Lecture Notes in Artificial Intelligence 2744

Edited by J. G. Carbonell and J. Siekmann

Subseries of Lecture Notes in Computer Science

Springer Berlin

Berlin Heidelberg New York Hong Kong London Milan Paris Tokyo Vladimír Mařík Duncan McFarlane Paul Valckenaers (Eds.)

Holonic and Multi-Agent Systems for Manufacturing

First International Conference on Industrial Applications of Holonic and Multi-Agent Systems, HoloMAS 2003 Prague, Czech Republic, September 1-3, 2003 Proceedings



Series Editors

Jaime G. Carbonell, Carnegie Mellon University, Pittsburgh, PA, USA Jörg Siekmann, University of Saarland, Saarbrücken, Germany

Volume Editors

Vladimír Mařík Czech Technical University, Fac

Czech Technical University, Faculty of Electrical Engineering Technicka 2, 16627, Prague 6, Czech Republic and

Rockwell Automation Research Center Prague Americká 22, 12000 Prague 2, Czech Republic

E-mail: marik@labe.felk.cvut.cz

Duncan McFarlane University of Cambridge, Institute for Manufacturing Mill Lane, Cambridge, CB2 1RX, UK E-mail: dcm@eng.cam.ac.uk

Paul Valckenaers
Katholieke Universiteit Leuven
Mechanical Engineering Department - P.M.A.
Celestijnenlaan 300 B, 3001 Leuven, Belgium
E-mail: Paul. Valckenaers@mech.kuleuven.ac.be

Cataloging-in-Publication Data applied for

A catalog record for this book is available from the Library of Congress.

Bibliographic information published by Die Deutsche Bibliothek Die Deutsche Bibliothek lists this publication in the Deutsche Nationalbibliografie; detailed bibliographic data is available in the Internet at http://dnb.ddb.de>.

CR Subject Classification (1998): I.2.11, I.2, J.1, D.2, I.6

ISSN 0302-9743

ISBN 3-540-40751-0 Springer-Verlag Berlin Heidelberg New York

This work is subject to copyright. All rights are reserved, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, re-use of illustrations, recitation, broadcasting, reproduction on microfilms or in any other way, and storage in data banks. Duplication of this publication or parts thereof is permitted only under the provisions of the German Copyright Law of September 9, 1965, in its current version, and permission for use must always be obtained from Springer-Verlag. Violations are liable for prosecution under the German Copyright Law.

Springer-Verlag Berlin Heidelberg New York a member of BertelsmannSpringer Science+Business Media GmbH

http://www.springer.de

© Springer-Verlag Berlin Heidelberg 2003 Printed in Germany

Typesetting: Camera-ready by author, data conversion by PTP Berlin GmbH Printed on acid-free paper SPIN: 10929254 06/3142 5 4 3 2 1 0

Preface

The increasing complexity of manufacturing systems as well as the overall demands for flexible and fault-tolerant control of production processes stimulates (among many others) two key emerging technologies that are already making an important breakthrough in the field of intelligent manufacturing, control, and diagnostics. These two paradigms are:

- the holonic approach based on the event-driven control strategy, usually aimed at modular control systems that are directly physically linked with the manufacturing hardware equipment, and
- the multi-agent approach developed in the area of distributed information processing.

The research communities working in both these fields are approaching the problem of intelligent manufacturing from different viewpoints and, until recently, to a certain extent, in an independent way. We can however observe quite a clear convergence of these fields in the last few years: the communities have started to cooperate, joining efforts to solve the painful problems involved in achieving effective industrial practice. We can see convergence in the terminology, standards and methods being applied.

The shift in the focus of holonic research over the last five years is significant: Whereas Phase I of the HMS (Holonic Manufacturing Systems) Consortium project was aimed primarily at low-level real-time control and resulted, for example, in the IEC 61499 standard for real-time function-block oriented holonic control, the proposals for Phase II of this consortium are much more concentrated on agent-based control solutions, including knowledge management methods, simulation tools and standards developed by the multi-agent community within the framework of the FIPA consortium activities. The best evidence of this trend is the title and contents of the recently published book

M.S. Deen (ed.): Agent-Based Manufacturing –Advances in the Holonic Approach, Springer-Verlag, Heidelberg, 2003

On the other hand, the multi-agent community realizes to a much wider extent than before that one of the most challenging areas for the application of the agent-based information and decision-making systems is the field of intelligent manufacturing. More and more agent-based systems have started to appear in the manufacturing domain, for simulation, production planning and scheduling goals, and for reconfiguration purposes. In the latter, coalition formation and teamwork planning methods are often applied for this purpose. This trend is strongly supported by the challenging visions of virtual manufacturing and virtual enterprises. The other important emerging challenge is the opportunity to consider each product or semiproduct as an agent/holon – this vision is supported by, for example, the recent results of the AUTO-ID initiative aimed at integrating RFID tagging technology with a global information network.

We should stress that the convergence mentioned above is catalyzed mainly by real industrial needs: a very high flexibility in changing production plans and schedules, real-time fault detection and reconfiguration capabilities, as well as allowing

autonomous subsystems to be easily integrated with various kinds of communication networks are stressed more and more. Satisfying these more complex and demanding requirements needs an exploration of knowledge-intensive solutions as well as the leveraging of the current communication and database technologies. The holonic and multi-agent ideas support trends towards higher degrees of local autonomy connected with larger volumes of knowledge "owned" locally in the control elements, and towards more powerful processors (capable of running real-time, ladder-logic types of code as well as higher-level code written, for example, in C++ or Java in parallel) and Web-enabled devices.

Many topics important for agent-based manufacturing are still in the early stages of their research. This is the case in, for example, semantics and ontologies (it would be desirable to use technologies similar or compatible to those in the Semantic Web area, but this seems to be currently more than difficult), or applying holarchy principles in the agent-oriented solutions.

We hope that the first three HoloMAS workshops held under the DEXA-event umbrella (HoloMAS 2000 in Greenwich, HoloMAS 2001 in Munich and HoloMAS 2002 in Aix-en-Provence) helped to bridge the gap between the holonic and multiagent communities. The interest of both the camps has been increasing and because we have seen there is a chance to cover the whole scene, we decided to transform the HoloMAS workshop into a conference, the **1st International Conference HoloMAS 2003** within the framework of the DEXA 2003 event. We are very thankful to the DEXA Association (Linz, Austria) for supporting the conference idea from the very beginning and to the EU Centre of Excellence MIRACLE at the Czech Technical University of Prague for general support.

We are very glad to declare that 43 papers were submitted, prepared by the most important research bodies engaged in holonic and agent-based manufacturing world-wide to HoloMAS 2003. The PC chose 29 papers to be presented and included in this volume. They contain the most representative results of the corresponding research inside and outside the HMS consortium and provide an excellent overview of the current situation in this subject's research field.

The HoloMAS 2003 conference created an excellent, highly motivating environment, and helped to integrate the community. We believe that it contributed to a better clarification of the goals and to a more efficient coordination of the research in this subject field. The conference also aimed to serve as a display window of holonic and agent-based manufacturing research, offering information about the state-of-the-art to specialists in neighbouring, knowledge-processing research fields covered by the DEXA multi-conference event.

Prague, Cambridge, Leuven June 2003 Vladimir Mařík Duncan McFarlane Paul Valckenaers

HoloMAS 2003

1st International Conference on Industrial Applications of Holonic and Multi-agent Systems, HoloMAS 2003

Applications of Holonic and Multi-agent Systems

Prague, Czech Republic, September 1–3, 2003

Program Co-chairs

Vladimír MAŘÍK Czech Technical University in Prague, and

Rockwell Automation, Czech Republic

Duncan McFARLANE University of Cambridge, UK

Paul VALCKENAERS Katholieke Universiteit, Leuven, Belgium

Program Committee

Hamideh AFSARMANESH University of Amsterdam, The Netherlands

Franz AUINGER Profactor, Austria

Jose BARATA Universidade Nova de Lisboa, Portugal Jeff BRADSHAW University of West Florida, USA

Robert W. BRENNAN University of Calgary, Canada

Sven BRUECKNER ALTARUM, USA

Luis M. CAMARINHA-MATOS Universidade Nova de Lisboa, Portugal

Eduardo CASTELLANO IKERLAN, Spain
Armando COLOMBO Schneider Group, France
Misbah DEEN University of Keele, UK
Klaus FISCHER DFKI GmbH, Germany

Martyn FLETCHER

William GRUVER

Kenneth HALL

Matthias KLUSCH

Agent Oriented Software Ltd., UK

Simon Fraser University, Canada

Rockwell Automation, USA

DFKI GmbH, Germany

Dilip B. KOTAK National Research Council of Canada, Canada Jiří LAŽANSKÝ Czech Technical University, Czech Republic

Peter LUH University of Connecticut, USA Francisco MATURANA Rockwell Automation, USA

Gerard MOREL CRAN, France

Jörg MÜLLER Siemens AG, Germany
Douglas NORRIE University of Calgary, Canada

Michal PĚCHOUČEK Czech Technical University, Czech Republic

Gregory PROVAN Rockwell Scientific Company, USA Leonid SHEREMETOV Mexican Oil Institute, Mexico

Alexander SMIRNOV SPIIRAS, Russia

Shinsuke TAMURA Ambalavanar THARUMARAJAH Mihaela ULIERU Hendrik VAN BRUSSEL Edwin H. VAN LEEUWEN

Tomáš VLČEK Michael ZWICK Fukui University, Japan Buddy Co. Ltd., Australia University of Calgary, Canada Katholieke Universiteit, Leuven, Belgium

BHP-Billiton, Australia

Open University, UK

Czech Technical University, Czech Republic IFW, University of Hannover, Germany

External Reviewers

Jaroslav BÁRTA
Petr BEČVÁŘ
Petr CHARVÁT
Jiří HODÍK
Marek OBITKO
Jiří POSPÍŠIL
Libor PŘEUČIL
Aleš ŘÍHA
Petr ŠLECHTA
Olga ŠTĚPÁNKOVÁ
Pavel TICHÝ
Jiří VOKŘÍNEK
Pavel VRBA
Zdeněk ZDRÁHAL

Czech Technical University, Czech Republic CertiCon, Czech Republic CertiCon, Czech Republic Czech Technical University, Czech Republic ProTyS, Czech Republic CertiCon, Czech Republic Czech Technical University, Czech Republic Czech Technical University, Czech Republic ProTyS, Czech Republic Czech Technical University, Czech Republic Czech Technical University, Czech Republic Rockwell Automation, Czech Republic Czech Technical University, Czech Republic ProTyS, Czech Republic

Organizing Committee

Hana KRAUTWURMOVÁ Zuzana HOCHMEISTEROVÁ Jaroslav BÁRTA Jiří HODÍK Aleš ŘÍHA Jiří VOKŘÍNEK Czech Technical University, Czech Republic Czech Technical University, Czech Republic

Table of Contents

Holonic Manufacturing Systems – Device Control	
Holonic Manufacturing Systems: Phase II	1
A Mechanism for Ensuring Safe Behaviors of Holonic Manufacturing Systems	15
A Real-Time Interface for Holonic Control Devices	25
Integration of Automation Resources in Holonic Manufacturing Applications	35
Foundations/Platforms	
JAVA-Based Agent Platform Evaluation	47
An Approach to the Formal Specification of Holonic Control Systems Paulo Leitão, Armando W. Colombo, Francisco Restivo	59
Holonic Multiagent Systems: A Foundation for the Organisation of Multiagent Systems	71
The Link between Autonomy and Organisation in Multiagent Systems $$ $$ $$ $$ $$ $$ $$ $$ $$ $$ $$	81
Scheduling and Resource Allocation	
Fault-Tolerant Behaviour in Holonic Manufacturing Systems: A Simulation Study	91
Multiagent-Based Process Planning and Scheduling in Context of	100
Supply Chains	100

Improving Multi-agent Based Scheduling by Neurodynamic Programming	110
Agent Architecture for Dynamic Job Routing in Holonic Environment Based on the Theory of Constraints	124
Simulation and Integration	
A Heterogeneous Multi-agent Modelling for Distributed Simulation of Supply Chains	134
Integration of Shop Floor Holons with Automated Business Processes Klaus Glanzer, Thomas Schmidt, Gerald Wippel, Christoph Dutzler	146
Proposal of Holonic Manufacturing Execution Systems Based on Web Service Technologies for Mexican SMEs	156
Multi-agent Systems	
Secure FIPA Compliant Agent Architecture Draft	167
Agent Exchange – Virtual Trading Environment	179
Adding OWL Semantics to Ontologies Used in Multi-agent Systems for Manufacturing	189
Complex Data Integration Based on a Multi-agent System	201
A Multi-agent Architecture for Distributed Design	213
AgentAllocator: An Agent-Based Multi-criteria Decision Support System for Task Allocation	225

App	licat	tions

An Approach to Process Automation Based on Cooperating Subprocess Agents	236
Ilkka Seilonen, Teppo Pirttioja, Pekka Appelqvist, Aarne Halme, Kari Koskinen	200
Evaluating a Holonic Packing Cell	246
FABMAS: An Agent-Based System for Production Control of Semiconductor Manufacturing Processes	258
A Case Study for Modular Plant Control	268
Implementation of Mobile-Agent-Based Network Management Systems for National Broadband Experimental Networks in Taiwan Li-Der Chou, Kun-Chang Shen, Ko-Chung Tang, Chi-Chia Kao	280
An Agent-Based Simulator for Electricity Markets: Seller, Buyer, and Trader Players	290
AgenTec – Concepts for Agent Technology in Automation	302
Cost-Based Dynamic Reconfiguration System for Evolving Holarchies Francisco P. Maturana, Pavel Tichý, Petr Šlechta, Raymond J. Staron, Fred M. Discenzo, Kenwood Hall, Vladimír Mařík	310
Author Index	321