER) track, six to the SBSE Challenge track, and two to the Hot Off the Press (HOP) track. Each valid submission to the Research track were double-blind reviewed by at least three PC members and, eventually, six papers were accepted. For the RENE/NIER track, three papers were accepted. For the SBSE Challenge track, five papers were accepted. The HOP track accepted two papers.

December 2023

Paolo Arcaini  
Tao Yue

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# Keynotes




# Search-Based Software Engineering for Learning-Enabled Self-Adaptive Systems

Betty H. C. Cheng

Michigan State University, USA

**Abstract.** Trustworthy artificial intelligence (Trusted AI) is essential when autonomous, safety-critical systems use learning-enabled components (LECs) in uncertain environments. When reliant on deep learning, these learning-enabled systems (LES) must address the reliability, interpretability, and robustness (collectively, the assurance) of learning models. Three types of uncertainty most significantly affect assurance. First, uncertainty about the physical environment can cause suboptimal, and sometimes catastrophic, results as the system struggles to adapt to unanticipated or poorly understood environmental conditions. For example, when lane markings are occluded (either on the camera and/or the physical lanes), lane management functionality can be critically compromised. Second, uncertainty in the cyber environment can create unexpected and adverse consequences, including not only performance impacts (network load, real-time responses, etc.) but also potential threats or overt (cybersecurity) attacks. Third, uncertainty can exist with the components themselves and affect how they interact upon reconfiguration. Left unchecked, this may cause unexpected and unwanted feature interactions. While learning-enabled technologies have made great strides in addressing uncertainty, challenges remain in addressing the assurance of such systems when encountering uncertainty not addressed in training data. Furthermore, we need to consider LESs as first-class software-based systems that should be rigorously developed, verified, and maintained (i.e., software engineered). In addition to developing specific strategies to address these concerns, appropriate software architectures are needed to coordinate LECs and ensure they deliver acceptable behavior even under uncertain conditions. To this end, this presentation overviews a number of our multi-disciplinary research projects involving industrial collaborators, which collectively support a search-based software engineering, model-based approach to address Trusted AI and provide assurance for learning-enabled systems (i.e., SBSE4LES). In addition to sharing lessons learned from more than two decades of research addressing assurance for (learning-enabled) self-adaptive systems operating under a range of uncertainty, near-term and longer-term research challenges for addressing assurance of LESs will be overviewed.

# SSBSE Summary of .NET/C# Instrumentation for Search-Based Software Testing

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**Abstract.** C# is a widely used programming language. However, to the best of our knowledge, there is no documented work on enabling Search-Based Software Testing methods for C# and .NET applications. This paper introduces a white-box testing approach and an open-source tool for C# applications that collects code coverage information in real-time via .NET bytecode instrumentation. The method improves the search's direction by using *Branch Distance* heuristics. The tool was evaluated on three .NET RESTful APIs after being integrated into the EvoMaster test generator. Results show that our strategy achieves significantly higher code coverage than grey-box testing tools.

**Keywords:** .NET instrumentation · SBST · REST APIs

## Summary

This paper provides a summary of [3].

We have used the `Mono.Cecil` library to implement instrumentation for .NET programs, allowing analysis and modification of CIL code. This works offline with .NET libraries compiled as DLLs. Integration with SBST techniques is essential for generating tests. Our experiments leverage EVOMASTER [2], which produces system-level tests for RESTful APIs. EVOMASTER has two main components: a core process and a driver, facilitating instrumentation and interaction through RESTful APIs. This instrumentation takes place via a .NET Core console application. To utilize EVOMASTER, we created a C# driver mirroring the existing JVM driver's endpoints. The core, written in Kotlin, was adapted to include C# output, enabling the generation of test cases as HTTP call sequences based on xUnit.

.NET programs consist of assemblies with classes containing methods. EVOMASTER is designed to optimize test case creation, maximizing coverage of these methods' targets. For tracking coverage, `EnteringStatement` and `CompletedStatement` probes are inserted before and after each statement. These probes, essentially calls to

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This project has received funding from the European Research Council (ERC) under the European Union's Horizon 2020 research and innovation programme (grant agreement No 864972).

static methods in a console application developed to support the instrumentation, use parameters like class name and line number to uniquely identify statements. Coverage is measured heuristically between 0 (not covered) and 1 (fully covered). While `EnteringStatement` marks a statement's start, its error-free execution is confirmed by `CompletedStatement`. Inserting these probes presents challenges, especially with control-altering instructions such as jump or exit instructions (i.e., `br`, `throw`, `rethrow`, `endfinally`, `leave` and `ret`).

During the search, calculating branch distances for both numeric and string values are vital as they can provide gradient to the search algorithm to solve constraints. Numeric branch instructions are categorized into three types: *one-arg jump*, *two-arg compare*, and *two-arg jump*. One-arg jumps decide control flow based on a single value, while two-arg compare instructions compare two values and push the result (i.e., either 0 or 1) back on the evaluation stack, and two-arg jumps combine both. Calculating numeric branch distance involves challenges like duplication of values on the stack, using bytecode method replacements, and detecting specific data types. For string branch distances, boolean-returning operators and methods within `System.String` class are identified and replaced with probes to calculate the distance while retaining original functionality. The entire process ensures better test coverage and represents an intricate part of understanding how a system's control flow works, enhancing overall software reliability.

Our team assessed the efficacy of our approach by integrating bytecode instrumentation and branch distance-based heuristics into EVOMASTER, calling it EVOMASTER.NET. Utilizing default settings, we contrasted it with a grey-box testing approach on three .NET REST APIs (i.e., `rest-ncs`, `rest-scs`, and `menu-api`) from *EMB* repository [1]. The findings revealed substantial improvements in the numerical and string problems (i.e., `rest-ncs` and `rest-scs`, respectively) up to 98% and 86% line coverage respectively compared to the grey-box approach, but equivalent results for the `menu-api`. The enhanced performance illustrates our method's ability to resolve the majority of numeric and string branches. However, for the `menu-api`, which involves working with a database, the performance was not enhanced, signifying the necessity for SQL database-specific adaptations.

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