# Lecture Notes in Artificial Intelligence

# 7508

# Subseries of Lecture Notes in Computer Science

### **LNAI Series Editors**

Randy Goebel
University of Alberta, Edmonton, Canada
Yuzuru Tanaka
Hokkaido University, Sapporo, Japan
Wolfgang Wahlster
DFKI and Saarland University, Saarbrücken, Germany

# **LNAI Founding Series Editor**

Joerg Siekmann

DFKI and Saarland University, Saarbrücken, Germany

Chun-Yi Su Subhash Rakheja Honghai Liu (Eds.)

# Intelligent Robotics and Applications

5th International Conference, ICIRA 2012 Montreal, QC, Canada, October 3-5, 2012 Proceedings, Part III



#### Series Editors

Randy Goebel, University of Alberta, Edmonton, Canada Jörg Siekmann, University of Saarland, Saarbrücken, Germany Wolfgang Wahlster, DFKI and University of Saarland, Saarbrücken, Germany

Volume Editors

Chun-Yi Su Concordia University Department of Mechanical and Industrial Engineering Montreal, QC H3G 1M8, Canada E-mail: cysu@alcor.concordia.ca

Subhash Rakheja Concordia University Department of Mechanical and Industrial Engineering Montreal, QC H3G 1M8, Canada E-mail: rakheja@alcor.concordia.ca

Honghai Liu The University of Portsmouth School of Creative Technologies Portsmouth, PO1 2DJ, UK E-mail: honghai.liu@port.ac.uk

ISSN 0302-9743 e-ISSN 1611-3349 ISBN 978-3-642-33502-0 e-ISBN 978-3-642-33503-7 DOI 10.1007/978-3-642-33503-7 Springer Heidelberg Dordrecht London New York

Library of Congress Control Number: 2012946931

CR Subject Classification (1998): I.2.8-11, I.5.3-4, I.4.8-9, K.4.2, J.2, J.3, C.3, C.2, G.1.10

#### LNCS Sublibrary: SL 7 – Artificial Intelligence

© Springer-Verlag Berlin Heidelberg 2012

This work is subject to copyright. All rights are reserved, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, re-use of illustrations, recitation, broadcasting, reproduction on microfilms or in any other way, and storage in data banks. Duplication of this publication or parts thereof is permitted only under the provisions of the German Copyright Law of September 9, 1965, in its current version, and permission for use must always be obtained from Springer. Violations are liable to prosecution under the German Copyright Law.

The use of general descriptive names, registered names, trademarks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations and therefore free for general use.

Typesetting: Camera-ready by author, data conversion by Scientific Publishing Services, Chennai, India

Printed on acid-free paper

Springer is part of Springer Science+Business Media (www.springer.com)

## **Preface**

The Organizing Committee of the 5<sup>th</sup> International Conference on Intelligent Robotics and Applications aimed to facilitate interaction among participants in the field of intelligent robotics, automation, and mechatronics. Through this conference, the committee intended to enhance the sharing of individual experiences and expertise in intelligent robotics with particular emphasis on technical challenges associated with varied applications such as biomedical applications, industrial automations, surveillance, and sustainable mobility.

The 5<sup>th</sup> International Conference on Intelligent Robotics and Applications was most successful in attracting 271 submissions addressing state-of-the-art developments in robotics, automation, and mechatronics. Owing to the large number of submissions, the committee was faced with the difficult challenge of selecting the most deserving papers for inclusion in these lecture notes and for presentation at the conference, held in Montreal, Canada, October 3–5, 2012. For this purpose, the committee undertook a rigorous review process. Despite the high quality of most of the submissions, a total of 197 papers were selected for publication in 3 volumes of Springer's Lecture Notes in Artificial Intelligence, a subseries of Lecture Notes in Computer Science.

The selected articles were submitted by scientists from 25 different countries. The contribution of the Technical Program Committee and the referees is deeply appreciated. Most of all, we would like to express our sincere thanks to the authors for submitting their most recent work and the Organizing Committee for their enormous efforts to turn this event into a smoothly running meeting. Special thanks go to Concordia University for their generosity and direct support. Our particular thanks are due to Mr. Alfred Hofmann and the editorial staff of Springer-Verlag for enthusiastically supporting the project.

We sincerely hope that these volumes will prove to be an important resource for the scientific community.

July 2012

Chun-Yi Su Subhash Rakheja Honghai Liu

# Conference Organization

# **International Advisory Committee**

Jorge Angeles McGill University, Canada Suguru Arimoto Ritsumeikan University, Japan

Hegao Cai Harbin Institute of Technology, China

Tianyou Chai Northeastern University, China

Clarence De Silva University of British Columbia, Canada

Han Ding Huazhong University of Science and Technology,

China

Sabina Jeschke RWTH Aachen University, Germany

Ming Li National Natural Science Foundation of China,

China

Zhongqin Lin Shanghai Jiao Tong University, China Ding Liu Xi'an University of Technology, China

Jinping Qu South China University of Technology, China

Bruno Siciliano University of Naples, Italy

Mohammad Siddique Fayetteville State University, USA Mark W. Spong University of Texas at Dallas, USA

Kevin Warwick University of Reading, UK

Ming Xie Nanyang Technological University, Singapore Youlun Xiong Huazhong University of Science and Technology,

China

#### **General Chairs**

Chun-Yi Su Concordia University, Canada Rama B. Bhat Concordia University, Canada

Xiangyang Zhu Shanghai Jiao Tong University, China

# **Program Chairs**

Subhash Rakheja Concordia University, Canada

Jangmyung Lee Pusan National University, South Korea

Camille Alain Rabbath DRDC, Canada

# **Publicity Chairs**

Tongwen Chen University of Alberta, Canada Li-Chen Fu National Taiwan University, Taiwan

Shuzhi Sam Ge National University of Singapore, Singapore

#### VIII Conference Organization

Naoyuki Kubota Tokyo Metropolitan University, Japan Kok-Meng Lee Georgia Institute of Technology, USA Ning Xi City University of Hong Kong, Hong Kong Xiaohua Xia University of Pretoria, South Africa Peter Xu University of Auckland, New Zealand

Huayong Yang Zhejiang University, China Bin Yao Purdue University, USA

Xinghuo Yu Royal Melbourne Institute of Technology,

Australia

Chaohai Zhang Harbin Institute of Technology, China

## Organized Session Chairs

Mirco Alpen Helmut Schmidt University, Germany
Shengyong Chen Zhejiang University of Technology, China
Weidong Chen Shanghai Jiao Tong University, China

Xiang Chen University of Windsor, Canada

Xinkai Chen Shibaura Institute of Technology, Japan

Mingcong Deng Tokyo University of Agriculture and Technology,

Japan

Jun Fu Massachusetts Institute of Technology, USA

Xin Fu Zhejiang University, China

Haibo Gao Harbin Institute of Technology, China

Yueming Hu South China University of Technology, China Yangmin Li University of Macau, Macau, SAR China Zhijun Li South China University of Technology, China

Guangjun Liu Ryerson University, Canada Xinjun Liu Tsinghua University, China

Daniel Schilberg RWTH Aachen University, Germany

Yandong Tang Shengyang Institute of Automation, CAS, China Danwei Wang Nanyang Technological University, Singapore

Enrong Wang Nanjing Normal University, China

Caihua Xiong Huazhong University of Science and Technology,

China

Simon Yang University of Guelph, Canada Hongnian Yu Staffordshire University, UK Jianhua Zhang Shanghai University, China Youmin Zhang Concordia University, Canada

Limin Zhu Shanghai Jiao Tong University, China

#### **Publication Chairs**

Honghai Liu University of Portsmouth, UK

Xinjun Sheng Shanghai Jiao Tong University, China

#### **Award Chair**

Farhad Aghili Canadian Space Agency, Canada

# Registration Chairs

Zhi Li Concordia University, Canada Sining Liu Concordia University, Canada

#### Finance Chair

Ying Feng South China University of Technology, China

## Local Arrangement Chairs

Wen-Fang Xie Concordia University, Canada Chevy Chen Concordia University, Canada

# **International Program Committee**

Amir Aghdam Concordia University, Canada DongPu Cao Lancaster University, UK

Qixin Cao Shanghai Jiao Tong University, China Jie Chen Beijing Institute of Technology, China

Mingyuan Chen Concordia University, Canada Zuomin Dong University of Victoria, Canada

Guangren Duan Harbin Institute of Technology, China

Shumin Fei Southeast University, China

Gang Feng City University of Hong Kong, China Huijun Gao Harbin Institute of Technology, China Luis E. Garza C. Tecnológico de Monterrey, México Andrew A. Goldenberg University of Toronto, Canada

Guoying Gu Shanghai Jiao Tong University, China

Jason J. Gu Dalhousie University, Canada Peihua Gu University of Calgary, Canada

Zhi-Hong Guan Huazhong University of Science & Technology,

China

Shuxiang Guo Kagawa University, Japan Lina Hao Northeastern University, China Henry Hong Concordia University, Canada

Liu Hsu Federal University of Rio de Janeiro, Brazil

Huosheng Hu University of Essex, UK

Qinglei Hu Harbin Institute of Technology, China

Chunqing Huang Xiamen University, China

Wei Lin Case Western Reserve University, USA Derong Liu University of Illinois at Chicago, USA

Min Liu Tsinghua University, China
Peter X. Liu Carleton University, Canada
Jun Luo Shanghai University, China
Tao Mao Dartmouth College, USA
Daniel Miller University of Waterloo, Canada
Yuichiro Oya University of Miyazak, Japan

Hailong Pei South China University of Technology, China

Juntong Qi Chinese Academy of Sciences, China
Joe Qin University of Southern California, USA
Yaohong Qu Northwestern Polytechnical University, China

Lbrir Salim The University of Trinidad and Tobago,

Trinidad and Tobago

Inna Sharf McGill University, Canada
Yang Shi Victoria University, Canada
Gangbing Song University of Houston, USA
Jing Sun University of Michigan, USA
XiaoBo Tan Michigan State University, USA
Yonghong Tan Shanghai Normal University, China

Yong Tang South China University of Technology, China

Gang Tao University of Virginia, USA
Didier Theilliol University of Lorraine, France
Hong Wang University of Manchester, UK
Xingsong Wang Southeast University, China

Pak Kin Wong University of Macau, Macau, SAR China

Shaorong Xie Shanghai University, China

Xin Xin Okayama Prefectural University, Japan Zhenhua Xiong Shanghai Jiao Tong University, China

Bugong Xu South China University of Technology, China Jianxin Xu National University of Singapore, Singapore

Deyi Xue University of Calgary, Canada Zijiang Yang Ibaraki University, Japan

Dingguo Zhang Shanghai Jiao Tong University, China Guangming Zhang Nanjing University of Technology, China Yanzheng Zhao Shanghai Jiao Tong University, China Wenhong Zhu Canadian Space Agency, Canada

#### List of Reviewers

We would like to acknowledge the support of the following people, who peer reviewed articles from ICIRA 2012.

Mitchell Donald Achint Aggarwal Farhad Aghili Xiao-Gang Duan Jose Alarcon Herrera Su-Hong Eom Mirco Alpen Ole Falkenberg Nicolas Alt Yuanjie Fan Philippe Archambault Yongchun Fang Ramprasad Balasubramanian Wei Feng Mark Becke Simon Foitu Andrev Belkin Gustavo Freitas Francisco Beltran-Carbajal Klaus Frick Stanley Birchfield Zhuang Fu Jun Fu

Swetha Sampath Bobba

Swetha Sampath Bobba

Hans-Joachim Böhme

Itziar Cabanes

Yifan Cai

Yang Cao

Jason Geder

Zhiqiang Cao Hernan Gonzalez Acuña

Alberto Cavallo Guo-Ying Gu
Abbas Chamseddine Tianyu Gu
Mingyuan Chen Yongxin Guo
Xiang Chen Zhao Guo
Wei Chen Roger Halkyard
Diansheng Chen Jianda Han
Xinkai Chen Lina Hao

Shengyong Chen

Yixiong Chen

Xiang Chen

Xiang Chen

Weidong Chen

Chaobin Chen

Sven Hellbach

Shengyong Chen

Chevy Chen

Shengyong Chen

Tront Hilliard

Chevy Chen

Zhao Cheng

Trent Hilliard

Yushing Cheung

Dong-Il Cho

Yunfei Dai

David D'Ambrosio

Katharina Hertkorn

Trent Hilliard

Johannes Höcherl

Joachim Horn

Mir Amin Hosseini

Oinglei Hu

David D'Ambrosio Qinglei Hu
Krispin Davies Yonghui Hu
Hua Deng Jin Hu
Mingcong Deng Chunging Hu

Mingcong Deng Chunqing Huang
Wenhua Ding Jidong Huang
Xuejun Ding Aitore Ibarguren
John Dolan Satoshi Iwaki

#### XII Conference Organization

Markus Janssen Qiuling Jia Ying Jin

Balajee Kannan Jun Kanno Bijan Karimi

Mohammad Keshmiri

Sungshin Kim Alexandr Klimchik Yukinori Kobayashi

Tim Köhler Naoyuki Kubota Xu-Zhi Lai Lin Lan

Marco Langerwisch Jangmyung Lee

Sang-Hoon Lee

Min Lei Yan Li Shunchong Li Jing Li

Zhijun Li Hengyu Li Nanjun Li Yinxiao Li Qingguo Li

Yangming Li

Zhi Li
Binbin Lian
Junli Liang
Guanhao Liang
Miguel Lima
Xinjun Liu
Han Liu

Chengliang Liu Peter Liu

Chao Liu Jia Liu Sining Liu Jun Luo Xiaomin Ma

Yumin Ma António Machado

Werner Maier

Jörn Malzahn

Mohamed Mamdouh Ida Bagus Manuaba

Tao Mao

Farhat Mariem Luis Mateos Iñaki Maurtua Aaron Mavrinac Deging Mei

Yi Min Lei Mo

Abolfazl Mohebbi Vidya Murali Mahmoud Mustafa Keitaro Naruse Ashutosh Natraj Myagmarbayar Nergui

Bin Niu

Scott Nokleby

Farzad Norouzi fard Farzan Nowruzi Ernesto Olguín-Díaz Godfrey Onwubolu Tomas Pajdla Chang-Zhong Pan Lizheng Pan

Ricardo Pérez-Alcocer Andreas Pichler Charles Pinto Erion Plaku Peter Poschmann Radius Prasetiyo Marius Pruessner

Juntong Qi Xiaoming Qian Guo Qiwei Yaohong Qu

Mohammad Rahman Ahmed Ramadan Christian Rauch

Laura Ray

Hamd ul Moqeet Riaz Martijn Rooker Miti Ruchanurucks

Kunjin Ryu

Iman Sadeghzadeh

Thomas Schlegl Christian Schlette Sven Severin

Inna Sharf Karam Shava Huiping Shen Huimin Shen Xinjun Sheng Thierry Simon Olivier Simonin Dalei Song Zhenguo Sun Tadeusz Szkodny

XiaoBo Tan Wenbin Tang Yandong Tang Alberto Tellaeche Didier Theilliol

Christopher Tomaszewski Abhinav Valada Prasanna Velagapudi Tianmiao Wang Xiaovan Wang Xinmin Wang Jingchuan Wang Yancheng Wang

Xin Wang Enrong Wang Ralf Waspe Zhixuan Wei Graeme Wilson Jonas Witt Christian Wögerer Pak Kin Wong

Olarn Wongwirat Chong Wu Yier Wu Jianhua Wu Min Wu Xiaojun Wu Baihua Xiao Fugui Xie Rong Xie

Wen-Fang Xie

Shaorong Xie

Pu Xie

Le Xie Xin Xin Jing Xin

Zhenhua Xiong Rong Xiong Caihua xiong Bugong Xu Bin Xu Xiong Xu You-Nan Xu Devi Xue Zijiang Yang Jie Yang

Chenguang Yang Wenvu Yang Jing Yang Chang-En Yang

Lin Yao

Gen'ichi Yasuda Michael Yeh Zhouping Yin Yong-Ho Yoo Haovong Yu Xinghuo Yu Mimoun Zelmat Shasha Zeng Jie Zhang

Zhengchen Zhang

Gang Zhang Xiaoping Zhang Jianjun Zhang He Zhang Dingguo Zhang Yifeng Zhang Xuebo Zhang Yegun Zhang Jinsong Zhang Wenzeng Zhang Chaohai Zhang Yanzheng Zhao Pengbing Zhao Zhaowei Zhong Hangfei Zhou Li-Min Zhu Asier Zubizarreta

# Table of Contents – Part III

Robot	Actuators	and	sensors

Hands-Free Head-Motion Interface Using Air Pillow	1
A Self-localization System with Global Error Reduction and Online Map-Building Capabilities	13
Sensor Classification Methods Applied to Robotics	23
Design and Simulation of Bio-inspired Flexible Tactile Sensor for	
Prosthesis	32
A Monitoring Network Based on Embedded Vision Nodes Suitable for Robotic Systems	42
Conceptual Design and Kinematic Analysis of a Parallel Rotational Robot	52
Robot Design, Development and Control	
Attitude Control of the Unicycle Robot Using Fuzzy-Sliding Mode Control	62
Evaluation of Response Models to a Series of Commands in a Telerobotics Supervisory Control System	73
An Embedded Control System for Automatic Guided Vehicle	85

Predictive Delay Compensation for Camera Based Oscillation Damping of a Multi Link Flexible Robot	93
Control of an Ostrich-Like Knee Joint for a Biped Robot Based on Passive Dynamic Walking	103
Adaptive Neural Network Control of Robot with Passive Last Joint Chenguang Yang, Zhijun Li, Jing Li, and Alex Smith	113
4M-Model Based Bionic Design of Artificial Skeletal Muscle Actuated by SMA	123
Design Considerations of a Robotic Head for Telepresence Applications	131
Scaling Studies for an Actively Controlled Curvature Robotic  Pectoral Fin	141
Control of a Passive-Dynamic-Walking-Based Biped Model with Semicircular Feet for a Small Stair Step	151
Evaluation of a Proposed Workspace Spanning Technique for Small Haptic Device Based Manipulator Teleoperation	161
Robot Intelligence, Learning and Linguistics	
Prior Knowledge Employment Based on the K-L and Tanimoto Distances Matching for Intelligent Autonomous Robots	171
Interactive Features for Robot Viewers	181
Searching Energy-Efficient Route in Rough Terrain for Mobile Robot with Ant Algorithm	194
Real-Time Recognizing Human Hand Gestures	205

Table of Contents – Part III	XVII
Safe Robot Learning by Energy Limitation	216
Robot Mechanism and Design	
Motion Recovery of Parallel Manipulators Using Task-Decomposition  Approach	226
Derivation of Dynamic Equations of Serial Robot Manipulators with Coupled Ideal Joint Motion	236
Mechatronics Design Applied to the Concept of Service Robot to Clean	0.40
Storage Tanks	248
Research on the Impact of the Number of Wheels and Layouts to the Performances of Omni-Directional Chassis	258
A Novel Distributed Tuned Mass Damper Design Approach	268
Robot Motion Analysis and Planning	
The Basic Component of Computational Intelligence for AX-12 Robotic Arm Manipulator	277
Guiding Sampling-Based Motion Planning by Forward and Backward Discrete Search	289
Kinematic Modeling of a Heavy-Duty Forging Manipulator	299
Simultaneous Localization and Map Building for Wheeled Robot with Colored Measurement Noise	311
A Comparison of Different Metaheuristic Algorithms for Optimizing Blended PTP Movements for Industrial Robots	321

Stable Gait Planning for Biped Robot's Lower Limb Based on Natural ZMP Trajectories	331
Numerical and Analytical Methods for Synthesis of Central Pattern Generators	342
Trajectory Planning for Omni-Directional Mobile Robot Based on Bezier Curve, Trigonometric Function and Polynomial	352
A Low-Cost, Practical Localization System for Agricultural Vehicles Gustavo Freitas, Ji Zhang, Bradley Hamner, Marcel Bergerman, and George Kantor	365
Static Gait Control for Quadruped Robot	376
Robotic Vision, Recognition and Reconstruction	
Accurate Correction of Robot Trajectories Generated by Teaching Using 3D Vision by Laser Triangulation	385
Improved Method of Robot Trajectory in IBVS Based on an Efficient Second-Order Minimization Technique	395
Tactile Sensors Based Object Recognition and 6D Pose Estimation Achint Aggarwal and Peter Kampmann	406
Graph-Based Detection of Objects with Regular Regions	417
Semantic Interpretation of Novelty in Images Using Histograms of Oriented Gradients	427
Far-Field Terrain Perception Using Max-Margin Markov Networks Jun Tu, Chengliang Liu, Mingjun Wang, Liang Gong, and Yanming Li	437
An Adaptive Trajectory Prediction Method for Ping-Pong Robots  Yifeng Zhang, Rong Xiong, Yongsheng Zhao, and Jian Chu	448
A New Method of Stereo Localization Using Dual-PTZ-Cameras Jing Xin, Xiaomin Ma, Yi Deng, Ding Liu, and Han Liu	460

Monocular Depth from Motion Using a New Closed-Form Solution Mohamed Hasan and Mohamed Abdellatif	473
Fast Template Matching of Objects for Visual SLAM	484
Body Pixel Classification by Neural Network	494
Robust Recognition against Illumination Variations Based on SIFT Farzan Nowruzi, Mohammad Ali Balafar, and Saeid Pashazadeh	503
Robust Real-Time Stereo Edge Matching by Confidence-Based Refinement	512
A Symbol Identifier Based Recognition and Relative Positioning Approach Suitable for Multi-robot Systems	523
New Stereovision Self-calibration Method and Its Application in Vision Guided Approaching	532
Planning and Navigation	
A Real-Time On-Board Orthogonal SLAM for an Indoor UAV	542
An Infrastructure-Free Indoor Navigation System for Blind People Diansheng Chen, Wei Feng, Qiteng Zhao, Muhua Hu, and Tianmiao Wang	552
Q-Tree: Automatic Construction of Hierarchical State Representation for Reinforcement Learning	562
Navigation and Localization for Autonomous Vehicle at Road Intersections with Low-Cost Sensors	577
On-Road Motion Planning for Autonomous Vehicles	588
On the Development of an Open-Source Vehicle Dynamics Simulation	598

Table of Contents – Part III

XIX

# XX Table of Contents – Part III

A Study of New Path Planning Algorithm Using Extended A*	
Algorithm with Survivability	
Min-Ho Kim, Hee-Mu Lee, Yuanlong Wei, and Min-Cheol Lee	
Author Index	619