

Olivier Sigaud and Jan Peters (Eds.)

From Motor Learning to Interaction Learning in Robots

Studies in Computational Intelligence, Volume 264

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Olivier Sigaud and Jan Peters (Eds.)

From Motor Learning to Interaction Learning in Robots

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To all our hard-working robotics students...

Preface

From an engineering standpoint, the increasing complexity of robotic systems and the increasing demand for more autonomous robots result in a surge of interest about learning methods.

This book is largely based on the successful workshop “From motor to interaction learning in robots” held at the IEEE/RSJ International Conference on Intelligent Robot Systems. The major aim of the book is to give students a chance to get started faster and researchers a helpful compandium for the study of learning in robotics.

Paris, August 2009
Tübingen, August 2009

Olivier Sigaud
Jan Peters

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